



**EECS 16B**

**Designing Information Devices and Systems II**

**Lecture 18**

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# Outline

- Orthonormalization (Gram-Schmidt) and QR Decomposition
- Upper Triangularization

# Gram-Schmidt Procedure (Summary)

$$\vec{z}_1 = \vec{d}_1$$

$$\vec{z}_2 = \vec{d}_2 - (\vec{d}_2^\top \vec{q}_1) \vec{q}_1$$

$$\vec{z}_3 = \vec{d}_3 - (\vec{d}_3^\top \vec{q}_1) \vec{q}_1 - (\vec{d}_3^\top \vec{q}_2) \vec{q}_2$$

$\vdots$

$$\vec{z}_k = \vec{d}_k - \sum_{j=1}^{k-1} (\vec{d}_k^\top \vec{q}_j) \vec{q}_j$$

$$\vec{q}_1 = \vec{z}_1 / \|\vec{z}_1\|$$

$$\vec{q}_2 = \vec{z}_2 / \|\vec{z}_2\|$$

$$\vec{q}_3 = \vec{z}_3 / \|\vec{z}_3\|$$

$$\vdots$$

$$\vec{q}_k = \vec{z}_k / \|\vec{z}_k\|$$

Claim: 1.  $\vec{z}_j^\top \vec{q}_i = 0$  for all  $i < j$     2.  $\|\vec{z}_i\| = \vec{d}_i^\top \vec{q}_i$

(1)  $\vec{z}_j^\top \vec{q}_i = (\vec{d}_j - \sum_{l=1}^{j-1} (\vec{d}_j^\top \vec{q}_l) \vec{q}_l)^\top \vec{q}_i = \vec{d}_j^\top \vec{q}_i - (\vec{d}_j^\top \vec{q}_i) = 0$

$$D = [\vec{d}_1 \ \vec{d}_2 \ \dots \ \vec{d}_K]_{n \times K}$$

$\vec{q}_l^\top \vec{q}_j = \begin{cases} 0 & l \neq j \\ 1 & l = j \end{cases}$

②  $\|\vec{z}_j\|$

$$\vec{z}_j = \|\vec{z}_j\| \vec{q}_j$$

$$\vec{z}_j \cdot \vec{q}_j = \vec{d}_j^\top \vec{q}_j - 0$$

$$\frac{\|\vec{z}_j\|}{\|\vec{z}_j\|} = \vec{d}_j^\top \vec{q}_j$$

# Gram-Schmidt & QR Decomposition

$$\vec{d}_1 = (\vec{d}_1^\top \vec{q}_1) \vec{q}_1$$

$$\vec{d}_2 = (\underbrace{\vec{d}_2^\top \vec{q}_1}_{\vec{q}_1}) \vec{q}_1 + (\underbrace{\vec{d}_2^\top \vec{q}_2}_{\vec{q}_2}) \vec{q}_2$$

$$\vec{d}_3 = (\vec{d}_3^\top \vec{q}_1) \vec{q}_1 + (\underbrace{\vec{d}_3^\top \vec{q}_2}_{\vec{q}_2}) \vec{q}_2 + (\underbrace{\vec{d}_3^\top \vec{q}_3}_{\vec{q}_3}) \vec{q}_3$$

$$\vec{d}_k = (\vec{d}_k^\top \vec{q}_1) \vec{q}_1 + (\vec{d}_k^\top \vec{q}_2) \vec{q}_2 + \cdots + (\underbrace{\vec{d}_k^\top \vec{q}_k}_{\| \vec{d}_k \|} \vec{q}_k)$$

$$\underline{D_{n \times n}} = Q_{n \times n} R_{n \times n}$$

$$D_{n \times k} = \underline{Q_{n \times k}} R_{k \times k}$$

$$Q^T Q = I = Q Q^T - \text{orthogonal complete}$$

$Q^T Q_{n \times k} = 0$

$\downarrow \downarrow \quad (r_{ij} = \underbrace{\vec{d}_j^\top \vec{q}_i}_{\vec{q}_i})$ 
  
 $[\vec{d}_1, \vec{d}_2, \dots, \vec{d}_k] = [\vec{q}_1, \vec{q}_2, \dots, \vec{q}_k]$

