

(Post lecture notes in purple)  
(Imp't equations boxed in green)

- I. ADCs
- II. Discrete Frequency Domain
  - a. Intuitive Review of DFT Matrix
  - b. Sampling Frequency and the DFT
  - c. Sampling and Aliasing Examples
- III. Sampling
  - a. Nyquist Theorem
  - b. Sampling Window
    - i. Application Example
- IV. Anti-Aliasing Filter

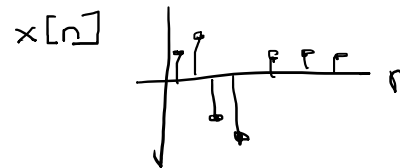
### Sampling and Aliasing

The world is continuous



however

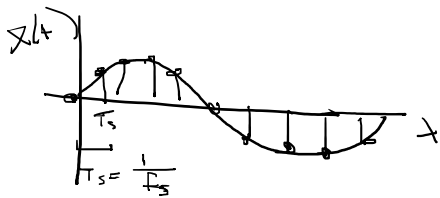
Computers need discrete



#### I. Analog to Digital Converter (ADC)

Given a cont. time waveform and an ADC that samples at freq ( $f_s$ ), collect N samples

Time Domain



Sampling freq:  $f_s$   
Sampling window: N

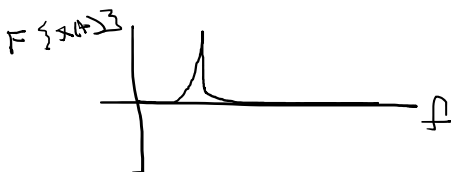


$$x[n] = [x(0) \quad x(T_s) \quad x(2T_s) \quad \dots \quad x((N-1)T_s)]$$

$\Downarrow$  FT

$\Downarrow$  DFT

Frequency Domain



any freq  
 $0 \rightarrow \infty$   
w/ infinite res.

$$F_x = \begin{bmatrix} x_0 e^{j\phi_0} \\ x_1 e^{j\phi_1} \\ \vdots \\ x_{N-1} e^{j\phi_{N-1}} \end{bmatrix} \quad \text{limited to discrete freq}$$

## II. Intuitive Review of DFT

### Purpose of DFT?

- Find how much of each frequency is in a signal (data analysis)
  - filter design
  - signal processing
- Project the signal into a basis of orthogonal sinusoids (math easier)
  - phasor domain
  - convolution

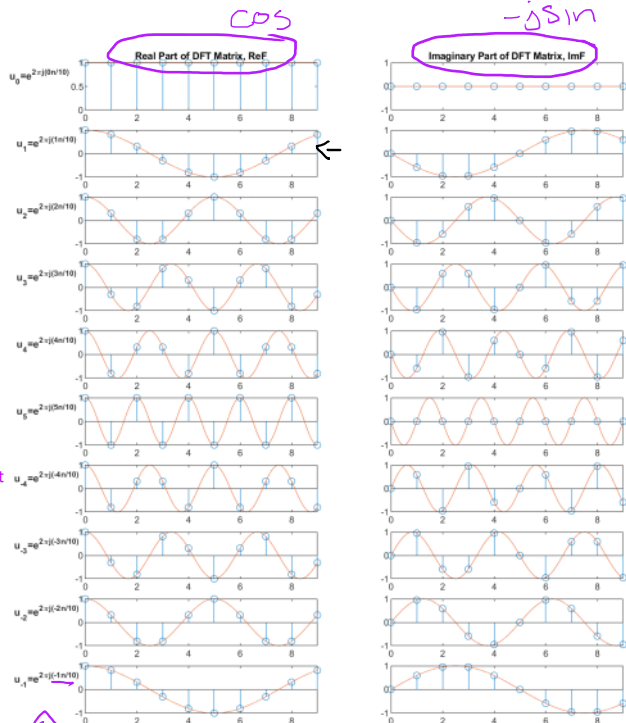
### a. DFT Matrix

$$F_X = \begin{bmatrix} \text{--- } U_0 \text{ ---} \\ \text{--- } U_1 \text{ ---} \\ \text{--- } U_2 \text{ ---} \\ \vdots \\ \text{--- } U_{N-1} \text{ ---} \end{bmatrix} \begin{bmatrix} x_1 \\ x_1 \\ \vdots \\ x_{N-1} \end{bmatrix}$$

$$U_k = e^{-j \frac{2\pi k}{N} n}$$

↑ traversals around the unit circle at diff freq

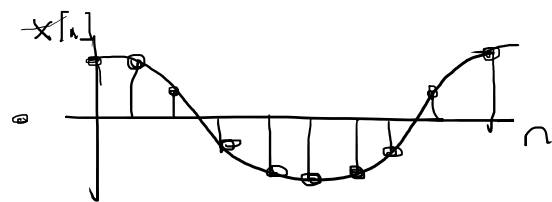
### Visual Representation of $F$ for $N$ samples



