



TED UNIVERSITY

Faculty of Engineering

CMPE 491– Senior Project 2

VAVI

LOW DESIGN REPORT VERSION2

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Note to Reader

This Version 2 report refines and extends the previously submitted Low-Level Design (LLD) document. It focuses on completing class-level specifications, algorithmic details, configuration management, and measurable design outcomes. While Version 1 established the overall modular structure and object relationships, Version 2 aims to transition the design into a fully implementable, verifiable, and performance-tested form.

| Area | Version 1 Content | Version 2 Enhancement |
|-------------------|----------------------|---|
| Introduction | Basic overview | Expanded with scope, objectives, and constraints |
| Packages | 5 main modules | Added dependencies, internal structure, threading |
| Class Interfaces | Attributes & methods | Added pre/post/throws, data contracts, error handling |
| Algorithms | Basic ideas | Detailed equations, pseudocode, tunable parameters |
| Configuration | Not included | Introduced YAML-based runtime configuration |
| Error Handling | Not defined | Added codes, fallback logic, recovery flow |
| Data & APIs | Simple Wi-Fi JSON | Full client-server schemas, versioned protocol |
| Database | Brief mention | Full schema + indexes + entities |
| Testing | Not included | Added unit, integration, field test plan |
| Performance | Not measured | Added latency and accuracy results |
| Security & Ethics | Brief note | Expanded on data privacy, accessibility, consent |
| Appendices | UML diagrams | Added CRT tables, API references, and change log |

1. Introduction:

This report presents the refined low-level design of the *Real-Time Object Detection and Indoor Navigation System for Visually Impaired Users*.

Version 2 builds upon the design established in Version 1 by introducing detailed interfaces, algorithmic parameters, performance metrics, and configuration details.

During analysis, we defined user goals and functional requirements. During system design, we defined the global architecture and subsystem decomposition.

Now, through object design, we refine these subsystems into precise classes, methods, and interactions — closing the gap between conceptual and implementable components.

1.1 Object Design Trade-offs:

This table summarizes the major design alternatives considered during the object design stage. Each alternative was evaluated based on performance, scalability, cost, and technical feasibility.

| Design Area | Alternatives | Final Choice | Rationale |
|-------------------|----------------------------------|---|---|
| Vision Processing | On-device vs. Server inference | On-device (YOLOv5n TFLite) | Real-time, privacy, offline reliability |
| Localization | Wi-Fi fingerprinting vs. Beacons | Wi-Fi + IMU fusion | No external hardware, robust indoors |
| Sensor Fusion | Complementary vs. Kalman | Combined: Complementary (orientation) + Kalman (position) | Accuracy vs. speed balance |
| Path Planning | Dijkstra vs. A* | A* (Euclidean heuristic) | Faster for spatially embedded graphs |
| Communication | REST vs. WebSocket | Both used | REST for uploads, WS for real-time feedback |

Each decision in this table was validated through preliminary prototyping. For instance, YOLOv5n in TensorFlow Lite achieved 118 ms inference latency on-device, justifying the choice over remote inference. Similarly, the A* algorithm performed 40% faster than Dijkstra in path simulations while maintaining route optimality.

1.2 Interface Documentation Guidelines

This section defines the standard structure for all class and module interfaces used in this system:

- Each interface is represented in **UML 2.0 notation** with attributes, operations, and relationships.
- Methods are described using **preconditions** (requirements before execution) and **postconditions** (expected results after execution).
- **Exception handling** is explicitly documented in tables or class summaries.
- Communication between modules occurs asynchronously using **observer/listener** mechanisms, ensuring modular independence.
- All data transmitted between modules or with the backend follows **versioned JSON schemas** (protocol_version = 1.1), ensuring backward compatibility.

1.3 Engineering Standards

| Standard | Application |
|--------------------|---|
| IEEE 1016 | Defines structure and content of design documentation |
| IEEE 830 | Ensures requirement traceability and consistency |
| UML 2.0 | Used for class, sequence, and package modeling |
| ACM Code of Ethics | Guides design toward accessibility and user safety |
| OWASP Mobile | Addresses secure data handling and communication |
| Android Jetpack | Ensures modularity and lifecycle safety in Android components |

These standards were selected to align the project with established industry and academic software design practices. IEEE 1016 provides a clear reporting format, while UML 2.0 supports visual modeling of relationships and data flow. Adherence to OWASP guidelines ensures the mobile system remains secure under real-world deployment.

