Analizador Léxico

Ariana Bermúdez, Ximena Bolaños, Dylan Rodríguez

Instituto Tecnológico de Costa Rica

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Análisis Sintáctico

Se hizo un analizador sintáctico con la ayuda de la herramienta de Bison, para el lenguaje C y que corre en C, este analizador trabaja en conjunto con Flex, para tomar los tokens que este le otorga y revisar con las gramáticas que les sean ingresadas.

Bison

jaajaj

```
2
3
4
5 static int Hres :
6 static int Vres :
7 static int maxAA :
8 static int maxReflection :
9 static int maxTransparency ;
10 static long double rays = 0;
11 static long double similar = 0;
12 static long double Xmax;
13 static long double Ymax;
14 static long double Xmin;
15 static
```

```
1 long double Ymin;
2 static long double Xdif ;
3 static long double Ydif;
4 static long double la ;
5 static long double e :
6 static int debug = 0;
7 \text{ static int rec} = 0:
8 struct Color {
9 long double r;
10 long double g;
11 long double b;
12 } ;
13 struct Point2D {
14 long
```

```
1 double u ;
2 long double v;
3 } ;
4 struct Point3D {
5 long double x;
6 long double y;
7 long double z ;
8 } ;
9 struct Vector {
10 long double x;
11 long double y;
12 long double z ;
13 } ;
14 struct
```

```
1 Light {
2 long double Xp;
3 long double Yp;
4 long double Zp;
5 long double c1;
6 long double c2;
7 long double c3;
8 long double lp ;
10 struct Object {
11 long double Xc;
12 long double Yc;
13 long double Zc;
14 long
```

```
double other ;
2 struct Vector directionVector :
3 long double extraD ;
4 long double Xother;
5 long double Yother;
6 long double Zother;
7 long double Kd;
8 long double Ka;
 long double Kn;
 long double Ks;
11 long double o1;
12 long double o2;
13 long double o3;
14 long
```

```
1 double A;
2 long double B;
3 long double C;
4 long double D;
5 long double E:
6 long double F;
7 long double G;
8 long double H;
 long double I;
 long double J;
int pointAmount ;
12 long double D1;
13 long double D2;
14 long
```

```
double K1 ;
2 long double K2;
3 long double height;
4 struct Color color :
5 struct Point2D * points2D ;
6 struct Point3D * points3D ;
7 struct Vector ( * normalVector ) ( );
8 struct Intersection ( * intersectionFuncion ) ( );
9 struct Color ( * retrieveTextureColor ) ( );
10 struct Vector x0y0z0 :
struct Vector x1y1z1 ;
12 struct Vector x2y2z2;
13 struct Vector x3y3z3;
14 int
```

```
numberPlaneCuts :
2 int numberTextures :
3 int numberDraftPlanes :
4 struct PlaneCut * planeCuts ;
5 struct Texture * textures ;
6 struct DraftPlane * draftPlanes :
7 } ;
8 struct PlaneCut {
9 struct Vector normal:
10 struct Vector point ;
11 long double d;
12 } ;
13 struct Texture {
14 char
```

```
1 * filename :
2 struct Color * * textureMap ;
3 int vRes:
4 int hRes;
5 struct Vector greenwich ;
6 struct Vector north:
7 } ;
8 struct DraftPlane {
9 char * filename ;
struct Color * * textureMap ;
11 int vRes:
12 int hRes ;
13 struct Vector greenwich ;
14 struct
```

```
1 Vector north ;
3 struct Intersection {
4 long double Xi;
5 long double Yi;
6 long double Zi;
7 long double distance ;
8 struct Object object ;
9 long double null;
10 } :
static struct Light * Lights ;
12 static struct Object * Objects;
13 static struct Vector eye;
14 static
```

```
struct Color * * Framebuffer ;
2 static struct Color background ;
static int numberObjects = 0 ;
4 static int numberLights = 0 ;
5 static int lightlndex = 0:
6 static int objectIndex = 0;
7 static char * escenaFile = "escena1.txt" ;
8 long double min (long double a , long double b) {
9 if ( a < b ) { return a ; }</pre>
10 else { return b ; }
11 }
12 long double max (long double a , long double b ) {
if (a > b) { return a; }
14 else
```

```
1 { return b ; }
3 int testPlaneCut ( struct PlaneCut plane , long double
      x , long double y , long double z ) {
4 \text{ int } \text{val} = ( \text{ plane } . \text{ normal } . \text{ } \text{x} * \text{x} ) + ( \text{ plane } . \text{ normal }
        y * y + (plane . normal . z * z) + plane . d
_{5} if ( val > 0 ) {
6 return 1 :
7 } else {
8 return 0 :
10 }
11 int testIntersection (long double x , long double y ,
      long double z , struct Object object ) {
12 int k , sign ;
int accept = 1;
14 int
```

```
1 amount = object . numberPlaneCuts ;
2 for (k = 0; k < amount; k ++)
sign = testPlaneCut ( object . planeCuts [ k ] , x , y
     , z ) ;
4 \text{ if } ( \text{ sign} = 1 ) 
5 \text{ accept} = 0:
6 }
8 return accept ;
9 }
10 long double pointProduct ( struct Vector a , struct
     Vector b ) {
11 long double pp = 0;
12 pp += (a . x * b . x);
pp += (a . y * b . y);
14 pp
```

```
1 += (a . z * b . z);
2 return pp ;
3 }
4 struct Vector crossProduct ( struct Vector a , struct
     Vector b ) {
5 struct Vector newVector :
6 newVector . x = (a . y * b . z) - (a . z * b . y);
7 \text{ newVector} \cdot y = (a \cdot z * b \cdot x) - (a \cdot x * b \cdot z);
8 newVector . z = (a . x * b . y) - (a . y * b . x)
9 return newVector :
11 long double getNorm ( struct Vector vector ) {
long double norm = sqrt ( pow ( vector x , 2 ) + pow
      (vector . y , 2) + pow (vector . z , 2));
13 return norm ;
14 }
```

```
2 struct Vector normalize ( struct Vector vector ) {
3 long double norm = getNorm ( vector );
4 struct Vector unitVector :
_{5} if ( norm != 0 ) {
6 unitVector x = vector x / norm ;
7 \text{ unitVector} . y = \text{vector} . y / \text{norm} ;
8 unitVector z = vector z / norm;
9 } else {
unit Vector x = vector x;
unit Vector y = vector y;
_{12} unitVector . z = vector . z :
13 }
14 return
```

```
unitVector :
3 void saveFile ( ) {
4 int i , j ;
5 FILE * file :
6 file = fopen ( "scene.ppm" , "w" ) ;
_{7} if ( file == NULL ) {
8 printf ( "Error creating/opening file!\n" );
9 exit (1);
11 fprintf ( file , "%s\n" , "P3" ) ;
12 fprintf (file, "%i %i\n", Hres, Vres);
13 fprintf (file, "%i \ n", 255);
14 for
```

```
1 ( i = Vres - 1 ; i >= 0 ; i -- ) 
_{2} for ( j = 0 ; j < Hres ; j ++ ) {
3 int R = (int) 255 * Framebuffer [i] [j] . r;
4 int G = (int) 255 * Framebuffer [i] [j] . g;
5 int B = (int) 255 * Framebuffer [i] [j] . b;
6 fprintf (file, "%i %i %i ", R, G, B);
8 fprintf ( file , "\n" ) ;
10 fclose (file);
11 }
12 long double getAttenuationFactor ( struct Light light ,
      long double distance ) {
13 long double value = 1 / ( light . c1 + ( light . c2 *
     distance ) + ( light . c3 * pow ( distance , 2 ) )
14 return
```

```
_1 min ( 1.0 , value );
struct Color difusseColor ( long double I , struct
      Color color ) {
4 struct Color newColor :
5 \text{ newColor} \cdot r = 1 * \text{color} \cdot r;
6 \text{ newColor} \cdot g = I * \text{color} \cdot g;
7 \text{ newColor} \cdot b = 1 * \text{color} \cdot b;
8 return newColor ;
9 }
10 struct Color specularHighlight (long double E, struct
        Color color ) {
11 struct Color newColor ;
newColor \cdot r = \text{color} \cdot r + (E * (1 - \text{color} \cdot r));
newColor . g = color . g + (E * (1 - color . g));
14 newColor
```

```
1. b = color . b + (E * (1 - color . b));
2 return newColor :
4 struct Intersection sphereIntersection ( struct Vector
     anchor, struct Vector direction, struct Object
     object ) {
5 long double t , t1 , t2 ;
6 long double Xdif = anchor . x - object . Xc ;
7 long double Ydif = anchor . y - object . Yc ;
8 long double Zdif = anchor . z - object . Zc ;
9 struct Intersection tempIntersect ;
10 tempIntersect . null = 0;
11 long double B = 2 * ( direction . x * Xdif ) + (
     direction . y * Ydif ) + ( direction . z * Zdif ) )
12 long double C = pow (Xdif, 2) + pow (Ydif, 2) +
     pow ( Zdif , 2 ) - pow ( object . other , 2 ) ;
long double discriminant = pow ( B , 2 ) - ( 4 * C );
14 if
```

```
1 ( discriminant >= 0 ) {
2 long double root = sqrt ( discriminant );
^{3} B *= -1 ;
4 t1 = (B + root) / 2;
5 t2 = (B - root) / 2;
6 if (t1 > e)
7 if (t2 > e)
8 t = min (t1, t2);
9 tempIntersect . distance = t ;
10 tempIntersect . object = object ;
11 tempIntersect . Xi = anchor . x + (t * direction . x)
12 tempIntersect . Yi = anchor . y + ( t * direction . y )
13 tempIntersect . Zi = anchor . z + ( t * direction . z )
14 int
```

```
1 accept = testIntersection ( tempIntersect . Xi ,
     tempIntersect . Yi , tempIntersect . Zi , object )
_2 if ( accept = 0 ) {
3 t = max (t1, t2);
4 tempIntersect . distance = t ;
5 tempIntersect . object = object ;
6 tempIntersect . Xi = anchor . x + (t * direction . x)
7 tempIntersect . Yi = anchor . y + (t * direction . y)
8 tempIntersect . Zi = anchor . z + (t * direction . z)
9 int accept = testIntersection ( tempIntersect . Xi ,
     tempIntersect . Yi , tempIntersect . Zi , object )
10 if ( accept = 0 ) {
11 tempIntersect . null = 1;
12 }
```

```
1 else {
2 t = t1 :
3 tempIntersect . distance = t ;
4 tempIntersect . object = object ;
5 tempIntersect . Xi = anchor . x + (t * direction . x)
6 tempIntersect . Yi = anchor . y + (t * direction . y)
7 tempIntersect . Zi = anchor . z + (t * direction . z)
8 int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
9 if (accept = 0) {
10 tempIntersect . null = 1;
11 }
12
13 } else {
14 if
```

```
1 ( t2 > e ) {
2 t = t2 :
3 tempIntersect . distance = t ;
4 tempIntersect . object = object ;
5 tempIntersect . Xi = anchor . x + (t * direction . x)
6 tempIntersect . Yi = anchor . y + (t * direction . y)
7 tempIntersect . Zi = anchor . z + (t * direction . z)
8 int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
9 if (accept = 0) {
10 tempIntersect . null = 1;
11 }
12 } else {
13 tempIntersect . null = 1;
14 }
```

```
1
3 return tempIntersect ;
4 } else {
5 \text{ tempIntersect} . null = 1 ;
6 return tempIntersect;
7
9 struct Vector sphereNormal ( struct Object object ,
      struct Vector vector ) {
10 struct Vector normal :
normal . x = vector . x - object . Xc ;
normal y = vector y - object Yc;
normal z = vector \cdot z - object \cdot Zc;
14 return
```

```
normal:
2 }
3 int getSign ( long double v ) {
4 if (v >= 0) \{ return 1; \}
5 else { return 0 ; }
7 struct Intersection polygonIntersection ( struct Vector
      anchor, struct Vector direction, struct Object
     object ) {
8 long double denominator = ( direction . x *  object . Xc
      ) + (direction . y * object . Yc) + (direction)
     z * object . Zc ) :
9 struct Intersection tempIntersect ;
10 tempIntersect . null = 0 ;
if ( denominator = 0 ) {
12 tempIntersect . null = 1;
13 return tempIntersect;
14 }
```

```
1 else {
_{2} long double numerator = - ( anchor . \times * object . \times \times *
      anchor . y * object . Yc + anchor . z * object . Zc
      + object . other ) ;
3 long double t = numerator / denominator ;
4 tempIntersect . distance = t ;
5 tempIntersect . object = object ;
6 tempIntersect . Xi = anchor . x + (t * direction . x)
7 tempIntersect . Yi = anchor . y + (t * direction . y)
8 tempIntersect . Zi = anchor . z + (t * direction . z)
9 \text{ long double } \max A_B = \max ( fabs ( object . Xc ) , fabs
     ( object . Yc ) );
10 long double maxA_B_C = max ( maxA_B , fabs ( object .
     Zc ) ) :
11 long double u , v ;
if (maxA_B_C = fabs (object . Xc))
```

```
1 = tempIntersect . Yi ;
_{2} } else if ( maxA_B_C = fabs ( object . Yc ) ) {
u = tempIntersect . Xi ;
4 v = tempIntersect . Zi ;
_{5} } else if ( maxA_B_C = fabs ( object . Zc ) ) {
6 u = tempIntersect . Xi :
7 v = tempIntersect . Yi ;
9 int NC = 0 :
int NV = object . pointAmount ;
struct Point2D * points2DArrayTemp = malloc ( sizeof (
     struct Point2D ) * NV );
12 for ( int i = 0 ; i < NV ; i ++ ) {
points2DArrayTemp [ i ] . u = object . points2D [ i ] .
      u - u:
14 points2DArrayTemp
```

```
[i] \cdot v = object \cdot points2D [i] \cdot v - v;
int SH = getSign ( points2DArrayTemp [ 0 ] . v );
4 int NSH;
5 int a = 0:
6 int b = (a + 1) \% NV;
7 for (a = 0; a < NV - 1;)
8 \text{ NSH} = \text{getSign} ( \text{points2DArrayTemp} [ b ] . v ) ;
9 if ( SH != NSH ) {
if ( points2DArrayTemp [ a ] . u > 0 \&\&
     points2DArrayTemp [b].u>0 ) {
11 NC ++ ;
| 12  else if ( points2DArrayTemp [ a ] . u > 0 ||
      points2DArrayTemp [b] . u > 0 ) {
long double N = (points2DArrayTemp [b] . u -
     points2DArrayTemp [ a ] . u ) ;
14 long
```

```
1 \text{ double } D = (points2DArrayTemp } [b] . v -
     points2DArrayTemp [ a ] . v );
_{2} if ( D != 0 ) {
3 if (points2DArrayTemp [a].u-((
     points2DArrayTemp [a].v*N)/D)>0
4 NC ++ :
9 SH = NSH;
10 a ++ :
11 b ++ ;
12 }
if (NC \% 2 == 0) { tempIntersect . null = 1; }
14 else
```

```
1 { tempIntersect . null = 0 ; }
int accept = testIntersection ( tempIntersect . Xi ,
     tempIntersect . Yi , tempIntersect . Zi , object )
_3 if ( accept = 0 ) {
4 tempIntersect . null = 1;
6 free ( points2DArrayTemp ) ;
7 return tempIntersect ;
8 }
10 struct Vector polygonNormal ( struct Object object ) {
struct Point3D point0 = object . points3D [ 0 ] ;
struct Point3D point1 = object . points3D [ 1 ] ;
struct Point3D point2 = object . points3D [ 2 ] ;
14 struct
```

```
1 \text{ Vector vector} 1 = \{ \text{ point} 1 . x - \text{ point} 0 . x , \text{ point} 1 . y \}
       - point0 . y , point1 . z - point0 . z \} ;
_2 struct Vector vector2 = { point2 . x - point1 . x ,
      point2 . y - point1 . y , point2 . z - point1 . z 
struct Vector normal = crossProduct ( vector1 , vector2
4 return normal;
6 struct Intersection cilinderIntersection ( struct
      Vector anchor, struct Vector direction, struct
      Object object ) {
7 struct Intersection tempIntersect ;
8 \text{ tempIntersect} \cdot \text{null} = 0;
9 long double xo = object . Xc;
long double yo = object . Yc ;
long double zo = object . Zc ;
long double xq = object . direction Vector . x;
long double yq = object . directionVector . y ;
```

```
double zg = object . directionVector . z ;
2 long double xd = direction . x ;
3 long double yd = direction . y ;
4 long double zd = direction . z ;
5 long double xe = anchor . x ;
6 long double ye = anchor . y ;
7 long double ze = anchor . z ;
8 long double radius = object . other ;
9 long double xdxq = xd * xq;
10 long double ydyq = yd * yq;
11 long double zdzq = zd * zq ;
12 long double xexq = xe * xq;
long double yeyq = ye * yq ;
14 long
```

```
1 double zezg = ze * zg ;
   2 long double xoxq = xo * xq ;
   3 long double yoyq = yo * yq ;
   4 long double zozq = zo * zq;
   solution 1 = solution 1 = solution 1 = solution 1 = solution 2 = sol
                                          xd:
   \log \text{long double coef2} = xdxq * yq + ydyq * yq + zdzq * yq - \log xdzq * yq + zdzq * yq + z
                                           vd :
   7 long double coef3 = xdxq * zq + ydyq * zq + zdzq * zq -
                                           zd:
   8 long double coef4 = xo + xexq * xq - xoxq * xq + yeyq *
                                          xq - yoyq * xq + zezq * xq - zozq * xq - xe;
   9 long double coef5 = yo + xexq * yq - xoxq * yq + yeyq *
                                           yq - yoyq * yq + zezq * yq - zozq * yq - ye ;
long double coef6 = zo + xexq * zq - xoxq * zq + yeyq *
                                           zq - yoyq * zq + zezq * zq - zozq * zq - ze;
11 long double A = pow (coef1, 2) + pow (coef2, 2) +
                                           pow ( coef3 , 2 ) ;
12 long double B = 2 * (coef1 * coef4 + coef2 * coef5 +
```

```
_{1} ( coef5 , 2 ) +
_2 pow ( coef6 , _2 ) _-
3 pow ( radius , 2 ) ;
4 long double discriminant = pow (B, 2) - (4 * A * C
5 long double t , t1 , t2 ;
_{6} if ( discriminant >= 0 ) {
7 long double root = sqrt ( discriminant );
8 B *= -1 :
9 t1 = (B - root) / (2 * A);
10 t2 = (B + root) / (2 * A):
11 long double Xi;
12 long double Yi;
13 long double Zi;
14 long
```

```
1 \text{ double } d1 = \text{ object } . D1 ;
2 long double d2 = object . D2 ;
3 \text{ if } (t1 > e) 
4 if (t2 > e)
5 t = min (t1, t2);
6 Xi = xe + (t * xd);
7 \text{ Yi} = ye + (t * yd);
8 Zi = ze + (t * zd);
9 if (d2 >= ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo) * zq) && ((Xi - xo) * xq + (Yi - yo)
     * yq + (Zi - zo) * zq) >= d1) {
10 tempIntersect . Xi = Xi;
11 tempIntersect . Yi = Yi;
12 tempIntersect . Zi = Zi;
13 tempIntersect . distance = t ;
14 tempIntersect
```

```
1 . object = object ;
int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
3 if ( accept = 0 ) {
t = \max(t1, t2);
5 Xi = xe + (t * xd);
6 \text{ Yi} = \text{ye} + (\text{t} * \text{yd});
7 \text{ Zi} = ze + (t * zd);
s \text{ if } (d2) = ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo ) *zq ) && ( (Xi - xo ) *xq + (Yi - yo )
      * yq + (Zi - zo) * zq) >= d1) {
9 tempIntersect . Xi = Xi ;
10 tempIntersect . Yi = Yi ;
11 tempIntersect . Zi = Zi;
tempIntersect . distance = t ;
13 tempIntersect . object = object ;
14 int
```

```
1 accept = testIntersection ( tempIntersect . Xi
      tempIntersect . Yi , tempIntersect . Zi , object )
_2 if ( accept = 0 ) {
3 tempIntersect . null = 1 ;
5 return tempIntersect ;
6 } else {
7 \text{ tempIntersect} . null = 1;
8 return tempIntersect ;
9
10
11 return tempIntersect;
12 } else {
t = \max(t1, t2);
14 Xi
```

```
1 = xe + (t * xd);
_{2} Yi = ye + (t * yd);
3 Zi = ze + (t * zd);
4 \text{ if } (d2) = ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo) * zq) & ((Xi - xo) * xq + (Yi - yo)
      * yq + (Zi - zo) * zq) >= d1) {
5 \text{ tempIntersect} . Xi = Xi;
6 tempIntersect . Yi = Yi ;
7 \text{ tempIntersect} . Zi = Zi;
8 tempIntersect . distance = t ;
9 tempIntersect . object = object ;
10 } else {
11 tempIntersect . null = 1;
12 }
int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
14 if
```

```
_1 ( accept = 0 ) {
_{2} tempIntersect . null = 1 ;
3 }
4 return tempIntersect;
6 } else {
7 t = t1 ;
8 Xi = xe + (t * xd);
9 Yi = ye + (t * yd);
Zi = ze + (t * zd);
if (d2 >= ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo) * zq) && ((Xi - xo) * xq + (Yi - yo)
     * yq + (Zi - zo) * zq) >= d1) {
12 tempIntersect . Xi = Xi;
13 tempIntersect . Yi = Yi ;
14 tempIntersect
```

```
_1 . Zi = Zi :
2 tempIntersect . distance = t ;
3 tempIntersect . object = object ;
4 int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
_{5} if ( accept = 0 ) {
6 \text{ tempIntersect} . null = 1;
7 }
8 return tempIntersect ;
9 } else {
10 tempIntersect . null = 1;
11 return tempIntersect;
12 }
13 }
14 }
```

```
1 else {
_{2} if ( t2 > e ) {
3 t = t2 :
4 Xi = xe + (t * xd);
5 \text{ Yi} = ye + (t * yd);
6 Zi = ze + (t * zd);
7 if (d2 >= ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo) * zq) && ((Xi - xo) * xq + (Yi - yo)
     * yq + (Zi - zo) * zq) >= d1) {
8 tempIntersect . Xi = Xi;
9 \text{ tempIntersect} . Yi = Yi;
10 tempIntersect . Zi = Zi ;
11 tempIntersect . distance = t ;
tempIntersect . object = object ;
int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
14 if
```

```
_1 ( accept = 0 ) {
_{2} tempIntersect . null = 1 ;
3 }
4 return tempIntersect ;
5 } else {
6 \text{ tempIntersect} . null = 1;
7 return tempIntersect ;
9 } else {
10 tempIntersect . null = 1;
11 return tempIntersect ;
12
13
14
```

```
1 else {
_{2} tempIntersect . null = 1 ;
3 return tempIntersect ;
4 }
6 struct Vector cilinderNormal ( struct Object object ,
      struct Vector intersectionPoint ) {
7 struct Vector normalCilinder ;
8 long double x = intersectionPoint . x ;
9 long double y = intersectionPoint . <math>y ;
long double z = intersection Point . z ;
long double xo = object . Xc ;
logo 12 long double yo = object . Yc ;
long double zo = object . Zc ;
14 long
```

```
1 \text{ double } xq = \text{ object } . \text{ directionVector } . x ;
2 long double yq = object . directionVector . y ;
3 long double zq = object . directionVector . z ;
4 long double xxoxq = (x - xo) * xq;
5 long double vyovq = (v - vo) * vq :
6 long double zzozq = (z - zo) * zq;
