Gaussian Naive Bayes (2)

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Beria Ayşenur CAN 090200705

#Gaussian Naive Bayes

Gaussian Naive Bayes modeli Naive Bayes sınıflandırmasına aittir. Bu algoritmada sürekli (continous) veri ele alınır. Her sınıfla ilişkili sürekli özellikler normal (veya Gaussian) dağılıma göre dağıtılır. Bu yöntem kullanılarak eğitim verisinden her sınıf için ortalama (mean) ve standart sapma (standard deviation) değerleri tahmin edilir. Bu sayede dağılım özetlenir.

Gaussian Naive Bayes algoritmasında her sınıfın olasılıklarına ek olarak her sınıfın ortalama ve standart sapma değerleri de saklanır. Bayes Teoermi kullanılarak çalışır:

Bayes Teoremi:

P(A|B), B olayı gerçekleştiğinde A olayının olasılığını temsil eder ve şu şekilde ifade edilir:

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)} \tag{1}$$

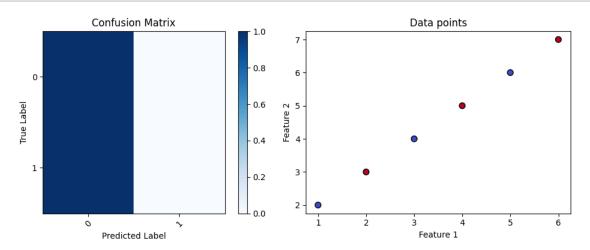
Gaussian Naive Bayes (GaussianNB) modelini olusturan bu fonksiyonları sırayla açıklayalım:

```
[15]: import numpy as np import matplotlib.pyplot as plt from sklearn.model_selection import train_test_split from sklearn.metrics import accuracy_score, confusion_matrix from sklearn.naive_bayes import GaussianNB # Using sklearn's GaussianNB for → demonstration
```

```
X = np.array(X, dtype=np.float64)
        except ValueError:
            raise ValueError("Input data X must be a numeric array.")
    return X
def logprior(self, class_ind):
    return np.log(self.class_priors_[class_ind])
def loglikelihood(self, Xi, class_ind):
    mean = self.theta_[class_ind]
    var = self.var_[class_ind]
    # Debugging print statements
    #print("Xi type:", type(Xi), "Xi shape:", Xi.shape)
    #print("Mean type:", type(mean), "Mean shape:", mean.shape)
    #print("Var type:", type(var), "Var shape:", var.shape)
    numerator = -0.5 * np.sum(np.log(2. * np.pi * var))
    denominator = -0.5 * np.sum(((Xi - mean) ** 2) / var)
    return numerator + denominator
def posterior(self, Xi, class_ind):
    return self.logprior(class_ind) + self.loglikelihood(Xi, class_ind)
def fit(self, X, y):
    n_samples, n_features = X.shape
    self.classes_ = np.unique(y)
    n_classes = len(self.classes_)
    self.theta_ = np.zeros((n_classes, n_features))
    self.var_ = np.zeros((n_classes, n_features))
    self.class_priors_ = np.zeros(n_classes)
    for c_ind, c_id in enumerate(self.classes_):
        X_class = X[y == c_id]
        self.theta_[c_ind, :] = np.mean(X_class, axis=0)
        self.var_[c_ind, :] = np.var(X_class, axis=0) + self.var_smoothing
        self.class_priors_[c_ind] = np.sum(y == c_id) / n_samples
def predict(self, X):
    X = self._check_input(X) # Ensuring X is a NumPy array
    predictions = []
    for xi in X:
        # Debugging: Check the type of xi
        if isinstance(xi, str):
```

```
print("Error: Non-numeric data found:", xi)
                      continue
                  post = [self.posterior(xi, class_ind) for class_ind in_
       →range(len(self.classes_))]
                  predictions.append(self.classes_[np.argmax(post)])
              return np.array(predictions)
     #örnek kullanım
[17]: X = \text{np.array}([[1.0, 2.0], [2.0, 3.0], [3.0, 4.0], [4.0, 5.0], [5.0, 6.0], [6.0])
      y = np.array([0, 1, 0, 1, 0, 1])
[18]: model = GaussianNB_()
      model.fit(X, y)
[19]: new_data = np.array([[2.5, 3.5], [4.5, 5.5]])
      # Make predictions
      predictions = model.predict(new_data)
      print("Predictions:", predictions)
     Predictions: [0 1]
[20]: # Veri setini eğitim ve doğrulama setlerine ayırma
      X_train, X_val, y_train, y_val = train_test_split(X, y, test_size=0.2,__
       →random_state=42)
      # Modeli eğitim setiyle eğitme
      model.fit(X_train, y_train)
      # Doğrulama seti üzerinde tahmin yapma
      y_pred = model.predict(X_val)
      # Başarı metriklerini hesaplama
      accuracy = accuracy_score(y_val, y_pred)
      conf_matrix = confusion_matrix(y_val, y_pred)
      print("Accuracy:", accuracy)
      print("Confusion Matrix:\n", conf_matrix)
     Accuracy: 0.5
     Confusion Matrix:
      [[1 0]
      [1 0]]
```

```
[21]: # Plotting the results
      plt.figure(figsize=(10, 4))
      # Plotting confusion matrix
      plt.subplot(1, 2, 1)
      plt.imshow(conf_matrix, interpolation='nearest', cmap=plt.cm.Blues)
      plt.title('Confusion Matrix')
      plt.colorbar()
      tick_marks = np.arange(len(np.unique(y)))
      plt.xticks(tick_marks, np.unique(y), rotation=45)
      plt.yticks(tick_marks, np.unique(y))
      plt.xlabel('Predicted Label')
      plt.ylabel('True Label')
      # Plotting samples
      plt.subplot(1, 2, 2)
      plt.scatter(X[:, 0], X[:, 1], c=y, cmap=plt.cm.coolwarm, edgecolor='k', s=50)
      plt.title('Data points')
      plt.xlabel('Feature 1')
      plt.ylabel('Feature 2')
      plt.tight_layout()
      plt.show()
      # Printing accuracy
      print("Accuracy:", accuracy)
```



```
Accuracy: 0.5
```