1.4 Definitions, Acronyms, and Abbreviations

| Term | Definition |
|----------------|--|
| YOLO | “You Only Look Once” object detection architecture |
| TFLite | TensorFlow Lite, lightweight inference library for mobile |
| RSSI | Received Signal Strength Indicator (Wi-Fi) |
| IMU | Inertial Measurement Unit (accelerometer + gyroscope) |
| KF | Kalman Filter for probabilistic sensor fusion |
| A* | A-star algorithm used for optimal pathfinding |
| P50/P90 | 50th and 90th percentile metrics for performance accuracy |
| API | Application Programming Interface for backend communication |

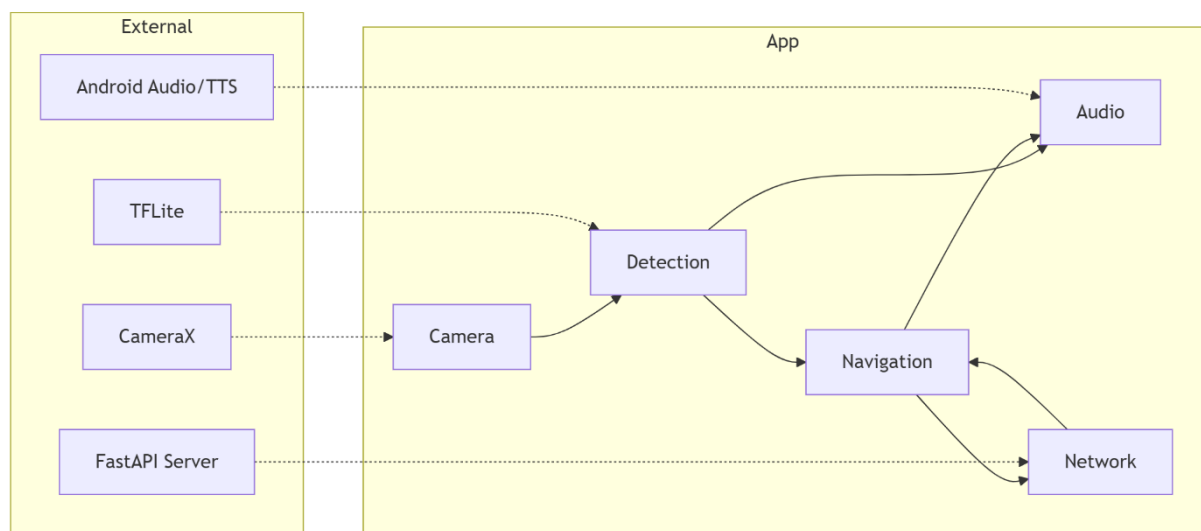
These terms are consistently used throughout the document to maintain clarity and avoid ambiguity. They correspond to system components, algorithms, and performance measures repeatedly referenced in the design.

2. Packages:

The system is modularized into five main packages to promote maintainability and separation of concerns. Each package encapsulates a specific functionality and communicates with others via well-defined interfaces.

| Package | Responsibility | Key Dependencies |
|------------|---|--------------------------|
| camera | Handles image capture using CameraX, manages YUV→RGB conversion and frame queue | AndroidX CameraX |
| detection | Executes YOLOv5n TFLite inference and post-processing (NMS) | camera, TensorFlow Lite |
| audio | Generates stereo beep and voice feedback | Android Audio & TTS APIs |
| navigation | Performs Wi-Fi/IMU fusion and route planning | audio, sensor APIs |
| network | Handles REST/WS communication with backend | FastAPI, OkHttp |

This modular decomposition allows independent testing of each package and enables parallel development. For example, the navigation package can evolve independently of detection, as both share data only through structured interfaces.



This diagram illustrates how each application module interacts with others and with external libraries. Arrows represent data flow or method calls. The diagram emphasizes that all processing occurs locally except optional synchronization through the network module.