$r_{11}$	$r_{12}$	$\cdots$	$r_{1k}$
0	$r_{22}$	$\cdots$	$r_{2k}$
$\vdots$	$\ddots$	$\ddots$	$\vdots$
0	$\cdots$	0	$r_{kk}$

$D_{n \times k} = \underline{Q_{n \times k}} \underline{R_{k \times k}}$

$$Q = [Q_{n \times k}, \tilde{Q}_{(n-k) \times k}] \quad \tilde{Q}^T Q_{n \times k} = 0$$

# QR, Diagonalization, Triangularization

QR Decomposition for  $D \in \mathbb{R}^{n \times k}$ :  $[\vec{d}_1, \vec{d}_2, \dots, \vec{d}_k] = [\vec{q}_1, \vec{q}_2, \dots, \vec{q}_k]$

$$y = Ax$$

$$\boxed{D = QR} \quad \boxed{Q^T D = R}$$

$$\begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1k} \\ 0 & r_{22} & \cdots & r_{2k} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & r_{kk} \end{bmatrix}$$

~~for all~~

Diagonalization for  $A \in \mathbb{R}^{n \times n}$ :

$$AV = V\Lambda$$

$$\underbrace{A}_{V} \underbrace{V^{-1} A V = \Lambda}_{V} \underbrace{V^{-1}}_{V} \underbrace{V} = \Lambda$$

$$\begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \lambda_n \end{bmatrix}$$

↙

Triangularization for  $A \in \mathbb{R}^{n \times n}$ :

$$AU = U\Gamma$$

$$\underbrace{A}_{U} \underbrace{U^{-1} A U = \Gamma}_{U} \underbrace{U^{-1}}_{U} \underbrace{U} = \Gamma$$

$$\begin{bmatrix} t_{11} & t_{12} & \cdots & t_{1n} \\ 0 & t_{22} & \cdots & t_{2k} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & t_{nn} \end{bmatrix}$$

↙

$$\boxed{U^{-1} A U = \Gamma}$$

$U$  - orthogonal

$$\boxed{U^T A U = \Gamma}$$

# Diagonalization v.s. Triangularization

Conditions for diagonalization of  $A \in \mathbb{R}^{n \times n}$ :

$$AV = V\Lambda \quad \leftarrow$$

$$A v_i = \lambda_i v_i \quad i=1, \dots, n.$$

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 0 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$(A - \lambda I) v = \begin{bmatrix} 0 & 1 & \cdots & 0 \\ 0 & 0 & \ddots & \vdots \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \cdots & 0 \end{bmatrix}_{n \times n} v = 0$$

$$\begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \lambda_n \end{bmatrix}$$



$$V^{-1} \quad \text{Jordan}$$
$$\begin{bmatrix} \lambda & 1 & 0 & \cdots & 0 \\ 0 & \lambda & 1 & \ddots & \vdots \\ 0 & 0 & \lambda & \ddots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda \end{bmatrix} A$$

$$A v = \lambda v$$

$$\underbrace{P^n(\lambda) = 0}_{\text{sic!}}$$

## Upper-Triangularization

Upper-triangularization for  $A \in \mathbb{R}^{n \times n}$ :  $U^{-1}AU =$

$$U^{-1}AU = \begin{bmatrix} t_{11} & t_{12} & \cdots & t_{1n} \\ 0 & t_{22} & \cdots & t_{2k} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & t_{nn} \end{bmatrix}$$

Eigenvalues of an upper-triangular matrix:

$$z = U^{-1}x$$

$$x[i+1] \leftarrow A \cdot x[i]$$

$$z[1:i] = \frac{U^{-1}AU}{\tilde{A}} z[i]$$

$$\det(\lambda I - \tilde{A}) = \underbrace{\det(U)}_{= \det(U \lambda I U^{-1} - U \tilde{A} U^{-1})} \det(\lambda I - \tilde{A}) \underbrace{\det(U^{-1})}_{\lambda^{-1}}$$

$$= \det(\lambda I - A)$$

$$\det(\lambda I - T) = \det$$

$$\left[ \begin{array}{cccc} \lambda - t_{11} & * & & \\ \lambda - t_{22} & \ddots & & \\ 0 & \ddots & \ddots & \lambda - t_{nn} \end{array} \right] = \boxed{(\lambda - t_{11}) \cdots (\lambda - t_{nn})}$$