7 \text{ long double parenth} = (xxoxq + yyoyq + zzozq);
8 long double pxq = 2 * (xo + parenth * xq - x);
9 long double pyq = 2 * (yo + parenth * yq - y);
10 long double pzq = 2 * (zo + parenth * zq - z);
normalCilinder . x = pxq * (pow (xq , 2) - 1) +
12 pyq * (yq * xq) +
13 pzq * (zq * xq);
14 normalCilinder
```

```
1 . y = pxq * (xq * yq) +
_{2} pyq * ( pow ( yq , 2 ) - 1 ) +
3 pzq * (zq * yq);
4 normalCilinder . z = pxq * (xq * zq) +
_{5} pyq * ( yq * zq ) +
6 \text{ pzq} * (\text{pow} (\text{zq}, 2) - 1);
7 normalCilinder = normalize ( normalCilinder ) ;
8 return normalCilinder :
10 struct Intersection coneIntersection ( struct Vector
      anchor, struct Vector direction, struct Object
      object ) {
struct Intersection tempIntersect ;
12 tempIntersect . null = 0;
long double xo = object . Xc ;
14 long
```

```
double yo = object . Yc ;
2 long double zo = object . Zc ;
3 long double xq = object . directionVector . x ;
4 long double yq = object . directionVector . y ;
5 long double zq = object . directionVector . z ;
6 long double xd = direction . x ;
7 long double yd = direction . y ;
8 long double zd = direction . z ;
9 long double k1 = object . K1;
10 long double k2 = object . K2;
11 long double xe = anchor \cdot x;
12 long double ye = anchor . y ;
13 long double ze = anchor . z ;
14 long
```

```
1 double xdxq = xd * xq;
2 long double ydyq = yd * yq ;
3 long double zdzq = zd * zq ;
4 long double xexq = xe * xq ;
5 long double yeyq = ye * yq ;
6 long double zezq = ze * zq ;
7 long double xoxq = xo * xq ;
8 long double yoyq = yo * yq ;
9 long double zozq = zo * zq;
long double coef1 = xdxq * xq + ydyq * xq + zdzq * xq -
      xd:
11 long double coef2 = xdxq * yq + ydyq * yq + zdzq * yq -
       yd ;
12 long double coef3 = xdxq * zq + ydyq * zq + zdzq * zq -
       zd :
13 long double coef4 = xo + xexq * xq - xoxq * xq + yeyq *
      xq - yoyq * xq + zezq * xq - zozq * xq - xe;
14 long
```

```
1 double coef5 = yo + xexq * yq - xoxq * yq + yeyq * yq -
                        yoyq * yq + zezq * yq - zozq * yq - ye;
 2 \log double coef6 = zo + xexq * zq - xoxq * zq + yeyq *
                        zq - yoyq * zq + zezq * zq - zozq * zq - ze;
 long double coefk = pow (k2 / k1, 2);
 4 long double coef7 = xdxq + ydyq + zdzq;
 5 long double coef8 = xexq - xoxq + yeyq - yoyq + zezq -
                    zoza :
 6 long double A = pow (coef1, 2) + pow (coef2, 2) +
                        pow ( coef3 , 2 ) - ( coefk * pow ( coef7 , 2 ) )
 7 long double B = 2 * ( coef1 * coef4 + coef2 * coef5 + coef
                        coef3 * coef6 ) - ( coefk * coef7 * coef8 ) ) ;
 8 long double C = pow (coef4, 2) + pow (coef5, 2) +
                        pow ( coef6 , 2 ) - ( coefk * pow ( coef8 , 2 ) )
 9 long double discriminant = pow ( B , 2 ) - ( 4 * A * C
10 long double t , t1 , t2 ;
```

```
1 = (B + root) / (2 * A);
2 t2 = (B - root) / (2 * A);
3 long double Xi;
4 long double Yi;
5 long double Zi;
6 long double d1 = object . D1 ;
7 long double d2 = object . D2 ;
8 \text{ if } (t1 > e) 
9 if (t2 > e)
t = min(t1, t2);
11 Xi = xe + (t * xd);
Yi = ye + (t * yd);
Zi = ze + (t * zd);
14 if
```

```
1 (d2 >= ((Xi - xo) * xq + (Yi - yo) * yq + (Zi -
     zo ) * zq ) && ( (Xi - xo ) * xq + (Yi - yo ) *
     yq + (Zi - zo) * zq) >= d1) {
_2 tempIntersect . Xi = Xi ;
3 tempIntersect . Yi = Yi ;
_{4} tempIntersect . Zi = Zi ;
5 tempIntersect . distance = t ;
6 tempIntersect . object = object ;
7 int accept = testIntersection ( tempIntersect . Xi ,
     tempIntersect . Yi , tempIntersect . Zi , object )
8 \text{ if } (\text{accept} = 0) 
9 t = max (t1, t2);
10 Xi = xe + (t * xd);
11 Yi = ye + (t * yd);
Zi = ze + (t * zd);
13 if (d2 >= ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
     -zo) * zq) && ( (Xi - xo) * xq + (Yi - yo)
     * vq + (Zi - zo) * zq) >= d1) {
```

```
_1 . Xi = Xi :
_2 tempIntersect . Yi = Yi ;
3 tempIntersect . Zi = Zi ;
4 tempIntersect . distance = t ;
5 tempIntersect . object = object ;
6 int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
7 \text{ if } (\text{accept} = 0) 
8 \text{ tempIntersect} . null = 1;
10 return tempIntersect;
11 } else {
12 tempIntersect . null = 1;
13 return tempIntersect;
14 }
```

```
1
3 return tempIntersect ;
4 } else {
t = \max(t1, t2);
6 Xi = xe + (t * xd);
7 \text{ Yi} = ye + (t * yd);
8 Zi = ze + (t * zd);
9 if (d2 >= ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo) * zq) && ((Xi - xo) * xq + (Yi - yo)
     * yq + (Zi - zo) * zq) >= d1) {
10 tempIntersect . Xi = Xi;
11 tempIntersect . Yi = Yi ;
12 tempIntersect . Zi = Zi;
13 tempIntersect . distance = t ;
14 tempIntersect
```

```
1 . object = object ;
int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
_3 if ( accept = 0 ) {
4 tempIntersect . null = 1;
6 return tempIntersect;
7 } else {
8 \text{ tempIntersect} . null = 1 ;
9 return tempIntersect ;
10
12 } else {
13 t = t1;
14 Xi
```

```
1 = xe + (t * xd);
_{2} Yi = ye + (t * yd);
3 Zi = ze + (t * zd);
4 \text{ if } (d2) = ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo) * zq) & ((Xi - xo) * xq + (Yi - yo)
      * yq + (Zi - zo) * zq) >= d1) {
5 \text{ tempIntersect} . Xi = Xi;
6 tempIntersect . Yi = Yi ;
7 \text{ tempIntersect} . Zi = Zi;
8 tempIntersect . distance = t ;
9 tempIntersect . object = object ;
_{10} int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
if ( accept = 0 ) {
tempIntersect . null = 1;
13 }
14 return
```

```
1 tempIntersect ;
2 } else {
3 \text{ tempIntersect} . null = 1;
4 return tempIntersect;
5 }
7 } else {
8 \text{ if } (t2 > e) 
9 t = t2 :
10 Xi = xe + (t * xd);
11 Yi = ve + (t * vd);
Zi = ze + (t * zd);
if (d2 >= ((Xi - xo) * xq + (Yi - yo) * yq + (Zi)
      -zo) * zq) && ((Xi - xo) * xq + (Yi - yo)
     * yq + (Zi - zo) * zq) >= d1) {
14 tempIntersect
```

```
_1 . Xi = Xi :
_2 tempIntersect . Yi = Yi ;
3 tempIntersect . Zi = Zi ;
4 tempIntersect . distance = t ;
5 tempIntersect . object = object ;
6 int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
7 \text{ if } (\text{accept} = 0) 
8 \text{ tempIntersect} . null = 1;
10 return tempIntersect;
11 } else {
12 tempIntersect . null = 1;
13 return tempIntersect;
14 }
```

```
2 } else {
3 \text{ tempIntersect} . null = 1;
4 return tempIntersect ;
7 } else {
8 \text{ tempIntersect} . null = 1;
9 return tempIntersect ;
10
11
12 struct Vector coneNormal ( struct Object object ,
      struct Vector intersectionPoint ) {
13 struct Vector normalCone;
14 long
```

```
1 \text{ double } x = intersection Point . x :
2 long double y = intersectionPoint . y ;
3 long double z = intersectionPoint . z ;
4 long double xo = object . Xc ;
5 long double vo = object . Yc :
6 long double zo = object . Zc ;
7 long double xq = object . directionVector . x ;
8 long double yq = object . directionVector . y ;
9 long double zq = object . directionVector . z ;
10 long double k1 = object . K1;
long double k2 = object . K2 ;
long double xxoxq = (x - xo) * xq;
long double yyoyq = (y - yo) * yq;
14 long
```

```
1 double zzozq = (z - zo) * zq;
2 long double parenth = (xxoxq + yyoyq + zzozq);
3 long double pxq = 2 * (xo + parenth * xq - x);
4 long double pyq = 2 * (yo + parenth * yq - y);
5 long double pzq = 2 * (zo + parenth * zq - z);
6 long double k1sq = pow (k1, 2);
7 long double k2sq2 = 2 * pow (k2, 2);
8 long double lastFactorDerivedX = (k2sq2 * xq * parenth)
      ) / k1sg :
9 \text{ long double lastFactorDerivedY} = (k2sq2 * yq * parenth
      ) / k1sg :
long double lastFactorDerivedZ = (k2sq2 * zq * parenth)
      ) / k1sq ;
normalCone . x = pxq * (pow (xq , 2) - 1) +
12 \text{ pyq} * ( \text{ yq} * \text{xq} ) +
pzq * (zq * xq) - lastFactorDerivedX;
14 normalCone
```

```
1 . y = pxq * (xq * yq) +
_{2} pyq * ( pow ( yq , 2 ) - 1 ) +
3 pzq * (zq * yq) - lastFactorDerivedY;
4 normalCone . z = pxq * (xq * zq) +
_{5} pyq * ( yq * zq ) +
6 pzq * ( pow ( zq , 2 ) - 1 ) - lastFactorDerivedZ ;
7 normalCone = normalize ( normalCone ) ;
8 return normalCone :
10 long double whatsTheD ( struct Object object ) {
struct Point3D point = object . points3D [ 0 ] ;
12 long double the D = -((object . Xc * point . x) + (
     object . Yc * point . y ) + ( object . Zc * point .
      z ) ) :
13 return theD ;
14 }
```

```
2 long double whatsTheDGeneral ( struct Vector
     normalNotNormalized , struct Vector point ) {
3 long double theD = - ( ( normalNotNormalized . x *
      point .x) + ( normalNotNormalized .y * point .y
      ) + ( normalNotNormalized . z * point . z ) );
4 return theD :
6 struct Object getABCD ( struct Object object ) {
7 struct Vector normal = polygonNormal ( object ) ;
8 object Xc = normal \cdot x;
9 object . Yc = normal . y ;
10 object . Zc = normal . z ;
object . other = whatsTheD ( object ) ;
12 long double L = getNorm ( normal ) ;
object . Xc \neq L;
14 object
```

```
1 . Yc /= L :
2 object . Zc /= L ;
3 object . other /= L ;
4 return object;
6 struct Intersection discIntersection ( struct Vector
      anchor, struct Vector direction, struct Object
      object ) {
7 \text{ long double denominator} = ( \text{ direction } . \times * \text{ object } .
      directionVector . x ) + ( direction . y * object .
      directionVector . y ) + ( direction . z * object .
      direction Vector . z ) ;
8 struct Intersection tempIntersect ;
9 tempIntersect . null = 1;
if ( denominator = 0 ) {
11 tempIntersect . null = 1 ;
12 return tempIntersect;
13 } else {
14 long
```

```
1 double numerator = - ( anchor . x * object .
      directionVector . x ) + ( anchor . y * object .
      directionVector . y ) + ( anchor . z * object .
      directionVector . z ) + object . extraD ) ;
2 long double t = numerator / denominator ;
3 tempIntersect . distance = t ;
4 tempIntersect . object = object ;
5 tempIntersect . Xi = anchor . x + (t * direction . x)
6 tempIntersect . Yi = anchor . y + (t * direction . y)
7 \text{ tempIntersect} . Zi = anchor . z + (t * direction . z )
8 long double distanceToCenter = sqrt ( pow (
      tempIntersect . Xi - object . Xc , 2 ) +
9 pow ( tempIntersect . Yi - object . Yc , 2 ) +
10 pow ( tempIntersect . Zi - object . Zc , 2 ) );
if ( distanceToCenter < object . other ) {</pre>
12 \text{ tempIntersect} \cdot \text{null} = 0;
```

```
1 accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
_2 if ( accept = 0 ) {
3 tempIntersect . null = 1 ;
4 }
5 return tempIntersect ;
6 }
8 struct Vector discNormal ( struct Object object ) {
9 return object . directionVector ;
10 }
11 struct Intersection elipseIntersection ( struct Vector
      anchor, struct Vector direction, struct Object
      object ) {
logo 12 long double denominator = ( direction . x * object .
      directionVector . x ) + ( direction . y * object .
      directionVector . y ) + ( direction . z * object .
      direction Vector . z ) ;
```

```
_{1} . _{1} _{2} _{3} _{4} _{1} _{4} _{5} _{7}
_2 if ( denominator = 0 ) {
3 \text{ tempIntersect} . null = 1;
4 return tempIntersect ;
5 } else {
oldsymbol{1} long double numerator = - ( ( anchor . x * object .
      directionVector . x ) + ( anchor . y * object .
      directionVector . y ) + ( anchor . z * object .
      directionVector . z ) + object . extraD ) ;
7 long double t = numerator / denominator ;
8 tempIntersect . distance = t ;
9 tempIntersect . object = object ;
10 tempIntersect . Xi = anchor . x + (t * direction . x)
11 tempIntersect . Yi = anchor . y + (t * direction . y)
tempIntersect . Zi = anchor . z + (t * direction . z)
long double distance ToD1 = sqrt (pow (tempIntersect .
```

```
1 ( tempIntersect . Yi - object . Yc , 2 ) +
2 pow ( tempIntersect . Zi - object . Zc , 2 ) ) ;
3 long double distanceToD2 = sqrt ( pow ( tempIntersect .
       Xi - object . Xother , 2 ) +
4 pow ( tempIntersect . Yi - object . Yother , 2 ) +
5 pow ( tempIntersect . Zi - object . Zother , 2 ) );
_{6} if ( distanceToD1 + distanceToD2 ) < object . other )
7 \text{ tempIntersect} \cdot \text{null} = 0;
8 }
9 else {
10 tempIntersect . null = 1;
11 }
12 int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
if ( accept = 0 ) {
14 tempIntersect
```

```
_{1} . _{1} _{2} _{3} _{4} _{1} _{5} _{7} _{1} _{2} _{3} _{4} _{5} _{1} _{2} _{3} _{4} _{5} _{7} _{1} _{2} _{3} _{4} _{5} _{1} _{2} _{3} _{4} _{5} _{1} _{2} _{3} _{4} _{5} _{5} _{5} _{7} _{1} _{2} _{3} _{4} _{5} _{5} _{5} _{5} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7} _{7}
  3 return tempIntersect ;
  4 }
  6 struct Vector elipseNormal ( struct Object object ) {
  7 return object . directionVector ;
  9 struct Intersection quadraticIntersection ( struct
                       Vector anchor, struct Vector direction, struct
                       Object object ) {
10 long double t , t1 , t2 ;
11 struct Intersection tempIntersect;
12 \text{ tempIntersect} \cdot \text{null} = 0;
long double a = (object . A * pow (direction . x , 2)
                      ) ) + ( object . B * pow ( direction . y , 2 ) ) +
                      ( object . C * pow ( direction . z , 2 ) ) +
14 2
```

```
_{1} * ( ( object . D * direction . x * direction . y ) * (
     object . E * direction . y * direction . z ) * (
     object . F * direction . x * direction . z ) ) ;
2 long double b = 2 * ( object . A * anchor . x *
     direction .x + (object B * anchor y *
     direction . y ) + ( object . C * anchor . z *
     direction . z )
3 + (object . D * anchor . x * direction . y) + (
     object . D * anchor . y * direction . x )
4 + (object . E * anchor . y * direction . z) + (
     object . E * anchor . z * direction . y)
5 + (object . F * anchor . z * direction . x) + (
     object . F * anchor . x * direction . z )
_{6} + ( object . G * direction . x ) + ( object . H *
     direction . y ) + ( object . J * direction . z ) )
7 \text{ long double } c = (object . A * pow (anchor . x , 2))
      + ( object . B * pow ( anchor . y , 2 ) ) + (
     object . C * pow (anchor . z , 2)
```

```
1 = (b + root) / (2 * a);
2 t2 = (b - root) / (2 * a);
3 \text{ if } (t1 > e) 
4 if (t2 > e)
5 t = min (t1, t2);
6 tempIntersect . distance = t ;
7 tempIntersect . object = object ;
8 tempIntersect . Xi = anchor . x + (t * direction . x)
9 tempIntersect . Yi = anchor . y + ( t * direction . y )
10 tempIntersect . Zi = anchor . z + ( t * direction . z )
int accept = testIntersection ( tempIntersect . Xi ,
     tempIntersect . Yi , tempIntersect . Zi , object )
if ( accept = 0 ) {
t = \max(t1, t2);
14 tempIntersect
```

```
1 . distance = t ;
2 tempIntersect . object = object ;
3 tempIntersect . Xi = anchor . x + (t * direction . x)
4 tempIntersect . Yi = anchor . y + ( t * direction . y )
5 \text{ tempIntersect} . Zi = anchor . z + (t * direction . z )
6 int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
7 \text{ if } (\text{accept} = 0) 
8 \text{ tempIntersect} . null = 1;
9 }
10
11 } else {
12 t = t1 :
13 tempIntersect . distance = t ;
14 tempIntersect
```

```
1 . object = object ;
2 tempIntersect . Xi = anchor . x + (t * direction . x)
3 tempIntersect . Yi = anchor . y + ( t * direction . y )
4 tempIntersect . Zi = anchor . z + (t * direction . z)
int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
_{6} if ( accept = 0 ) {
7 \text{ tempIntersect} . null = 1;
8 }
10 } else {
11 if (t2 > e)
12 t = t2;
13 tempIntersect . distance = t ;
14 tempIntersect
```

```
1 . object = object ;
2 tempIntersect . Xi = anchor . x + (t * direction . x)
3 tempIntersect . Yi = anchor . y + ( t * direction . y )
4 tempIntersect . Zi = anchor . z + (t * direction . z)
int accept = testIntersection ( tempIntersect . Xi ,
      tempIntersect . Yi , tempIntersect . Zi , object )
_{6} if ( accept = 0 ) {
7 \text{ tempIntersect} . null = 1;
8 }
9 } else {
10 tempIntersect . null = 1;
11 }
12
13 return tempIntersect;
14
```

```
1 else {
_{2} tempIntersect . null = 1 ;
3 return tempIntersect ;
4 }
6 struct Vector quadraticNormal ( struct Object object ,
      struct Vector intersectionVector ) {
7 long double xElement = ( ( object . A *
      intersectionVector . x ) + (object . D *
      intersection Vector . y )
* + (object . F * intersectionVector . z) + (object .
     G));
9 long double yElement = ( ( object . D *
      intersectionVector . x ) + ( object . B *
      intersection Vector . y )
_{10} + ( object . E * intersectionVector . z ) + ( object .
     H ) ) ;
long double zElement = ( ( object . F *
      intersectionVector . x ) + (object . E *
```

```
normalNotNormalized :
2 }
3 long double uRectangle ( struct Vector x0y0z0 , struct
     Vector x1y1z1, struct Vector xiyizi) {
4 struct Vector U:
5 U . x = x1y1z1 . x - x0y0z0 . x ;
0 \ U \ . \ y = x1y1z1 \ . \ y - x0y0z0 \ . \ y ;
7 U . z = x1y1z1 . z - x0y0z0 . z ;
8 struct Vector i0 :
9 i0 . x = xiyizi . x - x0y0z0 . x;
10 i0 . y = xiyizi . y - x0y0z0 . y ;
11 i0 . z = xiyizi . z - x0y0z0 . z;
long double H = getNorm (U);
U = \text{normalize} (U);
14 return
```

```
pointProduct ( i0 , U ) / H ;
2 }
3 long double vRectangle ( struct Vector x0y0z0 , struct
      Vector x3y3z3 , struct Vector xiyizi ) {
4 struct Vector V:
5 \text{ V} \cdot x = x3y3z3 \cdot x - x0y0z0 \cdot x ;
6 \text{ V} . y = x3y3z3 . y - x0y0z0 . y ;
7 \text{ V} . z = x3y3z3 . z - x0y0z0 . z ;
8 struct Vector i0 :
9 i0 . x = xiyizi . x - x0y0z0 . x;
10 i0 . y = xiyizi . y - x0y0z0 . y ;
11 i0 . z = xiyizi . z - x0y0z0 . z;
long double L = getNorm (V);
V = \text{normalize} (V);
14 return
```

```
pointProduct ( i0 , V ) / L ;
2 }
struct Color planeTexture ( struct Intersection in ,
      struct Vector normal ) {
4 struct Object object = in . object ;
5 struct Vector ipoint ;
6 ipoint x = in Xi;
7 \text{ ipoint} . y = \text{in} . Yi ;
8 \text{ ipoint} \cdot z = \text{in} \cdot Zi;
9 long double u = uRectangle (object . x0y0z0 , object .
       \times 1y1z1 , ipoint ) ;
10 long double v = vRectangle (object . x0y0z0 , object .
       x3y3z3 , ipoint );
11 struct Color color;
for ( int i = 0 ; i < object . numberTextures ; i ++ )
int xs = object . textures [ i ] . hRes * u ;
14 int
```

```
vs = object . textures [ i ] . vRes * v ;
color = object . textures [ i ] . textureMap [ xs ] [
     vs 1 :
3 }
4 return color :
5 }
6 long double uCylinder ( struct Vector anchor , struct
     Vector Q , struct Vector normal , struct Vector
     greenwich , struct Vector xivizi ) {
7 long double tempu = acos ( pointProduct ( normal ,
     greenwich ) ) / ( 2 * 3.14159265 );
8 struct Vector darkSide = crossProduct ( Q , greenwich )
9 long double d = whatsTheDGeneral ( darkSide , anchor )
10 long double test = darkSide . x * xiyizi . x + darkSide
       y * xiyizi . y + darkSide . z * xiyizi . z + d ;
if (test < 0)
12 \text{ tempu} = 1 - \text{tempu};
```

```
1 tempu ;
2 }
3 long double vCylinder ( struct Vector anchor , struct
     Vector Q , struct Vector xiyizi , long double den )
4 struct Vector i0 ;
5 i0 . x = xiyizi . x - anchor . x ;
6 i0 . y = xiyizi . y - anchor . y ;
7 i0 . z = xiyizi . z - anchor . z ;
8 return pointProduct ( Q , i0 ) / den ;
9 }
10 struct Color cylinderTexture ( struct Intersection in ,
       struct Vector normal ) {
struct Object object = in . object ;
12 struct Vector gw = object . textures [ 0 ] . greenwich
13 struct Vector ipoint;
14 ipoint
```

```
1 . x = in . Xi ;
_2 ipoint . y = in . Yi;
3 ipoint . z = in . Zi;
4 struct Vector anchor:
5 anchor .x = object .Xc;
6 anchor . y = object . Yc ;
7 \text{ anchor} \cdot z = \text{object} \cdot Zc;
8 long double u = uCylinder ( anchor , object .
      direction Vector , normal , gw , ipoint ) ;
9 long double v = vCylinder ( anchor , object .
      direction Vector, ipoint, object. D2 - object.
      D1 ) :
10 struct Color color;
11 for ( int i = 0 ; i < object . numberTextures ; i ++ )
int xs = object \cdot textures [i] \cdot hRes * u;