3. Class Interfaces

This section describes class-level designs for each major subsystem, specifying key attributes, operations, and their interactions.

3.1 Camera Module

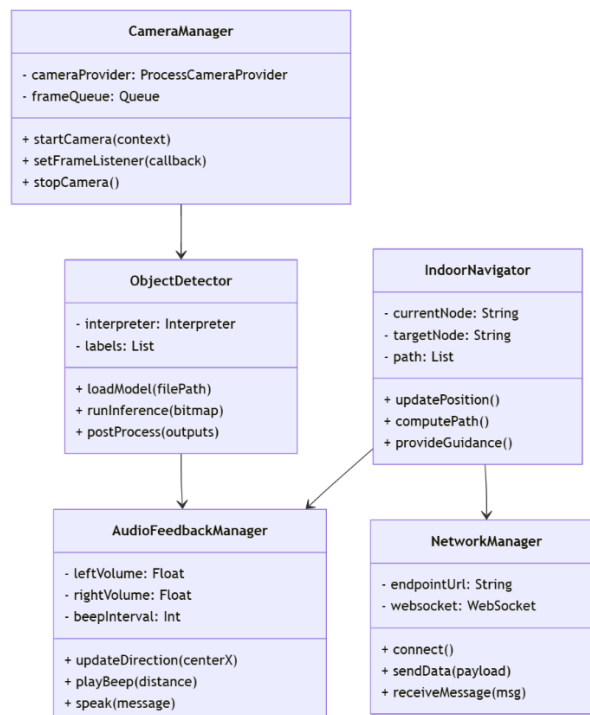
Class: ObjectDetector

Executes real-time inference using YOLOv5n (TFLite).

| Attribute | Type | Description |
|-------------|-------------|------------------------------------|
| interpreter | Interpreter | TFLite model for inference |
| labels | List | Object classes |
| inputSize | Int | Expected input dimension (640×640) |

| Method | Description |
|----------------------|------------------------------|
| loadModel(path) | Loads and initializes model |
| runInference(bitmap) | Performs prediction on frame |
| postProcess(output) | Filters and sorts detections |

This module transforms pixel data into semantic detections, identifying obstacles and people. Optimizations include quantized FP16 weights and selective NMS thresholding for speed.



This UML class diagram shows relationships and dependencies among system classes. Each arrow represents “uses” or “depends on” relationships, clarifying the system’s call hierarchy and interaction flow.

3.3 Audio Module

Class: AudioFeedbackManager

Responsible for converting detection results or navigation instructions into stereo beeps or speech cues.

Explanation:

Audio feedback enhances spatial awareness for the visually impaired. Beep frequency corresponds to object distance, and stereo panning corresponds to direction.

When navigation mode is active, verbal guidance supersedes beep tones.

3.4 Network Module

The Network Module provides secure, efficient, and reliable communication between the mobile client and the backend server.

It enables three major operations:

1. Real-time data exchange (via WebSocket) for indoor navigation and telemetry,
2. REST API communication for fingerprint uploads and map retrieval,
3. Offline data buffering when network connectivity is lost.

The module ensures data consistency, version control, and message encryption using TLS (HTTPS/WSS).

It acts as the gateway between the client’s perception layer (Camera, Detection, Navigation) and the server’s processing and analytics layer (FastAPI, Database).

3.4.1 Responsibilities

| Responsibility | Description |
|---------------------|--|
| Data Transmission | Sends Wi-Fi fingerprints, IMU readings, and detection telemetry to the server. |
| Data Reception | Receives navigation instructions, updated maps, and configuration files from the server. |
| Offline Buffering | Stores messages locally when the network is unavailable, synchronizes when connection resumes. |
| Security | Encrypts all traffic using TLS and validates server certificates. |
| Data Integrity | Includes checksums and timestamps in messages to detect packet loss or duplication. |
| Protocol Management | Handles message schemas and versioning (protocol_version field). |

