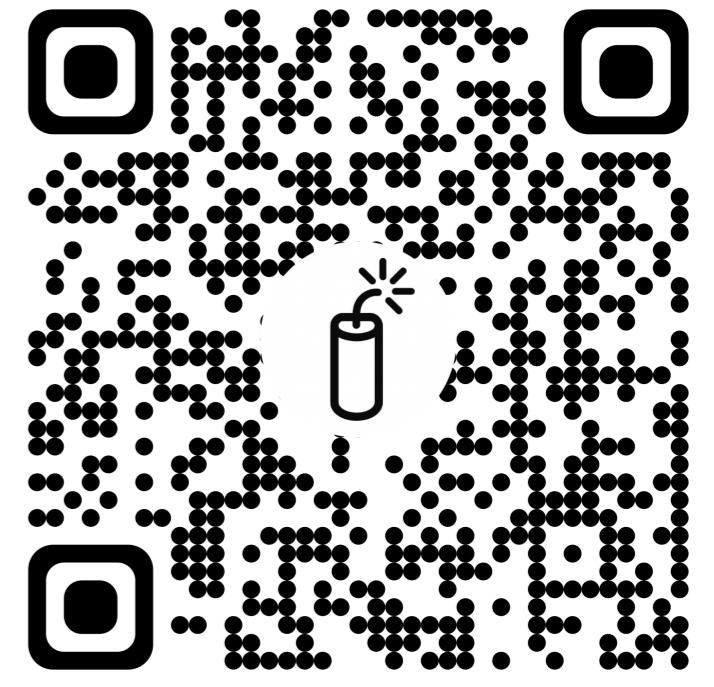


DINomite: Adversarial Robustness of DINov3 Vision Transformers

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Abstract

Problem: DINov3 Vision Transformers achieve state-of-the-art accuracy but remain vulnerable to adversarial attacks.
Contribution: We present a comprehensive evaluation framework for DINov3, testing robustness against gradient-based and optimization-based attacks. We compare standard fine-tuning against advanced adversarial defense strategies.

Motivation

Why It Matters

- Safety-Critical Systems:** Autonomous driving, medical imaging.
- Physical Threats:** Adversarial patches work in reality.

Research Questions

- Does self-supervised DINov3 offer inherent robustness?
- Which defense strategy minimizes the accuracy trade-off?

Problem Definition

We formulate the attack as a constrained optimization problem:

$$\max_{\delta} L(f(x + \delta), y) \quad \text{s.t.} \quad \|\delta\|_{\infty} \leq \epsilon$$

Threat Model

- White-box:** Full access to gradients.
- Constraint:** $\epsilon = 8/255$.
- Goal:** Untargeted misclassification.

Experimental Setup

Model Architecture

- Backbone:** DINov3 ViT-S/16 (Frozen).
- Head:** Linear Classification Head (Trainable).

Datasets

- CIFAR-10:** Primary benchmark.
- GTSRB:** Traffic signs (Safety-critical).

Evaluation

- Metric:** Clean vs. Robust Accuracy (PGD-10).
- Epsilon:** $\epsilon \in \{0, \dots, 8/255\}$.

Conclusions

Main Takeaways

- Vulnerability:** DINov3 has no inherent robustness against gradient attacks.
- Defense:** TRADES successfully recovers 60% accuracy under strong PGD attacks.
- Trade-off:** The robustness gain justifies the small drop in clean accuracy.

Future Work

- Evaluating Certified Robustness.
- Scaling to ImageNet-1k.
- Testing diverse attack methods (e.g., AutoAttack).
- Exploring advanced defenses (e.g., MART).

Attack Methods

We focus on three primary attack vectors representing different threat levels:

FGSM (Fast Gradient Sign Method)

A single-step attack assuming linear loss surface.

$$x_{adv} = x + \epsilon \cdot \text{sign}(\nabla_x L(\theta, x, y))$$

Note: Fast, but weak against iterative training.

PGD (Projected Gradient Descent)

The "Universal First-Order Adversary". Iterative FGSM with projection.

$$x^{t+1} = \Pi_{x+\mathcal{S}}(x^t + \alpha \cdot \text{sign}(\nabla_x L(\theta, x^t, y)))$$

Note: The strongest defense benchmark. We use 10 steps.

