

EECS 16A
July 2, 2020
Lecture 1D

Topics:
- Nullspace
- Columnspace

Announcements:

- 1) Friday OH happening today
- 2) Friday HW party moved to Monday

* For an n-dimensional space, we need n basis vectors.

$$A \in \mathbb{R}^{m \times n} \quad \text{For } A\bar{x} = \bar{b}$$

$$\begin{aligned}\bar{x} &\in \mathbb{R}^n \\ \bar{b} &\in \mathbb{R}^m\end{aligned} \quad \begin{array}{l}\text{Transformation} \\ \mathbb{R}^n \rightarrow \mathbb{R}^m\end{array}$$

$$\text{If, } \bar{x} = \begin{bmatrix} m \\ n \end{bmatrix} \in \mathbb{R}^2 \quad A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \in \mathbb{R}^{3 \times 2}$$

$$\bar{b} = A\bar{x} = \begin{bmatrix} m \\ n \\ m+n \end{bmatrix} \in \mathbb{R}^3$$

← Dim = 2

Lecture 1C

Nullspace: All solutions for $A\bar{x} = 0$
 is called the nullspace of A .
 For $A \in \mathbb{R}^{m \times n}$, $N(A) = \{\bar{x} \in \mathbb{R}^n \mid A\bar{x} = 0\}$

Ex 1: Show that $N(A)$ is a subspace of \mathbb{R}^n , where $A \in \mathbb{R}^{m \times n}$.

i) If $\bar{x}_1 \in N(A)$, $\bar{x}_2 \in N(A)$

$$(I) \quad A\bar{x}_1 = \bar{0} \quad (II) \quad A\bar{x}_2 = \bar{0}$$

$$A\bar{x}_1 + A\bar{x}_2 = \bar{0}$$

$$\Rightarrow A(\bar{x}_1 + \bar{x}_2) = \bar{0}$$

$$\text{so } (\bar{x}_1 + \bar{x}_2) \in N(A)$$

ii) If $\bar{x} \in N(A)$

$$\Rightarrow A\bar{x} = \bar{0}$$

$$\Rightarrow \alpha A\bar{x} = \bar{0} \Rightarrow A(\alpha\bar{x}) = \bar{0}$$

$\Rightarrow \alpha\bar{x} \in N(A)$, α is a scalar

iii) $A(\bar{0}) = \bar{0}$, $\bar{0} \in N(A)$

$N(A)$ is a subspace of \mathbb{R}^n

* can be also proven for columnspace

Columnspace / range: Span of columns of A .

If $A = \begin{bmatrix} \bar{a}_1 & \bar{a}_2 & \dots & \bar{a}_n \end{bmatrix} \in \mathbb{R}^{m \times n}$, columnspace

$$= C(A) = \text{Range}(A)$$

$$= \{ A\bar{x} \mid \bar{x} \in \mathbb{R}^n \}$$

$$A\bar{x} = \begin{bmatrix} \bar{a}_1 & \dots & \bar{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$= [\bar{a}_1 x_1 + \bar{a}_2 x_2 + \dots]$$

= linear comb of $\{\bar{a}_1, \dots, \bar{a}_n\}$

For all values of \bar{x}

$$A\bar{x} \rightarrow \text{span} \{ \bar{a}_1, \dots, \bar{a}_n \} \quad \text{Lecture 0D}$$

Takeaway :

$$\left. \begin{array}{l} \text{If } \bar{x} \in N(A), A\bar{x} = \underline{0} \\ \text{If } \bar{x} \notin N(A), A\bar{x} \neq \underline{0} \end{array} \right\} A\bar{x} \rightarrow C(A)$$

Ex 2

$$A = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 2 & 4 & 4 & 6 \end{bmatrix}$$

Find $N(A)$, $C(A)$ & their basis/dim.

Nullspace: $A\bar{x} = \bar{0}$

$$\left[\begin{array}{cccc|c} 1 & 2 & 3 & 5 & 0 \\ 2 & 4 & 4 & 6 & 0 \end{array} \right]$$

lin indep columns

$$R_2' \leftarrow R_2 - 2R_1 \quad \left[\begin{array}{cccc|c} 1 & 2 & 3 & 5 & 0 \\ 0 & 0 & -2 & -4 & 0 \end{array} \right]$$

$$R_2' \leftarrow R_2 / -2 \quad \left[\begin{array}{cccc|c} 1 & 2 & 3 & 5 & 0 \\ 0 & 0 & 1 & 2 & 0 \end{array} \right]$$

$$R_1' \leftarrow R_1 - 3R_2 \quad \left[\begin{array}{cccc|c} 1 & 2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 2 & 0 \end{array} \right]$$

Free variables: x_2, x_4

Basic variables: $x_1 = -2x_2 + x_4$

$$x_3 = -2x_4$$

$$N(A) = \begin{bmatrix} -2x_2 + x_4 \\ x_2 \\ -2x_4 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -2 \end{bmatrix}$$

$$= \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ -2 \end{bmatrix} \right\}$$