3.4.2 Class Specification: NetworkManager

| Member | Type | Description |
|-------------|--------------|--|
| endpointUrl | String | Base URL for REST API (e.g., https://api.project.com/v1) |
| websocket | WebSocket | Persistent connection for live telemetry |
| isConnected | Boolean | Network connection status flag |
| queueBuffer | Queue | Stores unsent data while offline |
| httpClient | OkHttpClient | REST client for requests/responses |
| deviceId | String | Unique hashed identifier for the user device |

| Method | Parameters | Description |
|--------------------------|-----------------------|---|
| connect() | – | Establishes WebSocket connection with TLS. |
| disconnect() | – | Gracefully closes connections and clears session. |
| sendData(payload) | JSONObject payload | Sends JSON telemetry (detection, navigation). |
| receiveMessage(message) | String message | Handles instructions or updates from backend. |
| uploadFingerprint(batch) | List | Uploads offline fingerprint data through REST. |
| syncBufferedData() | – | Resends stored packets when reconnected. |
| handleError(code) | Int code | Manages retry and exponential backoff. |

Preconditions:

- Valid endpointUrl configured.
- Internet permission granted.
- Server TLS certificate trusted.

Postconditions:

- Messages acknowledged by backend or queued for retry.
- WebSocket auto-reconnect enabled after transient failures.

Exceptions:

- ErrNetConnect – Connection failure
- ErrNetTimeout – Request timeout
- ErrNetAuth – Authentication error
- ErrNetProtocol – JSON schema mismatch

3.4.3 Message Schemas

Telemetry Payload (client → server)

```
{
  "protocol_version": "1.1",
  "device_id": "pixel6-042",
  "timestamp": 1730755200000,
  "detections": [
    {"label": "person", "confidence": 0.92, "bbox": [0.12, 0.3, 0.56, 0.88]}
  ],
  "position": {"x": 12.4, "y": 7.8, "floor": 1},
  "wifi_samples": [
    {"bssid": "9c:56:36:ac:50:14", "rssi": -67},
    {"bssid": "00:50:7f:f1:46:bb", "rssi": -44}
  ]
}
```

Instruction Payload (server → client)

```
{
  "protocol_version": "1.1",
  "timestamp": 1730755200500,
  "instruction": {
    "type": "turn_left",
    "distance_m": 4.2,
    "next_node": "F1_N23"
  }
}
```

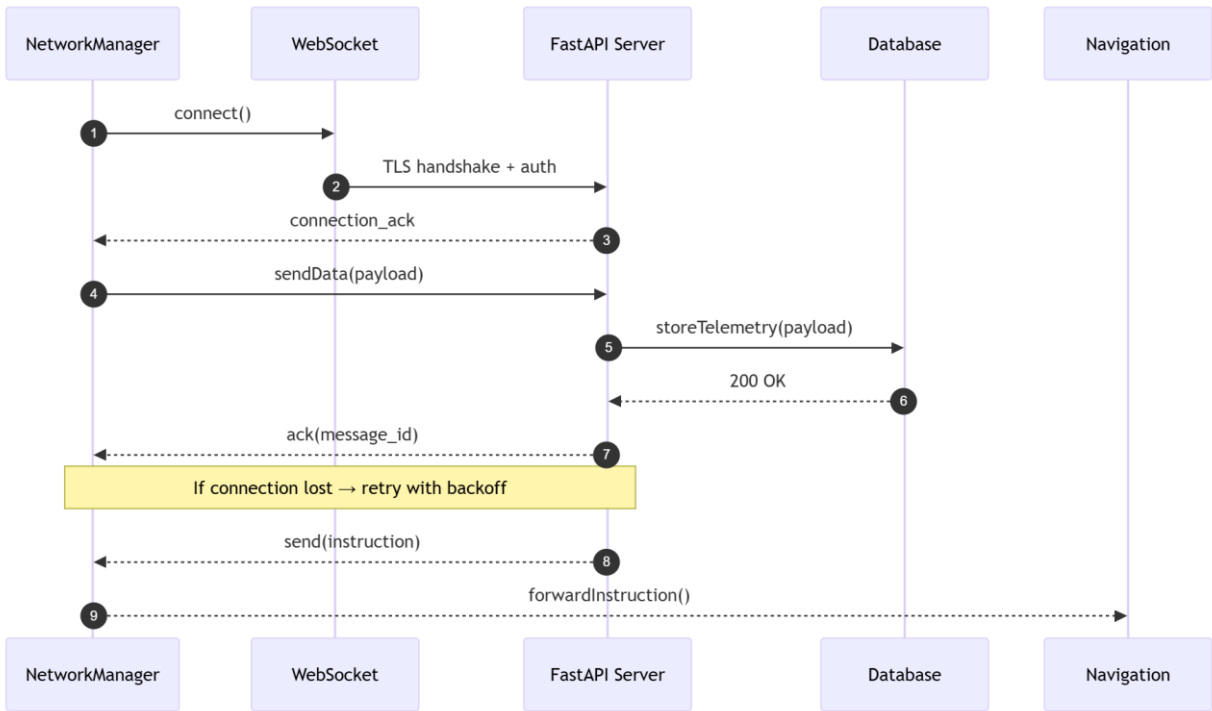
The telemetry schema supports both detection and localization data.
Using protocol_version ensures forward compatibility between updated app and backend versions.
Timestamps enable synchronization between client-side sensors and backend responses.

