

PHY 321 HW 8 1)

1) a) $m\ddot{r} = -\frac{dV(r)}{dr} + m\dot{\phi}^2 r$ and $\dot{\phi} = \frac{L}{mr^2} \Rightarrow m\ddot{r} = -\frac{dV(r)}{dr} + \frac{L^2}{mr^3}$

Looking at $m\ddot{r} = -\frac{dV(r)}{dr} + \frac{L^2}{mr^3}$

We want to define V_{eff} such that $m\ddot{r} = -\frac{dV_{eff}(r)}{dr}$

So we want $V_{eff}(r) = \int -m\ddot{r} dr = \int \left(\frac{dV(r)}{dr} - \frac{L^2}{mr^3} \right) dr$

$$\int \left(\frac{dV(r)}{dr} - \frac{L^2}{mr^3} \right) dr = \underbrace{\int \frac{dV(r)}{dr} dr}_{=V(r)} - \underbrace{\int \frac{L^2}{mr^3} dr}_{= -\frac{1}{2} \cdot \frac{L^2}{mr^2}}$$

$$\int \frac{L^2 r^{-3}}{m} dr = -\frac{1}{2} \frac{L^2}{m} r^{-2}$$

$\Rightarrow V_{eff}(r) = V(r) - \frac{1}{2} \frac{L^2}{mr^2}$

So $V_{eff} = V(r) + \frac{L^2}{2mr^2}$ allows $m\ddot{r} = -\frac{dV_{eff}(r)}{dr}$

b) Specify $V(r) = -\frac{\alpha}{r}$

Th. gives $m\ddot{r} = \frac{d}{dr} \left(-\frac{\alpha}{r} + \frac{L^2}{2mr^2} \right)$ the value that m\ddot{r}. $m\ddot{r} = -\frac{d}{dr} \left(-\frac{\alpha}{r} + \frac{L^2}{2mr^2} \right)$

$\Rightarrow m\ddot{r} = -\left[\frac{\alpha}{r^2} - \frac{L^2}{mr^3} \right] \Rightarrow m\ddot{r} = -\frac{\alpha}{r^2} + \frac{L^2}{mr^3}$

Plotting done in python, along with discussion.

2) a) $V(r) = \frac{1}{2}kr^2 = \frac{1}{2}k(x^2+y^2)$

As shown in 1a, $V_{eff} = V(r) + \frac{L^2}{2mr^2}$ where we now have new $V(r)$ and m instead of m_0 .

using th., we have $V_{eff} = \frac{1}{2}kr^2 + \frac{L^2}{2mr^2}$

$V_{eff} = \frac{1}{2}kr^2 + \frac{L^2}{2mr^2}$

To find r_{min} , $\frac{dV_{eff}}{dr} = 0$ gives $kr - \frac{L^2}{mr^3} = 0$

$kr^4 - \frac{L^2}{m} = 0$


$r_{min} = \left(\frac{L^2}{km} \right)^{1/4}$

Using this r_{\min} with equation $\dot{\phi} = \frac{L}{mr^2}$ gives $\dot{\phi} = \frac{L}{mr_{\min}^2}$
 $\Rightarrow \dot{\phi} = \frac{L}{m} \cdot \frac{(km)^{1/2}}{L}$ because $\frac{1}{r_{\min}} = \left(\frac{L^2}{km}\right)^{1/2} = \frac{(km)^{1/2}}{L}$

$$\Rightarrow \boxed{\dot{\phi} = \sqrt{\frac{k}{m}}}$$

r indeed constant at r_{\min} given plot (in python).

To change r at r_{\min} with fixed k and m , we could change L since that's the only other variable in $r_{\min} = \left(\frac{L^2}{km}\right)^{1/4}$

Plot of V_{eff} done in python! Looks like V_{eff} 

b) We have $V_{\text{eff}} = \frac{1}{2}kr^2 + \frac{L^2}{2mr^2}$

Curvature of V_{eff} is simply second derivative, so we want k_{eff} = second derivative of V_{eff} at $r = r_{\min}$.

$$\frac{d^2}{dr^2}[V_{\text{eff}}] = \frac{d}{dr}\left[kr - \frac{L^2}{mr^3}\right] = \boxed{k + \frac{3L^2}{mr^4}} \quad \text{so } \boxed{k_{\text{eff}} = k + \frac{3L^2}{mr_{\min}^4}}$$