int ys = object . textures [ i ] . vRes * v ;
14 color
```

```
1 = object . textures [ i ] . textureMap [ xs ] [ ys ] ;
2 }
3 return color ;
4 }
5 long double uSphere ( struct Vector center , struct
     Vector north, long double radius, struct Vector
      xiyizi , struct Vector greenwich ) {
6 struct Vector ic :
7 ic . x = xiyizi . x - center . x;
8 ic . y = xiyizi . y - center . y;
9 ic . z = xiyizi . z - center . z;
10 long double icnorth = pointProduct ( north , ic );
11 struct Vector inprime ;
in prime x = xiyizi \cdot x - north \cdot x * icnorth ;
in prime y = xiyizi \cdot y - north \cdot y * icnorth ;
14 inprime
```

```
1. z = xiyizi . z - north . z * icnorth;
2 struct Vector nprime ;
3 nprime x = inprime \cdot x - center \cdot x;
4 nprime y = inprime y - center y;
5 nprime . z = inprime . z - center . z ;
6 nprime = normalize ( nprime ) ;
7 long double tempu = acos ( pointProduct ( nprime ,
      greenwich ) ) / (2 * 3.14159265);
8 struct Vector darkSide = crossProduct ( north ,
      greenwich ) ;
9 long double d = whatsTheDGeneral ( darkSide , center )
long double test = darkSide . x * xiyizi . x + darkSide
       y * xiyizi . y + darkSide . z * xiyizi . z + d ;
if ( test < 0 ) {
12 \text{ tempu} = 1 - \text{tempu};
13 }
14 return
```

```
1 tempu ;
2 }
3 long double vSphere ( struct Vector center , struct
     Vector north, long double radius, struct Vector
      xivizi ) {
4 struct Vector south :
south x = center \cdot x - radius * north \cdot x;
6 south y = center y - radius * north y ;
7 south z = center \cdot z - radius * north \cdot z;
8 struct Vector i0 :
9 i0 . x = xiyizi . x - south . x;
10 i0 . y = xiyizi . y - south . y ;
11 i0 . z = xiyizi . z - south . z ;
return pointProduct ( north , i0 ) / ( 2 * radius ) ;
13 }
14 struct
```

```
1 Color sphereTexture ( struct Intersection in , struct
      Vector normal ) {
struct Object object = in . object ;
struct Vector gw = object . textures [ 0 ] . greenwich
4 struct Vector north = object . textures [ 0 ] . north ;
5 struct Vector ipoint ;
6 ipoint x = in Xi;
7 \text{ ipoint} \cdot y = \text{in} \cdot Yi ;
8 \text{ ipoint} \cdot z = \text{in} \cdot Zi;
9 struct Vector center :
10 center x = object Xc;
11 center y = object Yc;
12 center . z = object . Zc;
long double u = uSphere (center, north, object.
      other , ipoint , gw ) ;
14 long
```

```
1 \text{ double } v = vSphere (center, north, object. other,
                   ipoint ) ;
  2 struct Color color ;
  _3 for ( int i = 0 ; i < object . numberTextures ; i ++ )
 u int u int u int u int u in u 
  5 int ys = object . textures [ i ] . vRes * v ;
  6 color = object . textures [ i ] . textureMap [ xs ] [
                  vs ] :
  8 return color ;
10 long double uCone ( struct Vector anchor , struct
                  Vector Q , struct Vector normal , struct Vector
                  greenwich , struct Vector xiyizi ) {
struct Vector aux = crossProduct ( normal , Q ) ;
struct Vector nprime = crossProduct ( aux , Q ) ;
13 long double tempu = acos ( pointProduct ( nprime ,
                  greenwich ) ) / (2 * 3.14159265);
```

```
1 Vector darkSide = crossProduct ( Q , greenwich ) ;
2 long double d = whatsTheDGeneral ( darkSide , anchor )
3 long double test = darkSide . x * xiyizi . x + darkSide
       y * xiyizi . y + darkSide . z * xiyizi . z + d ;
_{4} if ( test < 0 ) {
5 \text{ tempu} = 1 - \text{tempu};
7 return tempu ;
9 struct Color coneTexture ( struct Intersection in ,
     struct Vector normal ) {
10 struct Object object = in . object ;
11 struct Vector gw = object . textures [ 0 ] . greenwich
12 struct Vector ipoint;
ipoint x = in Xi;
14 ipoint
```

```
1 \cdot y = in \cdot Yi;
_2 ipoint . z = in . Zi;
3 struct Vector anchor;
4 anchor . x = object . Xc :
5 anchor . y = object . Yc ;
6 \text{ anchor} \cdot z = \text{object} \cdot Zc;
7 \text{ long double } u = uCone \text{ (anchor, object.)}
      directionVector , normal , gw , ipoint ) ;
8 long double v = vCylinder ( anchor , object .
      direction Vector, ipoint, object. D2 - object.
      D1 ) :
9 struct Color color;
for ( int i = 0 ; i < object . numberTextures ; i ++ )
int xs = object \cdot textures [i] \cdot hRes * u;
int ys = object \cdot textures [i] \cdot vRes * v ;
13 color = object . textures [ i ] . textureMap [ xs ] [
     ys ] ;
14 }
```

```
2 return color ;
4 struct Intersection getFirstIntersection ( struct
      Vector anchor, struct Vector direction) {
5 \text{ rays} += 1;
6 int k :
7 int objectsAmount = numberObjects ;
8 long double tmin ;
9 struct Intersection intersection :
10 struct Intersection tempIntersection;
intersection . null = 1;
12 \text{ tmin} = 10000000;
13 tempIntersection . null = 1;
14 for
```

```
1 ( k = 0 ; k < objectsAmount ; k ++  ) {
_{2} tempIntersection = Objects [ k ] . intersectionFuncion
     (anchor, direction, Objects [k]);
_3 if ( tempIntersection . null != 1 && tempIntersection .
       distance > e && tempIntersection . distance < tmin
4 tmin = tempIntersection . distance ;
5 intersection = tempIntersection ;
6 }
7 \text{ tempIntersection} . null = 1;
9 return intersection ;
10 }
11 struct Color ponderColor ( struct Color baseColor ,
      struct Color reflectionColor, long double o1,
     long double o2 ) {
12 struct Color color:
13 color . r = baseColor . r * o1 + reflectionColor . r *
      02:
```

```
1 . g = baseColor . g * o1 + reflectionColor . g * o2 ;
_2 color . b = baseColor . b * o1 + reflectionColor . b *
    02 :
3 return color :
4 }
5 struct Color getColor ( struct Vector anchor , struct
     Vector direction, struct Vector V, int rLevel) {
6 struct Color color ;
7 struct Intersection intersection ;
8 struct Intersection * tempIntersection ;
9 intersection = getFirstIntersection ( anchor ,
      direction ) ;
if (intersection . null = 1) {
11 color = background ;
12 } else {
13 int k :
14 int
```

```
1 lightsAmount = numberLights ;
struct Object Q = intersection . object ;
3 struct Vector L:
4 struct Vector intersectVector = { intersection . Xi,
      intersection . Yi , intersection . Zi } ;
struct \ Vector \ N = normalize \ (Q . normalVector \ (Q ,
      intersectVector ) );
6 struct Vector R :
_{7} if ( pointProduct ( N , direction ) > 0 ) {
8 N . x *= -1 :
9 N . v *= -1 ;
10 N . z *=-1 :
12 long double Fatt;
13 long double I = 0.0;
14 long
```

```
_{1} double E = 0.0 ;
2 for (k = 0; k < numberLights; k ++)
3 struct Intersection obstacle ;
4 struct Vector light = { Lights [ k ] . Xp -
     intersection . Xi , Lights [ k ] . Yp -
     intersection . Yi , Lights [ k ] . Zp -
     intersection . Zi };
5 L = light;
6 L = normalize ( light ) ;
7 \text{ long double pp} = pointProduct (N, L);
8 obstacle = getFirstIntersection ( intersectVector , L )
9 long double distanceToLight = getNorm ( light ) ;
_{10} if ( obstacle . null =1 || ( obstacle . distance > e
     && obstacle . distance > distanceToLight ) ) {
11 Fatt = getAttenuationFactor ( Lights [ k ] ,
     distanceToLight ) :
12 if (pp > 0.0)
13 R . x = (2 * N . x * pp) - L . x ;
```

```
1. y = (2 * N . y * pp) - L . y ;
_{2} R . z = (2 * N . z * pp) - L . z ;
3 R = normalize (R);
4 \ I = I + (pp * Q . Kd * Fatt * Lights [k] . Ip);
5 }
6 long double pp2 = pointProduct (R, V);
7 if (pp2 > 0.0)
8 E = E + (pow (pp2, Q.Kn) * Q.Ks * Lights [k]
     . Ip * Fatt ) ;
9 }
10 }
if (Q \cdot numberTextures != 0) { color = Q .}
     retrieveTextureColor ( intersection , N ) ; }
13 else { color = Q . color ; }
14 if
```

```
1 \text{ (isnan (color.r.))} \{ \text{color} = Q. \text{color}; \}
_{2} I = I + Ia * Q . Ka ;
_{3} I = min (1.0 , I) ;
4 color = difusseColor ( I , color ) ;
5 E = min (1.0, E);
6 color = specularHighlight ( E , color ) ;
7 if (rLevel > 0) {
8 long double pNV = pointProduct (N, V);
9 R . x = (2 * N . x * pNV) - V . x ;
10 R . y = (2 * N . y * pNV) - V . y ;
11 R . z = (2 * N . z * pNV) - V . z;
12 R = normalize (R);
struct Vector other V = \{ -R \cdot x , -R \cdot y , -R \cdot z \}
14 struct
```

```
_{1} Color reflection Color = getColor ( intersectVector , R
      , other V , rLevel - 1 );
_{2} color = ponderColor ( color , reflectionColor , Q . o1
      , Q . o2 ) ;
4 struct Color transparencyColor = background ;
5 int levelsAllowed = maxTransparency ;
_{6} while ( levels Allowed > 0 && intersection . object . o3
      > 0 ) {
7 transparencyColor = getColor ( intersectVector ,
      direction , V , maxReflection ) ;
8 levelsAllowed -- ;
9 if (transparencyColor \cdot r == background \cdot r &&
      transparencyColor . g == background . g \&\&
      transparencyColor . b = background . b ) {
10 break :
11 }
12
color = ponderColor ( color , transparencyColor , 1 ,
```

```
2 return ( color ) ;
4 void printPlaneCuts ( struct Object objeto ) {
5 if ( objeto . planeCuts == NULL ) {
6 printf ( "\n Este objeto no tiene planos de corte
      asociados. \n" ) :
7 return :
8 } else {
9 int i = 0:
10 struct Vector normal:
11 struct Vector punto ;
12 for (i = 0; i < objeto . numberPlaneCuts; i ++ ) {
13 printf ( "Plano %i: \n" , i ) ;
14 normal
```

```
1 = objeto . planeCuts [ i ] . normal ;
punto = objeto . planeCuts [ i ] . point ;
g printf ( "\t Normal unitaria: %LF, %LF, %LF \n" ,
      normal . x , normal . y , normal . z ) ;
4 printf ( "\t Punto base: %LF, %LF, %LF \n\n", punto .
      x , punto . y , punto . z ) ;
8 void printTextures ( struct Object objeto , int
      currentTypeObjectReading ) {
9 if (objeto . textures = NULL ) {
10 printf ( "\n Este objeto no tiene texturas asociados. \
     n" ) ;
11 return :
12 } else {
13 int i = 0;
14 struct
```

```
1 Vector norte :
2 struct Vector greenwich ;
_3 for ( i = 0 ; i < objeto . numberTextures ; i +++ ) {
4 printf ("Textura %i: \n", i);
5 printf ("Resoluci n Textura: %ix%i \n", objeto.
     textures [ i ] . hRes , objeto . textures [ i ] .
     vRes ) ;
6 printf ("Primer texel de la textura: (%LF, %LF, %LF)"
     , objeto . textures [ i ] . textureMap [ 0 ] [ 0 ]
     . r * 255 , objeto . textures [ i ] . textureMap [
     0 ] [ 0 ] . g * 255 , objeto . textures [ i ] .
     textureMap [ 0 ] [ 0 ] . b * 255 );
7 int last X = objeto . textures [ i ] . hRes -1 ;
8 int lastY = objeto . textures [i] . vRes - 1;
9 printf ( " Itimo texel de la textura: (%LF, %LF, %LF)"
      , objeto . textures [ i ] . textureMap [ lastX ] [
      lastY ] . r * 255 , objeto . textures [ i ] .
     textureMap [ lastX ] [ lastY ] . g * 255 , objeto .
      textures [ i ] . textureMap [ lastX ] [ lastY ] .
```

```
2 if ( currentTypeObjectReading == 2 ||
     currentTypeObjectReading == 4
     currentTypeObjectReading == 5
     currentTypeObjectReading == 8 ) {
greenwich = objeto . textures [ i ] . greenwich ;
4 printf ( "\t Greenwich unitario: %LF, %LF, %LF \n",
     greenwich . x , greenwich . y , greenwich . z ) ;
5 if ( currentTypeObjectReading == 2 ||
     currentTypeObjectReading == 8) {
6 norte = objeto . textures [ i ] . north ;
7 printf ("\t Norte unitario: %LF, %LF, %LF \n", norte
     . x , norte . y , norte . z ) ;
8 }
10
12
13 void printDraftPlanes ( struct Object objeto , int
```

```
_{1} ( objeto . draftPlanes = NULL ) {
2 printf ("\n Este objeto no tiene planos de calado
     asociados. \n");
з return :
4 } else {
5 int i = 0;
6 struct Vector norte;
7 struct Vector greenwich;
8 for (i = 0; i < objeto . numberDraftPlanes; i ++) {
9 printf ("N mero de planos de calado: %i \n", objeto
     . numberDraftPlanes ) ;
printf ("plano de calado %i: \n", i);
printf ("Resoluci n plano de calado: %ix%i \n",
     objeto . draftPlanes [ i ] . hRes , objeto .
     draftPlanes [ i ] . vRes );
12 printf ("Primer texel del plano de calado: (%LF, %LF,
     %LF)", objeto . draftPlanes [ i ] . textureMap [ 0
      [ 0 ] . r , objeto . draftPlanes [ i ] .
     textureMap [ 0 ] [ 0 ] . g * 255 , objeto .
```

```
1 \text{ lastY} = \text{objeto} . \text{draftPlanes} [ i ] . \text{vRes} - 1 ;
2 printf ( " Itimo texel del plano de calado: (%LF, %LF,
      %LF)", objeto . draftPlanes [ i ] . textureMap [
     lastX \mid [lastY] \cdot r * 255, objeto . draftPlanes
     [ i ] . textureMap [ lastX ] [ lastY ] . g * 255 ,
     objeto . draftPlanes [ i ] . textureMap [ lastX ] [
      lastY ] . b * 255 ) ;
3 }
4 if ( currentTypeObjectReading = 2 \mid \mid
     currentTypeObjectReading = 4 \mid \mid
     currentTypeObjectReading = 5 \mid \mid
     currentTypeObjectReading == 8) {
5 greenwich = objeto . draftPlanes [ i ] . greenwich ;
6 printf ("\t Greenwich unitario: %LF, %LF, %LF\n",
     greenwich . x , greenwich . y , greenwich . z ) ;
7 if ( currentTypeObjectReading = 2 \mid \mid
     currentTypeObjectReading == 8) {
8 norte = objeto . draftPlanes [ i ] . north ;
9 printf ( "\t Norte unitario: %LF, %LF, %LF \n" , norte
```

```
1 createObjectFromData ( long double * data , int
     whichObjectCreate, int quantityData, struct
     PlaneCut * planeCutsFound , struct Texture *
     texturesFound , struct DraftPlane *
     draftPlanesFound, int numberPlaneCuts, int
     numberTextures , int numberDraftPlanes ) {
2 switch ( whichObjectCreate ) {
3 case 0 : {
_4 if ( debug == 1 ) {
5 printf ( "Insertando datos de escena \n" );
6 printf ("Reflexiones: %LF, Transparencia: %LF, Anti-
     aliasing: %LF \ n", data [0], data [1], data
     [2]);
7 printf ("Iluminaci n ambiente: %LF \n", data [3])
8 printf ( "Plano de proyecci n (Xmin, Ymin) (Xmax, Ymax
     ) : (%LF, %LF) (%LF, %LF) \n" , data [ 4 ] , data [
      5 ] , data [ 6 ] , data [ 7 ] ) ;
9 printf ("Resolucin: %LFx%LF\n", data [8], data
```

```
1 = data [0];
maxReflection = data [ 1 ] ;
3 maxTransparency = data [ 2 ];
4 la = data [ 3 ] ;
5 \text{ Xmin} = \text{data} [4];
6 \text{ Ymin} = \text{data} \begin{bmatrix} 5 \end{bmatrix};
7 \text{ Xmax} = \text{data} \begin{bmatrix} 6 \end{bmatrix};
8 \text{ Ymax} = \text{data} [7];
9 Hres = data [ 8 ] ;
10 Vres = data [9];
11 e = data [10];
12 eye . x = data [11];
13 eye . y = data [12];
14 eye
```

```
1 . z = data [13];
2 background . r = data [14];
3 \text{ background} . g = data [ 15 ] ;
4 background . b = data [16];
5 Framebuffer [ Hres ] [ Vres ] ;
_{6} Framebuffer = ( struct Color * * ) malloc ( Vres *
      sizeof ( struct Color * ) );
7 for ( int i = 0 ; i < Vres ; i ++ ) {
8 Framebuffer [i] = (struct Color *) malloc (Hres *)
      sizeof ( struct Color ) );
10 return :
12 case 1 : {
if ( debug == 1 ) {
14 printf
```

```
1 ( "Insertando Luz...\n" );
2 printf ("Pos luz (%LF, %LF, %LF) \n", data [0],
     data [1], data [2]);
g printf ( "c1: %LF, c2: %LF, c3 %LF \n" , data [ 3 ] ,
     data [4], data [5]);
4 printf ("Ip luz: %LF \n", data [6]);
6 struct Object polygon;
7 struct Color colorPolygon ;
8 struct Light luz ;
9 luz . Xp = data [0];
10 luz . Yp = data [1];
luz . Zp = data [2];
12 |uz . c1 = data [3];
13 |uz . c2 = data [4];
14 Luz
```

```
1 . c3 = data [5];
_{2} luz . lp = data [ 6 ] ;
3 Lights [ lightIndex ] = luz ;
4 lightIndex ++;
5 return :
7 case 2 : {
8 if (debug = 1) {
9 printf ("Insertando Esfera...");
10 printf ("Pos esfera (%LF, %LF, %LF) \n", data [0],
      data [1], data [2]);
printf ( "o1: %LF, o2: %LF, o3: %LF \n" , data [ 3 ] ,
      data [4], data [5]);
12 printf ("Radio esfera: %LF \n", data [ 6 ] );
13 printf ( "Esfera Kd: %LF \n" , data [ 6 ] ) ;
14 printf
```

```
1 ( "Esfera Ka: %LF \n" , data [ 8 ] ) ;
2 printf ("Esfera Kn: %LF \n", data [ 9 ] );
3 printf ("Esfera Ks: %LF \n", data [ 10 ] );
4 printf ("Color esfera (%LF, %LF, %LF) \n", data [ 11
     ] , data [ 12 ] , data [ 13 ] ) ;
6 struct Object polygon;
7 struct Color colorPolygon;
8 struct Object esfera ;
9 esfera . Xc = data [ 0 ] ;
10 esfera . Yc = data [1];
11 esfera . Zc = data [2];
12 esfera . o1 = data [3];
13 esfera . o2 = data [ 4 ] ;
14 esfera
```

```
1 . o3 = data [5];
_2 esfera . other = data [6];
3 \text{ esfera} . Kd = data \begin{bmatrix} 7 \end{bmatrix};
4 \text{ esfera} . Ka = data [8];
5 \text{ esfera} . Kn = data [9];
6 \text{ esfera} . Ks = data [10];
7 esfera . normalVector = sphereNormal ;
8 esfera . intersectionFuncion = sphereIntersection ;
9 esfera . retrieveTextureColor = sphereTexture ;
10 struct Color colorSphere;
11 colorSphere \cdot r = data [11];
12 colorSphere . g = data [12];
colorSphere . b = data [13];
14 esfera
```

```
1 . color = colorSphere ;
2 esfera . planeCuts = planeCutsFound ;
3 esfera . numberPlaneCuts = numberPlaneCuts :
4 esfera . textures = texturesFound ;
5 esfera . numberTextures = numberTextures ;
6 Objects [ objectIndex ] = esfera ;
_{7} if ( debug == 1 ) {
8 printPlaneCuts ( Objects [ objectIndex ] );
printTextures ( Objects [ objectIndex ] ,
      whichObjectCreate ) :
10 }
11 objectIndex ++;
12 return :
13 }
14 case
```

```
1 3 : {
int vertexPolygonIndex = 0 ;
\frac{1}{2} int numVertexesPolygon = ( quantityData - 10 - 12 ) / 3
      + 1 :
_{4} int inicioPlano = 10 + (numVertexesPolygon - 1) * 3;
_{5} if ( debug = 1 ) {
6 printf ( "quantityData: %i \n" , quantityData ) ;
7 printf ( "numVertexesPolygon: %i \n" ,
      numVertexesPolygon ) ;
8 printf ( "%i inicioPlano \n" , inicioPlano );
printf ( "Insertando pol gono ... " );
10 printf ("Color pol gono (%LF, %LF, %LF) \n", data [
      0 ] , data [ 1 ] , data [ 2 ] ) ;
11 printf ( "o1: %LF, o2: %LF, o3: %LF \n", data [ 3 ],
       data [ 4 ] , data [ 5 ] ) ;
printf ( "Poligono Kd: %LF \n" , data [ 6 ] ) ; printf ( "Poligono Ka: %LF \n" , data [ 7 ] ) ;
14 printf
```

```
1 ( "Poligono Kn: %LF \n" , data [ 8 ] ) ;
2 printf ( "Poligono Ks: %LF \n" , data [ 9 ] );
3 printf ("Esquina inferior izquierda (%LF, %LF, %LF) \n
     ", data [inicio\mathsf{Plano}], data [inicio\mathsf{Plano}+1]
       , data [ inicioPlano + 2 ] ) ;
4 printf ("Esquina inferior derecha (%LF, %LF, %LF) \n"
      , data [ inicioPlano + 3  ] , data [ inicioPlano + 4 
      ], data [ inicioPlano + 5 ] );
5 printf ("Esquina superior derecha (%LF, %LF, %LF) \n"
      , data [ inicioPlano + 6 ] , data [ inicioPlano + 7
      ], data [ inicioPlano + 8 ]);
6 printf ("Esquina superior izquierda (%LF, %LF, %LF) \n
     ", data [inicioPlano + 9], data [inicioPlano +
      10 , data [ inicioPlano + 11 ] );
8 struct Point3D vertex ;
9 struct Point2D squashedVertex ;
10 struct Object temp;
11 struct Vector x0y0z0 ;
```

```
1. z = data [inicioPlano + 2];
2 struct Vector x1y1z1 ;
x1y1z1 . x = data [inicioPlano + 3];
5 \times 1 \times 1 \times 1 = data [inicio Plano + 5];
6 struct Vector x2y2z2;
7 \times 2y2z2 . x = data [inicioPlano + 6];
8 \times 2y2z2 . y = data [inicioPlano + 7];
9 \times 2y2z2 . z = data [inicioPlano + 8];
10 struct Vector x3y3z3 :
11 \times 3y3z3 . x = data [inicioPlano + 9];
x3y3z3 . y = data [inicioPlano + 10];
x3y3z3 . z = data [inicioPlano + 11];
14 temp
```

```
1. points3D = malloc ( size of ( struct Point3D ) * 3 );
2 for ( int i = 0 ; i + 10 < quantityData - 12 ; ) {
_3 if (vertexPolygonIndex = 3) {
4 break:
5 }
6 vertex . x = data [10 + i]:
7 i ++ :
8 vertex . y = data [10 + i];
9 i ++ :
vertex z = data [10 + i];
11 i ++ ;
temp . points3D [ vertexPolygonIndex ] = vertex ;
vertexPolygonIndex ++ ;
14 }
```

```
1
2 struct Object polygon ;
3 \text{ vertexPolygonIndex} = 0;
4 polygon = getABCD ( temp ) ;
_{5} if ( debug == 1 ) {
6 printf ( "A del poligono %LF\n" , polygon . Xc ) ;
7 printf ( "B del poligono %LF\n" , polygon . Yc ) ;
8 printf ( "C del poligono %LF\n" , polygon . Zc ) ;
9 printf ( "D del poligono %LF\n" , polygon . other ) ;
10 }
_{11} polygon . points 3D = malloc ( size of ( struct Point <math>3D )
       * numVertexesPolygon ) ;
polygon . points2D = malloc ( size of ( struct Point2D )
       * numVertexesPolygon ) ;
13 struct Color colorPolygon;
14 colorPolygon
```

```
1 \cdot r = data [0];
_2 colorPolygon . g = data [1];
