

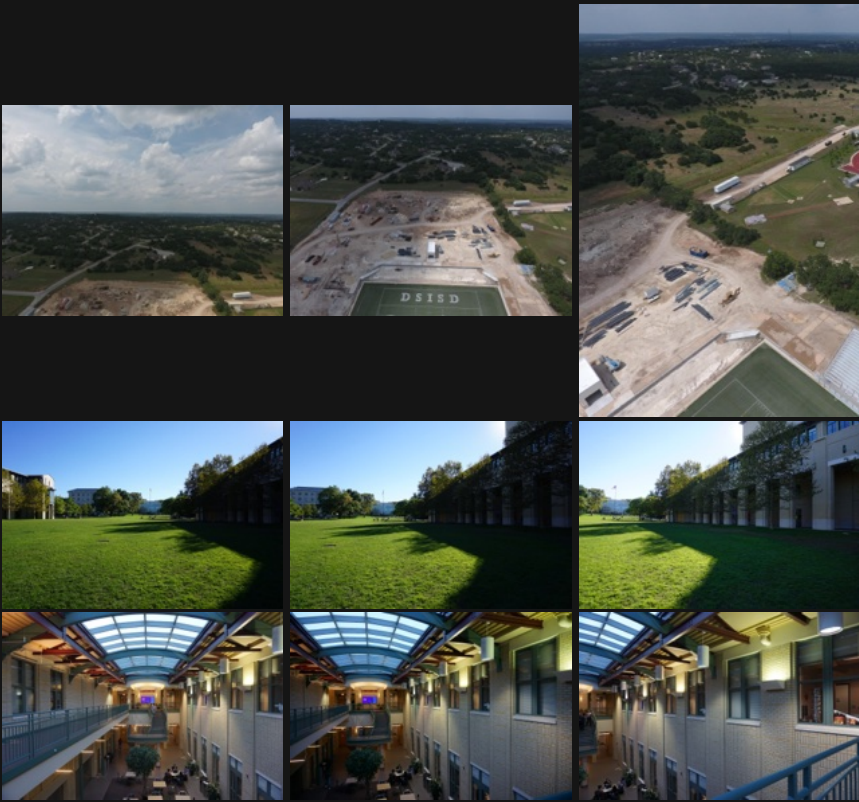
CS180j Project 4 - Naïve R

github: [https://github.com/berkeleybear22ryan/CS180\\_Project4](https://github.com/berkeleybear22ryan/CS180_Project4)

website: [https://berkeleybear22ryan.github.io/CS180\\_Project4/](https://berkeleybear22ryan.github.io/CS180_Project4/)

Part 1: Shoot and Digitize Pictures

For this project, I took multiple sets of photos of my own. I imaged a couple of the buildings at the University of California, Berkeley, with homographies and mosaic. For the sets I worked with:



Here are the personal image sets that I took:



Part 2: Recover Homographies

Homographies are a piece of information that describe a point in the image and where it is in the world. I used the `code/points` directory to store the homographies. I used the `compute_homography` function to compute the homography from a set of points. The homography is stored under `code/homography`.

Example of points visualization:

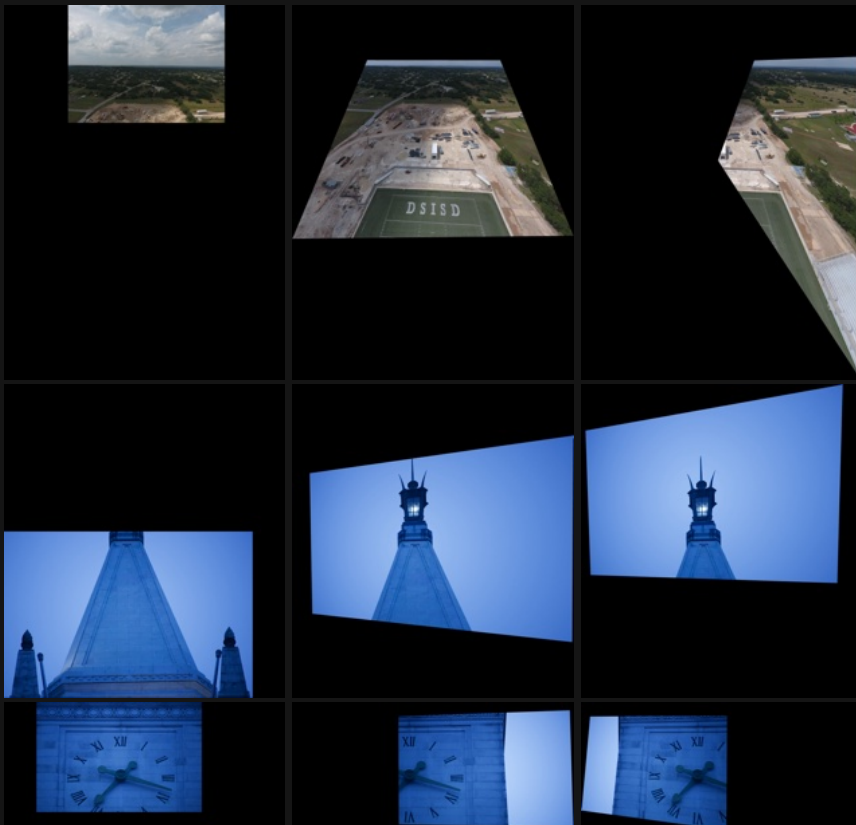


Homography reference image sets:

- `code/h_matrix/1m/H/MC_6786_to_MC_6783.txt`
- `code/h_matrix/1m/H/MC_6792_to_MC_6783.txt`
- `code/h_matrix/9/H/002_to_001.txt`
- `code/h_matrix/9.5/H/002_to_001.txt`
- `code/h_matrix/11/H/003_to_001.txt`

#### Part 8p. Wheel Images

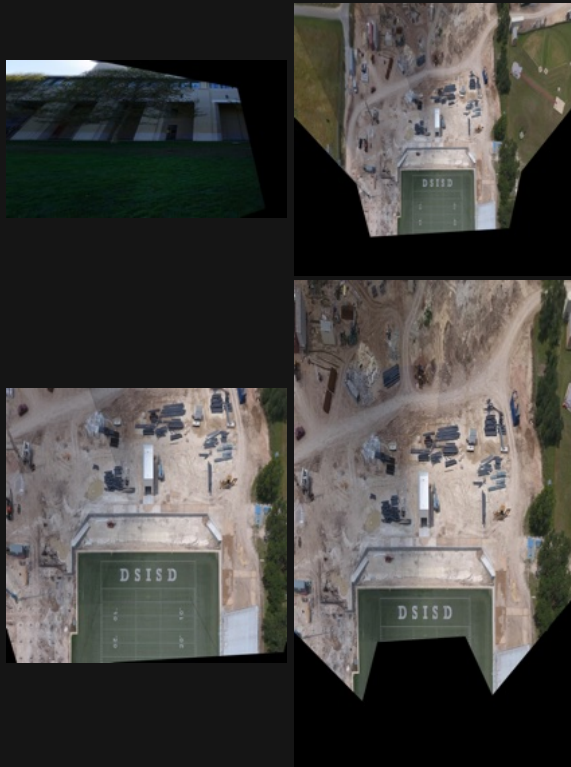
On this page, we provide a set of images for the wheel images. The images are provided in a folder named `code/output/7` for the first set of images.





Part 4: Image Rectification

For the next step, we need to rectify the images. This means we need to transform the images so that they are all in the same perspective. We can use the `code/rectify/` folder to do this.



Part 5: Blend the Images into a Mosaic

In the final step, I blend the images into a mosaic. I compute the weights for each image and then blend them together. I implemented both basic weighted averaging and a more advanced method using a Gaussian kernel. The results are shown in the `code/output/` folder.

