# EECS 16A Spring 2021

## Designing Information Devices and Systems I Discussion 1A

### 1. Gaussian Elimination

Use Gaussian elimination to solve the following systems. Does a solution exist? Is it unique?

(a)

$$\begin{bmatrix} 2 & 0 & 4 \\ 0 & 1 & 2 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ -3 \\ 3 \end{bmatrix}$$

**Answer:** 

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5 \\ -1 \\ -1 \end{bmatrix}$$

(b)

$$\begin{bmatrix} 1 & 4 & 2 \\ 1 & 2 & 8 \\ 1 & 3 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}$$

#### **Answer:**

No solution. Performing Gaussian Elimination on the augmented matrix will lead to a row of zeros with a non zero constant term.

(c)

$$\begin{bmatrix} 2 & 2 & 3 \\ 0 & 1 & 1 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix}$$

### **Answer:**

There are an infinite number of solutions. One solutions is:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 3 \end{bmatrix}$$

(d) True or False: A system of equations with more equations than unknowns will always have either infinite solutions or no solutions.

**Answer:** False, a counter example of this is when we have N equations and K unknowns (N > K) and N - K of the equations are linear combinations of the first K. This means that there are actually K unique equations and K unique unknowns; therefore a unque solution will exist. This can be observed when Gaussian elimination is performed and the last N - K rows are all 0.

For example, here is a system of four equations and two unknowns,

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 2 & 4 & 2 \\ 2 & 5 & 3 \end{bmatrix} \xrightarrow{-2R_1 + R_3 \to R_3} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 2 & 5 & 3 \end{bmatrix} \xrightarrow{-2R_1 - R_2 + R_3 \to R_3} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
(1)

Solving, we get a single exact solution, x = -1 and y = 1.

(e) (Practice)

$$\left[\begin{array}{cc|c} 3 & -1 & 2 & 1 \\ 0 & 0 & 2 & 1 \end{array}\right]$$

### **Answer:**

There are an Infinite number of solutions. One solutions is:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 6 \\ \frac{1}{2} \end{bmatrix}$$

Performing Gaussian elimination will lead to a row of zeros on the bottom row.

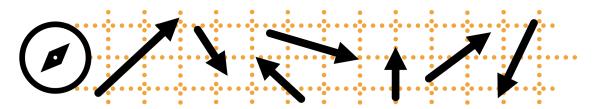
(f) (Practice)

$$\begin{bmatrix} 2x & + & 4y & + & 2z & = & 8 \\ x & + & y & + & z & = & 6 \\ x & - & y & - & z & = & 4 \end{bmatrix}$$

**Answer:** 

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 3 \end{bmatrix}$$

### 2. Vectors



A vector is an ordered list of numbers. For instance, a point on a plane (x,y) is a vector! We label vectors using an arrow overhead  $\vec{v}$ , and since vectors can live in ANY dimension of space we'll need to leave our notation general  $(x,y) \rightarrow \vec{v} = (v_1,v_2,...)$ . Below are few more examples (the left-most form is the general definition):

$$\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{R}^n$$
  $\vec{a} = \begin{bmatrix} 3 \\ 1 \\ 4 \end{bmatrix} \in \mathbb{R}^3$   $\vec{b} = \begin{bmatrix} 2.4 \\ 5.3 \end{bmatrix} \in \mathbb{R}^2$ 

Just to unpack this a bit more,  $\vec{b} \in \mathbb{R}^3$  in english means "vector  $\vec{b}$  lives in 3-Dimensional space".

- The ∈ symbol literally means "in"
- The  $\mathbb R$  stands for "real numbers" (FUN FACT:  $\mathbb Z$  means "integers" like -2,4,0,...)
- The exponent  $\mathbb{R}^n$   $\leftarrow$  indicates the dimension of space, or the amount of numbers in the vector.

One last thing: it is standard to write vectors in column-form, like seen with  $\vec{a}, \vec{b}, \vec{x}$  above. We call these *column vectors*, in contrast to horizontally written vectors which we call *row vectors*.

Okay, let's dig into a few examples:

(a) Which of the following vectors live in  $\mathbb{R}^2$  space?

$$i. \begin{bmatrix} 3 \\ 6 \end{bmatrix} \qquad \qquad ii. \begin{bmatrix} 5 \\ 0 \\ 3 \\ 5 \end{bmatrix} \qquad \qquad iii. \begin{bmatrix} -4.76 \\ 1.32 \\ 0.01 \end{bmatrix} \qquad \qquad iv. \begin{bmatrix} -20 \\ 100 \end{bmatrix}$$

### **Solution/Answer:**

i. Yes ii. No iii. No iv. Yes

Remember  $\mathbb{R}^2$  means 2D space, which hosts vectors with 2 terms.

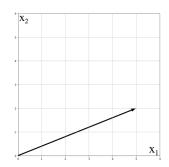
We count and see only i. and iv. have 2 terms.

(b) Graphically show the vectors (either in a sketch with axes, or a plot on a computer):

$$i. \begin{bmatrix} 2 \\ 5 \end{bmatrix}$$
  $ii. \begin{bmatrix} 5 \\ 2 \end{bmatrix}$ 

**Solution/Answer:** Although these vectors look similar, remember that the ordering matters!



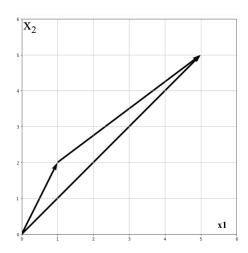


(c) Compute the sum  $\vec{a} + \vec{b} = \vec{c}$  from the vectors below, and then graphically sketch or plot these vectors. (show them in a way that forms a triangle; also is there only one possible triangle?)

$$\vec{a} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\vec{a} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
  $\vec{b} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$ 

**Solution/Answer:** 



Computation is done element-wise:

$$\vec{c} = \vec{a} + \vec{b} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \end{bmatrix}$$