Plugging in r_{\min} gives $k_{\text{eff}} = k + \frac{3L^2}{m} \cdot \frac{km}{L^2} = k + 3k = 4k$, so $\boxed{k_{\text{eff}} = 4k}$

$$\boxed{\omega = \sqrt{\frac{k_{\text{eff}}}{m}} = \sqrt{\frac{4k}{m}} = 2\sqrt{\frac{k}{m}} = 2\dot{\phi}} \quad \text{since we show } \dot{\phi} = \sqrt{\frac{k}{m}} \text{ in part a.}$$

c) $\ddot{x} = -\frac{kx}{m}, \quad \ddot{y} = -\frac{ky}{m}$

I'm not really sure what work is needed here. There are pretty standard, very simple second order differential equations. We know we need "oscillating", repetitive solutions, so sines or cosines or the combination thereof. This gives.

$$\begin{aligned} x &= A \cos \omega t + B \sin \omega t \\ y &= C \cos \omega t + D \sin \omega t \end{aligned} \quad \text{where } \omega = \sqrt{\frac{k}{m}}$$

This indeed works, since $\ddot{x} = -A\omega^2 \cos \omega t - B\omega^2 \sin \omega t = -\omega^2 x = -\frac{kx}{m}$
 $\ddot{y} = -C\omega^2 \cos \omega t - D\omega^2 \sin \omega t = -\omega^2 y = -\frac{ky}{m}$

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d) $\alpha = \frac{A^2+B^2+C^2+D^2}{2}$, $\beta = \frac{A^2-B^2+C^2-D^2}{2}$, $\gamma = AB+CD$. show $r^2 = \alpha + (\beta^2 + \gamma^2)^{1/2} \cos(2\omega t - \delta)$
where $\delta = \arctan(\frac{\gamma}{\beta})$

I don't think there's any way around a bunch of algebra !!
Have $x^2 + y^2 = r^2$, and equations of x and y .

$$x^2 = (A \cos \omega t + B \sin \omega t)^2 = A^2 \cos^2(\omega t) + B^2 \sin^2(\omega t) + 2AB \sin(\omega t) \cos(\omega t)$$

$$y^2 = (C \cos \omega t + D \sin \omega t)^2 = C^2 \cos^2(\omega t) + D^2 \sin^2(\omega t) + 2CD \sin(\omega t) \cos(\omega t)$$

$$\Rightarrow r^2 = x^2 + y^2 = (A^2 + C^2) \cos^2(\omega t) + (B^2 + D^2) \sin^2(\omega t) + 2(AB + CD) \sin(\omega t) \cos(\omega t)$$

using $\sin x \cdot \cos y = \frac{1}{2}(\sin(x+y) + \sin(x-y))$ we know $\sin(\omega t) \cos(\omega t) = \frac{1}{2} \sin(2\omega t) + \overset{\sin 0 = 0}{\cancel{0}}$

$$\Rightarrow (A^2 + C^2) \cos^2(\omega t) + (B^2 + D^2) \sin^2(\omega t) + (AB + CD) \sin(2\omega t)$$

I need to get a $\cos(2\omega t)$ in there somehow. I'll use $\cos(2x) = \cos^2 x - \sin^2 x$ I think.
or $\cos(2x) = 2\cos^2 x - 1$

I had to work
backward to
figure out I
needed this

Think $5\cos^2 x + 3\sin^2 x = (5-3)\cos^2 x + 3$.

Applying the idea gives, $(B^2 + D^2) + (A^2 - B^2 + C^2 - D^2) \cos^2(\omega t) + \gamma \sin(2\omega t)$

knew I needed

this from
Susskind's
lecture
notes

Now use $\cos^2 x = \frac{\cos(2x) + 1}{2} \Rightarrow \cancel{(B^2 + D^2)} + \cancel{(A^2 - B^2 + C^2 - D^2)}$

$$\Rightarrow (B^2 + D^2) + (A^2 - B^2 + C^2 - D^2) \left(\frac{\cos(2\omega t) + 1}{2} \right) + \gamma \sin(2\omega t)$$

$$= B^2 + D^2 + \beta (\cos(2\omega t) + 1) + \gamma \sin(2\omega t)$$

$$\cancel{(B^2 + D^2)} + \beta \cos(2\omega t) + \frac{A^2 - B^2 + C^2 - D^2}{2} + \gamma \sin(2\omega t)$$

$$= \frac{A^2 + B^2 + C^2 + D^2}{2} + \beta \cos(2\omega t) + \gamma \sin(2\omega t)$$

$$= \alpha + \beta \cos(2\omega t) + \gamma \sin(2\omega t)$$

Now I'm stuck & overmind

identity ~~But~~ identity $\sqrt{a^2 + b^2} \cos(x - \tan^{-1}(\frac{b}{a}))$

That should pretty much do it.