3 \text{ colorPolygon} . b = data [2];
  polygon . color = colorPolygon ;
_{5} polygon . o1 = data [ 3 ]
6 \text{ polygon} . o2 = data [ 4 ]
7 \text{ polygon} . o3 = data [ 5 ] ;
8 polygon . Kd = data [ 6 ]
polygon . Ka = data [ 7 ]
10 polygon . Kn = data [8];
polygon . Ks = data [9]
polygon . pointAmount = numVertexesPolygon ;
13 polygon . normalVector = polygonNormal ;
14 polygon
```

```
intersectionFuncion = polygonIntersection ;
   polygon . retrieveTextureColor = planeTexture ;
   3 long double u :
   4 long double v :
   5 \text{ long double maxA}_B = \text{max (fabs (polygon . Xc)}, fabs
                                     (polygon . Yc));
   formula = 100 \text{ long double maxA} = 100 \text{ maxA}
                               Zc ) ) :
   7 int choice = 0:
   8 if ( maxA_B_C = fabs ( polygon . Xc ) ) { choice = 0 ;}
   9 else if (\max A_B_C = \text{fabs } (\text{polygon } . \text{Yc })) { choice
                              = 1 ; }
10 else if (maxA_B_C = fabs (polygon . Zc)) { choice
                              = 2 :  }
for ( int i = 0 ; i + 10 < quantityData - 12 ; ) {
vertex x = data [10 + i];
13 i ++ ;
14 vertex
```

```
1. y = data [10 + i];
2 i ++ :
y vertex z = data [10 + i];
4 i ++ ;
_{5} if ( debug == 1 ) {
6 printf ("Vertice: (%LF,%LF,%LF) \n", vertex . x ,
     vertex . y , vertex . z ) ;
8 if (choice = 0) { u = vertex . z ; v = vertex . y ;
9 else if (choice == 1) { u = vertex . x ; v = vertex .
      z ; }
10 else if (choice == 2) { u = vertex . x ; v = vertex .
11 squashed Vertex . u = u ;
12 squashed Vertex . v = v ;
polygon . points3D [ vertexPolygonIndex ] = vertex ;
14 polygon
```

```
1 . points2D [ vertexPolygonIndex ] = squashedVertex ;
vertexPolygonIndex ++ ;
4 vertex x = data [10];
5 \text{ vertex} . y = data [ 11 ] ;
6 vertex z = data [12];
7 \text{ if } ( \text{ choice } == 0 ) \{ u = \text{ vertex } . z ; v = \text{ vertex } . y ; \}
8 else if (choice == 1) { u = vertex . x ; v = vertex .
       z : }
gelse if (choice = 2) { u = vertex . x ; v = vertex .
       v : }
10 squashed Vertex . u = u ;
_{11} squashed Vertex . v = v ;
polygon . points3D [ vertexPolygonIndex ] = vertex ;
polygon . points2D [ vertexPolygonIndex ] =
      squashedVertex :
14 polygon
```

```
1 . planeCuts = planeCutsFound ;
polygon . numberPlaneCuts = numberPlaneCuts ;
3 polygon . textures = texturesFound ;
polygon . numberTextures = numberTextures ;
5 polygon . x0y0z0 = x0y0z0;
6 polygon . x1y1z1 = x1y1z1 ;
7 polygon x2y2z2 = x2y2z2;
8 polygon . x3y3z3 = x3y3z3;
9 Objects [ objectIndex ] = polygon ;
if ( debug == 1 ) {
printPlaneCuts ( Objects [ objectIndex ] );
12 printTextures (Objects [objectIndex],
     whichObjectCreate );
13 }
14 objectIndex
```

```
1 ++ ;
2 return :
3 }
4 case 4 : {
_{5} if ( debug == 1 ) {
6 printf ("Insertando cilindro...");
7 printf ( "Ancla: (%LF, %LF, %LF) \n", data [ 0 ],
     data [1], data [2]);
8 printf ( "Vector: (%LF, %LF, %LF) \n" , data [ 3 ] ,
     data [ 4 ] , data [ 5 ] ) ;
9 printf ( "o1: %LF, o2: %LF, o3: %LF \n" , data [ 6 ] ,
      data [7], data [8]);
printf ("Cilindro Radio: %LF \n", data [9]);
11 printf ("Cilindro d1: %LF Cilindro d2: %LF \n", data
     [ 10 ] , data [ 11 ] ) ;
printf ("Cilindro Kd: \%LF \n", data [ 12 ] );
13 printf ("Cilindro Ka: %LF \n", data [ 13 ] );
14 printf
```

```
1 ( "Cilindro Kn: \%LF \n" , data [ 14 ] ) ;
2 printf ( "Cilindro Ks: %LF \n" , data [ 15 ] );
3 printf ("RGB Cilindro: (%LF, %LF, %LF) \n", data [ 16
      ] , data [ 17 ] , data [ 18 ] ) ;
5 struct Object cilinder ;
6 cilinder . Xc = data [0];
7 \text{ cilinder} . Yc = data [1] :
8 cilinder . Zc = data [2];
9 struct Vector cilinderVector :
10 cilinder Vector x = data [3];
cilinderVector . y = data [4];
12 cilinder Vector . z = data [5];
13 cilinderVector = normalize ( cilinderVector ) ;
14 cilinder
```

```
. directionVector = cilinderVector :
_2 cilinder . o1 = data [ 6 ] ;
3 cilinder . o2 = data [ 7 ]
4 cilinder . o3 = data [8];
5 cilinder . other = data [ 9 ] ;
6 cilinder . D1 = data [10];
7 \text{ cilinder} . D2 = data [ 11 ] :
8 cilinder . Kd = data [ 12 ] ;
g cilinder . Ka = data [ 13 ]
10 cilinder . Kn = data [ 14 ] ;
11 cilinder . Ks = data [ 15 ] ;
cilinder . height = cilinder . D2 - cilinder . D1 ;
13 cilinder . normalVector = cilinderNormal ;
14 cilinder
```

```
intersectionFuncion = cilinderIntersection :
cilinder . retrieveTextureColor = cylinderTexture ;
3 struct Color cilinderColor :
4 cilinderColor . r = data [ 16 ] ;
5 cilinderColor . g = data [ 17 ] ;
6 cilinderColor . b = data [ 18 ] ;
7 cilinder . color = cilinderColor ;
8 cilinder . planeCuts = planeCutsFound ;
g cilinder . numberPlaneCuts = numberPlaneCuts :
10 cilinder . textures = texturesFound ;
cilinder . numberTextures = numberTextures :
Objects [ objectIndex ] = cilinder ;
if ( debug == 1 ) {
14 printPlaneCuts
```

```
1 ( Objects [ objectIndex ] );
printTextures ( Objects [ objectIndex ] ,
     whichObjectCreate );
3 }
4 objectIndex ++ ;
5 return :
7 case 5 : {
8 if (debug == 1) {
9 printf ("Insertando cono...");
10 printf ( "Ancla: (%LF, %LF, %LF) \n", data [ 0 ],
     data [1], data [2]);
11 printf ( "Vector: (%LF, %LF, %LF) \n" , data [ 3 ] ,
     data [4], data [5]);
12 printf ( "o1: %LF, o2: %LF, o3: %LF \n", data [ 6 ]
      data [7], data [8]);
13 printf ( "Cono k1: %LF COno k2: %LF \n" , data [ 9 ] ,
     data [ 10 ] );
14 printf
```

```
1 ( "Cono d1: %LF COno d2: %LF \n" , data [ 11 ] , data [
      12 ] ) ;
printf ( "Cono Kd: %LF \n" , data [ 13 ] )
g printf ( "Cono Ka: %LF \n" , data [ 14 ] );
4 printf ( "Cono Kn: %LF \n" , data [ 15 ] ) ;
5 printf ( "Cono Ks: %LF \n" , data [ 16 ] ) ;
6 printf ("RGB Cono: (%LF, %LF, %LF) \n", data [ 17 ],
      data [ 18 ] , data [ 19 ] ) ;
7 }
8 struct Object cone ;
9 \text{ cone} . Xc = data [0];
10 cone . Yc = data [1];
11 cone . Zc = data [2]:
12 struct Vector coneVector :
13 coneVector . x = data [3];
14 coneVector
```

```
1. y = data [4];
z = data [5];
3 coneVector = normalize ( coneVector ) ;
4 \text{ cone} . direction Vector = coneVector :
5 \text{ cone} \cdot \text{ol} = \text{data} \left[ 6 \right] ;
6 cone . o2 = data [7];
7 cone . o3 = data \begin{bmatrix} 8 \end{bmatrix} ;
8 cone . K1 = data [9];
9 cone . K2 = data [10];
10 cone . D1 = data [11];
11 cone . D2 = data [12];
cone . height = cone . D2 - cone . D1 ;
cone . Kd = data [13];
14 cone
```

```
1 . Ka = data [14];
_2 cone . Kn = data [ 15 ] ;
3 cone . Ks = data [ 16 ] ;
4 cone . intersectionFuncion = coneIntersection :
5 cone . retrieveTextureColor = coneTexture :
6 cone . normalVector = coneNormal :
7 struct Color coneColor :
8 \text{ coneColor} . r = \text{data} [17];
g = coneColor \cdot g = data [18];
10 coneColor . b = data [19];
11 cone . color = coneColor ;
12 cone . planeCuts = planeCutsFound ;
cone . numberPlaneCuts = numberPlaneCuts :
14 cone
```

```
1 . textures = texturesFound :
cone . numberTextures = numberTextures ;
3 Objects [ objectIndex ] = cone ;
_4 if ( debug == 1 ) {
5 printPlaneCuts ( Objects [ objectIndex ] );
6 printTextures (Objects [objectIndex],
     whichObjectCreate );
8 objectIndex ++ ;
9 return :
10 }
11 case 6 : {
if ( debug == 1 ) {
printf ("Insertando disco...");
14 printf
```

```
1 ( "Punto Central: (%LF, %LF, %LF) \n" , data [ 0 ] ,
     data [1], data [2]);
2 printf ("Normal: (%LF, %LF, %LF) \n", data [3],
     data [4], data [5]);
g printf ( "Color: (%LF, %LF, %LF) \n" , data [ 6 ] ,
     data [7], data [8]);
4 printf ("Disco Radio: %LF \n", data [9]);
5 printf ( "o1: %LF, o2: %LF, o3: %LF \n" , data [ 10 ]
      , data [ 11 ] , data [ 12 ] ) ;
6 printf ("Dlsco Kd: %LF \n", data [ 13 ] );
7 printf ("DIsco Ka: %LF \n", data [ 14 ] );
8 printf ("DIsco Kn: %LF \n", data [ 15 ] );
9 printf ( "Disco Ks: %LF \n" , data [ 16 ] );
10 printf ("Esquina inferior izquierda (%LF, %LF, %LF) \n
    ", data [ 17 ], data [ 18 ], data [ 19 ]);
11 printf ("Esquina inferior derecha (%LF, %LF, %LF) \n"
      , data [ 20 ] , data [ 21 ] , data [ 22 ] ) ;
12 printf ("Esquina superior derecha (%LF, %LF, %LF) \n"
     , data [ 23 ] , data [ 24 ] , data [ 25 ] ) ;
```

```
1
2 struct Object disco ;
struct Vector x0y0z0 ;
4 \times 0 \times 0 \times 20 = 0 . \times = data [ 17 ] ;
5 \times 0 \times 0 \times 0 \times 0 = 0 data [ 18 ];
6 \times 0 \times 0 \times 0 = 0 . z = data [ 19 ] ;
7 struct Vector x1y1z1 ;
8 \times 1 \times 1 \times 1 = data [20];
10 x1y1z1 . z = data [ 22 ] ;
11 struct Vector x2y2z2;
12 \times 2y2z2 . x = data [ 23 ] ;
x^2y^2z^2 . y = data [24];
14 x2y2z2
```

```
1 . z = data [25];
2 struct Vector x3y3z3 ;
x3y3z3 . x = data [ 26 ] ;
4 \times 3y3z3 . y = data [ 27 ] ;
5 \times 3y3z3 . z = data [ 28 ] ;
6 disco . x0y0z0 = x0y0z0 ;
7 disco x1y1z1 = x1y1z1;
8 disco . x2y2z2 = x2y2z2 ;
9 disco . x3y3z3 = x3y3z3;
10 disco . Xc = data [0] :
11 disco . Yc = data \begin{bmatrix} 1 \end{bmatrix};
12 \text{ disco} . Zc = data [ 2 ] ;
disco : intersectionFuncion = discIntersection :
14 disco
```

```
1 . normalVector = discNormal :
2 disco . retrieveTextureColor = planeTexture ;
struct Vector puntoCentral ;
4 punto Central . x = data [0];
5 punto Central . y = data [1];
6 punto Central . z = data [2];
7 struct Vector normalNotNormalized :
8 normalNotNormalized x = data [3];
9 normalNotNormalized y = data [4];
normalNotNormalized z = data [5];
11 struct Color colorDisco:
12 colorDisco . r = data [6];
13 colorDisco . g = data [7];
14 colorDisco
```

```
1 . b = data [8];
2 disco . color = colorDisco :
3 long double dPlano = whatsTheDGeneral (
      normalNotNormalized , puntoCentral ) ;
4 dPlano = dPlano / getNorm ( normalNotNormalized );
5 \text{ disco} . extraD = dPlano :
6 normalNotNormalized = normalize ( normalNotNormalized )
7 disco . directionVector = normalNotNormalized :
8 disco . other = data [9];
9 \text{ disco} . o1 = data [ 10 ] ;
10 disco . o2 = data [11];
11 \text{ disco} . o3 = data [ 12 ] ;
12 \text{ disco} . Kd = data [ 13 ] ;
disco . Ka = data [ 14 ] ;
14 disco
```

```
1 . Kn = data [15];
_2 disco . Ks = data [16];
3 disco . planeCuts = planeCutsFound ;
4 disco . numberPlaneCuts = numberPlaneCuts :
5 disco . textures = texturesFound ;
6 disco . numberTextures = numberTextures :
7 Objects [ objectIndex ] = disco ;
8 if ( debug == 1 ) {
9 printPlaneCuts ( Objects [ objectIndex ] );
printTextures ( Objects [ objectIndex ] ,
     whichObjectCreate );
11 }
12 objectIndex ++;
13 return ;
14 }
```

```
2 case 7 : {
_3 if ( debug == 1 ) {
4 printf ("Insertando Elipses...");
_{5} printf ("Foco 1: (%LF, %LF, %LF) \n", data [0],
     data [1], data [2]);
6 printf ("Foco 2: (%LF, %LF, %LF) \n", data [ 3 ],
     data [4], data [5]);
7 printf ("Normal no normalizada: (%LF, %LF, %LF) \n",
     data [6], data [7], data [8]);
8 printf ( "Color: (%LF, %LF, %LF) \n" , data [ 9 ] ,
     data [8], data [9]);
9 printf ("K del elipse: %LF \n", data [ 12 ] );
10 printf ( "o1: %LF, o2: %LF, o3: %LF \n", data [ 13 ]
     , data [ 14 ] , data [ 15 ] ) ;
printf ( "Elipse Kd: %LF \n" , data [ 16 ] );
12 printf ("Elipse Ka: %LF \n", data [ 17 ] );
printf ("Elipse Kn: %LF \n", data [ 18 ] );
14 printf
```

```
1 ("Elipse Ks: %LF \n", data [ 19 ] );
printf ( "Esquina inferior izquierda (%LF, %LF, %LF) \n
     ", data [ 20 ], data [ 21 ], data [ 22 ] );
3 printf ("Esquina inferior derecha (%LF, %LF, %LF) \n"
      , data [ 23 ] , data [ 24 ] , data [ 25 ] ) ;
4 printf ("Esquina superior derecha (%LF, %LF, %LF) \n"
      , data [ 26 ] , data [ 27 ] , data [ 28 ] ) ;
5 printf ("Esquina superior izquierda (%LF, %LF, %LF) \n
      ", data [ 29 ], data [ 30 ], data [ 31 ] );
7 struct Object elipse ;
8 struct Vector x0v0z0 ;
9 \times 0 \times 0 \times 0 = 0 . x = data [ 20 ] ;
x0y0z0 . y = data [21];
11 \times 0 \times 0 \times 2 = data [22];
12 struct Vector x1y1z1 ;
x1y1z1 . x = data [ 23 ] ;
14 \times 1 \times 1 \times 1
```

```
1. y = data [24];
z \times 1y1z1 . z = data [25];
struct Vector x2y2z2 ;
4 \times 2y2z2 . x = data [ 26 ] ;
5 \times 2y2z2 . y = data [ 27 ] ;
6 \times 2y2z2 . z = data [ 28 ] ;
7 struct Vector x3y3z3 ;
8 \times 3y3z3 . x = data [ 29 ] ;
9 \times 3y3z3 . y = data [ 30 ] ;
10 x3y3z3 . z = data [ 31 ] ;
11 elipse x_0y_0z_0 = x_0y_0z_0;
12 elipse x_1y_1z_1 = x_1y_1z_1;
13 elipse . x2y2z2 = x2y2z2 ;
14 elipse
```

```
1 . x3y3z3 = x3y3z3;
2 elipse . intersectionFuncion = elipseIntersection ;
g elipse . normalVector = elipseNormal ;
4 elipse . retrieveTextureColor = planeTexture ;
5 struct Vector focol:
6 focol . x = data [0];
7 \text{ focol} . y = \text{data} [1];
8 \text{ focol} . z = \text{data} [2];
9 elipse . Xc = data [0];
10 elipse . Yc = data [1];
11 elipse . Zc = data [2];
12 elipse . Xother = data [3];
13 elipse . Yother = data [4];
14 elipse
```

```
1. Zother = data [5];
2 struct Vector normalNotNormalized :
3 \text{ normalNotNormalized} . x = data [ 6 ] ;
4 normalNotNormalized y = data [7];
5 normalNotNormalized . z = data [8];
6 struct Color colorElipse;
7 \text{ colorElipse} . r = data [ 9 ] ;
8 colorElipse . g = data [10];
g colorElipse . b = data [ 11 ] ;
10 elipse . color = colorElipse ;
11 long double dPlano = whatsTheDGeneral (
      normalNotNormalized , foco1 ) ;
12 dPlano = dPlano / getNorm ( normalNotNormalized );
13 elipse . extraD = dPlano ;
14 normalNotNormalized
```

```
1 = normalize ( normalNotNormalized );
2 elipse . directionVector = normalNotNormalized ;
g elipse . other = data [ 12 ] ;
4 elipse . o1 = data [ 13 ] ;
_{5} elipse . o2 = data [ 14 ] ;
6 elipse . o3 = data [15];
7 elipse . Kd = data [ 16 ] ;
8 elipse . Ka = data [ 17 ] ;
9 elipse . Kn = data [ 18 ] ;
10 elipse . Ks = data [ 19 ]
elipse . planeCuts = planeCutsFound ;
12 elipse . numberPlaneCuts = numberPlaneCuts :
13 elipse . textures = texturesFound ;
14 elipse
```

```
numberTextures = numberTextures :
2 Objects [ objectIndex ] = elipse ;
_3 if ( debug == 1 ) {
4 printPlaneCuts (Objects [objectIndex]);
5 printTextures ( Objects [ objectIndex ] ,
     whichObjectCreate ) ;
7 objectIndex ++ ;
8 return :
10 case 8 : {
if ( debug == 1 ) {
printf ( "Insertando Cuadr tica..." );
printf ( "Coeficientes: \n\t A: %LF \n\t B: %LF \n\t C:
      %LF\n\t D: %LF\n\t E: %LF\n\t F: %LF\n\t G: %LF\
     n\t H: %LF \n\t I: %LF \n" , data [ 1 ] , data [ 2
      ] , data [ 3 ] , data [ 4 ] , data [ 5 ] , data [
     6 ] , data [7] , data [8] , data [9]);
14 printf
```

```
1 ( "Constante K: \%LF \setminus n", data [ 10 ] );
2 printf ( "o1: %LF, o2: %LF, o3: %LF \n" , data [ 11 ]
      , data [ 12 ] , data [ 13 ] ) ;
_3 printf ("Elipse Kd: %LF \n", data [ 14 ] );
4 printf ("Elipse Ka: %LF \n", data [ 15 ] );
5 printf ( "Elipse Kn: %LF \n" , data [ 16 ] ) ;
6 printf ("Elipse Ks: %LF \n", data [ 17 ] );
7 printf ("Color: (%LF, %LF, %LF) \n", data [ 18 ],
     data [ 19 ] , data [ 20 ] ) ;
9 struct Object cuadratica ;
10 cuadratica . A = data [0];
11 cuadratica . B = data [1];
12 cuadratica . C = data [2];
13 cuadratica . D = data [3];
14 cuadratica
```

```
1 . E = data [4];
_2 cuadratica . F = data [5];
3 cuadratica . G = data [6];
4 cuadratica . H = data [7]
5 cuadratica . I = data [8]
6 cuadratica . J = data [ 9 ]
7 cuadratica . other = data [10] :
8 cuadratica . o1 = data [11]
9 cuadratica . o2 = data [ 12 ]
10 cuadratica . o3 = data [13]
11 cuadratica . Kd = data [14];
12 cuadratica . Ka = data [ 15 ] ;
13 cuadratica . Kn = data [16]:
14 cuadratica
```

```
1 . Ks = data [17];
2 struct Color colorCuadratica :
_3 colorCuadratica . _r = data [18];
4 colorCuadratica . g = data [ 19 ] ;
_{5} colorCuadratica . b = data [20];
6 cuadratica . color = colorCuadratica :
7 cuadratica . intersectionFuncion =
      quadraticIntersection :
8 cuadratica . normalVector = quadraticNormal ;
g cuadratica . planeCuts = planeCutsFound ;
10 cuadratica . numberPlaneCuts = numberPlaneCuts :
11 cuadratica . textures = texturesFound :
12 cuadratica . numberTextures = numberTextures ;
Objects [ objectIndex ] = cuadratica ;
14 if
```

```
( debug = 1 ) \{
printPlaneCuts ( Objects [ objectIndex ] );
g printTextures ( Objects [ objectIndex ] ,
     whichObjectCreate );
4 printf ( "sup" ) ;
6 objectIndex ++ ;
7 return :
10
11 long double obtainSingleValueFromLine ( char line [ ] )
12 char * token :
13 char * search = "=" :
14 long
```

```
1 double numeric Value :
2 token = strtok ( line , search ) ;
3 \text{ token} = \text{strtok} ( \text{NULL} , \text{search} ) ;
4 sscanf ( token , "%LF" , & numericValue ) ;
5 return numericValue ;
7 long double * obtainPointFromString ( char stringPoint
      [ ] ) {
8 char * token :
9 char * search = "=" ;
10 long double numeric Value ;
token = strtok ( stringPoint , search );
token = strtok ( NULL , search ) ;
13 char * pch ;
14 long
```

```
double * pointDimensions = malloc ( sizeof ( long
      double )*3);
_{2} int currentDimension = 0 :
3 \text{ pch} = \text{strtok} ( \text{token}, "," ) ;
4 while ( pch != NULL )
6 sscanf ( pch , "%LF" , & pointDimensions [
      currentDimension ] );
7 \text{ pch} = \text{strtok} (\text{NULL}, ",");
8 currentDimension ++ :
10 return pointDimensions;
11 }
12 void strip ( char * s ) {
13 \text{ char } * p2 = s ;
14 while
```

```
1 ( * s != '\0') {
2 if ( * s != '\t' && * s != '\n' ) {
3 * p2 +++ = * s +++;
4 } else {
5 ++ s :
* p2 = ' \ 0' ; 
g char * obtainFilenameTexture ( char stringLine [ ] ) {
char * token = malloc ( sizeof ( char ) * 200 );
11 char * search = "=" ;
token = strtok ( stringLine , search );
token = strtok ( NULL , search ) ;
14 strip
```

```
1 ( token ) ;
2 return token ; }
struct PlaneCut * readPlaneCuts ( long int pos , int *
     numberPlanes , long int * posAfterReading ) {
4 char temporalBuffer [ 300 ];
5 struct PlaneCut * planeCutsFound = NULL ;
6 long double * datosPlanos ;
7 int indexPlaneCut = -1;
8 FILE * file :
9 if ( file = fopen ( escenaFile , "r" ) ) {
10 fseek ( file , pos , SEEK_SET ) ;
while (fgets (temporalBuffer, 300, file)!= NULL)
if ( temporal Buffer [0] = ' n' ) {
13 continue ;
14 }
```

```
2 if ( strstr ( temporalBuffer , "#" ) != NULL ) {
3 continue :
5 if ( strstr ( temporalBuffer , "NumberPlanes" ) != NULL
6 long double numberPlanes = obtainSingleValueFromLine (
     temporalBuffer ) ;
7 planeCutsFound = malloc ( sizeof ( struct PlaneCut ) *
     numberPlanes ) ;
8 continue :
9 } else if ( strstr ( temporalBuffer , "Plano_" ) !=
     NULL ) {
indexPlaneCut ++ ;
11 continue ;
12 } else if ( strstr ( temporalBuffer , "END_Planos" ) !=
      NULL ) {
* numberPlanes = indexPlaneCut + 1;
14 *
```

```
posAfterReading = ftell ( file );
2 return planeCutsFound ;
3 } else if ( strstr ( temporalBuffer , "Punto" ) != NULL
4 datosPlanos = obtainPointFromString ( temporalBuffer )
5 struct Vector temp ;
6 \text{ temp} . x = datosPlanos [ 0 ] ;
7 temp . y = datosPlanos [1];
8 temp . z = datosPlanos [2];
9 planeCutsFound [ indexPlaneCut ] . point = temp ;
10 free ( datosPlanos ) ;
11 continue :
12 } else if ( strstr ( temporalBuffer , "Normal" ) !=
      NULL ) {
13 datosPlanos = obtainPointFromString ( temporalBuffer )
14 struct
```

```
1 Vector temp;
2 temp . x = datosPlanos [0];
3 \text{ temp} . V = datosPlanos [1];
4 temp . z = datosPlanos [2];
5 long double dEquation = whatsTheDGeneral ( temp ,
      planeCutsFound [ indexPlaneCut ] . point );
6 dEquation = dEquation / getNorm ( temp ) ;
7 temp = normalize ( temp ) ;
8 planeCutsFound [ indexPlaneCut ] . normal = temp ;
9 planeCutsFound [ indexPlaneCut ] . d = dEquation ;
10 free ( datosPlanos ) ;
11 continue :
12 }
13 continue :
14 }
```

```
4 struct Color * * getTexels ( char * pFile , int * hRes
     , int * vRes ) {
5 int counter , x , y , i , j ;
6 char dump [ 100 ] ;
7 time_t t :
8 struct Color * * temp ;
g srand ( unsigned ) time ( & t ) );
10 FILE * file :
if (file = fopen (pFile, "r")) {