Basis for $N(A) = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ -2 \end{bmatrix} \right\}$

$$\begin{aligned} \dim(N(A)) &= \# \text{ basis vectors for } N(A) \\ &= \# \text{ free variables} \\ &= 2 \end{aligned}$$

$$\begin{aligned} C(A) &= \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 4 \\ 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \\ 1 \\ 4 \\ 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \\ 4 \\ 1 \\ 5 \\ 6 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 6 \\ 6 \\ 2 \\ 2 \\ 2 \\ 1 \\ 1 \end{bmatrix} \right\} (\mathbb{R}^2) \\ &= \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \\ 4 \\ 1 \end{bmatrix} \right\} (\text{still } \mathbb{R}^2) \end{aligned}$$

Basis for $C(A) = \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \\ 4 \\ 1 \end{bmatrix} \right\}$
 \rightarrow columns producing leading entries of 1.

$$\begin{aligned}
 GE : \# \text{ Free Variables} &= \dim(N(A)) \\
 \# \text{ Basic Variables} &= \dim(C(A)) \\
 \hline
 \# \text{ Variables} &= n \\
 &= \# \text{ columns}
 \end{aligned}$$

Rank-Nullity Theorem:

$$\text{Rank} = \dim(C(A))$$

$$\text{Nullity} = \dim(N(A))$$

If $A \in \mathbb{R}^{m \times n}$ is a linear

from $V \rightarrow W$, where $V \in \mathbb{R}^n$ & $W \in \mathbb{R}^m$

then

$$\begin{aligned}
 &\dim(C(A)) + \dim(N(A)) \\
 &= \text{Rank}(A) + \text{Nullity}(A) \\
 &= n = \dim(V)
 \end{aligned}$$

full rank matrix:

GE: All the columns having leading entries of 1 $\rightarrow A\bar{x} = b$
has unique solution

Ex 3 Ipython demo \rightarrow Website

<u>LHS</u>	<u>RHS</u>
\bar{x}	$A\bar{x}$
$N(A)$	$\{0\}$
Not of $N(A)$	$\neq \{0\}$

$\xrightarrow{\hspace{1cm}}$

$\{0\} \quad \underbrace{\hspace{1cm}}_{C(A)}$

$\neq \{0\} \quad \underbrace{\hspace{1cm}}$

Ex 1

Ex 2

Ex 3

$$\dim(N(A)) = 2 \quad \dim(C(A)) = 1 \quad \frac{2+1}{=3}$$

3×3 matrix: 3 rows \rightarrow all dependent

3 columns \rightarrow all dependent

$$\begin{aligned} \# \text{ Free Var} &= 2 \quad \rightarrow \dim(N(A)) \\ \# \text{ Basic Var} &= 1 \quad \rightarrow \dim(C(A)) \end{aligned}$$

Ex 9 $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 2 \end{bmatrix}$

Find Rank & nullity.
Nullspace:

$$\left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 2 & 0 \end{array} \right]$$

$$\xrightarrow{\quad} \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 1 & 0 \end{array} \right] \xrightarrow{\quad} \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{array} \right]$$

$$\xrightarrow{\quad} \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Free variables = 0 \rightarrow nullity
Basic variables = 2 \rightarrow rank

Significance of $N(A)$ & $C(A)$:

i) case 1: No solution

No \bar{x} exists that satisfies $A\bar{x} = \bar{b}$
All possible values of $A\bar{x} \rightarrow C(A\bar{x}) = \bar{b}$
 $\bar{b} \notin C(A)$