# Upper-Triangularization

Solution to an upper-triangular system of linear equations:

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} t_{11} & t_{12} & \cdots & t_{1n} \\ 0 & t_{22} & \cdots & t_{2n} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & t_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$\begin{aligned} y &= Ax \\ x &= A^{-1}y \end{aligned}$$

$$\begin{aligned} y_n &= t_{nn}x_n \quad \leftarrow x_n \equiv t_{nn}^{-1}y_n \\ y_{n-1} &= t_{n-1,n-1}x_{n-1} + \underbrace{t_{n-1,n}x_n}_{\vdots} \quad \leftarrow \underline{x_{n-1}} \\ y_1 &= t_{11}x_1 + \underline{\text{known}} \end{aligned}$$

# Upper-Triangularization

Solution to an upper-triangular system of linear differential equations:

$$\dot{x}(t) = A x(t)$$
$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \\ \vdots \\ \dot{x}_n(t) \end{bmatrix} = \begin{bmatrix} t_{11} & t_{12} & \cdots & t_{1n} \\ 0 & t_{22} & \cdots & t_{2n} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & t_{nn} \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_n(t) \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} u(t)$$


$$A = Q R$$

$$\underline{Q^T \dot{x}(t) = R x(t)}$$
$$\frac{d x_n(t)}{dt} = t_{nn} x_n(t) + b_n u(t)$$
$$x_n(t) = e^{\int_{t_0}^t t_{nn}(z - t_0) b_n u(z) dz} x(t_0)$$

$$\frac{d x_{n-1}(t)}{dt} = \underbrace{t_{n-1,n-1} x_{n-1}(t)}_{\vdots} + \underbrace{t_{n-1,t} x_n(t)}_{\text{known}} + b_{n-1} u(t)$$

$$\frac{d x_1(t)}{dt} = t_{11} x_1(t) + \underbrace{b_1 u(t)}_{\text{known}}$$

# Upper-Triangularization (Schur Decomposition)

**Claim:** For any matrix  $A \in \mathbb{R}^{n \times n}$  with real eigenvalues, there exists an orthogonal matrix:  $U \in \mathbb{R}^{n \times n}$  such that  $U^T U = I$  and

$$T = U^{-1}AU = U^T AU = \begin{bmatrix} t_{11} & t_{12} & \cdots & \overbrace{t_{1n}} \\ 0 & t_{22} & \cdots & t_{2k} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & t_{nn} \end{bmatrix}^T$$

**Proof (by induction):**

1.  $n=1$   $A = (a_{11})$  true

→ 2.  $n=k+1$   $A_{(k+1) \times (k+1)}$  can be triangulated  
if  $\forall A_{k \times k}$  can be triangulated

$$A \in \mathbb{R}^{(k+1) \times (k+1)}$$

$$AU = UT \quad \left[ \begin{array}{c|cc} * & & \\ \hline 0 & * & * \end{array} \right]$$

$$A\vec{u}_1 = t_{11}\vec{u}_1$$

$$\dot{x}(t) = \underline{A} x(t)$$

$$\dot{y}(t) = \underline{U}^{-1} x(t)$$

$$\dot{x}(t) = \underline{U} \dot{y}(t)$$

$$\dot{y}(t) = \underline{U}^T x(t)$$

# Upper-Triangularization (Schur Decomposition)

**Claim:** For any matrix  $A \in \mathbb{R}^{n \times n}$  with real eigenvalues, there exists an orthogonal matrix:  $U \in \mathbb{R}^{n \times n}$  such that  $U^\top U = I$  and  $T = U^{-1}AU = U^\top AU$  is upper-triangular.

