

## Outline

- 1) Syllabus
- 2) Course goals
- 3) Measure theory basics

# Measure theory basics

Measure theory is a rigorous grounding for probability theory [subject of 205A]

Simplifies notation & clarifies concepts, especially around integration & conditioning [Pset 0]

Given a set  $X$ , a measure  $\mu$  maps subsets  $A \subseteq X$  to non-negative numbers  $\mu(A) \in [0, \infty]$

Example  $X$  countable (e.g.  $X = \mathbb{Z}$ )

Counting measure  $\#(A) = \# \text{ points in } A$

Example  $X = \mathbb{R}^n$

Lebesgue measure  $\lambda(A) = \int_A \dots \int dx_1 \dots dx_n$   
 $= \text{Volume}(A)$

Standard Gaussian distribution:

$$\begin{aligned} P_z(A) &= \mathbb{P}(Z \in A) \quad \text{where } Z \sim N(0, 1) \\ &= \int_A \phi(x) dx \quad \phi(x) = \frac{e^{-x^2/2}}{\sqrt{2\pi}} \end{aligned}$$

NB Because of pathological sets,  $\lambda(A)$  can only be defined for certain subsets  $A \subseteq \mathbb{R}^n$  [HW 0, Prob. 3]

In general, the domain of a measure  $\mu$  is a collection of subsets  $\mathcal{F} \subseteq 2^X$  (power set)

$\mathcal{F}$  must be a  $\sigma$ -field meaning it satisfies certain closure properties (not important for us)

$$\textcircled{1} X \in \mathcal{F}$$

$$\textcircled{2} \text{ If } A \in \mathcal{F} \text{ then } X \setminus A \in \mathcal{F}$$

$$\textcircled{3} \text{ If } A_1, A_2, \dots \in \mathcal{F} \text{ then } \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$$

$$\underline{\text{Ex}}: X \text{ countable, } \mathcal{F} = 2^X$$

$$\underline{\text{Ex}}: X = \mathbb{R}^n, \mathcal{F} = \text{Borel } \sigma\text{-field } \mathcal{B}$$

$$\mathcal{B} = \text{smallest } \sigma\text{-field including all open rectangles} \\ (a_1, b_1) \times \dots \times (a_n, b_n) \quad a_i < b_i \quad \forall i$$

Given a measurable space  $(X, \mathcal{F})$  a measure is a map  $\mu: \mathcal{F} \rightarrow [0, \infty]$  with

$$\mu\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} \mu(A_i) \quad \text{for disjoint } A_1, A_2, \dots \in \mathcal{F}$$

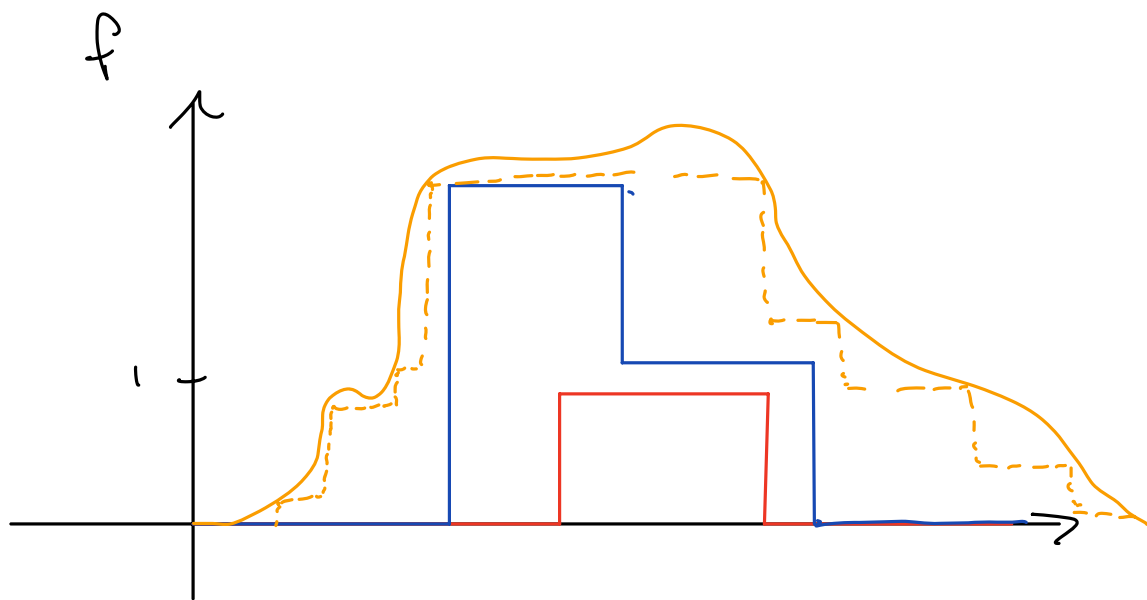
$$\mu(\emptyset) = 0$$

$\mu$  probability measure if  $\mu(X) = 1$

# Integrals

Measures let us define integrals that put weight  $\mu(A)$  on  $A \subseteq X$

Define  $\int 1_{\{x \in A\}} d\mu(x) = \mu(A)$ , extend to other functions by linearity & limits:



Indicator  $\int 1_{\{x \in A\}} d\mu(x) = \mu(A)$

Simple Function  $\int \left( \sum c_i 1_{\{x \in A_i\}} \right) d\mu(x) = \sum c_i \mu(A_i)$

"Nice enough" (measurable) function  $\int f(x) d\mu(x)$  approximated by simple functions

Examples:

Counting:  $\int f d\# = \sum_{x \in X} f(x)$

↙ Lebesgue  
integral

Lebesgue:  $\int f d\lambda = \int \dots \int f(x) dx_1 \dots dx_n$

Gaussian: Note  $\int 1_A(x) dP_z(x) = P_z(A) = \int_{-\infty}^{\infty} 1_A \phi dx$

By extension,

$$\int f dP_z = \int f(x) \phi(x) dx = \mathbb{E}[f(z)]$$

To evaluate  $\int f dP_z$  rewrite as  $\int f \phi dx$ .  
↙ density [can't always  
do this]  
e.g. Binom

It is nice to turn integrals we care  
about into Lebesgue integrals. When  
can we do this?

## Densities

$\lambda$  and  $P$  above are closely related. Want to make this precise.

Given  $(X, \mathcal{F})$ , two measures  $P, \mu$

We say  $P$  is absolutely continuous wrt  $\mu$   
if  $P(A) = 0$  whenever  $\mu(A) = 0$

Notation:  $P \ll \mu$  or we say  $\mu$  dominates  $P$

If  $P \ll \mu$  then (under mild conditions) we can always define a density function

$p: X \rightarrow [0, \infty)$  with

$$P(A) = \int_A p(x) d\mu(x)$$

$$\int f(x) dP(x) = \int f(x) p(x) d\mu(x)$$

Sometimes written  $p(x) = \frac{dP}{d\mu}(x)$ , called  
Radon - Nikodym derivative

Densities are very useful:

Turn  $\int f(x) dP(x)$  into something we know how to evaluate, such as

$$1) \int_{\mathcal{X}} f(x) p(x) dx \quad (X \text{ continuous, } \mathcal{X} \subseteq \mathbb{R}^n)$$

$p(x)$  called probability density function (pdf)

$$2) \sum_{x \in \mathcal{X}} f(x) p(x) \quad (X \text{ discrete, } \mathcal{X} \text{ countable})$$

$p(x)$  called probability mass function (pmf)

Often define distributions by giving their density wrt some known measure, e.g.

Ex: Binom  $(n, \theta)$  pmf:  $p(x) = \theta^n (1-\theta)^{n-x} \binom{n}{x}$ ,  $x = 0, \dots, n$

(density  $p$  wrt counting measure on  $\mathcal{X} = \{0, \dots, n\}$ )

Note this dist. has no density wrt Lebesgue:

$$\int_{\{0, \dots, n\}} p(x) dx = 0 \quad \text{for any function } p$$

# Probability Space, Random Variables

Typically, we set up a problem with multiple random variables having various relationships to one another.

Want to be able to talk about the "prob. that something happens"

Convenient setup:

R.V.s as functions of an abstract "outcome"  $\omega$

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space

$\omega \in \Omega$  called outcome

$A \in \mathcal{F}$  called event

$\mathbb{P}(A)$  called probability of  $A$

A random variable is a function  $X: \Omega \rightarrow \mathcal{X}$

We say  $X$  has distribution  $Q$  ( $X \sim Q$ )

$$\begin{aligned} \text{if } \mathbb{P}(X \in B) &= \mathbb{P}(\{\omega: X(\omega) \in B\}) \\ &= Q(B) \end{aligned}$$



More generally, could write events involving many R.V.s:

$$\mathbb{P}(X > Y > Z \geq 0) = \mathbb{P}(\{\omega: \dots\})$$

The expectation is an integral w.r.t.  $\mathbb{P}$

$$\mathbb{E}[f(X, Y)] = \int_{\Omega} f(X(\omega), Y(\omega)) d\mathbb{P}(\omega)$$

To do real calculations we must eventually boil  
 $\mathbb{P}$  or  $\mathbb{E}$  down to concrete integrals/sums/etc.

If  $\mathbb{P}(A) = 1$  we say  $A$  occurs almost surely

More in Keener ch. 1, much more in Stat 205A