


 **Code**

 Issues

 Pull requests

 Actions

 Projects

 Wiki

 Security

 master ▾

...

[ece523_doc21](#) / [ece523](#) / [hw](#) / [hw2](#) / hw2ece523.pdf



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 History

 1 contributor

4.99 MB

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① Linear classifier with a Margin :

a data set has 2 data points

$$x_1 \in C_1 (y_1 = +1)$$

$$x_2 \in C_2 (y_2 = -1)$$

Setup the minimization problem w/

constraints on $w^T x_1 + b$

$$w^T x_2 + b$$

To find the hyperplane, we need to solve

$$\arg \min_{w \in \mathcal{R}^p} \|w\|_2^2 = \arg \min_{w \in \mathcal{R}^p} w^T w$$

subject to :

$$w^T x_1 + b = 1$$

$$w^T x_2 + b = -1$$

Using Lagrange multiplier λ_1 and λ_2 , we can write the following:

$$L = \arg \min_{w \in \mathcal{R}^p} \left\{ \|w\|_2^2 + \lambda_1 (w^T x_1 + b - 1) + \lambda_2 (w^T x_2 + b + 1) \right\}$$

Taking the derivative w.r.t. w and b and make them equal to 0.

$$\frac{\partial L}{\partial w} = 0 \Rightarrow 2w + \lambda_1 x_1 + \lambda_2 x_2 = 0$$

$$\frac{\partial L}{\partial b} = 0 \Rightarrow \lambda_1 + \lambda_2 = 0$$

$$\lambda_1 = -\lambda_2$$

$$w = -\frac{1}{2} (\lambda_1 x_1 + \lambda_2 x_2) \Rightarrow \text{substituting } \lambda_1 = -\lambda_2$$

$$w = -\frac{1}{2} (-\lambda_2 x_1 + \lambda_2 x_2)$$

$$w = \frac{\lambda_2}{2} (x_1 - x_2)$$

$$2w = \lambda_2 (x_1 - x_2)$$

$$w^T x_1 + b = -w^T x_2 - b$$

$$2b = -w^T (x_1 + x_2)$$

$$b = -\frac{w^T}{2} (x_1 + x_2)$$

$$2 = 1+1 \Rightarrow 2 = (w^T x_1 + b) - (w^T x_2 + b)$$

$$2 = w^T x_1 - w^T x_2$$

$$2 = w^T (x_1 - x_2) \quad \text{We now substitute for } w.$$

$$2 = \frac{\lambda_2}{2} (x_1^T - x_2^T) (x_1 - x_2)$$

$$2 = \frac{\lambda_2}{2} (x_1^T x_1 + x_1^T x_2 - x_2^T x_1 + x_2^T x_2) \quad x_{n \times d}$$

$$\lambda_2 = 4 (x_1^T x_1 + x_1^T x_2 - x_2^T x_1 + x_2^T x_2)^{-1}$$

$$\lambda_1 = -\lambda_2$$

② Linear Regression with Regularization:

$$\text{The loss function } L(w) = \sum_{i=1}^n (y_i - w^T x_i)^2$$

$$= (y - Xw)^T (y - Xw)$$

sum of squared
errors from lecture notes

Adding the penalty:

$$\begin{aligned} L(w) &= (y - Xw)^T (y - Xw) + \lambda w^T w \\ &= (y^T - w^T X^T) (y - Xw) + \lambda w^T w \\ &= y^T y - y^T Xw - w^T X^T y + w^T X^T X w + \lambda w^T w \\ &= y^T y - 2 y^T Xw + w^T X^T X w + \lambda w^T w \end{aligned}$$

$$\frac{\partial L}{\partial w} = 0$$

$$0 = -2 X^T y + 2 X^T X w + 2 \lambda w \Rightarrow X^T X w + \lambda w = X^T y$$

$$\frac{\partial L}{\partial W} = 2X^T(W - Y) + 2\lambda W = 0$$

$$X^T Y = X^T X W + \lambda W$$

$$X^T Y = (X^T X + \lambda I) W$$

$$W = (X^T X + \lambda I)^{-1} X^T Y$$

parameter of linear regression with penalty.

It penalizes W for taking large values. It makes W small to prevent the coefficients from overfitting.

④ Conceptual.

$$P(W|X)$$

$$\frac{P(X|W) P(W)}{P(X)}$$

- Easier to model because it doesn't require modeling the joint distribution $P(W, X)$.
- Estimate the posterior directly.
- Can't detect outlier in the data.
- $P(X|W)$ become hard to model if the dimension X is large.
- uses the available data to estimate the prior $P(W)$, likelihood $P(X|W)$, and evidence $P(X)$.
- Known the evidence term $P(X)$ is useful because it normalizes the term and changes the posterior into probability $[0, 1]$.
The likelihood term can be bigger than 1.