12 for (i = 0; i < 11; ++ i)
13 fscanf ( file , "%s" , & dump [ 0 ] );
14 if
```

```
1 (i = 8 || i = 9) {
_{2} if ( i == 8 ) {
sscanf ( & dump [ 0 ] , "%i" , hRes ) ;
4 } else {
5 sscanf ( & dump [ 0 ] , "%i" , vRes ) ;
6 }
7 }
9 \text{ temp} = \text{malloc} ( \text{sizeof} ( \text{struct Color} * ) * ( * hRes )
10 for ( int r = 0 ; r < ( * hRes ) ; <math>r ++ ) {
11 temp [r] = malloc ( size of ( struct Color ) * ( *
     vRes ) ) ;
12 }
if (temp = NULL) {
14 printf
```

```
1 ("Devolvi NULL \n");
3 char temporalBuffer [ 2000 ] ;
int i = 0 , x = 0 , y = 0 , counter = 0 ;
5 while (fgets (temporalBuffer, 200, file)!= NULL)
6 if ( temporalBuffer [ 0 ] = ' n' ) 
7 continue :
9 struct Color texel :
10 long double number;
sscanf ( temporalBuffer , "%LF" , & number ) ;
int xs = * hRes - x - 1;
if (i = 0) {
14 temp
```

```
[y][xs].r = (number) / 255;
_{2} } else if ( i == 1 ) {
g = (y | xs | g = (number) / 255;
\{a, b\} else if \{a, b\} if \{a, b\} \{a, b\}
5 \text{ temp } [ y ] [ xs ] . b = ( number ) / 255 ;
7 i = (i + 1) \% 3;
8 \text{ if } ( i = 0 ) 
9 \ y = (y + 1);
10 y = y \% ( * vRes ) ;
if (y = 0) {
12 \times = ( \times + 1 ) ;
x = x \% (* hRes);
14 if
```

```
1 (x = 0) {
2 break :
6 \text{ counter} = 1 :
8 y = 0 ;
9 x = 0 :
while ( counter != 5 ) {
11 counter ++ ;
12 y ++ ;
13 }
14 }
```

```
2 else {
* (* vRes) = 128;
4 (*hRes) = 128;
5 \text{ temp} = \text{malloc} \left( \text{ size of } \left( \text{ struct Color } * \right) * 128 \right);
6 for ( int r = 0; r < (* hRes ); r ++ ) {
7 \text{ temp} [r] = \text{malloc} ( \text{sizeof} ( \text{struct} Color ) * 128 ) ;
9 if ( temp == NULL ) {
printf ( " Devolvi NULL \n" );
11 }
12 printf ("La textura de %s no pudo abrirse. Se
       sustituir por est tica\n", pFile);
13 for (x = 0; x < 128; x ++)
14 for
```

```
1 ( y = 0 ; y < 128 ; y ++ ) {
2 struct Color estatica :
_3 estatica . r = ( long double ) ( rand ( ) % 255 ) ) /
      255 :
4 estatica . g = (long double) (rand () % 255))
      255 :
_{5} estatica . b = ( (long double) (rand () % 255)) /
      255 ;
6 \text{ temp} [x] [y] = \text{estatica};
7 }
8
10 return temp ;
11 }
12 struct Texture * readTextures ( int currentTypeReading
      , long int pos , int * numberTextures , long int *
      posAfterReading ) {
13 char temporalBuffer [ 300 ];
14 struct
```

```
1 Texture * texturesFound = NULL :
2 long double * datosTexture ;
3 int indexTexture = -1;
4 FILE * file :
5 if ( file = fopen ( escenaFile , "r" ) ) {
6 fseek ( file , pos , SEEK_SET ) ;
while (fgets (temporalBuffer, 300, file)!= NULL)
8 if ( temporal Buffer [0] = ' n' ) {
9 continue :
10 }
if ( temporalBuffer [0] = ' t' ) {
12 continue :
13 }
14 if
```

```
1 ( strstr ( temporalBuffer , "#" ) != NULL ) {
2 continue :
3 }
4 if ( strstr ( temporalBuffer , "NumberTextures" ) !=
     NULL || strstr ( temporalBuffer , "NumberTexturas"
     ) != NULL ) {
5 long double numberTextures = obtainSingleValueFromLine
     ( temporalBuffer ) ;
6 texturesFound = malloc ( sizeof ( struct Texture ) *
     numberTextures ) ;
7 continue :
8 } else if ( strstr ( temporalBuffer , "Texture_" ) !=
     NULL || strstr ( temporalBuffer , "Textura_" ) !=
     NULL ) {
9 indexTexture ++ ;
10 continue :
11 } else if ( strstr ( temporalBuffer , "END_Textures" )
     != NULL || strstr ( temporalBuffer , "END_Texturas"
       ) != NULL ) {
```

```
texturesFound :
2 } else if ( strstr ( temporalBuffer , "Filename" ) !=
     NULL || strstr ( temporalBuffer , "filename" ) !=
     NULL ) {
3 char * filename = obtainFilenameTexture (
     temporalBuffer ) ;
4 int hRes , vRes ;
5 texturesFound [ indexTexture ] . filename = filename ;
6 struct Color * * textureMap = getTexels ( texturesFound
      [ indexTexture ] . filename , & hRes , & vRes ) ;
7 texturesFound [ indexTexture ] . textureMap =
     textureMap ;
8 texturesFound [ indexTexture ] . hRes = hRes ;
9 texturesFound [ indexTexture ] . vRes = vRes ;
10 continue :
if ( currentTypeReading = 2 || currentTypeReading = 4
     || currentTypeReading == 5 || currentTypeReading
     == 8 ) {
```

```
1 = obtainPointFromString ( temporalBuffer );
2 struct Vector temp ;
3 \text{ temp} . x = datosTexture [ 0 ] ;
4 temp . y = datosTexture [1];
5 \text{ temp} . z = datosTexture [ 2 ] ;
6 temp = normalize ( temp ) ;
7 texturesFound [ indexTexture ] . greenwich = temp ;
8 free ( datosTexture ) ;
9 continue :
10 }
if ( currentTypeReading = 2 || currentTypeReading = 8
if ( strstr ( temporalBuffer , "Norte" ) != NULL ||
      strstr ( temporalBuffer , "North" ) != NULL ) {
13 datosTexture = obtainPointFromString ( temporalBuffer )
14 struct
```

```
1 Vector temp;
2 temp . x = datosTexture [0];
3 \text{ temp} . y = datosTexture [1];
4 temp . z = datosTexture [2];
5 temp = normalize ( temp ) ;
6 texturesFound [ indexTexture ] . north = temp ;
7 free ( datosTexture ) ;
8 continue :
10
12 continue :
13 }
14
```

```
2
3 struct DraftPlane * readDraftPlanes ( int
      currentTypeReading , long int pos , int *
      numberDraftPlanes , long int * posAfterReading ) {
4 char temporalBuffer [ 300 ] :
5 struct DraftPlane * draftPlanesFound = NULL :
6 long double * datosDraftPlane ;
7 int indexDraftPlane = -1;
8 FILE * file :
9 if ( file = fopen ( escenaFile , "r" ) ) {
10 fseek ( file , pos , SEEK_SET ) ;
11 while (fgets (temporalBuffer, 300, file)!= NULL)
if ( temporal Buffer [0] = ' n' ) {
13 continue :
14 }
```

```
_{2} if ( temporalBuffer [ 0 ] = '\t' ) {
3 continue :
5 if ( strstr ( temporalBuffer , "#" ) != NULL ) {
6 continue :
8 if ( strstr ( temporalBuffer , "NumberPlanosCalado" )
     != NULL || strstr ( temporalBuffer , "
     NumberDraftPlanes" ) != NULL ) {
9 long double numberDraftPlanes =
      obtainSingleValueFromLine (temporalBuffer);
10 draftPlanesFound = malloc ( sizeof ( struct DraftPlane
    ) * numberDraftPlanes ) ;
11 continue :
12 } else if ( strstr ( temporalBuffer , "Plano_Calado_" )
      != NULL || strstr ( temporalBuffer , "PlanoCalado_
     " ) != NULL ) {
13 indexDraftPlane ++ :
```

```
2 } else if ( ( strstr ( temporalBuffer , "
     END_Planos_Calado" ) != NULL ) || ( strstr (
     temporalBuffer , "END_PlanosCalado" ) != NULL ) ||
     ( strstr ( temporalBuffer , "END_DraftPlanes" ) !=
     NULL ) || ( strstr ( temporalBuffer , "
     END_Draft_Planes" ) != NULL ) ) {
* numberDraftPlanes = indexDraftPlane + 1 :
4 * posAfterReading = ftell ( file );
5 return draftPlanesFound ;
6 } else if ( strstr ( temporalBuffer , "Filename" ) !=
     NULL || strstr ( temporalBuffer , "filename" ) !=
     NULL ) {
7 char * filename = obtainFilenameTexture (
     temporalBuffer );
8 int hRes , vRes ;
g draftPlanesFound [ indexDraftPlane ] . filename =
     filename:
struct Color * * textureMap = getTexels (
```

```
if ( currentTypeReading == 2 || currentTypeReading == 4
     || currentTypeReading == 5 || currentTypeReading
     == 8 ) {
4 if ( strstr ( temporalBuffer , "Greenwich" ) != NULL )
5 datosDraftPlane = obtainPointFromString (
     temporalBuffer ) :
6 struct Vector temp;
7 temp . x = datosDraftPlane [0];
8 temp . y = datosDraftPlane [1];
9 temp . z = datosDraftPlane [2];
temp = normalize ( temp ) ;
11 draftPlanesFound [ indexDraftPlane ] . greenwich = temp
free ( datosDraftPlane );
13 continue ;
14 }
```

```
_2 if ( currentTypeReading == 2 || currentTypeReading == 8
if ( strstr ( temporalBuffer , "Norte" ) != NULL ||
      strstr ( temporalBuffer , "North" ) != NULL ) {
4 datosDraftPlane = obtainPointFromString (
      temporalBuffer ) ;
5 struct Vector temp ;
6 \text{ temp} . x = datosDraftPlane [ 0 ] :
7 \text{ temp} . y = datosDraftPlane [ 1 ] ;
8 temp . z = datosDraftPlane [2];
9 temp = normalize ( temp ) ;
draftPlanesFound [ indexDraftPlane ] . north = temp ;
free ( datosDraftPlane );
12 continue :
13 }
14
```

```
3 continue :
7 long double * readValueFromLine ( int state , int *
     counterValueSegment , char * lineRead , int *
     numberValuesRead ) {
8 long double * values ;
9 switch ( state ) {
10 case 0:
if ( ( * counterValueSegment ) >= 0 && ( *
     counterValueSegment ) <= 10 ) {</pre>
values = malloc ( sizeof ( long double ) );
values [0] = obtainSingleValueFromLine (lineRead);
14
```

```
* counterValueSegment ) ++ ;
* numberValuesRead = 1;
3 return values :
\{a,b\} else if ( ( * counterValueSegment ) >= 11 && ( *
      counterValueSegment ) <= 12 ) {</pre>
5 long double * point = obtainPointFromString ( lineRead
_{6} values = malloc ( size of ( long double ) * 3 );
7 \text{ values } [0] = \text{point } [0];
8 \text{ values } [1] = \text{point } [1];
9 values [2] = point [2];
10 * numberValuesRead = 3 :
free ( point );
if ( ( * counterValueSegment ) = 12 ) {
13 ( * counterValueSegment ) = 0;
14 }
```

```
1 else {
2 ( * counterValueSegment ) ++ ;
4 return values :
6 case 1 :
7 if ( ( * counterValueSegment ) = 0 ) {
8 long double * positionLight = obtainPointFromString (
      lineRead ) ;
9 \text{ values} = \text{malloc} ( \text{sizeof} ( \text{long double} ) * 3 );
values [0] = positionLight [0];
values [1] = positionLight [1];
values [2] = positionLight [2];
13 ( * counterValueSegment ) ++ ;
14 *
```

```
numberValuesRead = 3:
2 free ( positionLight );
3 return values :
\{a,b\} else if ( ( * counterValueSegment ) >= 1 && ( *
      counterValueSegment <= 4 ) ) {</pre>
5 values = malloc ( sizeof ( long double ) );
6 values [ 0 ] = obtainSingleValueFromLine ( lineRead ) ;
7 if ( ( * counterValueSegment ) = 4 ) {
8 (* counterValueSegment) = 0;
9 } else {
10 ( * counterValueSegment ) ++ ;
11 }
12 * numberValuesRead = 1 :
13 return values :
14 }
```

```
1
2 case 2 :
_3 if ( ( * counterValueSegment ) = 0 || ( *
      counterValueSegment ) == 9 ) {
4 long double * positionSphere = obtainPointFromString (
      lineRead ) :
_{5} values = malloc ( _{sizeof} ( _{long} double ) * 3 );
_{6} values [0] = positionSphere <math>[0];
_{7} values [1] = positionSphere <math>[1];
8 \text{ values } [2] = \text{positionSphere } [2];
9 free ( positionSphere ) ;
10 * numberValuesRead = 3 :
if ( ( * counterValueSegment ) = 9 ) {
12 ( * counterValueSegment ) = 0;
13 } else {
14 (
```

```
* counterValueSegment ) ++ ;
2 }
3 return values :
\{a,b\} else if ( ( * counterValueSegment ) >= 1 && ( *
      counterValueSegment ) <= 8 ) {</pre>
5 values = malloc ( sizeof ( long double ) );
6 values [ 0 ] = obtainSingleValueFromLine ( lineRead ) ;
7 ( * counterValueSegment ) ++ ;
* numberValuesRead = 1 :
9 return values ;
10 }
11 case 3 :
if ( ( * counterValueSegment ) = 0 ) {
values = malloc ( sizeof ( long double ) * 3 ) :
14 long
```

```
double * rgbColors = obtainPointFromString ( lineRead )
_2 values [0] = rgbColors <math>[0];
3 \text{ values } [1] = \text{rgbColors } [1];
4 values [2] = rgbColors [2];
5 free ( rgbColors ) ;
* numberValuesRead = 3 :
7 ( * counterValueSegment ) ++ ;
8 return values :
9 } else if ( ( * counterValueSegment ) >= 1 && ( *
     counterValueSegment ) <= 7 ) {</pre>
10 values = malloc ( sizeof ( long double ) );
values [0] = obtainSingleValueFromLine (lineRead);
12 ( * counterValueSegment ) ++ ;
* numberValuesRead = 1;
14 return
```

```
1 values :
\{2\} else if ( ( * counterValueSegment ) == 8 ) {
if ( strstr ( lineRead , "END_Vertices" ) != NULL ) {
4 ( * counterValueSegment ) ++ ;
5 return values :
6 } else {
7 \text{ values} = \text{malloc} \left( \text{sizeof} \left( \text{long double} \right) * 3 \right);
8 long double * vertexPolygon = obtainPointFromString (
      lineRead ) ;
9 values [ 0 ] = vertexPolygon [ 0 ] ;
values [1] = vertexPolygon [1];
values [2] = vertexPolygon [2];
12 free ( vertexPolygon ) ;
13 * numberValuesRead = 3 :
14 if
```

```
1 ( ( * counterValueSegment ) = 12 ) {
_{2} ( * counterValueSegment ) = 0 ;
3 return values :
5 if ( ( * counterValueSegment ) != 8 ) {
6 ( * counterValueSegment ) ++ ;
8 return values ;
10 } else if ( ( * counterValueSegment ) >= 9 ) {
values = malloc ( sizeof ( long double ) * 3 );
12 long double * vertexPolygon = obtainPointFromString (
     lineRead ) :
values [0] = vertexPolygon [0];
14 values
```

```
[1] = vertexPolygon [1];
values [ 2 ] = vertexPolygon [ 2 ];
3 free ( vertexPolygon ) ;
* numberValuesRead = 3 :
_{5} if ( ( * counterValueSegment ) = 12 ) {
6 ( * counterValueSegment ) = 0 ;
7 return values :
9 ( * counterValueSegment ) ++ ;
10 return values :
12 case 4:
if ( * counterValueSegment = 0 || *
     counterValueSegment == 1 || * counterValueSegment
     == 12 ) {
14 long
```

```
double * positionCilinder = obtainPointFromString (
      lineRead ) :
_{2} values = malloc ( sizeof ( long double ) * 3 );
3 values [0] = positionCilinder <math>[0];
4 values [1] = positionCilinder [1];
5 values [ 2 ] = positionCilinder [ 2 ] ;
6 if ( * counterValueSegment == 12 ) {
7 (* counterValueSegment) = 0;
8 } else {
9 ( * counterValueSegment ) ++ ;
10 }
11 * numberValuesRead = 3 :
12 free ( positionCilinder ) ;
13 return values :
14 }
```

```
1 else if ( * counterValueSegment >= 2 && *
     counterValueSegment <= 11 ) {
values = malloc ( sizeof ( long double ) );
values [ 0 ] = obtainSingleValueFromLine ( lineRead ) ;
4 ( * counterValueSegment ) ++ ;
* numberValuesRead = 1 :
6 return values :
7 }
8 case 5 :
9 if ( * counterValueSegment = 0 || *
     counterValueSegment = 1 \mid \mid * counterValueSegment
     == 13 ) {
10 long double * positionCone = obtainPointFromString (
     lineRead ) :
values = malloc ( sizeof ( long double ) * 3 );
values [0] = positionCone [0];
values [1] = positionCone [1];
14 values
```

```
[2] = positionCone[2];
_2 if ( * counterValueSegment == 13 ) {
3 (* counterValueSegment) = 0;
4 } else {
5 ( * counterValueSegment ) ++ ;
7 * numberValuesRead = 3:
8 free ( positionCone ) ;
9 return values :
10 } else if ( * counterValueSegment >= 2 && *
     counterValueSegment <= 12 ) {
values = malloc ( sizeof ( long double ) );
values [0] = obtainSingleValueFromLine (lineRead);
13 ( * counterValueSegment ) ++ ;
14 *
```

```
1 \text{ numberValuesRead} = 1:
2 return values :
4 case 6 :
5 if ( ( * counterValueSegment >= 0 && *
      counterValueSegment <= 2 ) || ( *
      counterValueSegment >= 11 && * counterValueSegment
      <= 14 ) ) {
6 long double * tripleta = obtainPointFromString (
      lineRead ) ;
7 \text{ values} = \text{malloc} \left( \text{sizeof} \left( \text{long double} \right) * 3 \right);
8 \text{ values } [0] = \text{tripleta } [0];
9 values [1] = tripleta [1];
values [2] = tripleta [2];
if ( * counterValueSegment = 14 ) {
12 ( * counterValueSegment ) = 0;
13 } else {
14
```

```
* counterValueSegment ) ++ ;
2 }
* numberValuesRead = 3 :
4 free ( tripleta ) ;
5 return values ;
6 } else if ( ( * counterValueSegment \geq 3 && *
      counterValueSegment <= 10 ) ) {</pre>
7 values = malloc ( sizeof ( long double ) );
8 values [ 0 ] = obtainSingleValueFromLine ( lineRead ) ;
9 ( * counterValueSegment ) ++ ;
10 * numberValuesRead = 1;
11 return values :
12 }
13 case 7 :
14 if
```

```
1 ( ( * counterValueSegment >= 0 && * counterValueSegment
      <= 3 ) || ( * counterValueSegment >= 12 \&\& *
      counterValueSegment <= 15 ) ) {
2 long double * tripleta = obtainPointFromString (
      lineRead ) :
3 \text{ values} = \text{malloc} ( \text{sizeof} ( \text{long double} ) * 3 );
4 values [0] = tripleta [0];
5 values [ 1 ] = tripleta [ 1 ] ;
6 values [ 2 ] = tripleta [ 2 ] ;
_{7} if ( * counterValueSegment == 15 ) {
* ( * counterValueSegment ) = 0;
9 } else {
10 ( * counterValueSegment ) ++ ;
11 }
12 * numberValuesRead = 3 :
13 free (tripleta);
14 return
```

```
1 values :
_{2} } else if ( ( * counterValueSegment >= 4 && *
     counterValueSegment <= 11 ) ) {</pre>
3 values = malloc ( sizeof ( long double ) );
4 values [ 0 ] = obtainSingleValueFromLine ( lineRead ) ;
5 ( * counterValueSegment ) ++ ;
* numberValuesRead = 1 :
7 return values ;
9 case 8 :
if ( ( * counterValueSegment ) = 18 ) {
11 long double * tripleta = obtainPointFromString (
     lineRead ) ;
values = malloc ( sizeof ( long double ) * 3 );
values [0] = tripleta [0];
14 values
```

```
1 [ 1 ] = tripleta [ 1 ] ;
_2 values [2] = tripleta <math>[2];
3 (* counterValueSegment) = 0;
* numberValuesRead = 3;
5 free ( tripleta ) ;
6 return values :
7 } else if ( ( * counterValueSegment >= 0 \&\& *
      counterValueSegment <= 17 ) ) {</pre>
8 values = malloc ( sizeof ( long double ) );
9 values [ 0 ] = obtainSingleValueFromLine ( lineRead ) ;
10 ( * counterValueSegment ) ++ ;
11 * numberValuesRead = 1 :
12 return values ;
13 }
14 }
```

```
1
2 }
int plainCutsFound ( long int pos ) {
4 char temporalBuffer [ 300 ];
5 FILE * file :
6 if ( file = fopen ( escenaFile , "r" ) ) {
7 fseek ( file , pos , SEEK_SET ) ;
8 while ( fgets ( temporalBuffer , 300 , file ) != NULL )
9 if ( temporal Buffer [0] = ' n' ) {
10 continue :
11 }
if ( temporalBuffer [ 0 ] = '\t' ) {
13 continue :
14 }
```

```
2 if ( strstr ( temporalBuffer , "#" ) != NULL ) {
3 continue :
4 } else if ( strstr ( temporalBuffer , "Planos_Corte:" )
      != NULL ) {
5 return 1 :
6 } else if ( strstr ( temporalBuffer , "Texturas:" ) !=
     NULL ) {
7 return 0 :
8 } else if ( strstr ( temporalBuffer , "Planos_Calado:"
   ) != NULL ) {
9 return 0 ;
10 } else if ( strstr ( temporalBuffer , "Sphere_Object" )
   != NULL ) {
11 return 0 ;
12 } else if ( strstr ( temporalBuffer , "Polygon_Object"
    ) != NULL ) {
13 return 0 ;
14 }
```

```
1 else if ( strstr ( temporalBuffer , "Cylinder_Object" )
      != NULL ) {
2 return 0 :
3 } else if ( strstr ( temporalBuffer , "Cone_Object" )
      != NULL ) {
4 return 0 :
5 } else if ( strstr ( temporalBuffer , "Disc_Object" )
      != NULL ) {
6 return 0 :
7 } else if ( strstr ( temporalBuffer , "Elipse_Object" )
      != NULL ) {
8 return 0 ;
9 } else if ( strstr ( temporalBuffer , "Quadratic_Object
   " ) != NULL ) {
10 return 0;
11 } else if ( strstr ( temporalBuffer , "Scene_Data" ) !=
      NULL ) {
12 return 0;
13 } else if ( strstr ( temporalBuffer , "Light_Object" )
```

```
5 return 0 ; }
6 int texturesFound ( long int pos ) {
7 char temporalBuffer [ 300 ] ;
8 FILE * file :
9 if ( file = fopen ( escenaFile , "r" ) ) {
fseek ( file , pos , SEEK_SET ) ;
11 while (fgets (temporalBuffer, 300, file)!= NULL)
12 if ( temporal Buffer [0] = ' n' ) {
13 continue :
14 }
```

```
_{2} if ( temporalBuffer [ 0 ] = '\t' ) {
3 continue :
5 if ( strstr ( temporalBuffer , "#" ) != NULL ) {
6 continue :
7 } else if ( strstr ( temporalBuffer , "Texturas:" ) !=
      NULL || strstr ( temporalBuffer , "Textures:" ) !=
      NULL ) {
8 return 1 :
9 } else if ( strstr ( temporalBuffer , "Planos_Calado:"
   ) != NULL ) {
10 return 0 :
11 } else if ( strstr ( temporalBuffer , "Sphere_Object" )
      != NULL ) {
12 return 0 :
13 } else if ( strstr ( temporalBuffer , "Polygon_Object"
   ) != NULL ) {
14 return
```

```
2 } else if ( strstr ( temporalBuffer , "Cylinder_Object"
      ) != NULL ) {
3 return 0 :
4 } else if ( strstr ( temporalBuffer , "Cone_Object" )
      != NULL ) {
5 return 0 ;
6 } else if ( strstr ( temporalBuffer , "Disc_Object" )
      != NULL ) {
7 return 0 ;
8 } else if ( strstr ( temporalBuffer , "Elipse_Object" )
    != NULL ) {
9 return 0 ;
10 } else if ( strstr ( temporalBuffer , "Quadratic_Object
     " ) != NULL ) {
11 return 0 :
12 } else if ( strstr ( temporalBuffer , "Scene_Data" ) !=
    NULL ) {
13 return 0 ;
```

```
else if ( strstr ( temporalBuffer , "Light_Object" ) !=
      NULL ) {
2 return 0 :
3 }
4 }
6 return 0 ;
8 int draftPlanesFound ( long int pos ) {
9 char temporalBuffer [ 300 ] ;
10 FILE * file ;
if (file = fopen (escenaFile, "r")) {
12 fseek ( file , pos , SEEK_SET ) ;
13 while (fgets (temporalBuffer, 300, file)!= NULL)
14 if
```

```
1 ( temporalBuffer [ 0 ] = ' n' ) 
2 continue :
