

Agenda

Chair: Ben

1 Attendees

- Chair: Ben
- Facilitator: Pavi
- TimeKeeper: Sean
- Recorder: Isaac
- Sammy
- Huy Nguyen

2 Questions

Questions for the client.

2.1 General

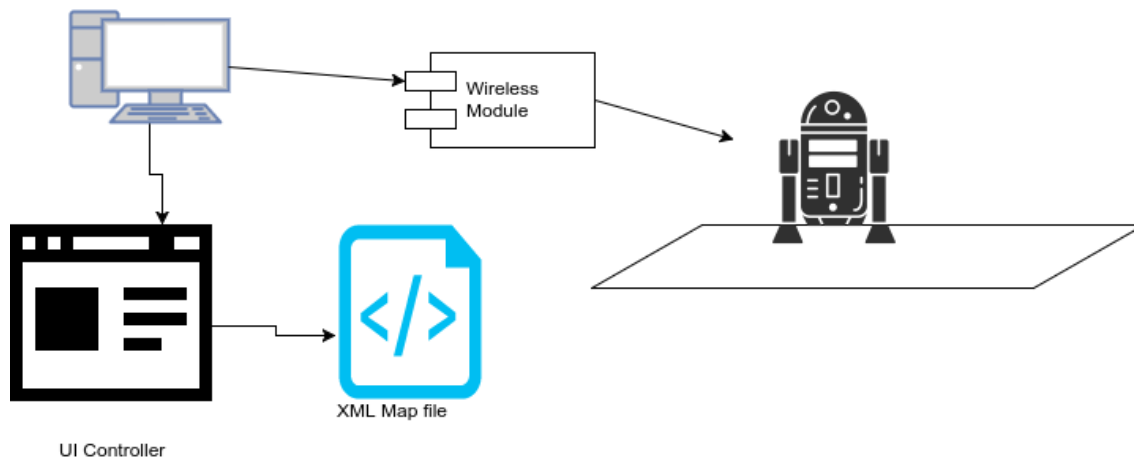
- What does the map look like, physical obstacles and lines?
- No go zones, are they represented physically or just graphically on the map?
- Is the starting location and orientation of the robot known?
- How much of the map do we explore?
- How is accuracy measured?
- When can we access the robot?

2.2 Technical

- Wifi control detail?
- How are the No Go Zones intended to be selected on the UI?

3 System Overview

PG29 - Robot System Diagram



4 Negotiation

- What milestones are most important?
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5 Next meeting

6 Other business

7 Close meeting