Proof (continued):

$\vec{q}_1$  to be the eigenvector w.r.t  $\lambda_1$  of  $A_{\underbrace{\text{I.C.F.}}_{k+1}}$ ,  $A \vec{q}_1 = \lambda_1 \vec{q}_1$  normal(i)

$$Q = [\vec{q}_1 \vec{q}_2 \dots \vec{q}_{k+1}]$$

G.S.

orthogonal

$$Q^\top Q = I$$

$$\overbrace{Q^\top A Q}^{\text{G.S.}} = \begin{bmatrix} \vec{q}_1^\top \\ \vec{q}_2^\top \\ \vdots \\ \vec{q}_{k+1}^\top \end{bmatrix} \left[ \underbrace{\{\lambda_1 \vec{q}_1, A \vec{q}_2, \dots, A \vec{q}_{k+1}\}}_{A_{\text{I.C.F.}}} \right] = \underbrace{\begin{bmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_{k+1} & \\ & & & 0 \end{bmatrix}}_{A_{\text{I.C.F.}}} = \begin{array}{c} \lambda_1 \\ \vdots \\ \lambda_{k+1} \end{array} \begin{bmatrix} \vec{q}_1 & & & \\ & \ddots & & \\ & & \vec{q}_{k+1} & \\ & & & \vec{q}_{k+1} \end{bmatrix} \quad \begin{array}{c} \lambda_1 \\ \vdots \\ \lambda_{k+1} \end{array} \begin{array}{c} \vec{q}_1 \\ \vec{q}_2 \\ \vdots \\ \vec{q}_{k+1} \end{array} \quad \begin{array}{c} \vec{q}_1 \\ \vec{q}_2 \\ \vdots \\ \vec{q}_{k+1} \end{array} \quad \begin{array}{c} \vec{q}_1 \\ \vec{q}_2 \\ \vdots \\ \vec{q}_{k+1} \end{array}$$

$k \times k$

# Upper-Triangularization (Schur Decomposition)

**Claim:** For any matrix  $A \in \mathbb{R}^{n \times n}$  with real eigenvalues, there exists an orthogonal matrix:  $U \in \mathbb{R}^{n \times n}$  such that  $U^\top U = I$  and  $T = U^{-1}AU = U^\top AU$  is upper-triangular.

Proof (continued):

$\hat{A}_{22}$   $t^r \times k$  has  
real eigenvalues

$$\begin{aligned}\det(\lambda I - \hat{A}) &= \det(\lambda I - \hat{A}) \\ &= \underbrace{(\lambda - \lambda_1)}_{\text{real eigenvalues}} \det(\lambda I - \hat{A}_{22})\end{aligned}$$

# Upper-Triangularization (Algorithm)

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**Algorithm 10** Real Schur Decomposition

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**Input:** A square matrix  $A \in \mathbb{R}^{n \times n}$  with real eigenvalues.

**Output:** An orthonormal matrix  $U \in \mathbb{R}^{n \times n}$  and an upper-triangular matrix  $T \in \mathbb{R}^{n \times n}$  such that  $A = UTU^\top$ .

```
1: function REALSCHURDECOMPOSITION( $A$ )
2:   if  $A$  is  $1 \times 1$  then
3:     return  $\begin{bmatrix} 1 \end{bmatrix}, A$ 
4:   end if
5:    $(\vec{q}_1, \lambda_1) := \text{FINDEIGENVECTOREIGENVALUE}(A)$ 
6:    $Q := \text{EXTENDBASIS}(\{\vec{q}_1\}, \mathbb{R}^n)$        $\triangleright$  Extend  $\{\vec{q}_1\}$  to a basis of  $\mathbb{R}^n$  using Gram-Schmidt; see Note 13
7:   Unpack  $Q := \begin{bmatrix} \vec{q}_1 & \tilde{Q} \end{bmatrix}$ 
8:   Compute and unpack  $Q^\top AQ = \begin{bmatrix} \lambda_1 & \vec{\tilde{a}}_{12}^\top \\ \vec{0}_{n-1} & \tilde{A}_{22} \end{bmatrix}$ 
9:    $(P, \tilde{T}) := \text{REALSCHURDECOMPOSITION}(\tilde{A}_{22})$ 
10:   $U := \begin{bmatrix} \vec{q}_1 & \tilde{Q}P \end{bmatrix}$ 
11:   $T := \begin{bmatrix} \lambda_1 & \vec{\tilde{a}}_{12}^\top P \\ \vec{0}_{n-1} & \tilde{T} \end{bmatrix}$ 
12:  return  $(U, T)$ 
13: end function
```

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