3 }
_{4} if ( temporalBuffer [ 0 ] = '\t' ) {
5 continue ;
_{7} if ( strstr ( temporalBuffer , "#" ) != NULL ) {
8 continue :
9 } else if ( ( strstr ( temporalBuffer , "Planos_Calado:
     ") != NULL) || ( strstr ( temporalBuffer , "
      PlanosCalado:") != NULL) || ( strstr (
      temporalBuffer , "DraftPlanes:" ) != NULL ) || (
      strstr ( temporalBuffer , "Draft_Planes" ) != NULL
     ) ) {
10 return 1:
11 } else if ( strstr ( temporalBuffer , "Sphere_Object" )
      != NULL ) {
12 return 0;
13 } else if ( strstr ( temporalBuffer , "Polygon_Object"
```

```
2 } else if ( strstr ( temporalBuffer , "Cylinder_Object"
      ) != NULL ) {
3 return 0 :
4 } else if ( strstr ( temporalBuffer , "Cone_Object" )
      != NULL ) {
5 return 0 ;
6 } else if ( strstr ( temporalBuffer , "Disc_Object" )
      != NULL ) {
7 return 0 ;
8 } else if ( strstr ( temporalBuffer , "Elipse_Object" )
    != NULL ) {
9 return 0 ;
10 } else if ( strstr ( temporalBuffer , "Quadratic_Object
     " ) != NULL ) {
11 return 0 :
12 } else if ( strstr ( temporalBuffer , "Scene_Data" ) !=
    NULL ) {
13 return 0 ;
```

```
1 else if ( strstr ( temporalBuffer , "Light_Object" ) !=
      NULL ) {
2 return 0 :
6 return 0 :
8 void getSceneObjects ( ) {
9 int i , j , c ;
int state = 0:
int counterValueSegment = 0 ;
12 char temporalBuffer [ 300 ];
13 long double * valuesRead ;
14 int
```

```
_1 indexValuesRead = 0:
2 int currentTypeObjectReading = 1 ;
struct PlaneCut * arrayPlaneCuts = NULL ;
4 struct Texture * arrayTextures = NULL ;
5 struct DraftPlane * arrayDraftPlanes = NULL ;
6 FILE * file :
7 if ( file = fopen ( escenaFile , "r" ) ) {
8 while ( fgets ( temporalBuffer , 300 , file ) != NULL )
9 if ( temporal Buffer [0] = ' n' ) {
10 continue :
11 }
if ( temporalBuffer [ 0 ] = '\t' ) {
13 continue :
14 }
```

```
2 if ( strstr ( temporalBuffer , "#" ) != NULL ) {
3 continue :
4 }
5 if ( strstr ( temporalBuffer , "Scene_Data" ) != NULL )
6 \text{ state} = 0;
7 \text{ counterValueSegment} = 0;
8 \text{ indexValuesRead} = 0:
9 \text{ valuesRead} = \text{NULL}:
valuesRead = malloc ( sizeof ( long double ) * 22 );
currentTypeObjectReading = 0 ;
12 continue :
13 } else if ( strstr ( temporalBuffer , "Light_Object" )
      != NULL ) {
14 state
```

```
_{1} = 1 :
counterValueSegment = 0 ;
3 \text{ indexValuesRead} = 0:
4 free ( valuesRead ) ;
_{5} valuesRead = malloc ( sizeof ( long double ) * 7 );
6 currentTypeObjectReading = 1 ;
7 continue :
8 } else if ( strstr ( temporalBuffer , "Sphere_Object" )
      != NULL ) {
9 \text{ state} = 2:
indexValuesRead = 0:
free ( valuesRead );
valuesRead = malloc ( sizeof ( long double ) * 22 );
13 counterValueSegment = 0;
14 currentTypeObjectReading
```

```
_{1} = 2 ;
2 continue :
3 } else if ( strstr ( temporalBuffer , "Polygon_Object"
    ) != NULL ) {
4 \text{ state} = 3 :
5 counterValueSegment = 0 :
6 \text{ indexValuesRead} = 0:
7 free ( valuesRead ) ;
8 \text{ valuesRead} = \text{malloc} ( \text{sizeof} ( \text{long double} ) * 2000000
   ) :
g currentTypeObjectReading = 3 ;
10 continue ;
11 } else if ( strstr ( temporalBuffer , "Cylinder_Object"
    ) != NULL ) {
12 \text{ state} = 4 :
13 counterValueSegment = 0;
14 indexValuesRead
```

```
_{1} = 0:
free ( valuesRead );
_3 valuesRead = malloc ( sizeof ( long double ) * 55 );
4 currentTypeObjectReading = 4 ;
5 continue :
6 } else if ( strstr ( temporalBuffer , "Cone_Object" )
      != NULL ) {
7 \text{ state} = 5:
8 counterValueSegment = 0;
9 \text{ indexValuesRead} = 0:
10 free ( valuesRead ) ;
_{11} valuesRead = malloc ( sizeof ( long double ) * 55 );
12 currentTypeObjectReading = 5 ;
13 continue :
14 }
```

```
else if ( strstr ( temporalBuffer , "Disc_Object" ) !=
      NULL ) {
_2 state = 6 :
3 counterValueSegment = 0;
_{4} indexValuesRead = 0 :
5 free ( valuesRead ) ;
_{6} valuesRead = malloc ( sizeof ( long double ) * 55 );
7 currentTypeObjectReading = 6 ;
8 continue :
9 } else if ( strstr ( temporalBuffer , "Elipse_Object" )
    != NULL ) {
10 \text{ state} = 7 :
11 counterValueSegment = 0;
12 \text{ indexValuesRead} = 0:
13 free ( valuesRead );
14 valuesRead
```

```
1 = malloc ( size of ( long double ) * 55 );
currentTypeObjectReading = 7 ;
3 continue :
4 } else if ( strstr ( temporalBuffer , "Quadratic_Object
      " ) != NULL ) {
5 \text{ state} = 8 :
6 counterValueSegment = 0;
7 \text{ indexValuesRead} = 0:
8 free ( valuesRead ) ;
9 \text{ valuesRead} = \text{malloc} ( \text{sizeof} ( \text{long double} ) * 55 );
10 currentTypeObjectReading = 8 ;
11 continue :
12 }
int number Values Read = 0:
14 long
```

```
double * valuesReadTemp = readValueFromLine ( state , &
      counterValueSegment , temporalBuffer , &
     numberValuesRead ) ;
2 if ( valuesReadTemp == NULL ) {
3 continue :
5 int i = 0;
for (i = 0; i < numberValuesRead; i ++)
_{7} valuesRead [ indexValuesRead + i ] = valuesReadTemp [ i
9 indexValuesRead += numberValuesRead :
if ( counterValueSegment = 0 ) {
int numberPlaneCuts = 0;
int numberTextures = 0 ;
int numberDraftPlanes = 0 ;
14 long
```

```
int posAfterReading ;
2 long int pos;
3 pos = ftell ( file ) ;
4 int areTherePlainCuts = plainCutsFound ( pos ) ;
_{5} if ( areTherePlainCuts == 1 ) {
6 pos = ftell ( file );
7 arrayPlaneCuts = readPlaneCuts ( pos , &
     numberPlaneCuts , & posAfterReading ) ;
8 fseek ( file , posAfterReading , SEEK_SET ) ;
10 pos = ftell ( file );
int areThereTextures = texturesFound ( pos );
if ( areThereTextures = 1 ) {
pos = ftell (file);
14 arrayTextures
```

```
1 = readTextures ( currentTypeObjectReading , pos , &
      numberTextures , & posAfterReading ) ;
2 fseek ( file , posAfterReading , SEEK_SET ) ;
3 }
4 int areThereDraftPlanes = draftPlanesFound ( pos ) ;
_{5} if ( _{areThereDraftPlanes}=1 ) {
6 pos = ftell ( file );
7 arrayDraftPlanes = readDraftPlanes (
      currentTypeObjectReading , pos , &
      numberDraftPlanes , & posAfterReading ) ;
8 fseek ( file , posAfterReading , SEEK_SET ) ;
10 createObjectFromData ( valuesRead ,
      currentTypeObjectReading , indexValuesRead ,
      arrayPlaneCuts, arrayTextures, arrayDraftPlanes,
       numberPlaneCuts , numberTextures ,
      numberDraftPlanes ) ;
11
```

```
2 fclose ( file );
4 void howManyObjectsLights ( ) {
5 char temporalBuffer [ 100 ] ;
6 FILE * file :
7 if ( file = fopen ( escenaFile , "r" ) ) {
8 while ( fgets ( temporalBuffer , 100 , file ) != NULL )
9 if ( temporalBuffer [0] = ' n' ) {
10 continue :
11 }
if ( strstr ( temporalBuffer , "#" ) != NULL ) {
13 continue :
14 }
```

```
2 if ( strstr ( temporalBuffer , "Light_Object" ) != NULL
3 numberLights ++ ;
4 continue :
5 } else if ( strstr ( temporalBuffer , "Sphere_Object" )
      != NULL ) {
6 numberObjects ++ ;
7 continue :
8 } else if ( strstr ( temporalBuffer , "Polygon_Object"
   ) != NULL ) {
9 numberObjects ++ ;
10 continue ;
11 } else if ( strstr ( temporalBuffer , "Cone_Object" )
      != NULL ) {
12 numberObjects ++ ;
13 continue :
14 }
```

```
1 else if ( strstr ( temporalBuffer , "Cylinder_Object" )
      != NULL ) {
numberObjects ++ ;
3 continue :
4 } else if ( strstr ( temporalBuffer , "Disc_Object" )
     != NULL ) {
5 numberObjects ++ ;
6 continue :
7 } else if ( strstr ( temporalBuffer , "Elipse_Object" )
      != NULL ) {
8 numberObjects ++ ;
9 continue :
10 } else if ( strstr ( temporalBuffer , "Quadratic_Object
    " ) != NULL ) {
numberObjects ++ ;
12 continue ;
13 }
14
```

```
3 fclose (file);
4 Objects = malloc ( sizeof ( struct Object ) *
     numberObjects );
5 Lights = malloc ( sizeof ( struct Light ) *
     numberLights ) ;
7 struct Vector throwRay (long double x, long double y
    ) {
8 struct Vector direction :
9 long double Xw , Yw ;
10 Xw = (long double) ((x) * Xdif) / Hres + Xmin;
11 Yw = (long double) ((y) * Ydif) / Vres + Ymin;
direction x = Xw - eye \cdot x;
direction y = Yw - eye y;
14 direction
```

```
1 . z = - eve . z ;
2 direction = normalize ( direction );
3 return direction ;
4 }
5 struct Color ponderAAcolors ( struct Color c1 , struct
     Color c2 , struct Color c3 , struct Color c4 ) {
6 struct Color color :
r = (c1 \cdot r + c2 \cdot r + c3 \cdot r + c4 \cdot r) / 4;
8 color . g = (c1 . g + c2 . g + c3 . g + c4 . g) / 4;
9 color . b = (c1 . b + c2 . b + c3 . b + c4 . b) / 4;
10 return color ;
11 }
12 long double getDistanceColors ( struct Color c1 ,
     struct Color c2 ) {
return sqrt ( pow ( c1 . r - c2 . r , 2 ) + pow ( c1 .
     g - c2 \cdot g \cdot 2 + pow(c1 \cdot b - c2 \cdot b \cdot 2);
14 }
```

```
int theyOK ( struct Color c1 , struct Color c2 , struct
       Color c3, struct Color c4) {
3 long double dist , dist1 , dist2 , dist3 , dist4 ,
      dist5 , dist6 ;
4 \text{ dist1} = \text{getDistanceColors} ( c1 , c2 ) ;
5 dist2 = getDistanceColors ( c1 , c3 ) ;
6 dist3 = getDistanceColors ( c1 , c4 ) ;
7 dist4 = getDistanceColors ( c2 , c3 ) ;
8 dist5 = getDistanceColors ( c2 , c4 ) ;
g dist6 = getDistanceColors ( c3 , c4 ) ;
10 dist = (dist1 + dist2 + dist3 + dist4 + dist5 + dist6)
    ) / 6 ;
if ( dist <= similar ) {</pre>
12 return 1:
13 } else {
14 return
```

```
4 struct Color getAAColor (long double x , long double y
      , int aaLevel ) {
5 int areOK:
6 int level = aaLevel :
7 struct Color color , color1 , color2 , color3 , color4
8 struct Vector direction , V ;
9 long double sum = 1 / pow (2, level);
10 level ++ :
long double nextSum = 1 / pow (2, level);
direction = throwRay (x, y);
13 V . x = - direction . x;
14 V
```

```
1. y = - direction . y;
_2 V . z = - direction . z ;
3 \text{ color1} = \text{getColor} ( eye , direction , V , maxReflection
4 direction = throwRay (x, y + sum);
5 \text{ V} \cdot \text{x} = - \text{ direction } \cdot \text{x};
_{6} V _{.} y _{=} - direction _{.} y ;
7 \text{ V} \cdot \text{z} = - \text{ direction } \cdot \text{z};
8 \text{ color2} = \text{getColor} ( eye , direction , V , maxReflection
g direction = throwRay ( x + sum , y );
10 V . x = - direction . x :
V \cdot y = - direction \cdot y;
_{12} V . z = - direction . z ;
color3 = getColor ( eye , direction , V , maxReflection
14 direction
```

```
1 = throwRay (x + sum , y + sum);
_{2} V . x = - direction . x ;
_3 V . _{\rm V} = - direction . _{\rm V} ;
_{4} V . z = - direction . z :
5 \text{ color4} = \text{getColor} ( eye , direction , V , maxReflection
_{6} areOK = theyOK ( color1 , color2 , color3 , color4 ) ;
_{7} if ( areOK == 0 && level <= maxAA ) {
8 \text{ color1} = \text{getAAColor} (x, y, \text{level});
9 \text{ color2} = \text{getAAColor} (x, y + \text{nextSum}, \text{level});
10 color3 = getAAColor ( x + nextSum , y , level );
11 color4 = getAAColor ( x + nextSum , y + nextSum , level
12 color = ponderAAcolors ( color1 , color2 , color3 ,
      color4);
13 } else {
14 color
```

```
1 = ponderAAcolors (color1, color2, color3, color4)
3 return color :
5 \text{ void} * \text{runRT} (\text{void} * \text{x}) 
6 int start , i , j ;
7 struct Color color ;
8 i = * ( (int *) x );
9 printf ( "%i\n" , i ) ;
10 for ( i ; i < Vres ; i += 4 ) {
11 for (i = 0; i < Hres; i ++)
12 color = getAAColor ( ( long double ) j , ( long double
     ) i , 0 ) ;
13 Framebuffer [ i ] [ j ] = color;
14 }
```

```
3 return NULL:
5 int main ( int argc , char * arcgv [ ] ) {
6 howManyObjectsLights ( );
7 printf ( "Lights: %i \n" , numberLights );
8 printf ( "Objects: %i \n" , numberObjects );
getSceneObjects ( );
10 int i :
pthread_t threads [4];
Xdif = Xmax - Xmin;
Ydif = Ymax - Ymin;
14 similar
```

```
1 = sqrt (3) / 32;
2 printf ( "\nRay Tracing\n...\n...\n" );
for ( i = 0 ; i < 4 ; i ++ ) {
4 pthread_create ( & ( threads [ i ] ) , NULL , & runRT ,
      & i ) :
5 sleep ( 1 ) ;
7 for (i = 0; i < 4; i ++)
8 pthread_join ( threads [ i ] , NULL ) ;
printf ( "Rays: %LF\n" , rays );
saveFile ( );
12 free (Objects);
13 free ( Lights );
14 free
```

```
1 ( Framebuffer );
2 printf ( "\nDONE.\n" );
3 }
```

```
1 static int Hres:
2 static int Vres;
3 static int maxAA;
4 static int maxReflection;
5 static int maxTransparency;
6 static long double rays = 0;
7 \text{ static long double similar} = 0;
8 static long double Xmax;
9 static long double Ymax;
10 static long double Xmin;
11 static long double Ymin;
12 static long double Xdif;
13 static long double Ydif;
```

```
1 static long double la;
2 static long double e;
3 static int debug = 0;
4 static int rec = 0;
5 struct Color
 long double r;
7
8 long double g;
   long double b;
  };
10
  struct Point2D
12
long double u;
```

```
long double v;
  };
3 struct Point3D
4
  long double x;
5
   long double y;
6
   long double z;
7
  struct Vector
10
   long double x;
11
     long double y;
12
     long double z;
13
```

```
1 };
2 struct Light
3
      long double Xp;
4
      long double Yp;
5
     long double Zp;
6
   long double c1;
7
   long double c2;
8
   long double c3;
9
    long double lp;
10
  struct Object
13
14
```

```
long double Xc;
1
      long double Yc:
2
      long double Zc:
3
      long double other;
4
       struct Vector direction Vector;
5
      long double extraD;
6
      long double Xother;
7
      long double Yother;
8
      long double Zother;
9
      long double Kd;
10
      long double Ka:
11
      long double Kn;
12
      long double Ks;
13
```

```
long double o1;
1
      long double o2;
      long double o3;
3
      long double A;
4
      long double B;
5
      long double C;
6
      long double D;
7
      long double E;
8
      long double F;
9
      long double G;
10
      long double H;
11
      long double I;
12
      long double J:
13
```

```
int pointAmount;
1
      long double D1;
2
      long double D2;
3
      long double K1;
4
      long double K2;
5
      long double height;
6
      struct Color color;
7
      struct Point2D * points2D;
8
      struct Point3D * points3D;
9
      struct Vector (* normalVector) ();
10
      struct Intersection (* intersectionFuncion) ();
11
      struct Color (* retrieveTextureColor) ();
12
      struct Vector x0v0z0;
13
```

```
struct Vector x1y1z1;
      struct Vector x2y2z2;
      struct Vector x3y3z3;
      int numberPlaneCuts;
4
      int numberTextures;
5
      int numberDraftPlanes;
6
      struct PlaneCut * planeCuts;
7
      struct Texture * textures;
8
      struct DraftPlane * draftPlanes:
9
10
  struct PlaneCut
12
      struct Vector normal;
13
```

```
struct Vector point;
 long double d;
 struct Texture
  char * filename;
6
   struct Color * * textureMap;
7
   int vRes;
   int hRes;
struct Vector greenwich;
   struct Vector north;
11
   };
12
  struct DraftPlane
14
```

```
char * filename;
1
      struct Color * * textureMap;
   int vRes:
3
   int hRes;
4
   struct Vector greenwich;
5
      struct Vector north;
   };
  struct Intersection
9
      long double Xi;
10
      long double Yi;
11
     long double Zi;
12
      long double distance;
13
```

```
struct Object object;
  long double null;
   };
4 static struct Light * Lights;
5 static struct Object * Objects;
6 static struct Vector eye;
7 static struct Color * * Framebuffer;
8 static struct Color background;
9 static int numberObjects = 0;
static int numberLights = 0;
11 static int lightlndex = 0;
12 static int objectIndex = 0;
static char * escenaFile = "escena1.txt":
```

```
long double min (long double a, long double b)
2
      if (a < b)
3
5
          return a;
6
      else
8
          return b;
9
10
  long double max (long double a, long double b)
13
14
```

```
if (a > b)
1
           return a;
3
4
       else
5
6
           return b:
7
8
9
  int testPlaneCut (struct PlaneCut plane, long double x,
       long double y, long double z)
      int val = (plane.normal.x * x)+ (plane.normal.y * y
12
      )+ (plane.normal.z * z)+ plane.d;
      if (val > 0)
13
14
15
```

```
return 1:
1
2
      else
3
4
           return 0;
5
6
7
  int testIntersection (long double x, long double y,
      long double z, struct Object object)
9
      int k, sign;
10
      int accept = 1;
11
      int amount = object.numberPlaneCuts;
12
      for (k = 0 ; k < amount ; k ++)
13
14
15
```

```
sign = testPlaneCut (object.planeCuts[k], x, y,
       z);
           if (sign = 1)
3
               accept = 0;
4
5
6
       return accept;
7
8
  long double pointProduct (struct Vector a, struct
      Vector b)
10
      long double pp = 0;
11
      pp += (a.x * b.x);
12
      pp += (a.y * b.y);
13
```

```
pp += (a.z * b.z);
    return pp;
2
3
4 struct Vector crossProduct (struct Vector a, struct
      Vector b)
5
      struct Vector newVector:
6
      newVector.x = (a.y * b.z) - (a.z * b.y);
7
      newVector.y = (a.z * b.x) - (a.x * b.z);
8
      newVector.z = (a.x * b.y) - (a.y * b.x);
      return newVector:
10
11
  long double getNorm (struct Vector vector)
13
14
```

```
long double norm = sqrt (pow (vector.x, 2)+ pow (
      vector.y, 2) + pow (vector.z, 2);
      return norm;
3
  struct Vector normalize (struct Vector vector)
5
      long double norm = getNorm (vector);
6
      struct Vector unitVector;
7
      if (norm != 0)
8
9
           unitVector.x = vector.x / norm;
10
           unitVector.y = vector.y / norm;
11
           unitVector.z = vector.z / norm;
12
13
```

```
else
           unitVector.x = vector.x;
           unitVector.y = vector.y;
4
           unitVector.z = vector.z;
5
6
       return unitVector;
7
8
  void saveFile ()
10
    int i, j;
11
      FILE * file;
12
       file = fopen ("scene.ppm", "w");
13
```

```
if (file = NULL)
1
           printf ("Error creating/opening file!\n");
3
           exit (1);
4
5
       fprintf (file, "%s\n", "P3");
6
      fprintf (file, "%i %i\n", Hres, Vres);
7
      fprintf (file, "%i \ n", 255);
8
      for (i = Vres - 1 ; i >= 0 ; i --)
9
10
           for (j = 0 ; j < Hres ; j ++)
11
               int R = (int)255 * Framebuffer[i][j].r;
13
```

```
int G = (int)255 * Framebuffer[i][j].g;
               int B = (int)255 * Framebuffer[i][i].b;
2
               fprintf (file, "%i %i %i ", R, G, B);
3
4
          fprintf (file, "\n");
5
6
      fclose (file);
7
8
  long double getAttenuationFactor (struct Light light,
      long double distance)
10
      long double value = 1 / (light.c1 + (light.c2 *
11
      distance)+ (light.c3 * pow (distance, 2)));
      return min (1.0, value);
12
13
```

```
1 struct Color difusseColor (long double I, struct Color
      color)
   struct Color newColor;
3
      newColor.r = I * color.r;
4
      newColor.g = I * color.g;
5
      newColor.b = I * color.b;
6
     return newColor;
7
  struct Color specular Highlight (long double E, struct
      Color color)
10
      struct Color newColor:
      newColor.r = color.r + (E * (1 - color.r));
12
      newColor.g = color.g + (E * (1 - color.g));
13
```

```
newColor.b = color.b + (E * (1 - color.b));
      return newColor;
2
3
4 struct Intersection sphereIntersection (struct Vector
      anchor, struct Vector direction, struct Object
      object)
5
      long double t, t1, t2;
6
      long double Xdif = anchor.x - object.Xc;
7
      long double Ydif = anchor.y - object.Yc;
8
      long double Zdif = anchor.z - object.Zc;
9
      struct Intersection tempIntersect;
10
      tempIntersect.null = 0;
11
      long double B = 2 * ((direction.x * Xdif) + (
12
      direction.y * Ydif)+ (direction.z * Zdif));
      long double C = pow (Xdif, 2) + pow (Ydif, 2) + pow (
13
      Zdif, 2)— pow (object.other, 2);
```

```
long double discriminant = pow (B, 2) (4 * C);
1
       if (discriminant >= 0)
           long double root = sqrt (discriminant);
4
           B *= - 1:
5
           t1 = (B + root) / 2;
6
           t2 = (B - root) / 2;
7
           if (t1 > e)
8
9
               if (t2 > e)
10
11
                    t = min(t1, t2);
12
                    tempIntersect.distance = t;
13
```