2/17/2021

hw2code

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt
import numpy as np
from matplotlib import cm
import matplotlib.mlab as ml
```

```
from scipy.interpolate import griddata
```

HW2 Q2

Using real data from <https://github.com/gditzler/UA-ECE-523-Sp2018/tree/master/data>

```
In [2]: path = '/home/safwan/Documents/spring2021/ece523/hw/hw2/acute-nephritis.csv'
data_pd = pd.read_csv(path, header=None)
```

```
In [3]: data_pd
```

```
Out[3]:
```

	0	1	2	3	4	5	6
0	-1.77236	-0.562162	0.841625	-1.408310	-0.979364	-0.841625	0
1	-1.55248	-0.562162	-1.178280	0.704154	1.012560	1.178280	0
2	-1.55248	-0.562162	0.841625	-1.408310	-0.979364	-0.841625	0
3	-1.49751	-0.562162	-1.178280	0.704154	1.012560	1.178280	0
4	-1.49751	-0.562162	0.841625	-1.408310	-0.979364	-0.841625	0
...
115	1.47094	-0.562162	0.841625	0.704154	-0.979364	1.178280	1
116	1.52591	-0.562162	-1.178280	-1.408310	-0.979364	-0.841625	0
117	1.52591	1.764020	0.841625	-1.408310	1.012560	-0.841625	1
118	1.52591	-0.562162	0.841625	0.704154	-0.979364	1.178280	1
119	1.52591	-0.562162	0.841625	0.704154	-0.979364	1.178280	1

120 rows × 7 columns

```
In [4]: #seperating the features and labels.
x = data_pd.iloc[:, 0:-1]
y = data_pd.iloc[:, -1]
#conveting to array
x_arr = x.values
y_arr = y.values
```

```
In [5]: # Adding 1 at the begining of every feature vector
x_arr = np.c_[np.ones((x_arr.shape[0], 1)), x_arr]
y_arr = y_arr[:, np.newaxis]
w = np.zeros((x_arr.shape[1],1)) #initializing the parameter vector w.
```

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1/6

2/17/2021

hw2code

```
In [37]: #creating training test date
X_train, X_test, y_train, y_test = \
    train_test_split(x_arr, y_arr, test_size=0.20)
```

```
In [38]: #creating the logistic function
def logistic_func(w, x):
    #x is a feature vector
    #w is the parameter vector
    regression = np.dot(x, w) #finding weighted sum of inputs
    result = 1 / (1 + np.exp(- regression))
    return result
```

```
In [39]: #creating cross entropy function
def cross_entropy_func(w , x, y):
    result = - np.sum (y * np.log(logistic_func(w,x)) + (1-y)* np.log(1- logistic_func(w,x)))
    return result
```

```
In [40]: #gradient function
def gradient_func(w, x, y, learning_rate):
    result = np.dot(x.T, logistic_func(w, x) - y)
    return learning_rate * result
```

```
In [41]: #gradient descent function
def sgd(w,x,y,iterations, learning_rate):
    m = len(y) # size of the training dataset
    cost_history = []
    for _ in range(iterations):

        for j in range(m): #loop through every sample
            x_i = x[1,:].reshape((1,len(w)))
            y_i = y[1,:].reshape((1,1))
            w = w - gradient_func(w,x_i,y_i, learning_rate)
            cost = cross_entropy_func(w, x_i, y_i)
            cost_history.append(cost)

    return w, cost_history
```

```
In [ ]:
```

```
In [42]: #testing the model
train = sgd(w, X_train, y_train,500, 0.005)
```

```
In [43]: #the optimized parameters
w_t = train[0]
w_t
```

```
Out[43]: array([[0.86030556],
                [0.93441229],
                [1.51759622],
                [0.72405467],
                [0.6057876 ],
                [0.871111  ],
                [1.01368084]])
```

```
In [44]: #showing some values of the cost function
train[1][:10]
```

2/17/2021

hw2code

```
Out[44]: [0.2267844997750445,
          0.12419529120361983,
          0.08384644412720996,
          0.06284558529725653,
          0.0500969894039993,
          0.041576957340538706,
          0.03549744285766436,
          0.030948776299568707,
          0.027421255026845663,
          0.024607842100965876]
```

```
In [45]: #testing with new data
predict = logistic_func(w_t, X_test)
# predict
```