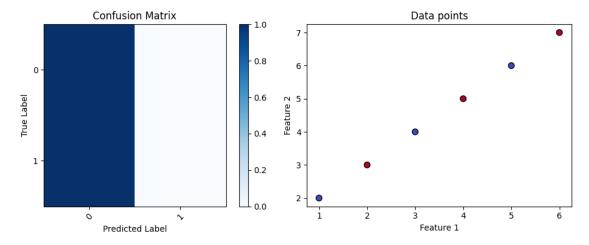
```
[22]: model_=GaussianNB()
model_.fit(X,y)
```

```
[22]: GaussianNB()
[23]: new_data = np.array([[2.5, 3.5], [4.5, 5.5]])
     # Make predictions
     predictions = model_.predict(new_data)
     print("Predictions:", predictions)
     Predictions: [0 1]
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     # Modeli eğitim setiyle eğitme
     model_.fit(X_train, y_train)
     # Doğrulama seti üzerinde tahmin yapma
     y_pred = model_.predict(X_val)
     # Başarı metriklerini hesaplama
     accuracy = accuracy_score(y_val, y_pred)
     conf_matrix = confusion_matrix(y_val, y_pred)
     print("Accuracy:", accuracy)
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     plt.xticks(tick_marks, np.unique(y), rotation=45)
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     plt.xlabel('Predicted Label')
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```
plt.subplot(1, 2, 2)
plt.scatter(X[:, 0], X[:, 1], c=y, cmap=plt.cm.coolwarm, edgecolor='k', s=50)
plt.title('Data points')
plt.xlabel('Feature 1')
plt.ylabel('Feature 2')

plt.tight_layout()
plt.show()

# Printing accuracy
print("Accuracy:", accuracy)
```



Accuracy: 0.5

hazır kütüphane ile de kontrol ettim her iki sonuçta da aynı çıkması yöntemin doğruluğunu kanıtlıyor.