$\frac{1}{\sqrt{N}}$   
(Note there is a scalar here that Matlab ignores. This matrix is not orthonormal, just orthogonal. So I'm applying the scalar out here)

↑ aliasing as negative freq

$$x(4) = 2 \cos\left(\frac{2\pi 4}{N}\right)$$



$$F_X = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ \alpha & -j0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \alpha + j0 & 0 & 0 & \dots & 0 \end{bmatrix}$$

← sinusoids are orthogonal

← aliasing

### b. Sampling Frequency and the DFT

How  $f_s$  relates to our DFT matrix

$$V_R = e^{j \frac{2\pi k}{N} n}$$

Discretizing  $\omega$

$$\omega = \frac{2\pi k}{N}$$

where

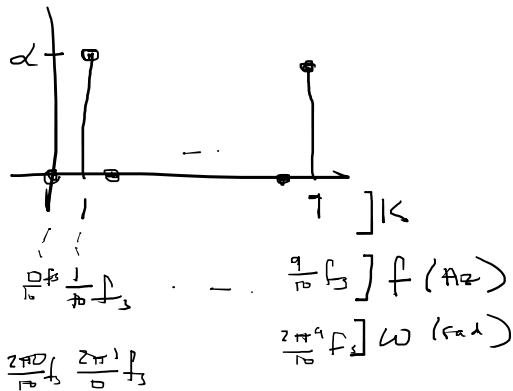
$$\frac{k}{N} = \frac{f}{f_s}$$

(for pleasant integer ratios of  $f/f_s$ )

Draw Prev example

$$[0 \ 0 \ 0 \dots 0 \ 0]$$

$\text{Re}\{F_k\}$



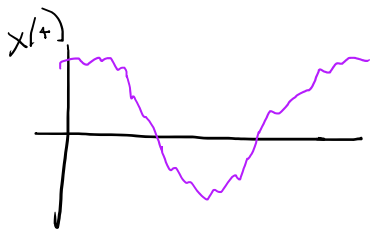
Aliasing

only happens in sampled signals

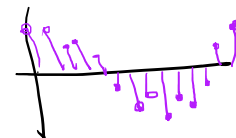
c. Examples of Sampling and Aliasing

Ex 1 Multi-Tone Signal

$$x_1(t) = \alpha_1 \cos(2\pi \cdot 1014 \cdot t) + \alpha_2 \sin(2\pi \cdot 4014 \cdot t)$$



$x[n]$



$$f_s = 100 \text{ Hz}$$

$$N = 10$$

Convert  $f_1 = 1014 \text{ Hz}$  &  $f_2 = 4014 \text{ Hz}$  into  $k$

$$f_1 = 1014 \text{ Hz}$$

$$\frac{k}{N} = \frac{f}{f_s} \Rightarrow$$

$$\frac{k}{10} = \frac{10}{100}$$

$$\Rightarrow 1, 10^{-1}$$

from aliasing

$$f_2 = 4014 \text{ Hz}$$

$$\frac{k}{10} = \frac{40}{100}$$

$$\Rightarrow 4, 10^{-1}$$

$$f_z = 40 \text{ Hz}$$

$$\frac{k}{10} = \frac{40}{100} \Rightarrow 4, 10^{-4}$$

$$F_x = \begin{bmatrix} x \cdot v_0 & x \cdot v_1 & x \cdot v_2 & \dots & x \cdot v_{N-1} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & \alpha_1 & 0 & 0 & -j\alpha_2 & 0 & +j\alpha_2 & 0 & 0 & \alpha_1 \end{bmatrix}$$

$$\cos(\omega t) = \cos(-\omega t)$$

$$\sin(\omega t) = -\sin(-\omega t)$$

$$v_k = e^{-j \frac{2\pi k}{N} n}$$

$$\text{Re}\{v_k\} = \cos$$

$$\text{Im}\{v_k\} = -\sin$$

$$\alpha_2 \sin(2\pi + f_z)$$

$$=$$

$$\alpha_2 e^{-j\pi} \cdot \cos(f_z 2\pi t)$$

$$\alpha_2 e^{-j\pi} = j\alpha_2$$

High freq vs Aliasing:

I can create a signal  $x'(t)$  which has the same  $x[n]$  and  $F_x[n]$

$$x'(t) = \alpha_1 \cos(2\pi \cdot 90 \text{ Hz} \cdot t) - \alpha_2 \sin(2\pi \cdot 60 \text{ Hz} \cdot t)$$

$$x''(t) = \alpha_1 \cos(2\pi \cdot 110 \text{ Hz} \cdot t) + \alpha_2 \sin(2\pi \cdot 140 \text{ Hz} \cdot t)$$

← unrepresentable freq

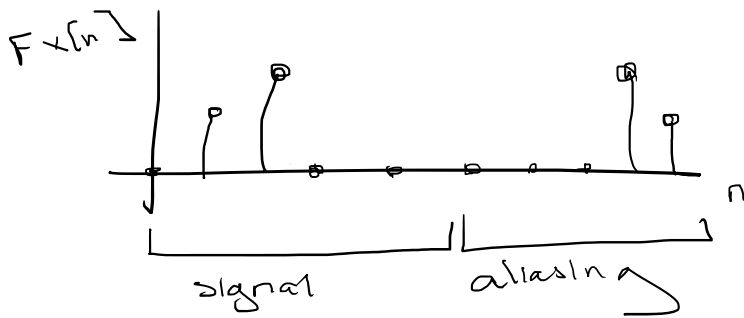
Ex2. Visual Aliasing  
Helicopter floating!

(also technically aliasing, but without the complex conjugate)

## II. Sampling Theorem

### a. Nyquist Sampling Theorem

Let's agree that when we sample, all of our frequencies will be the positive frequency, and all of our aliasing is just a copy



### Nyquist Sampling Theorem:

A bandlimited, cont time signal can be sampled and perfectly represented/ perfectly reconstructed from its samples, IF the sampling freq ( $f_s$ ) is over twice as fast as the signals highest freq component (B)

If you remember nothing else, remember this!

$$f_s > 2B$$

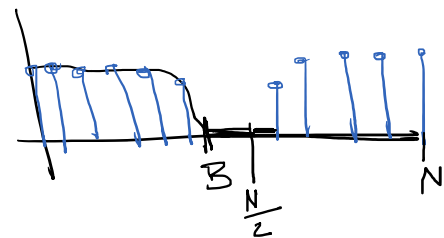
↑                      ↑  
sampling freq      bandwidth

Note: strictly greater than

Bandwidth is the signal's highest frequency (all higher frequencies are zero)



$\Rightarrow$



Nyquist Frequency  $\rightarrow \frac{f_s}{2}$

### b. Sampling Freq and Sampling Window

Intuition

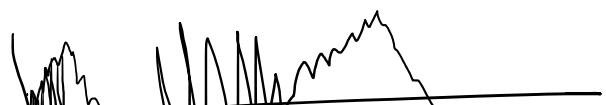
- Sample fast  $\rightarrow$  to get all the high, small freq details w/o aliasing

$$\text{large } f_s \text{ (small } T_s = \frac{1}{f_s})$$

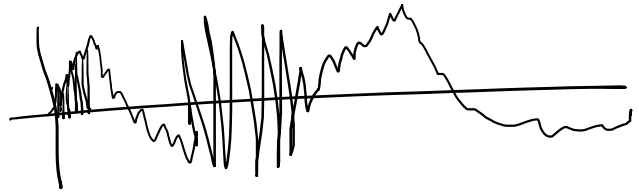
- Collect data over a long time period, represent low frequencies

$$\text{large } N : \quad \frac{k}{N} = \frac{f}{f_s} \Rightarrow \frac{1}{N} = \frac{f_{\min}}{f_s} \Rightarrow f_{\min} = \frac{f_s}{N}$$

Best like



Best life  
 super fast  $f_s$   
 super long  $N$



$$\text{Number of samples: } N = f_s (\text{samples/sec}) \cdot \frac{1}{f_{\min}} (\text{sec})$$

## Ex Application Heart-Rate Sensor

Healthy avg human : 60-100 beats/min  $\rightarrow \sim 1 \text{ beat/sec}$   
 Athlete : 40 beat/min  $\rightarrow 2/3 \text{ beat/sec}$   
 Fastest recorded : 480 beats/min  $\rightarrow 8 \text{ beats/sec}$

How fast must our ADC sample?

$$f_s > 2B$$

$$f_s > 2(8) > 16 \text{ Hz}$$

How many samples are needed

$$\frac{K}{N} = \frac{f_{\min}}{f_s} \Rightarrow \frac{1}{N} = \frac{2/3}{16} \Rightarrow N \geq 24 \text{ samp}$$