where $a = \beta$, $b = \gamma$ we get

$$\alpha + \sqrt{\beta^2 + \gamma^2} \cos(2\omega t - \delta)$$

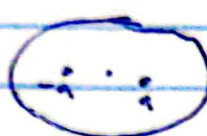
$$= \alpha + \sqrt{B^2 + \gamma^2} \cdot \cos(2\omega_0 t - \arctan(\frac{\gamma}{B}))$$

$$r^2 = \alpha + \sqrt{B^2 + \gamma^2} \cdot \cos(2\omega_0 t - \phi)$$

help.
~~dep~~

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4) $\sqrt{(x-a)^2 + y^2} + \sqrt{(x+a)^2 + y^2} = 2D$ with foci at $-a, a$.

$(\sqrt{(x-a)^2 + y^2} + \sqrt{(x+a)^2 + y^2}) / \dots = 1$  with $a) \frac{x^2}{D^2} + \frac{y^2}{D^2 - a^2} = 1$

Starting from
1.2.2.1

$$\Rightarrow (x-a)^2 + y^2 + 2\sqrt{(x-a)^2 + y^2}\sqrt{(x+a)^2 + y^2} + (x+a)^2 + y^2 = 4D^2$$

$$\Rightarrow (x-a)^2 + (x+a)^2 + 2y^2 + 2\sqrt{(x-a)^2 + y^2}\sqrt{(x+a)^2 + y^2} = 4D^2$$

simplifying square root

$$\sqrt{(x-a)^2 + y^2}\sqrt{(x+a)^2 + y^2}$$

$$(x-a)^2 = x^2 - 2ax + a^2 \quad (x+a)^2 = x^2 + 2ax + a^2$$

cancel

$$2x^2 + 2a^2 + 2y^2 + 2\sqrt{\text{all the stuff}} = 4D^2$$

$$x^2 + a^2 + y^2 + \sqrt{\text{stuff}} = 2D^2$$

$$x^2 + a^2 + y^2 + \sqrt{(x-a)^2(x+a)^2 + y^2(2x^2 + 2a^2 + y^2)} = 2D^2$$

$$\sqrt{\text{stuff}} = 2D^2 - x^2 - a^2 - y^2$$

$$\text{stuff} = (2D^2 - x^2 - a^2 - y^2)^2$$

$$(x-a)^2(x+a)^2 + y^2(2x^2 + 2a^2 + y^2) = 4D^4 - 4D^2a^2 - 4D^2x^2 - 4D^2y^2 + 4a^2x^2 + 4a^2y^2 + x^4 + 2x^2y^2 + y^4$$

$$x^4 - 2a^2x^2 + x^4 + 2x^2y^2 + 2a^2y^2 + y^4 = \text{same as before}$$

$$-2a^2x^2 = 4D^4 - 4D^2a^2 - 4D^2x^2 - 4D^2y^2 + 4a^2x^2$$

$$4D^4 - 4D^2a^2 - 4D^2x^2 - 4D^2y^2 + 4a^2x^2 = 0$$

$$D^4 - D^2a^2 - D^2x^2 - D^2y^2 + a^2x^2 = 0$$

$$D^2 - a^2 - x^2 - y^2 + \frac{a^2x^2}{D^2} = 0$$

$$x^2 + y^2 - \frac{a^2x^2}{D^2} = D^2 - a^2$$

$$x^2(1 - \frac{a^2}{D^2}) + y^2 = D^2 - a^2$$

$$x^2 \frac{(1 - \frac{a^2}{D^2})}{D^2 - a^2} + \frac{y^2}{D^2 - a^2} = 1$$

$$\boxed{\frac{x^2}{D^2} + \frac{y^2}{D^2 - a^2} = 1}$$

$$\frac{1 - \frac{a^2}{D^2}}{D^2 - a^2} = \frac{\frac{D^2 - a^2}{D^2}}{D^2 - a^2} = \frac{1}{D^2}$$