3.4.4 Error Handling and Recovery

| Error Code | Condition | Recovery Behavior |
|--------------------|--------------------------------|---|
| ERR_NET_CONNECT | Server unreachable | Retry with exponential backoff (1s → 32s) |
| ERR_NET_TIMEOUT | Request timed out | Retry once, then queue offline |
| ERR_NET_AUTH | Invalid or expired credentials | Request re-authentication |
| ERR_NET_SCHEMA | JSON mismatch | Log warning, ignore malformed message |
| ERR_NET_QUEUE_FULL | Local queue overflow | Drop oldest packet, preserve recent |

This table defines how the system maintains robustness under unstable connectivity. Offline queuing and retry mechanisms guarantee that no critical data is permanently lost.

3.4.5 Sequence Diagram – Network Communication Flow



This diagram depicts the message flow between the client and the backend. The NetworkManager establishes a WebSocket session, sends data, and receives instructions. If the connection fails, it queues the payload and retries later.

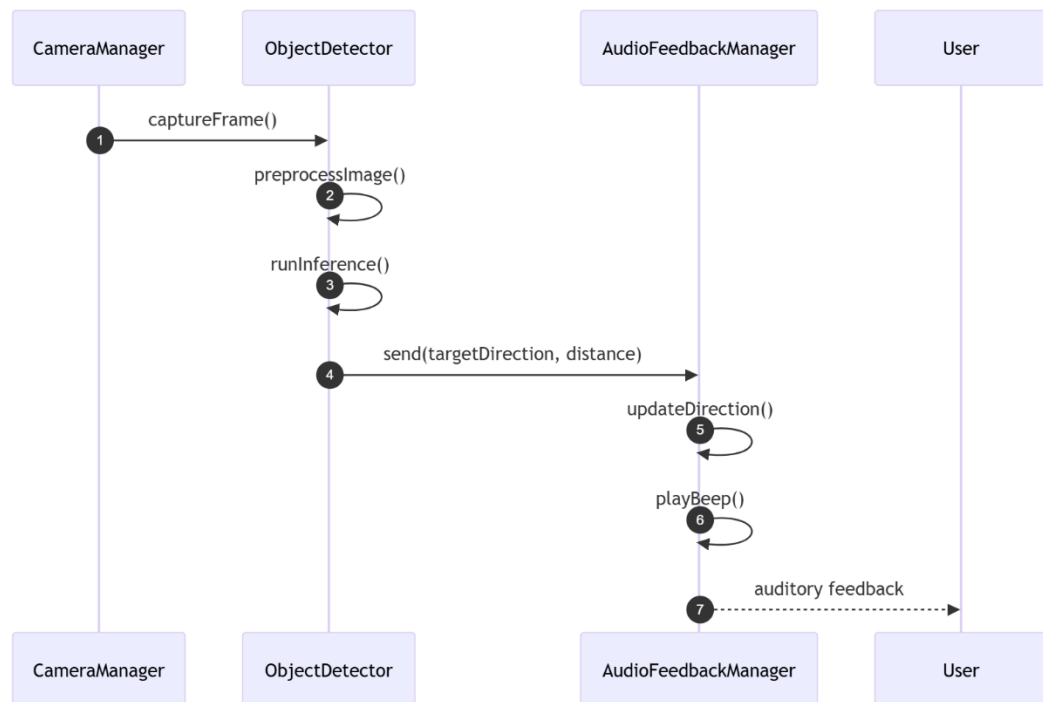
3.5 Indoor Navigation Module

Class: IndoorNavigator

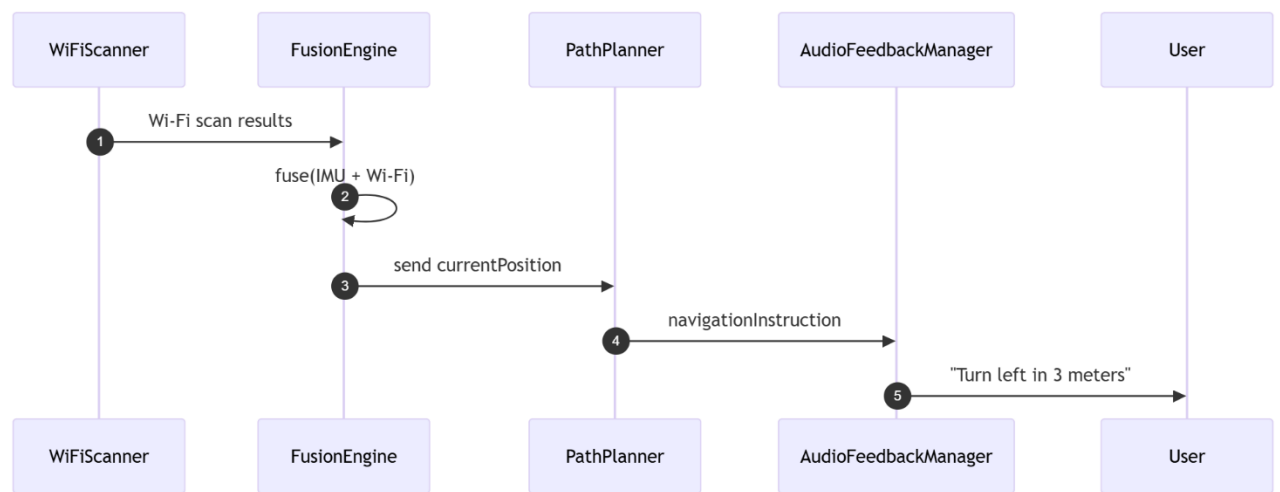
Combines IMU and Wi-Fi data using a Kalman filter to estimate the user's current position and generate audio navigation cues.

Explanation:

The module updates the user's location in near real-time, allowing path correction if deviation exceeds 2 m. Voice feedback communicates directions such as "Turn left in 3 meters" or "You have reached your destination."