```
In [46]: #finding the accuracy
for i in range(len(predict)):
```

```

    if predict[i] >= 0.5:
        predict[i] = 1
    else:
        predict[i] = 0
# predict= 0
diff = predict - y_test
accuracy = (1.0 - (float(np.count_nonzero(diff)) / len(diff)))*100
accuracy

```

Out[46]: 83.33333333333334

In [16]: `# predict.shape`

HW2 Q3

Density estimation

In [17]: `#generating training dataset`

```

def gen_cb(N, a, alpha):
    """
    N: number of points on the checkerboard
    a: width of the checker board (0<a<1)
    alpha: rotation of the checkerboard in radians
    """
    d = np.random.rand(N, 2).T # THIS IS THE LINE OF CODE THAT IS DIFFERENT
    d_transformed = np.array([d[0]*np.cos(alpha)-d[1]*np.sin(alpha),
                              d[0]*np.sin(alpha)+d[1]*np.cos(alpha)]).T
    s = np.ceil(d_transformed[:,0]/a)+np.floor(d_transformed[:,1]/a)
    lab = 2 - (s%2)
    data = d.T
    return data, lab

```

In [18]:

```

X, y = gen_cb(3000, .25, np.pi / 3)
plt.figure()
plt.plot(X[np.where(y==1)[0], 0], X[np.where(y==1)[0], 1], 'o')
plt.plot(X[np.where(y==2)[0], 0], X[np.where(y==2)[0], 1], 's', c = 'r')
plt.xlabel("x1")
plt.ylabel("x2")

```

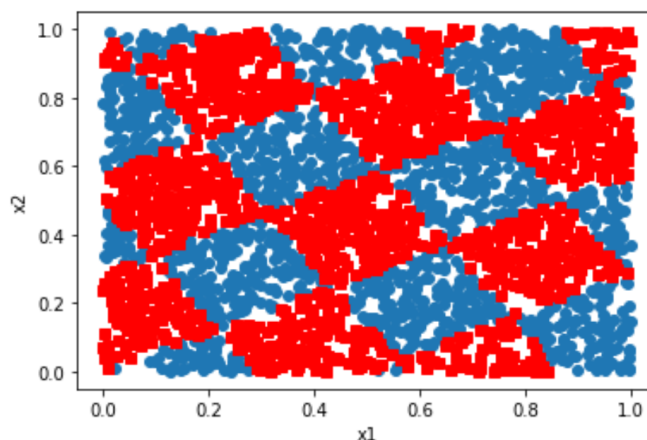
Out[18]: Text(0, 0.5, 'x2')

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3/6

2/17/2021

hw2code



In [19]: `#creating a function for implementing k nearest neighbor (knn)`

```

def knn(k, X ,y, point):
    x1, x2 = X[y==1], X[y==2] #x1blue x2red

```

```

n1 = len(x1)
n2 = len(x2)

dataset = X.tolist()
for i in range(len(dataset)):
    dataset[i].append(y[i])

n=len(dataset)
dist_list = []
for i in dataset:
    dist = np.linalg.norm(point-np.array(i[:-1])) #find the euclidean distar
    i.append(dist)
dataset.sort(key=lambda tup: tup[3]) #sort
k_nearest = dataset[:k] #take only the first k elements
largest_k = max(k_nearest, key=lambda x: x[3])

#now find how many neighbor in class blue 1
k_1 = [x for x in k_nearest if x[2] == 1.0]

#now find how many neighbor in class blue 2
k_2 = [x for x in k_nearest if x[2] == 2.0]

#calculating the volume
r = largest_k[-1]

#radius of the circle
v = np.pi * (r**2)

#p(x|y=blue)
pb = (len(k_1)/(n1*v))

#p(x|y=red)
pr = (len(k_2)/(n2*v))

#p(x)
px= len(k_nearest)/(n*v)

return pr,pb,px

```

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4/6

2/17/2021

hw2code

computing the liklihood

```

In [20]: x1, x2 = X[y==1], X[y==2] #x1blue x2red
#py(blue)
p_blue = len(x1)/len(X)
#py(red)
p_red = len(x2)/len(X)

```

generating test dataset

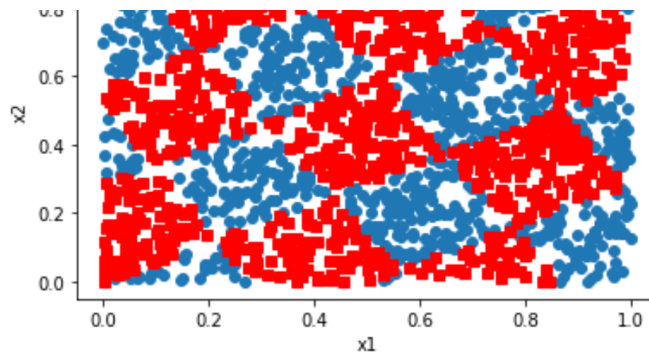
```

