

# Agenda

**Chair: Ben**

## **1 Attendees**

- Sean
- Sammy
- Pavi
- Isaac
- Ben
- Huy Nguyen

## **2 Questions**

Questions for the client.

### **2.1 General**

- What does the map look like, physical obstacles and lines?
- No go zones, are they represented physically or just graphically on the map?
- Is the starting location and orientation of the robot known?
- How much of the map do we explore?
- How is accuracy measured?
- When can we access the robot?

## **2.2 Technical**

- Wifi control detail?
- How are the No Go Zones intended to be selected on the UI?

## **3 Negotiation**

- What milestones are most important?
- ....

## **4 Next meeting**

## **5 Other business**

## **6 Close meeting**