2

3

4

5

6 7

8

9

10

```
tempIntersect.object = object;
             tempIntersect.Xi = anchor.x + (t *
direction.x);
            tempIntersect.Yi = anchor.y + (t *
direction.y);
            tempIntersect.Zi = anchor.z + (t *
direction.z);
            int accept = testIntersection (
tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
Zi, object);
             if (accept == 0)
                t = max(t1, t2);
                 tempIntersect.distance = t;
                 tempIntersect.object = object;
                 tempIntersect.Xi = anchor.x + (t *
direction.x);
                 tempIntersect.Yi = anchor.y + (t *
direction.y);
```

Analizador Léxico

```
int accept = testIntersection (
1
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                        if (accept == 0)
2
3
                            tempIntersect.null = 1;
4
5
6
               else
8
9
                   t = t1:
                   tempIntersect.distance = t;
                   tempIntersect.object = object;
                   tempIntersect.Xi = anchor.x + (t *
13
      direction .x);
```

```
tempIntersect.Yi = anchor.y + (t *
      direction.y);
                    tempIntersect.Zi = anchor.z + (t *
2
      direction.z);
                    int accept = testIntersection (
3
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                    if (accept = 0)
4
5
                        tempIntersect.null = 1;
6
7
8
9
           else
11
               if (t2 > e)
13
14
```

```
t = t2:
                   tempIntersect.distance = t;
2
                    tempIntersect.object = object;
3
                    tempIntersect.Xi = anchor.x + (t *
4
      direction .x);
                   tempIntersect.Yi = anchor.y + (t *
5
      direction.y);
                   tempIntersect.Zi = anchor.z + (t *
6
      direction.z);
                   int accept = testIntersection (
7
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                    if (accept = 0)
8
9
                        tempIntersect.null = 1;
10
11
12
               else
13
14
```

```
tempIntersect.null = 1;
2
           return tempIntersect;
5
      else
           tempIntersect.null = 1;
8
           return tempIntersect;
9
10
11
  struct Vector sphereNormal (struct Object object,
      struct Vector vector)
13
14
```

```
struct Vector normal;
      normal.x = vector.x - object.Xc;
2
      normal.y = vector.y - object.Yc;
3
      normal.z = vector.z - object.Zc;
4
       return normal;
5
6
  int getSign (long double v)
8
      if (v >= 0)
9
10
         return 1:
11
12
      else
13
14
15
```

```
return 0:
2
4 struct Intersection polygonIntersection (struct Vector
      anchor, struct Vector direction, struct Object
      object)
5
      long double denominator = (direction.x * object.Xc)
6
      + (direction.y * object.Yc)+ (direction.z * object.
      Zc):
      struct Intersection tempIntersect;
7
      tempIntersect.null = 0;
8
      if (denominator == 0)
9
10
          tempIntersect.null = 1;
11
          return tempIntersect;
12
13
```

```
else
2
          long double numerator = - (anchor.x * object.Xc
3
      + anchor.y * object.Yc + anchor.z * object.Zc +
      object.other):
          long double t = numerator / denominator;
4
          tempIntersect.distance = t;
5
          tempIntersect.object = object;
6
          tempIntersect.Xi = anchor.x + (t * direction.x)
7
          tempIntersect. Yi = anchor.y + (t * direction.y)
8
          tempIntersect.Zi = anchor.z + (t * direction.z)
9
          long double maxA_B = max (fabs (object.Xc),
10
      fabs (object.Yc));
          long double maxA_B_C = max (maxA_B, fabs (
      object.Zc));
          long double u, v;
```

```
u = tempIntersect.Zi;
               v = tempIntersect.Yi;
           else if (maxA_B_C = fabs (object.Yc))
4
               u = tempIntersect.Xi;
6
               v = tempIntersect.Zi;
8
           else if (maxA_B_C = fabs (object.Zc))
9
               u = tempIntersect.Xi;
11
               v = tempIntersect.Yi;
12
13
```

```
int NC = 0:
          int NV = object.pointAmount;
           struct Point2D * points2DArrayTemp = malloc (
3
      sizeof (struct Point2D)* NV);
           for (int i = 0; i < NV; i ++)
4
5
               points2DArrayTemp[i].u = object.points2D[i
6
      l.u - u;
               points2DArrayTemp[i].v = object.points2D[i
7
      1.v - v:
8
          int SH = getSign (points2DArrayTemp[0].v);
9
          int NSH:
10
          int a = 0;
          int b = (a + 1)\% NV;
12
          for (a = 0 ; a < NV - 1 ;)
13
14
15
```

3

4

5

6 7

8

9

11

12 13 14

```
NSH = getSign (points2DArrayTemp[b].v);
        if (SH != NSH)
             if (points2DArrayTemp[a].u > 0 &&
points2DArrayTemp[b].u > 0)
                NC ++:
            else if (points2DArrayTemp[a].u > 0 ||
points2DArrayTemp[b].u > 0)
                 long double N = (points2DArrayTemp[
b].u - points2DArrayTemp[a].u);
                 long double D = (points2DArrayTemp[
b].v - points2DArrayTemp[a].v);
                 if (D != 0)
```

```
if (points2DArrayTemp[a].u - ((
      points2DArrayTemp[a].v * N)/D)> 0)
                                 NC ++;
3
5
6
               SH = NSH:
8
               a ++;
9
                b ++:
11
           if (NC \% 2 == 0)
12
13
14
```

```
tempIntersect.null = 1;
2
           else
               tempIntersect.null = 0;
6
           int accept = testIntersection (tempIntersect.Xi
7
      , tempIntersect. Yi, tempIntersect. Zi, object);
           if (accept = 0)
8
9
               tempIntersect.null = 1;
11
          free (points2DArrayTemp);
           return tempIntersect;
13
```

```
2
  struct Vector polygonNormal (struct Object object)
4
      struct Point3D point0 = object.points3D[0];
5
      struct Point3D point1 = object.points3D[1];
6
      struct Point3D point2 = object.points3D[2];
7
      struct Vector vector1 =
8
9
           point1.x - point0.x, point1.y - point0.y,
10
      point1.z - point0.z
       };
      struct Vector vector2 =
12
13
14
```

```
point2.x - point1.x, point2.y - point1.y,
1
      point2.z - point1.z
       }:
2
      struct Vector normal = crossProduct (vector1,
3
      vector2);
      return normal;
4
6 struct Intersection cilinderIntersection (struct Vector
       anchor, struct Vector direction, struct Object
      object)
7
      struct Intersection tempIntersect;
8
      tempIntersect.null = 0;
g
      long double xo = object.Xc;
10
      long double vo = object. Yc:
11
      long double zo = object.Zc;
12
      long double xq = object.directionVector.x;
13
```

```
long double yq = object.directionVector.y;
1
      long double zq = object.directionVector.z;
2
      long double xd = direction.x;
3
      long double yd = direction.y;
4
      long double zd = direction.z;
5
      long double xe = anchor.x;
6
      long double ye = anchor.y;
7
      long double ze = anchor.z;
8
      long double radius = object.other;
g
      long double xdxq = xd * xq;
10
      long double ydyq = yd * yq;
11
      long double zdzq = zd * zq;
12
      long double xexq = xe * xq;
13
```

```
long double yeyq = ye * yq;
      long double zezq = ze * zq;
2
      long double xoxq = xo * xq;
3
      long double yoyq = yo * yq;
4
      long double zozq = zo * zq;
5
      long double coef1 = xdxq * xq + ydyq * xq + zdzq *
6
     xq - xd;
7
     long double coef2 = xdxq * yq + ydyq * yq + zdzq *
     vq - vd:
     long double coef3 = xdxq * zq + ydyq * zq + zdzq *
8
     zq - zd:
      long double coef4 = xo + xexq * xq - xoxq * xq +
g
      yeyq * xq - yoyq * xq + zezq * xq - zozq * xq - xe;
      long double coef5 = yo + xexq * yq - xoxq * yq +
10
      yeyq * yq - yoyq * yq + zezq * yq - zozq * yq - ye;
      long double coef6 = zo + xexq * zq - xoxq * zq +
11
      yeyq * zq - yoyq * zq + zezq * zq - zozq * zq - ze;
      long double A = pow (coef1, 2) + pow (coef2, 2) + pow
12
       (coef3, 2);
```

```
long double C = pow (coef4, 2) + pow (coef5, 2) + pow
1
       (coef6, 2)— pow (radius, 2);
      long double discriminant = pow (B, 2) – (4 * A * C);
2
      long double t, t1, t2;
3
       if (discriminant >= 0)
4
5
           long double root = sqrt (discriminant);
6
           B *= - 1:
7
           t1 = (B - root) / (2 * A);
8
           t2 = (B + root) / (2 * A);
9
          long double Xi;
10
          long double Yi;
11
          long double Zi;
12
           long double d1 = object.D1;
13
```

```
long double d2 = object.D2;
           if (t1 > e)
               if (t2 > e)
5
                   t = min(t1, t2);
6
                   Xi = xe + (t * xd);
7
                   Yi = ye + (t * yd);
                   Zi = ze + (t * zd):
9
                   if (d2 >= ((Xi - xo) * xq + (Yi - yo) *
10
     yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)*
      yq + (Zi - zo)*zq) >= d1)
                       tempIntersect.Xi = Xi;
                       tempIntersect.Yi = Yi;
13
```

```
tempIntersect.Zi = Zi;
                       tempIntersect.distance = t;
2
                       tempIntersect.object = object;
3
                       int accept = testIntersection (
4
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                       if (accept == 0)
5
6
                           t = max (t1, t2);
7
                           Xi = xe + (t * xd);
8
                           Yi = ye + (t * yd);
9
                            Zi = ze + (t * zd);
10
                            if (d2 >= ((Xi - xo) * xq + (Yi
11
     - yo)* yq + (Zi - zo)* zq) & ((Xi - xo)* xq + (Yi -
      yo)* yq + (Zi - zo)* zq)>= d1)
12
                                tempIntersect.Xi = Xi:
```

```
tempIntersect. Yi = Yi;
                                 tempIntersect.Zi = Zi;
2
                                 tempIntersect.distance = t;
3
                                 tempIntersect.object =
4
      object;
                                 int accept =
5
      testIntersection (tempIntersect.Xi, tempIntersect.
      Yi, tempIntersect.Zi, object);
                                 if (accept == 0)
6
7
                                     tempIntersect.null = 1;
8
9
                                 return tempIntersect;
10
                             else
12
13
14
```

```
tempIntersect.null = 1;
                                 return tempIntersect;
2
3
                        return tempIntersect;
5
6
                    else
7
8
                        t = max (t1, t2);
9
                        Xi = xe + (t * xd);
10
                        Yi = ye + (t * yd);
                        Zi = ze + (t * zd);
12
                        if (d2 >= ((Xi - xo) * xq + (Yi - yo)
13
      * yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)
      * yq + (Zi - zo)* zq) >= d1)
14
15
```

```
tempIntersect.Xi = Xi;
1
                            tempIntersect.Yi = Yi;
2
                            tempIntersect.Zi = Zi;
3
                            tempIntersect.distance = t;
4
                            tempIntersect.object = object;
5
6
                        else
8
                            tempIntersect.null = 1;
9
10
                        int accept = testIntersection (
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                        if (accept == 0)
14
```

```
tempIntersect.null = 1;
1
2
                        return tempIntersect;
3
5
               else
6
7
                   t = t1:
8
                   Xi = xe + (t * xd);
9
                   Yi = ye + (t * yd);
10
                   Zi = ze + (t * zd);
                    if (d2 >= ((Xi - xo) * xq + (Yi - yo) *
      yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)*
      yq + (Zi - zo)*zq) >= d1)
14
```

```
tempIntersect.Xi = Xi;
                        tempIntersect.Yi = Yi;
2
                        tempIntersect.Zi = Zi;
3
                        tempIntersect.distance = t;
4
                        tempIntersect.object = object;
5
                        int accept = testIntersection (
6
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                        if (accept == 0)
7
8
                            tempIntersect.null = 1;
9
10
                        return tempIntersect;
11
12
                    else
13
14
15
```

```
tempIntersect.null = 1;
1
                         return tempIntersect;
3
5
           else
6
7
                if (t2 > e)
8
9
                    t = t2:
10
                    Xi = xe + (t * xd);
11
                    Yi = ye + (t * yd);
12
                    Zi = ze + (t * zd);
13
```

```
if (d2 >= ((Xi - xo) * xq + (Yi - yo) *
      yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)*
      yq + (Zi - zo)*zq) >= d1)
                        tempIntersect.Xi = Xi;
3
                        tempIntersect.Yi = Yi;
4
                        tempIntersect.Zi = Zi;
5
                        tempIntersect.distance = t;
6
                        tempIntersect.object = object;
7
                        int accept = testIntersection (
8
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                        if (accept = 0)
9
10
                            tempIntersect.null = 1;
11
12
                        return tempIntersect;
13
```

```
else
3
                         tempIntersect.null = 1;
                         return tempIntersect;
5
                else
8
9
                    tempIntersect.null = 1;
10
                     return tempIntersect;
11
12
13
```

```
else
2
           tempIntersect.null = 1;
4
           return tempIntersect;
5
6
7
  struct Vector cilinderNormal (struct Object object,
      struct Vector intersectionPoint)
9
      struct Vector normalCilinder;
10
      long double x = intersectionPoint.x;
11
      long double y = intersectionPoint.y;
12
      long double z = intersectionPoint.z;
13
```

```
long double xo = object.Xc;
1
      long double vo = object. Yc:
2
      long double zo = object.Zc;
3
      long double xq = object.directionVector.x;
4
      long double yq = object.directionVector.y;
5
      long double zq = object.directionVector.z;
6
      long double xxoxq = (x - xo) * xq;
7
      long double yyoyq = (y - yo)*yq;
8
      long double zzozq = (z - zo)*zq;
9
      long double parenth = (xxoxq + yyoyq + zzozq);
10
      long double pxq = 2 * (xo + parenth * xq - x);
11
      long double pyq = 2 * (yo + parenth * yq - y);
12
      long double pzq = 2 * (zo + parenth * zq - z);
13
```

```
normalCilinder.x = pxq * (pow (xq, 2)- 1)+ pyq * (
      yq * xq) + pzq * (zq * xq);
      normalCilinder.y = pxq * (xq * yq) + pyq * (pow (yq,
2
      2)-1)+pzq*(zq*yq);
      normalCilinder.z = pxq * (xq * zq) + pyq * (yq * zq)
3
     + pzq * (pow (zq, 2) - 1);
      normalCilinder = normalize (normalCilinder);
4
      return normalCilinder;
5
7 struct Intersection coneIntersection (struct Vector
      anchor, struct Vector direction, struct Object
      object)
8
      struct Intersection tempIntersect;
9
      tempIntersect.null = 0;
10
      long double xo = object.Xc;
11
      long double yo = object. Yc;
12
      long double zo = object.Zc;
13
```

```
long double xq = object.directionVector.x;
1
      long double yq = object.directionVector.y;
2
      long double zq = object.directionVector.z;
3
      long double xd = direction.x;
4
      long double vd = direction.v;
5
      long double zd = direction.z;
6
      long double k1 = object.K1;
7
      long double k2 = object.K2;
8
      long double xe = anchor.x;
9
      long double ye = anchor.y;
10
      long double ze = anchor.z;
11
      long double xdxq = xd * xq;
12
      long double vdvq = vd * vq;
13
```

```
long double zdzq = zd * zq;
      long double xexq = xe * xq;
2
      long double yeyq = ye * yq;
3
      long double zezq = ze * zq;
4
      long double xoxq = xo * xq;
5
      long double yoyq = yo * yq;
6
      long double zozq = zo * zq;
7
      long double coef1 = xdxq * xq + ydyq * xq + zdzq *
8
     xq - xd:
      long double coef2 = xdxq * yq + ydyq * yq + zdzq *
9
     yq - yd;
     long double coef3 = xdxq * zq + ydyq * zq + zdzq *
10
     za - zd:
      long double coef4 = xo + xexq * xq - xoxq * xq +
11
      yeyq * xq - yoyq * xq + zezq * xq - zozq * xq - xe;
      long double coef5 = yo + xexq * yq - xoxq * yq +
12
      yeyq * yq - yoyq * yq + zezq * yq - zozq * yq - ye;
      long double coef6 = zo + xexq * zq - xoxq * zq +
13
      yeyq * zq - yoyq * zq + zezq * zq - zozq * zq - ze;
```

```
long double coefk = pow (k2 / k1, 2);
1
      long double coef7 = xdxq + ydyq + zdzq;
2
      long double coef8 = xexq - xoxq + yeyq - yoyq +
3
      zezq - zozq;
      long double A = pow (coef1, 2) + pow (coef2, 2) + pow
4
       (coef3, 2)- (coefk * pow (coef7, 2));
      long double B = 2 * ((coef1 * coef4 + coef2 * coef5)
5
      + coef3 * coef6)- (coefk * coef7 * coef8));
      long double C = pow (coef4, 2) + pow (coef5, 2) + pow
6
       (coef6, 2)- (coefk * pow (coef8, 2));
      long double discriminant = pow (B, 2)- (4 * A * C);
7
      long double t, t1, t2;
8
      if (discriminant >= 0)
9
10
          long double root = sqrt (discriminant);
11
          B *= - 1:
12
          t1 = (B + root) / (2 * A);
13
```

```
t2 = (B - root) / (2 * A);
1
           long double Xi;
           long double Yi;
3
           long double Zi;
4
           long double d1 = object.D1;
5
           long double d2 = object.D2;
6
           if (t1 > e)
7
8
                if (t2 > e)
9
10
                    t = min(t1, t2);
11
                    Xi = xe + (t * xd);
12
                    Yi = ye + (t * yd);
13
```

```
Zi = ze + (t * zd);
1
                   if (d2 >= ((Xi - xo) * xq + (Yi - yo) *
      yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)*
      yq + (Zi - zo)*zq) >= d1)
3
                        tempIntersect.Xi = Xi;
4
                        tempIntersect.Yi = Yi;
5
                        tempIntersect.Zi = Zi;
6
                        tempIntersect.distance = t;
7
                        tempIntersect.object = object;
8
                        int accept = testIntersection (
9
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                        if (accept = 0)
11
                            t = max (t1, t2);
12
                            Xi = xe + (t * xd):
13
```

```
Yi = ye + (t * yd);
                           Zi = ze + (t * zd):
                           if (d2 >= ((Xi - xo) * xq + (Yi
3
      - yo)* yq + (Zi - zo)* zq) & ((Xi - xo)* xq + (Yi -
       yo)* yq + (Zi - zo)* zq)>= d1)
4
                                tempIntersect.Xi = Xi;
5
                                tempIntersect.Yi = Yi;
6
                                tempIntersect.Zi = Zi;
                                tempIntersect.distance = t;
                                tempIntersect.object =
9
      object;
                                int accept =
      testIntersection (tempIntersect.Xi, tempIntersect.
      Yi, tempIntersect.Zi, object);
                                if (accept = 0)
12
                                    tempIntersect.null = 1;
13
```

```
return tempIntersect;
2
                              else
5
                                   tempIntersect.null = 1;
6
                                   return tempIntersect;
8
9
                         return tempIntersect;
10
                     else
12
13
14
```

```
t = max (t1, t2);
                       Xi = xe + (t * xd);
2
                       Yi = ve + (t * vd):
                       Zi = ze + (t * zd);
4
                       if (d2 >= ((Xi - xo) * xq + (Yi - yo)
5
      * yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)
      * yq + (Zi - zo)* zq) >= d1)
6
                            tempIntersect.Xi = Xi;
7
                            tempIntersect.Yi = Yi;
8
                            tempIntersect.Zi = Zi;
9
                            tempIntersect.distance = t;
10
                            tempIntersect.object = object;
11
                            int accept = testIntersection (
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                            if (accept == 0)
14
15
```

```
tempIntersect.null = 1;
2
                              return tempIntersect;
                         else
6
                              tempIntersect.null = 1;
                              return tempIntersect;
8
9
10
                else
12
13
14
```

```
t = t1:
                   Xi = xe + (t * xd);
2
                   Yi = ve + (t * vd):
                   Zi = ze + (t * zd);
4
                   if (d2 >= ((Xi - xo) * xq + (Yi - yo) *
5
      yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)*
      yq + (Zi - zo)*zq) >= d1)
6
                        tempIntersect.Xi = Xi;
7
                        tempIntersect.Yi = Yi;
8
                        tempIntersect.Zi = Zi;
9
                        tempIntersect.distance = t;
10
                        tempIntersect.object = object;
11
                        int accept = testIntersection (
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                        if (accept == 0)
14
15
```

```
tempIntersect.null = 1;
2
                         return tempIntersect;
                    else
6
                         tempIntersect.null = 1;
                         return tempIntersect;
8
9
10
           else
12
13
14
```

```
if (t2 > e)
2
                   t = t2:
                   Xi = xe + (t * xd);
                   Yi = ye + (t * yd);
5
                   Zi = ze + (t * zd);
6
                   if (d2 >= ((Xi - xo) * xq + (Yi - yo) *
7
     yq + (Zi - zo)* zq) \& ((Xi - xo)* xq + (Yi - yo)*
      yq + (Zi - zo)*zq) >= d1)
8
                       tempIntersect.Xi = Xi;
9
                       tempIntersect.Yi = Yi;
                       tempIntersect.Zi = Zi;
                       tempIntersect.distance = t;
                       tempIntersect.object = object;
13
```

```
int accept = testIntersection (
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                        if (accept == 0)
2
3
                            tempIntersect.null = 1;
5
                        return tempIntersect;
6
                   else
8
9
                        tempIntersect.null = 1;
                        return tempIntersect;
13
```

```
else
1
                     tempIntersect.null = 1;
3
                     return tempIntersect;
5
6
       else
8
9
            tempIntersect.null = 1;
10
            return tempIntersect;
11
12
13
```

```
1 struct Vector coneNormal (struct Object object, struct
      Vector intersection Point)
2
      struct Vector normalCone:
3
      long double x = intersectionPoint.x;
4
      long double v = intersectionPoint.v;
5
      long double z = intersectionPoint.z;
6
      long double xo = object.Xc;
7
      long double yo = object. Yc;
8
      long double zo = object.Zc;
9
      long double xq = object.directionVector.x;
10
      long double yq = object.directionVector.y;
11
      long double zq = object.directionVector.z;
12
      long double k1 = object.K1;
13
```

```
long double k2 = object.K2;
1
      long double xxoxq = (x - xo) * xq;
2
      long double yyoyq = (y - yo)*yq;
3
      long double zzozq = (z - zo)*zq;
4
      long double parenth = (xxoxq + yyoyq + zzozq);
5
      long double pxq = 2 * (xo + parenth * xq - x);
6
      long double pyq = 2 * (yo + parenth * yq - y);
7
      long double pzq = 2 * (zo + parenth * zq - z);
8
      long double k1sq = pow(k1, 2);
9
      long double k2sq2 = 2 * pow (k2, 2);
10
      long double lastFactorDerivedX = (k2sq2 * xq *
      parenth)/ k1sq:
      long double lastFactorDerivedY = (k2sq2 * yq *
12
      parenth)/ k1sq:
      long double lastFactorDerivedZ = (k2sq2 * zq *
13
      parenth)/ k1sq;
```

```
normalCone.x = pxq * (pow (xq, 2)- 1)+ pyq * (yq *
      xq)+ pzq * (zq * xq)- lastFactorDerivedX;
      normalCone.y = pxq * (xq * yq) + pyq * (pow (yq, 2) -
2
       1)+ pzg * (zg * yg)- lastFactorDerivedY;
      normalCone.z = pxq * (xq * zq) + pyq * (yq * zq) +
3
      pzq * (pow (zq, 2)- 1)- lastFactorDerivedZ;
      normalCone = normalize (normalCone);
4
      return normalCone;
5
  long double whatsTheD (struct Object object)
8
      struct Point3D point = object.points3D[0];
9
      long double theD = - ((object.Xc * point.x)+ (
10
      object.Yc * point.y)+ (object.Zc * point.z));
      return theD:
11
12
  long double whatsTheDGeneral (struct Vector
      normalNotNormalized, struct Vector point)
14
```

```
long double theD = - ((normalNotNormalized.x *
      point.x)+ (normalNotNormalized.y * point.y)+ (
      normalNotNormalized.z * point.z));
      return theD;
2
3
  struct Object getABCD (struct Object object)
5
      struct Vector normal = polygonNormal (object);
6
      object.Xc = normal.x;
7
      object.Yc = normal.y;
8
      object.Zc = normal.z;
9
      object.other = whatsTheD (object);
10
      long double L = getNorm (normal);
11
      object.Xc /= L;
12
      object.Yc /= L;
13
```

```
object.Zc /= L;
      object.other /= L;
      return object;
3
5 struct Intersection discIntersection (struct Vector
      anchor, struct Vector direction, struct Object
      object)
6
      long double denominator = (direction.x * object.
7
      directionVector.x)+ (direction.y * object.
      directionVector.y)+ (direction.z * object.
      direction Vector.z);
      struct Intersection tempIntersect;
8
      tempIntersect.null = 1;
9
      if (denominator = 0)
10
          tempIntersect.null = 1;
12
          return tempIntersect;
13
```

```
else
          long double numerator = - ((anchor.x * object.
4
      directionVector.x)+ (anchor.y * object.
      directionVector.y)+ (anchor.z * object.
      directionVector.z)+ object.extraD);
          long double t = numerator / denominator;
5
          tempIntersect.distance = t;
6
          tempIntersect.object = object;
7
          tempIntersect.Xi = anchor.x + (t * direction.x)
8
          tempIntersect.Yi = anchor.y + (t * direction.y)
9
          tempIntersect.Zi = anchor.z + (t * direction.z)
10
          long double distanceToCenter = sqrt (pow (
      tempIntersect.Xi - object.Xc, 2) + pow (
      tempIntersect.Yi - object.Yc, 2) + pow (
```

```
tempIntersect.null = 0;
2
          int accept = testIntersection (tempIntersect.Xi
       tempIntersect. Yi, tempIntersect. Zi, object);
          if (accept = 0)
4
               tempIntersect.null = 1;
          return tempIntersect;
8
9
  struct Vector discNormal (struct Object object)
      return object.directionVector;
13
```

```
2 struct Intersection elipseIntersection (struct Vector
      anchor, struct Vector direction, struct Object
      object)
3
      long double denominator = (direction.x * object.
4
      directionVector.x)+ (direction.y * object.
      directionVector.y)+ (direction.z * object.
      direction Vector.z);
      struct Intersection tempIntersect;
5
      tempIntersect.null = 1;
6
      if (denominator == 0)
8
           tempIntersect.null = 1;
9
           return tempIntersect;
10
11
      else
12
13
14
```