ii) Case 2: Unique solution

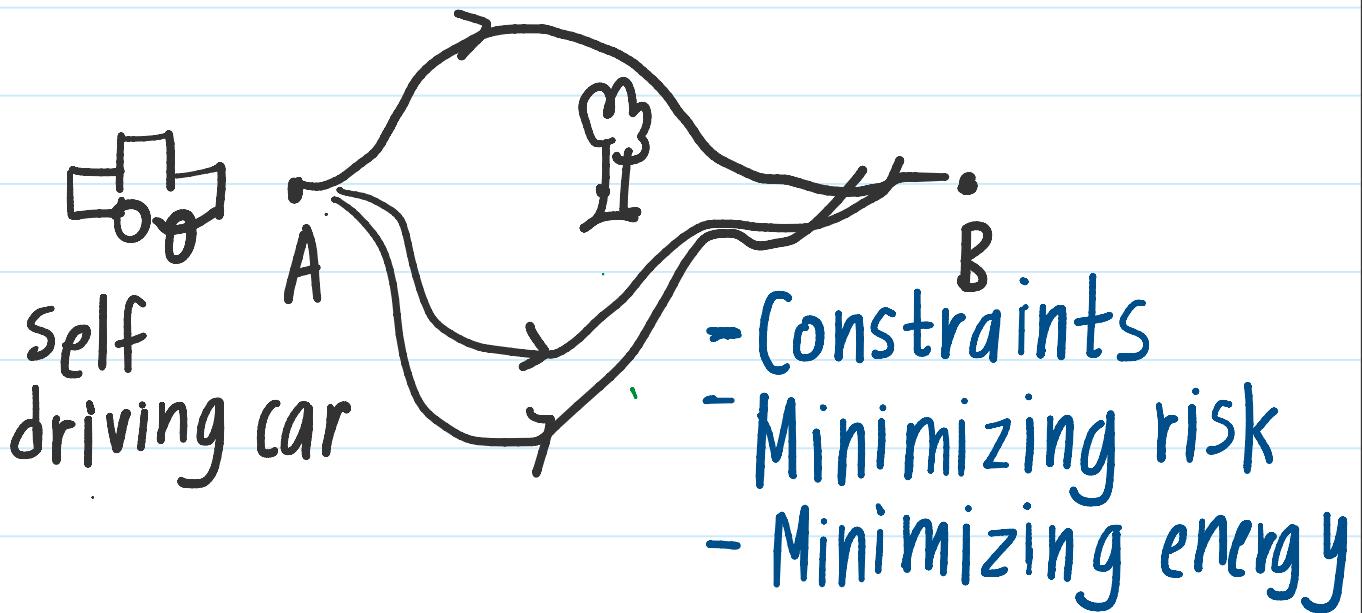
Free variables = 0
 $\dim(N(A)) = 0$

← trivial nullspace

iii) Case 3: Infinite solutions

Free var > 0
 $\dim(N(A)) > 0$

- * $C(A)$ can tell us if there is a solution to $A\bar{x} = \bar{b}$
- * $N(A)$ can characterize all existing solution.



Ex 5 If \bar{x}_0 is a solution to $A\bar{x} = \bar{b}$
 and $\bar{v} \in N(A)$,
 show that $\bar{x}_1 = \bar{x}_0 + \bar{v}$ should be
 another solution to $A\bar{x} = \bar{b}$

Given,

$A\bar{x}_0 = \bar{b}$	(I)
$A\bar{v} = \bar{b}$	(II)

$$(I) + (II) \Rightarrow A(\bar{x}_0 + \bar{v}) = \bar{b}$$

Want to show $A\bar{x}_1 = \bar{b}$
 $\bar{x}_1 = \bar{x}_0 + \bar{v}$ is a solution

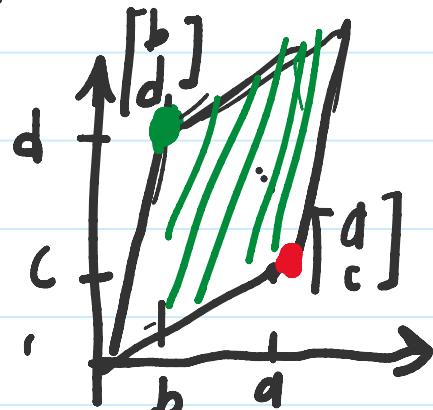
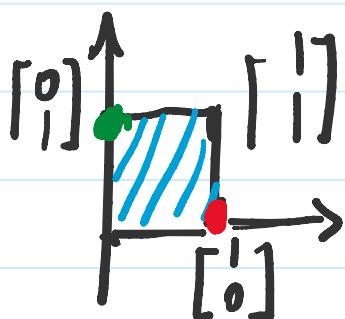
* If \bar{x}_0 is a solution to $A\bar{x} = \bar{b}$
 and $\bar{x}_1 = \bar{x}_0 + \bar{v}$ is another soln
 to $A\bar{x} = \bar{b} \Rightarrow \bar{v}$ must belong
 in the nullspace of A .

Determinant: For $A \in \mathbb{R}^{n \times n}$, $\det(A)$ is the volume of n -dimensional parallelepiped spanned by columns of A .

→ $\det(A)$ represents the change of volume when transformed by A .

Example: $A \in \mathbb{R}^{2 \times 2}$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$



Input: \bar{x}
 $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$
 $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$
 $\text{Volume} = 1$

$$\begin{aligned} A \begin{bmatrix} 1 \\ 0 \end{bmatrix} &= \begin{bmatrix} a \\ c \end{bmatrix} \\ A \begin{bmatrix} 0 \\ 1 \end{bmatrix} &= \begin{bmatrix} b \\ d \end{bmatrix} \end{aligned}$$

Output: $A\bar{x}$

$$\text{Volume} = ad - bc$$

$$\text{Change of volume} = \frac{ad - bc}{1} = ad - bc$$

$$\det(A) = ad - bc$$

For $\mathbb{R}^{2 \times 2}$, volume $\neq 0$, only when
the two col vectors are lin. indep