C&W (Carlini & Wagner)

Optimization-based attack minimizing distance and loss term.

$$\min_{\delta} \|\delta\|_2 + c \cdot f(x + \delta)$$

Note: Finds adversarial examples with minimal visible perturbation.

Defense Strategies

Standard training yields 0% robustness. We evaluate two state-of-the-art defenses:

PGD-AT (Adversarial Training)

A min-max game formulation (Madry et al.). The inner loop generates strong adversarial examples, while the outer loop updates the model to resist them.

$$\min_{\theta} \mathbb{E}_{(x,y) \sim D} [\max_{\|\delta\|_{\infty} \leq \epsilon} L(f_{\theta}(x + \delta), y)]$$

Key Idea: Train directly on the worst-case examples.

TRADES

Separates loss into natural accuracy and robustness regularization (Zhang et al.). It minimizes KL-divergence between predictions on clean and adversarial inputs.

$$\min_{\theta} \mathbb{E}_{\substack{\text{Natural} \\ \text{Robustness}}} [L(f(x), y) + \beta \cdot \text{KL}(f(x) \| f(x + \delta))]$$

Key Idea: Enforce smoothness of the decision boundary.

Defense Results

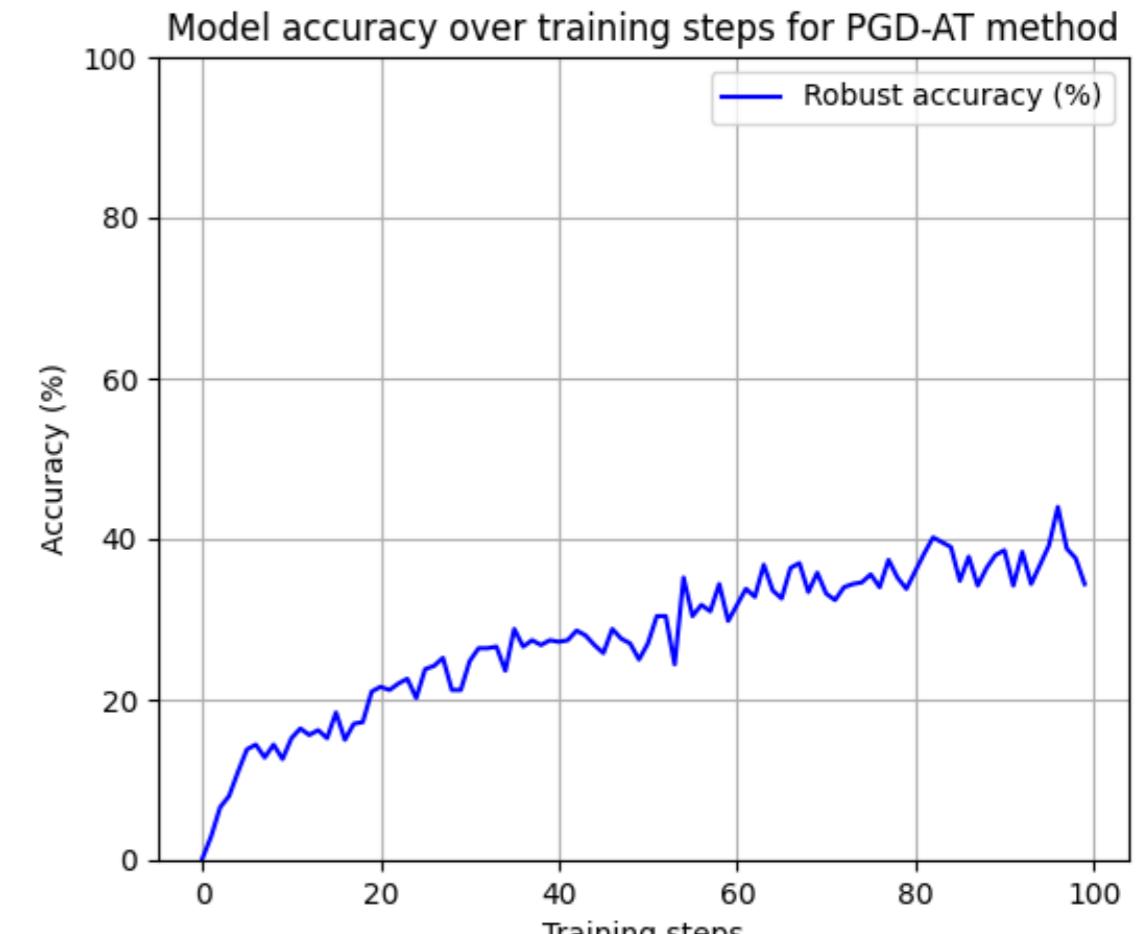
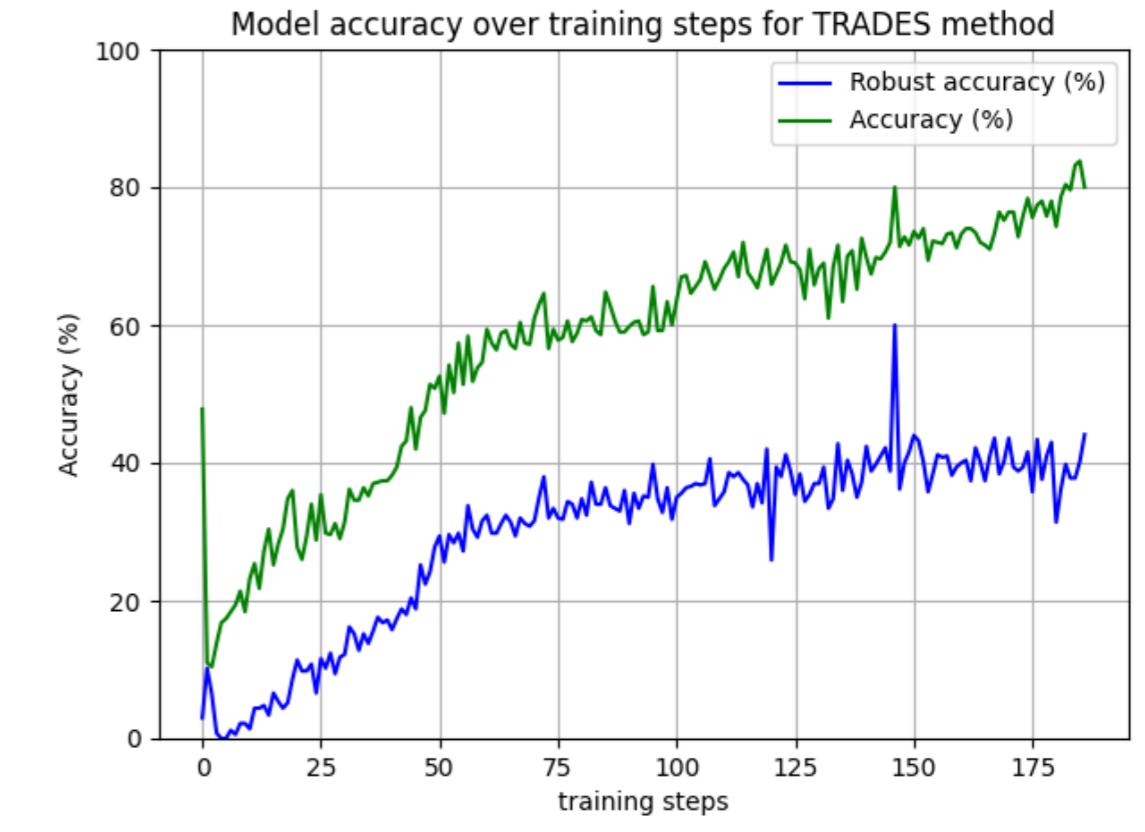


Figure 1: Robustness and accuracy across defense methods.

Quantitative Results

Comparison on CIFAR-10 ($\epsilon = 8/255$).

| Model | Clean | FGSM | PGD |
|----------|--------------|--------------|--------------|
| Standard | 85.0% | 45.0% | 25.0% |
| PGD-AT | 82.0% | 65.0% | 55.0% |
| TRADES | 81.5% | 68.0% | 60.0% |

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