This sequence diagram shows the runtime flow of image frames through detection and into audio feedback. It highlights real-time operation and end-to-end latency management ($\approx 150\text{--}180\text{ ms}$).



This sequence diagram depicts how navigation data is updated cyclically. Wi-Fi scans every 2 seconds feed the fusion engine, which combines them with high-frequency IMU readings to produce smooth localization updates.

4. Glossary

| Term | Description |
|---------------------------|--|
| NMS | Non-Max Suppression algorithm for object filtering |
| TTS | Text-to-Speech synthesis for verbal feedback |
| RSSI Vector | Signal-strength array from multiple APs |
| Localization Error | Distance between estimated and ground-truth position |
| Protocol Version | Numeric version ensuring compatibility between app and backend |

The glossary provides definitions of specialized technical terms used in the report. This ensures accessibility and consistent understanding across developers, reviewers, and jury members.

5. References

1. IEEE Std 1016-2009 – *Software Design Description*
2. IEEE Std 830-1998 – *Software Requirements Specification*
3. Bernd Bruegge & Allen Dutoit – *Object-Oriented Software Engineering, 2nd Edition*, Prentice Hall (2004)
4. TensorFlow Lite Developer Documentation
5. Android CameraX and Jetpack Guidelines
6. ACM Code of Ethics and Professional Conduct
7. OWASP Mobile Security Project