In [21]: X_t, y_t = gen_cb(2000, .25, np.pi / 3)
plt.figure()
plt.plot(X_t[np.where(y_t==1)[0], 0], X_t[np.where(y_t==1)[0], 1], 'o')
plt.plot(X_t[np.where(y_t==2)[0], 0], X_t[np.where(y_t==2)[0], 1], 's', c = 'r')
plt.xlabel("x1")
plt.ylabel("x2")

```

Out[21]: Text(0, 0.5, 'x2')





```
In [22]: #testing the model
result = X_t.tolist()
for i in range(len(X_t)):
    px_r,px_b,px = knn(15,X, y, X_t[i,:])
    p_1 = px_b*p_blue/px
    p_2 = px_r*p_red/px
    if p_1 > p_2:
        result[i].append(1.0)
    else:
        result[i].append(2.0)
```

```
In [23]: #convert to np array
r = np.array(result)
x_r = r[:, :2]
y_r = r[:, -1]
```

```
In [24]: def plot_contour(x,y,z,resolution = 50,contour_method='linear'):
    resolution = str(resolution)+'j'
    X,Y = np.mgrid[min(x):max(x):complex(resolution), min(y):max(y):complex(resolution)]
    points = [[a,b] for a,b in zip(x,y)]
    Z = griddata(points, z, (X, Y), method=contour_method)
```

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5/6

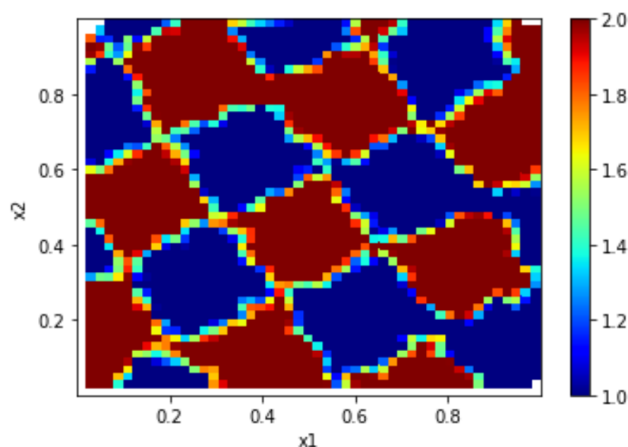
2/17/2021

hw2code

```
return X,Y,Z
```

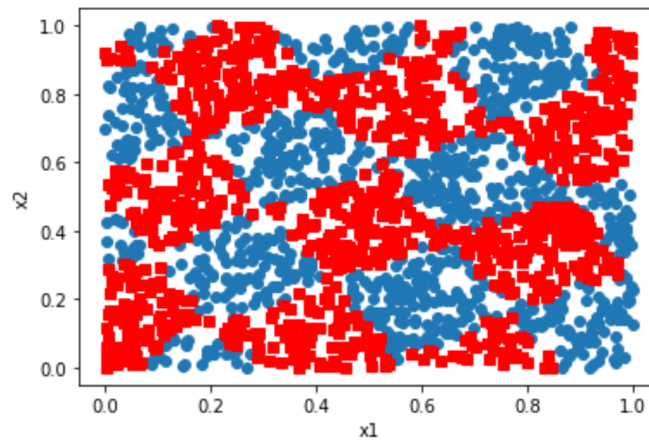
```
X,Y,Z = plot_contour(r[:,0],r[:,1],r[:,2],resolution = 50,contour_method='linear')
```

```
In [25]: #plotting P(x|y) with pcolor
plt.pcolor(X,Y, Z, cmap = 'jet')
plt.colorbar()
plt.xlabel("x1")
plt.ylabel("x2")
plt.show()
```



```
In [26]: #ploting  $P(x|y)$  with plot
plt.plot(x_r[np.where(y_r==1)[0], 0], x_r[np.where(y_r==1)[0], 1], 'o')
plt.plot(x_r[np.where(y_r==2)[0], 0], x_r[np.where(y_r==2)[0], 1], 's', c = 'r')
plt.xlabel("x1")
plt.ylabel("x2")
```

Out[26]: Text(0, 0.5, 'x2')



In []:

