



UNIVERSITY OF  
CALGARY

Department of Computer Science

# Graph Representation in Java

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CPSC 319 - Data Structures,  
Algorithms, and Their Applications

- Please read the lecture material first and then continue this tutorial:
- <http://pages.cpsc.ucalgary.ca/~hudsonj/CPSC319W20/Slides/CPSC319-8-1-Graphs.pdf>

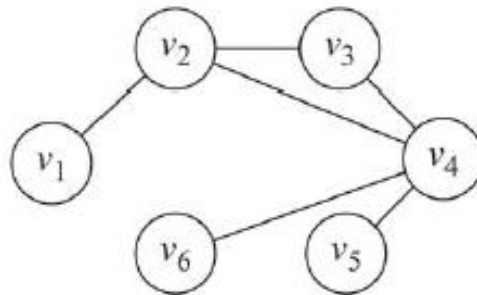
Quick question:

- What are the differences between graphs and trees?

- Well there are a number of differences, but one important one in my opinion is that:
  - In a tree there are no cycles, meaning that if start moving from a node you cannot come back to that node with passing each “edge” only once. But in graphs you can have loops.
- <https://www.geeksforgeeks.org/difference-between-graph-and-tree/>

- Now we're going to talk about two Graph Representation techniques:
  - Adjacency Matrix
  - Adjacency List
- Graph representation techniques allows us to store a graph into the memory therefore we will be able to work with them using programming languages like Java for example.
- First let's have a quick reminder of what these two techniques are.

- Vertices represent row and columns
- Edges are defined by values in the matrix.
- For more detailed info please checkout the lectures if you haven't done so already

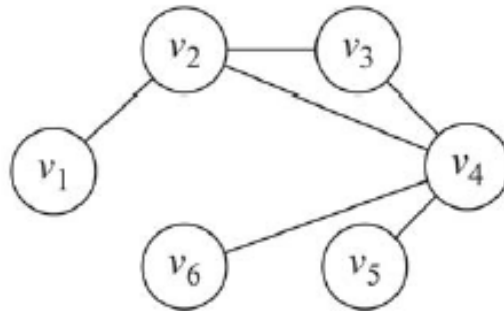


(a) Graph

	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$
$v_1$	0	1	0	0	0	0
$v_2$	1	0	1	1	0	0
$v_3$	0	1	0	1	0	0
$v_4$	0	1	1	0	1	1
$v_5$	0	0	0	1	0	0
$v_6$	0	0	0	1	0	0

(b) Adjacency Matrix

- We have a table (or an array) with the same size as the number of vertices.
- In that table, each element represents one vertex and is a list of variable size, listing all the other vertices that are connected to that vertex.



(a) Graph

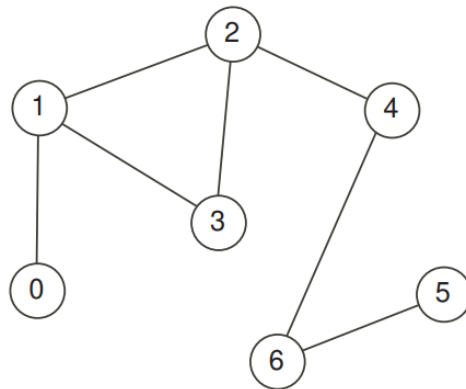
Table 2.1: Adjacency List

Node	Connected To
$v_1$	$v_2$
$v_2$	$v_1, v_3, v_4$
$v_3$	$v_2, v_4$
$v_4$	$v_2, v_3, v_5, v_6$
$v_5$	$v_4$
$v_6$	$v_4$

- Now the question is:
  - What are the practical differences between these two method?
  - When would use one and not the other?
- I will try to answer these by asking you a series of question.
- Please think about the answers before checking the answer slide!

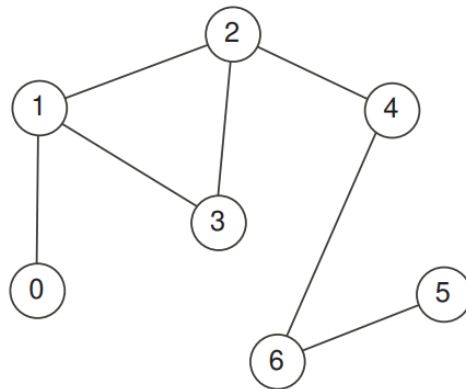


1. Consider an **adjacency matrix** representation of an undirected graph  $G = (V, E)$ . Let  $n = |V|$  be the number of vertices in this graph and let  $m = |E|$  be the number of edges in this graph.



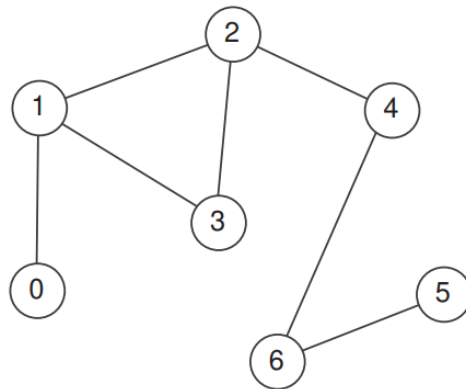
0	1	0	0	0	0	0
1	0	1	1	0	0	0
0	1	0	1	1	0	0
0	1	1	0	0	0	0
0	0	1	0	0	0	1
0	0	0	0	0	0	1
0	0	0	0	1	1	0

- (a) Describe the amount of **storage space** used by this representation of the graph  $G$ . This — and the answer to later questions — might depend on  $n$ ,  $m$ , or both.



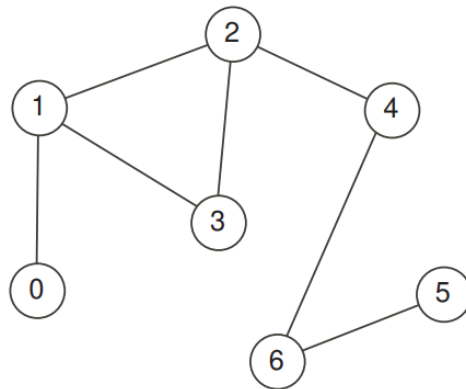
$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

**Solution:** Assuming the uniform cost criterion — and that vertices have names  $0, 1, \dots, n - 1$ , where  $n = |V|$ ,  $\Theta(n^2)$  storage locations are needed. Indeed, if the only data represented is the number  $n$  of vertices, and the matrix used to store information about edges, then  $n^2 + 1$  storage locations are used.



0	1	0	0	0	0	0
1	0	1	1	0	0	0
0	1	0	1	1	0	0
0	1	1	0	0	0	0
0	0	1	0	0	0	1
0	0	0	0	0	0	1
0	0	0	0	1	1	0

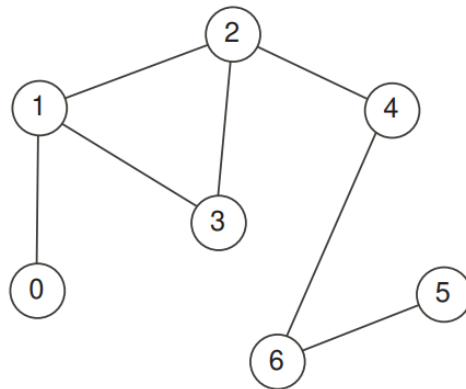
- (b) Describe how to decide whether a given pair of vertices are **neighbours** in  $G$ . Describe the number of steps that an algorithm would use to decide this, using this representation of  $G$ , in the worst case.



$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

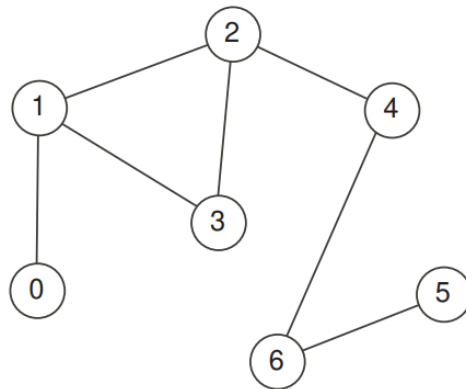
**Solution:** A `NoSuchElementException` should (probably) be thrown if the inputs are integers  $i$  and  $j$  that are *not* both between 0 and  $n-1$ , inclusive. Otherwise, if  $A$  is the matrix used to store information about edges, then `true` should be returned if  $A[i, j] = 1$ , and `false` should be returned otherwise.

This operation can be performed using a constant number of steps in the worst case.



0	1	0	0	0	0	0
1	0	1	1	0	0	0
0	1	0	1	1	0	0
0	1	1	0	0	0	0
0	0	1	0	0	0	1
0	0	0	0	0	0	1
0	0	0	0	1	1	0

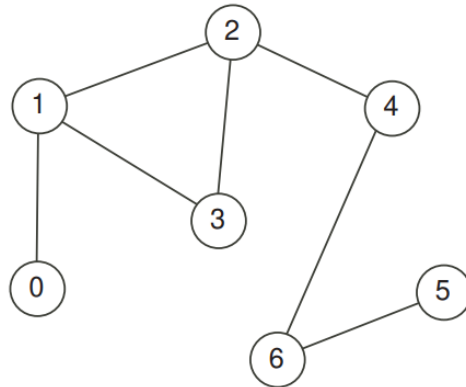
- (c) Describe how to **add an edge** between a given pair of vertices in  $G$ , using this representation. How many steps are needed to do this in the worst case?



$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

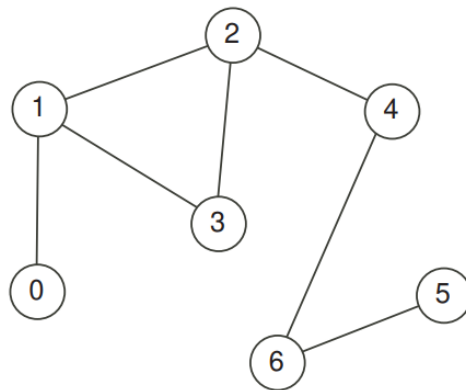
**Solution:** Once again, a `NoSuchElementException` should (probably) be thrown if the inputs are not a pair of integers  $i$  and  $j$  such that  $0 \leq i, j \leq n - 1$  where  $n = |V|$ . An `IllegalArgumentException` should be thrown if  $i = j$ . Another exception — possibly called an `EdgeFoundException` should be thrown if  $A[i, j] = 1$  already. In the only remaining case  $A[i, j]$  and  $A[j, i]$  should both set to be 1.

This operation can also be performed using a constant number of steps in the worst case.



0	1	0	0	0	0	0
1	0	1	1	0	0	0
0	1	0	1	1	0	0
0	1	1	0	0	0	0
0	0	1	0	0	0	1
0	0	0	0	0	0	1
0	0	0	0	1	1	0

(d) Describe how to **add a vertex** in  $G$ . How many steps are needed in the worst case?

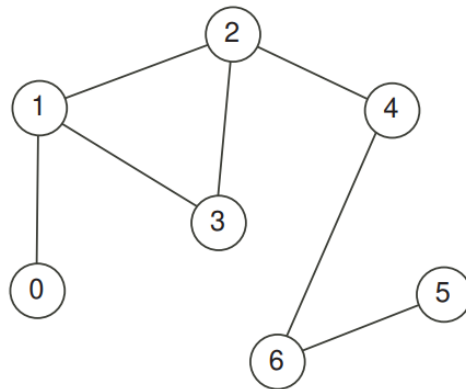


$$\begin{bmatrix}
 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 1 & 1 & 0 & 0 & 0 \\
 0 & 1 & 0 & 1 & 1 & 0 & 0 \\
 0 & 1 & 1 & 0 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & 0 & 1 & 1 & 0
 \end{bmatrix}$$



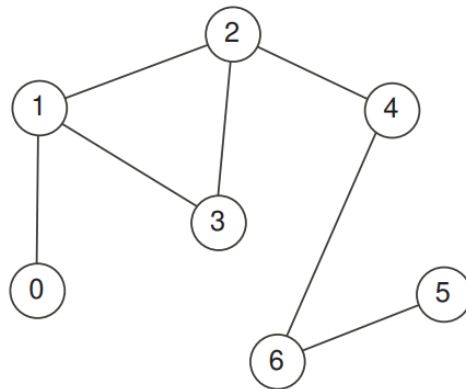
**Solution:** If an array is used then it is necessary to make a copy of the matrix, with one more row and column each filled with 0's.  $\Theta(n^2)$  steps will be required in this case, if the graph originally had  $n$  vertices.

If an ArrayList is used instead of an array then it is possible to use the add operation to extend rows, and to add a new one. It can be shown that the amortized cost will be smaller (indeed, an amortized cost linear in  $n$  can be established) but number of steps used in the worst case will still be in  $\Theta(n^2)$ .



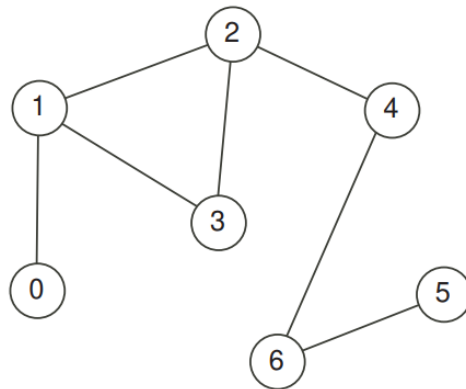
$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

- (e) Describe how to **list the neighbours** of a given vertex. How many steps are needed in the worst case?


$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

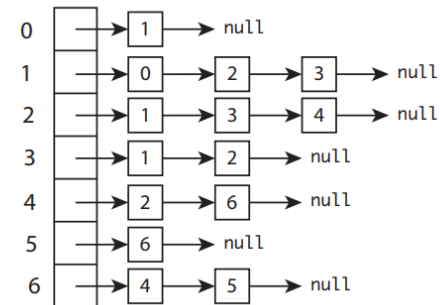
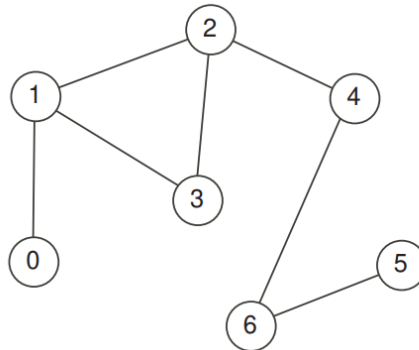
**Solution:** If the input is not an integer between 0 and  $n - 1$  (inclusive), where  $n$  is the current size of  $V$ , then a `NoSuchElementException` should be thrown. Otherwise the entries in row  $i$  should be checked: For  $0 \leq j \leq n - 1$ ,  $j$  should be listed as a neighbour if and only if  $A[i, j] = 1$ .

$\Theta(n)$  steps are used in the worst case.

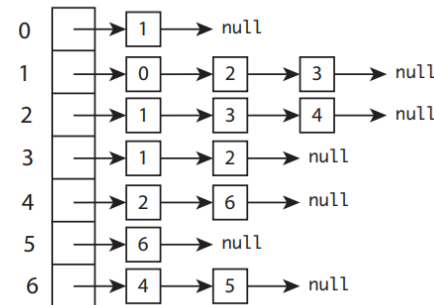
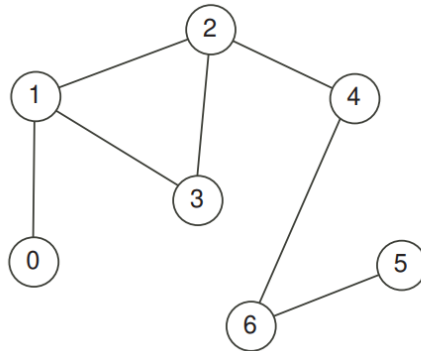


0	1	0	0	0	0	0
1	0	1	1	0	0	0
0	1	0	1	1	0	0
0	1	1	0	0	0	0
0	0	1	0	0	0	1
0	0	0	0	0	0	1
0	0	0	0	1	1	0

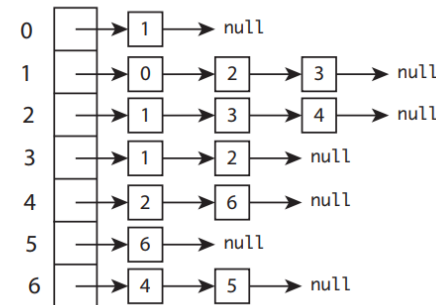
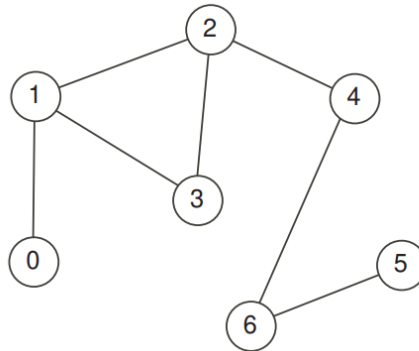
2. Repeat the above question, for an **adjacency list** representation instead of an adjacency matrix representation of an undirected graph  $G$ .



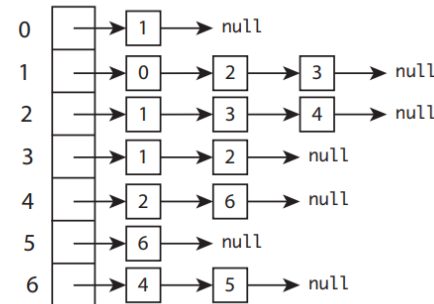
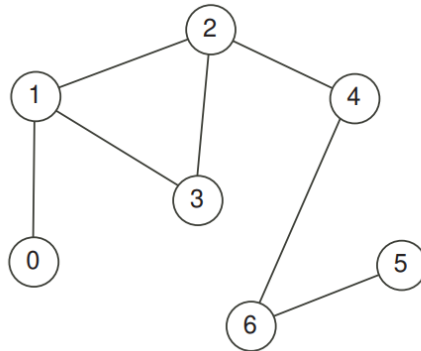
- (a) Describe the amount of **storage space** used by this representation of the graph  $G$ . This — and the answer to later questions — might depend on  $n$ ,  $m$ , or both.



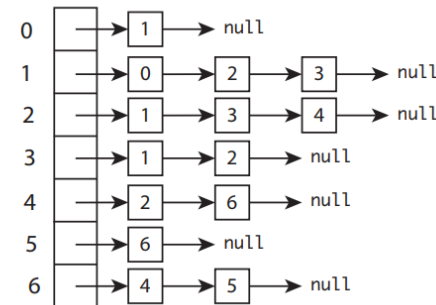
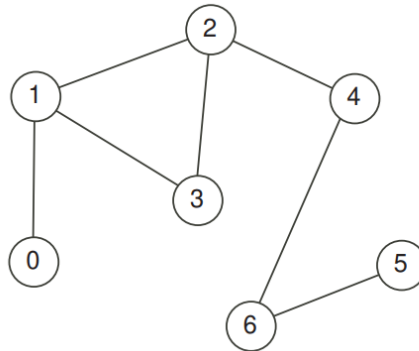
- (a) Assuming the uniform cost criterion and, once again, that vertices are named  $0, 1, 2, \dots, n-1$  where  $n = |V|$ ,  $\Theta(n + m)$  storage locations are used for this representation: One is needed to store  $n$ ,  $n$  are used to represent the one-dimensional array with indices  $0, 1, 2, \dots, n-1$  and storing the heads of linked lists, and (including space for references to nodes) slightly less than another  $2m$  locations are needed to store the linked lists of neighbours of nodes.



- (b) Describe how to decide whether a given pair of vertices are **neighbours** in  $G$ . Describe the number of steps that an algorithm would use to decide this, using this representation of  $G$ , in the worst case.

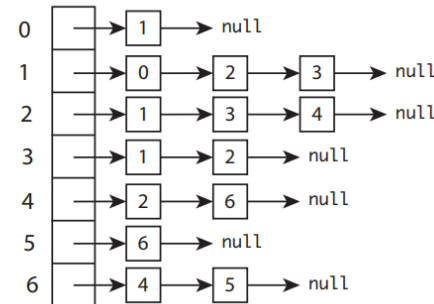
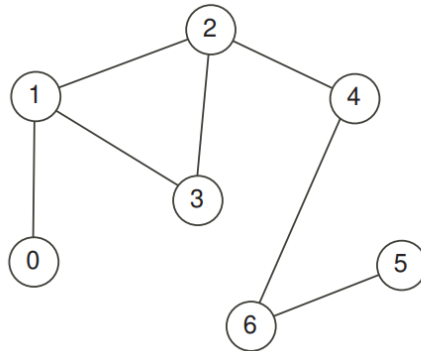


- (b) As for part (b) above, a `NoSuchElementException` should be thrown if the inputs  $(i, j)$  are not integers between  $0$  and  $n - 1$ , inclusive. Otherwise, if  $A$  is the (one-dimensional) array to store heads of linked lists, then either the linked list at  $A[i]$  should be traversed to search for  $j$ , or the linked list at  $A[j]$  should be traversed to search for  $i$  — returning `true` if the desired integer is found, and `false` otherwise.. In the worst case the number of steps used will be linear in the maximum degree of any node in the graph — in  $O(n)$ , in the worst case.



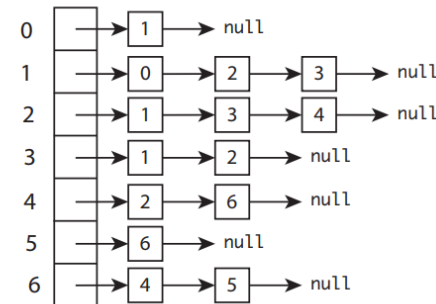
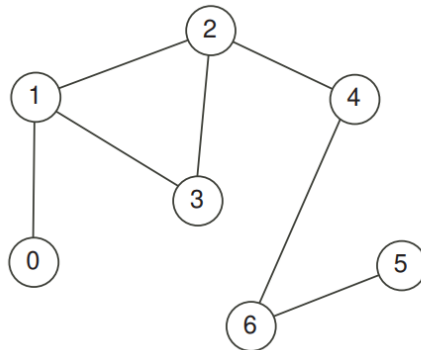


- (c) Describe how to **add an edge** between a given pair of vertices in  $G$ , using this representation. How many steps are needed to do this in the worst case?

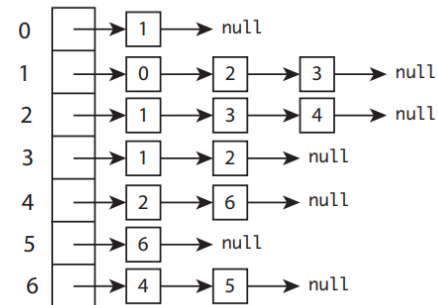
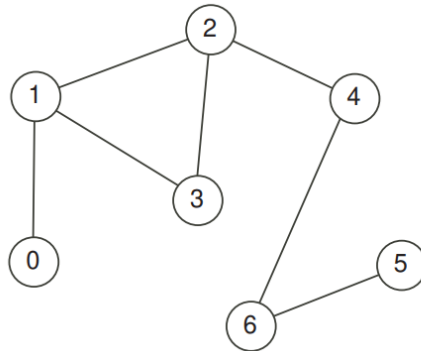


(c) As in part (c), above, a `NoSuchElementException` should be thrown if the inputs are not a pair of integers  $i$  and  $j$  such that  $0 \leq i, j \leq n - 1$  where  $n = |V|$ . An `IllegalArgumentException` should be thrown if  $i = j$ . Either the linked list at  $A[i]$  should be traversed in search for  $j$ , or the linked list at  $A[j]$  should be traversed in search for  $i$  — with an `EdgeFoundException` thrown if the integer is found. Otherwise,  $j$  should be inserted into the linked list  $A[i]$  and  $i$  should be inserted into the linked list at  $A[j]$ .

The number steps used by this process is at most linear in the maximum degree of any node — in  $O(n)$ , in the worst case.

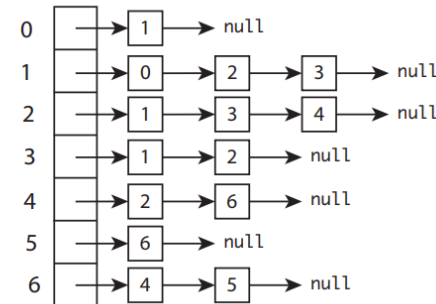
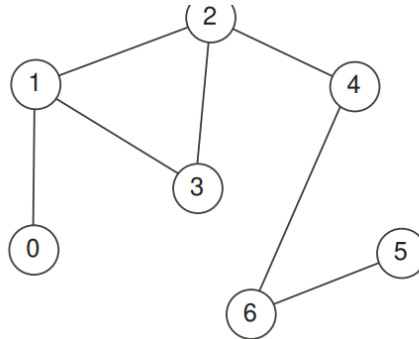


(d) Describe how to **add a vertex** in  $G$ . How many steps are needed in the worst case?

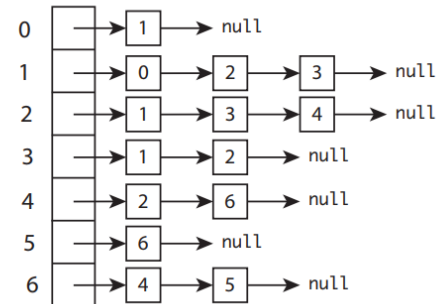
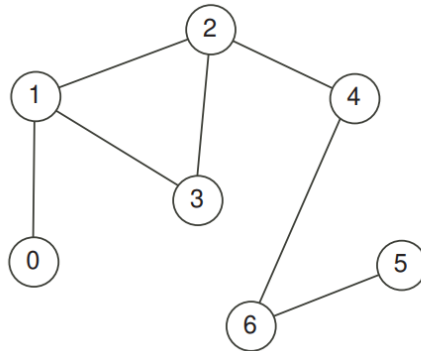


- (d) If an array is used to store linked lists then it is necessary to copy this array, with one more entry added. References to linked lists can be copied from the existing array to corresponding positions in the new array, and the final entry can be set to null.  $\Theta(n)$  steps are required in the worst case.

If an ArrayList is used to store linked lists then the add operation can be used to extend the ArrayList instead. The amortized cost of a sequence of operations will be reduced — indeed, a constant bound can be established — but the number of steps used will still be in  $\Theta(n)$  in the worst case.

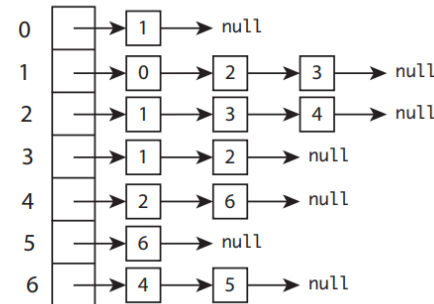
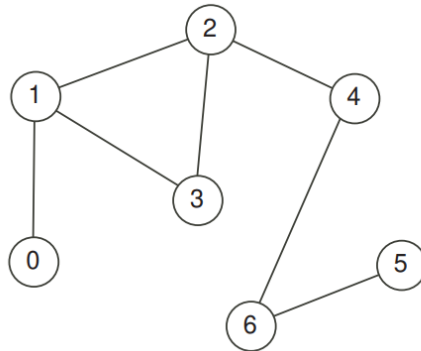


(e) Describe how to **list the neighbours** of a given vertex. How many steps are needed in the worst case?



(e) As for (e) above, a `NoSuchElementException` should be thrown if the input is not an integer  $i$  such that  $0 \leq i \leq n - 1$ , where  $n = |V|$ . Otherwise the linked list at  $A[i]$  should be traversed, with each integer stored in the list included as a neighbour of  $i$ .

The number of steps used in the worst case is linear in the largest degree of any node in the graph — in  $\Theta(n)$ , in the worst case.



- Allright! Let's do some coding now:
- Implementing the Adjacency List representation of graph in Java.
- Implement a weighted graph
  - Each element in the linked list should have a vertex and a weight.
  - It is better to have a subclass edge that has contains both destination vertex and the weight
- Construct a graph with n vertecies
  - `new graph(5) //five vertecies`
- Implement add edge. It should take two vertex index and a weight.
- Implement remove edge. It should take two vertex index.
- Implement getWeight. It should take two vertices and return the weight
- Implement a print function to see all the edges connected to each vertex. Use this for testing.

```
public static void main(String[] args) {  
    GraphAdjacencyList G1 = new GraphAdjacencyList(3);  
  
    G1.addEdge(0,2,0.5);  
    G1.addEdge(0,1,1.5);  
    G1.addEdge(1,2,1.3);  
  
    G1.print();  
    G1.addEdge(1,2,1.4);  
    G1.removeEdge(0, 1);  
  
    G1.print();  
  
    try {  
        System.out.println("Edge weight between v1 and v2 is:" + G1.getWeight(1,2));  
    } catch (Exception e) {  
        // TODO Auto-generated catch block  
        e.printStackTrace();  
    }  
}
```

```
V0 is connected to V2(0.5) V1(1.5)  
V1 is connected to V0(1.5) V2(1.3)  
V2 is connected to V0(0.5) V1(1.3)
```

```
V0 is connected to V2(0.5)  
V1 is connected to V2(1.4)  
V2 is connected to V0(0.5) V1(1.3)
```

```
Edge weight between v1 and v2 is:1.4
```

- Your code should work with this main function and produce the same result.



- First try your best to implement this yourself.
- I will include my code in the website so you can compare afterwards.

- Also, Implement the Adjacency Matrix representation of graph in Java.
- Implement a weighted graph
  - You can use either a two-dimensional array list or array.
- Construct a graph with n vertecies
  - `new graph(5) //five vertecies`
- Implement add edge. It should take two vertex index and a weight.
- Implement remove edge. It should take two vertex index.
- Implement getWeight. It should take two vertices and return the weight
- Implement a print function to see all the edges connected to each vertex.  
Use this for testing.

```
public static void main(String[] args) {
```

```
    GraphMatrixList G1 = new GraphMatrixList(3);
```

```
    G1.addEdge(0,2,0.5);
```

```
    G1.addEdge(0,1,1.5);
```

```
    G1.addEdge(1,2,1.3);
```

```
    |
```

```
    G1.print();
```

```
    G1.addEdge(1,2,1.4);
```

```
    G1.removeEdge(0, 1);
```

```
    G1.print();
```

```
    try {
```

```
        System.out.println("Edge weight between v1 and v2 is:" + G1.getWeight(1,2));
```

```
    } catch (Exception e) {
```

```
        // TODO Auto-generated catch block
```

```
        e.printStackTrace();
```

```
    }
```

V0 is connected to V2(0.5) V1(1.5)

V1 is connected to V0(1.5) V2(1.3)

V2 is connected to V0(0.5) V1(1.3)

V0 is connected to V2(0.5)

V1 is connected to V2(1.4)

V2 is connected to V0(0.5) V1(1.3)

Edge weight between v1 and v2 is:1.4

- Your code should work with this main function and produce the same result.

- If you have any questions about this tutorial, please post it here:

Topic 8: Graphs ▾

Topic 8: Graphs Questions

Topic	Threads	Posts	Last Post
<a href="#">General</a> ▾	0	0	

- Or email me: [hooman.khosravi1@ucalgary.ca](mailto:hooman.khosravi1@ucalgary.ca)