

# Video Reconstruction From a Single Blurry Image

Omri Berman

Deep Learning Course (05107-25501)

Tel-Aviv University

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# Motion Blur

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Rapid Dynamics

# Motion Blur

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- Caused by:
  - Rapid objects dynamics.
  - Camera motion at the time of the acquisition.



Rapid Dynamics



Camera Motion

# Motion Deblurring

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  - Multiple frame (video) deblurring (MIMO).

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  - Sharp video from blurry image (SIMO).

# Motion Deblurring

- Deblurring: Restoration of a sharp representation of the captured motion from the blurry input.
- Several senses:
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  - Sharp video from blurry image (SIMO).



Blurry Input



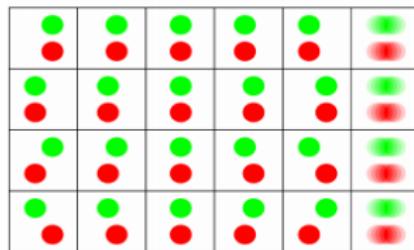
Sharp Output

Single Frame Deblurring Example

# Deblurring Challenges

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- Ambiguity.

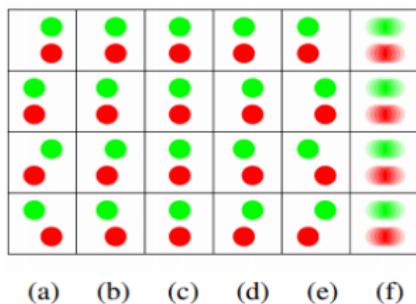


(a) (b) (c) (d) (e) (f)

Ambiguity

# Deblurring Challenges

- Ambiguity.
- Unknown Blur kernel, generally shift-variant.



Ambiguity



Shift-Variant Kernel

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Video From Blurry Motion

└ Proposed Solution

└ Ambiguity

# Blur Model Approximation

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- Blurry image  $\approx$  mean of subsequent sharp frames:

$$y = g\left(\frac{1}{T} \int_0^T \tilde{x}(t) dt\right) \approx g\left(\frac{1}{N} \sum_{i=1}^N x[i]\right)$$

- $y$ : Blurry frame
- $g$ : Camera's CRF
- $T$ : Exposure time (blurry frame).
- $\tilde{x}(t)$ : Instantaneous irradiance.
- $x[i]$ : Sharp frame (captured at  $\frac{N}{T}$  FPS).

Video From Blurry Motion

└ Proposed Solution

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# Dataset Manipulation

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- REDS (REalistic and Dynamic Scenes [1]) dataset (30K frames, 720x1280, 120FPS).

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# Gradual Learning

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- Jin et al. [2]: 7 separate FCNs (1 CNN per restored sharp frame).

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- Jin et al. [2]: 7 separate FCNs (1 CNN per restored sharp frame).
- - 1  $\hat{x}_4 = \phi_4(y)$
  - 2  $\hat{x}_3, \hat{x}_5 = \phi_3(\hat{x}_4, y), \phi_5(\hat{x}_3, \hat{x}_4, y)$
  - 3  $\hat{x}_i, \hat{x}_{8-i} = \phi_i(\hat{x}_{i+1}, \hat{x}_{i+2}, y), \phi_{8-i}(\hat{x}_{7-i}, \hat{x}_{6-i}, y), i \in 1, 2$

Video From Blurry Motion

└ Proposed Solution

  └ Unknown Blur kernel

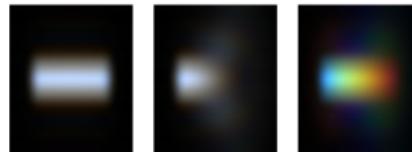
# Computational Imaging

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- Elmalem et al. [3]: Dynamically changing spatial phase-mask.

# Computational Imaging

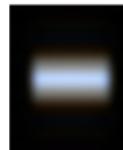
- Elmalem et al. [3]: Dynamically changing spatial phase-mask.
- Color coded PSF - direction and magnitude.



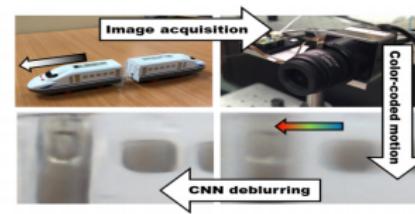
Blur PSF Simulation

# Computational Imaging

- Elmalem et al. [3]: Dynamically changing spatial phase-mask.
- Color coded PSF - direction and magnitude.
- FCN post-processing.



Blur PSF Simulation



Motion Deblurring Procedure

Video From Blurry Motion

└ Proposed Solution

└ My Innovation

# Methods Fusion

# Methods Fusion

- Goals:

- 1 Simulate phase-masked blur on REDS dataset.
- 2 Re-train Video-from-Image network with simulated data.

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- Goals:
  - 1 Simulate phase-masked blur on REDS dataset.
  - 2 Re-train Video-from-Image network with simulated data.
- Challenges:
  - 1 Generate blur simulations (standard and phase-masked).
  - 2 Implement training routine.
  - 3 Optimize hyper-parameters.
  - 4 Re-train network with standard and phase-masked blurred dataset.

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- **Re-trained (Masked):** After re-training with phase-masked simulated dataset.

# Image Quality Metrics

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- Diminished average accuracy in re-trained networks.

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Network	PSNR	SSIM
Pre-Trained	24.946	0.749
Re-trained (Standard)	24.602	0.72
Re-trained (Masked)	24.168	0.691

Video From Blurry Motion

└ Results

  └ Qualitative Comparison

## Qualitative Impression

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- Superior deblurring in re-trained networks (in most cases).

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- Superior deblurring in re-trained networks (in most cases).
- Masked re-training outperforms the standard (in some cases, ROIs).

# Middle-Frame Reconstruction



Full Image

# Middle-Frame Reconstruction



Zoomed In

# Middle-Frame Reconstruction



Full Image

# Middle-Frame Reconstruction



Zoomed In

# Video Reconstruction

- Temporally-consistent feet and faces
- Sharp tiger stripes

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**Questions?**

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