2

3

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```
long double numerator = - ((anchor.x * object.
directionVector.x)+ (anchor.y * object.
directionVector.y)+ (anchor.z * object.
directionVector.z)+ object.extraD);
    long double t = numerator / denominator;
    tempIntersect.distance = t;
    tempIntersect.object = object;
    tempIntersect.Xi = anchor.x + (t * direction.x)
    tempIntersect.Yi = anchor.y + (t * direction.y)
    tempIntersect.Zi = anchor.z + (t * direction.z)
    long double distanceToD1 = sqrt (pow (
tempIntersect.Xi - object.Xc, 2) + pow (
tempIntersect.Yi - object.Yc, 2) + pow (
tempIntersect.Zi - object.Zc, 2));
    long double distanceToD2 = sqrt (pow (
tempIntersect.Xi - object.Xother, 2) + pow (
```

```
else
1
2
               tempIntersect.null = 1;
           int accept = testIntersection (tempIntersect.Xi
5
      , tempIntersect. Yi, tempIntersect. Zi, object);
           if (accept = 0)
6
7
               tempIntersect.null = 1;
8
9
           return tempIntersect;
10
12
  struct Vector elipseNormal (struct Object object)
14
15
```

```
return object.directionVector;
2
3 struct Intersection quadraticIntersection (struct
     Vector anchor, struct Vector direction, struct
     Object object)
4
     long double t, t1, t2;
5
     struct Intersection tempIntersect;
6
     tempIntersect.null = 0;
7
     long double a = (object.A * pow (direction.x, 2))+
8
     (object.B * pow (direction.y, 2))+ (object.C * pow
     (direction.z, 2)+2*((object.D*direction.x*)
     direction.y)* (object.E * direction.y * direction.z
     ) * (object.F * direction.x * direction.z));
     long double b = 2 * ((object.A * anchor.x *
9
     direction.x)+ (object.B * anchor.y * direction.y)+
     (object.C * anchor.z * direction.z)+ (object.D *
     anchor.x * direction.y)+ (object.D * anchor.y *
     direction.x)+ (object.E * anchor.y * direction.z)+
```

```
long double root = sqrt (discriminant);
          b *= -1:
2
          t1 = (b + root) / (2 * a);
          t2 = (b - root) / (2 * a);
           if (t1 > e)
5
               if (t2 > e)
7
                   t = min(t1, t2);
9
                   tempIntersect.distance = t;
                   tempIntersect.object = object;
                   tempIntersect.Xi = anchor.x + (t *
      direction .x);
                   tempIntersect.Yi = anchor.y + (t *
13
      direction.y);
```

2

3

5

6

7

8

9

10

```
tempIntersect.Zi = anchor.z + (t *
direction.z);
            int accept = testIntersection (
tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
Zi, object);
             if (accept = 0)
                t = max (t1, t2);
                 tempIntersect.distance = t;
                 tempIntersect.object = object;
                 tempIntersect.Xi = anchor.x + (t *
direction .x);
                 tempIntersect.Yi = anchor.y + (t *
direction.y);
                 tempIntersect.Zi = anchor.z + (t *
direction.z);
                 int accept = testIntersection (
tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
Zi, object);
```

2

5

7

8

9

10

12

```
tempIntersect.null = 1;
         else
             t = t1:
             tempIntersect.distance = t;
             tempIntersect.object = object;
             tempIntersect.Xi = anchor.x + (t *
direction .x);
             tempIntersect.Yi = anchor.y + (t *
direction.y);
             tempIntersect.Zi = anchor.z + (t *
direction.z);
             int accept = testIntersection (
tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
Zi, object);
```

```
if (accept == 0)
1
                         tempIntersect.null = 1;
3
5
6
           else
8
                if (t2 > e)
9
10
                    t = t2:
11
                    tempIntersect.distance = t;
12
                    tempIntersect.object = object;
13
```

```
tempIntersect.Xi = anchor.x + (t *
      direction.x);
                    tempIntersect.Yi = anchor.y + (t *
2
      direction.y);
                   tempIntersect.Zi = anchor.z + (t *
3
      direction.z);
                   int accept = testIntersection (
4
      tempIntersect.Xi, tempIntersect.Yi, tempIntersect.
      Zi, object);
                    if (accept == 0)
5
6
                        tempIntersect.null = 1;
7
8
9
               else
10
                    tempIntersect.null = 1;
12
13
```

```
return tempIntersect;
2
      else
5
          tempIntersect.null = 1;
6
          return tempIntersect;
7
8
9
  struct Vector quadraticNormal (struct Object object,
      struct Vector intersection Vector)
      long double xElement = ((object.A *
12
      intersectionVector.x)+(object.D*
      intersectionVector.y)+ (object.F *
      intersectionVector.z)+ (object.G));
      long double yElement = ((object.D *
13
      intersectionVector.x)+ (object.B *
      intersectionVector.y)+ (object.E *
```

```
long double zElement = ((object.F *
      intersectionVector.x)+(object.E*
      intersectionVector.y)+ (object.C *
      intersectionVector.z)+ (object.C));
      struct Vector normalNotNormalized =
2
3
          xElement, yElement, zElement
4
5
        };
      return normalNotNormalized;
6
7
  long double uRectangle (struct Vector x0y0z0, struct
      Vector x1y1z1, struct Vector xiyizi)
9
      struct Vector U:
10
      U.x = x1y1z1.x - x0y0z0.x;
11
      U.y = x1y1z1.y - x0y0z0.y;
12
      U.z = x1y1z1.z - x0y0z0.z;
13
```

```
struct Vector i0:
1
      i0.x = xiyizi.x - x0y0z0.x;
2
      i0.y = xiyizi.y - x0y0z0.y;
3
      i0.z = xiyizi.z - x0y0z0.z;
4
      long double H = getNorm(U);
5
      U = normalize (U);
6
      return pointProduct (i0, U)/H;
7
8
  long double vRectangle (struct Vector x0y0z0, struct
      Vector x3y3z3, struct Vector xiyizi)
10
    struct Vector V:
11
12
      V.x = x3y3z3.x - x0y0z0.x;
      V.v = x3v3z3.v - x0v0z0.v;
13
```

```
V.z = x3y3z3.z - x0y0z0.z;
1
      struct Vector i0:
2
      i0.x = xiyizi.x - x0y0z0.x;
3
      i0.y = xiyizi.y - x0y0z0.y;
4
      i0.z = xiyizi.z - x0y0z0.z;
5
      long double L = getNorm(V);
6
      V = normalize (V);
7
      return pointProduct (i0, V)/L;
8
9
  struct Color planeTexture (struct Intersection in,
      struct Vector normal)
11
      struct Object object = in.object;
12
      struct Vector ipoint;
13
```

```
ipoint.x = in.Xi;
1
      ipoint.y = in.Yi;
2
      ipoint.z = in.Zi;
3
      long double u = uRectangle (object.x0y0z0, object.
4
      \times 1y1z1, ipoint);
      long double v = vRectangle (object.x0y0z0, object.
5
      x3y3z3, ipoint);
      struct Color color;
6
      for (int i = 0; i < object.numberTextures; i ++)
7
8
           int xs = object.textures[i].hRes * u;
9
           int ys = object.textures[i].vRes * v;
10
           color = object.textures[i].textureMap[xs][ys];
11
12
      return color:
13
```

```
2 long double uCylinder (struct Vector anchor, struct
      Vector Q, struct Vector normal, struct Vector
      greenwich, struct Vector xiyizi)
3
      long double tempu = acos (pointProduct (normal,
4
      greenwich))/ (2 * 3.14159265);
      struct Vector darkSide = crossProduct (Q, greenwich
5
      );
      long double d = whatsTheDGeneral (darkSide, anchor)
6
      long double test = darkSide.x * xiyizi.x + darkSide
7
      .y * xiyizi.y + darkSide.z * xiyizi.z + d;
      if (test < 0)
8
g
          tempu = 1 - tempu;
10
11
12
      return tempu;
13
```

```
1 long double vCylinder (struct Vector anchor, struct
      Vector Q, struct Vector xiyizi, long double den)
2
      struct Vector i0:
3
      i0.x = xiyizi.x - anchor.x;
4
      i0.y = xiyizi.y - anchor.y;
5
      i0.z = xiyizi.z - anchor.z;
6
      return pointProduct (Q, i0)/den;
7
 struct Color cylinderTexture (struct Intersection in,
      struct Vector normal)
10
      struct Object object = in.object;
11
      struct Vector gw = object.textures[0].greenwich;
12
      struct Vector ipoint;
13
```

```
ipoint.x = in.Xi;
      ipoint.y = in.Yi;
      ipoint.z = in.Zi;
      struct Vector anchor:
4
      anchor.x = object.Xc;
5
      anchor.v = object.Yc;
6
      anchor.z = object.Zc;
7
      long double u = uCylinder (anchor, object.
8
      direction Vector, normal, gw, ipoint);
      long double v = vCylinder (anchor, object.
9
      direction Vector, ipoint, object.D2 - object.D1);
      struct Color color:
10
      for (int i = 0; i < object.numberTextures; i ++)
11
12
          int xs = object.textures[i].hRes * u;
13
```

```
int ys = object.textures[i].vRes * v;
           color = object.textures[i].textureMap[xs][ys];
2
3
      return color;
5
  long double uSphere (struct Vector center, struct
      Vector north, long double radius, struct Vector
      xivizi, struct Vector greenwich)
7
      struct Vector ic:
8
      ic.x = xiyizi.x - center.x;
      ic.y = xiyizi.y - center.y;
10
      ic.z = xiyizi.z - center.z;
11
      long double icnorth = pointProduct (north, ic);
12
      struct Vector inprime;
13
```

```
inprime.x = xiyizi.x - north.x * icnorth;
      inprime.y = xiyizi.y - north.y * icnorth;
2
      inprime.z = xiyizi.z - north.z * icnorth;
3
      struct Vector nprime;
4
      nprime.x = inprime.x - center.x;
5
      nprime.v = inprime.v - center.v;
6
      nprime.z = inprime.z - center.z;
7
      nprime = normalize (nprime);
8
      long double tempu = acos (pointProduct (nprime,
9
      greenwich))/ (2 * 3.14159265);
      struct Vector darkSide = crossProduct (north.
10
      greenwich);
      long double d = whatsTheDGeneral (darkSide, center)
11
      long double test = darkSide.x * xiyizi.x + darkSide
12
      .y * xiyizi.y + darkSide.z * xiyizi.z + d;
      if (test < 0)
13
14
15
```

```
tempu = 1 - tempu;
2
      return tempu;
3
  long double vSphere (struct Vector center, struct
      Vector north, long double radius, struct Vector
      xiyizi)
6
      struct Vector south:
7
      south.x = center.x - radius * north.x;
8
      south.y = center.y - radius * north.y;
9
      south.z = center.z - radius * north.z;
10
      struct Vector i0:
      i0.x = xiyizi.x - south.x;
12
      i0.y = xiyizi.y - south.y;
13
```

```
i0.z = xiyizi.z - south.z;
1
      return pointProduct (north, i0)/ (2 * radius);
2
3
4 struct Color sphereTexture (struct Intersection in,
      struct Vector normal)
5
      struct Object object = in.object;
6
      struct Vector gw = object.textures[0].greenwich;
7
      struct Vector north = object.textures[0].north;
8
      struct Vector ipoint;
9
      ipoint.x = in.Xi;
10
      ipoint.y = in.Yi;
11
      ipoint.z = in.Zi;
12
      struct Vector center;
13
```

```
center.x = object.Xc;
1
      center.y = object.Yc;
2
      center.z = object.Zc;
3
      long double u = uSphere (center, north, object.
4
      other, ipoint, gw);
      long double v = vSphere (center, north, object.
5
      other, ipoint);
      struct Color color:
6
      for (int i = 0; i < object.numberTextures; i ++)
7
8
          int xs = object.textures[i].hRes * u;
9
          int ys = object.textures[i].vRes * v;
10
           color = object.textures[i].textureMap[xs][ys];
12
      return color:
13
```

```
2 long double uCone (struct Vector anchor, struct Vector
     Q, struct Vector normal, struct Vector greenwich,
      struct Vector xiyizi)
3
      struct Vector aux = crossProduct (normal, Q);
4
      struct Vector nprime = crossProduct (aux, Q);
5
      long double tempu = acos (pointProduct (nprime,
6
      greenwich))/ (2 * 3.14159265);
      struct Vector darkSide = crossProduct (Q, greenwich
7
      );
      long double d = whatsTheDGeneral (darkSide, anchor)
8
      long double test = darkSide.x * xiyizi.x + darkSide
9
      .y * xiyizi.y + darkSide.z * xiyizi.z + d;
      if (test < 0)
10
11
          tempu = 1 - tempu;
12
13
```

```
return tempu;
3 struct Color coneTexture (struct Intersection in,
      struct Vector normal)
4
      struct Object object = in.object;
5
      struct Vector gw = object.textures[0].greenwich;
6
      struct Vector ipoint;
7
       ipoint.x = in.Xi;
8
       ipoint.y = in.Yi;
9
       ipoint.z = in.Zi;
10
      struct Vector anchor;
11
      anchor.x = object.Xc;
12
      anchor.y = object.Yc;
13
```

```
anchor.z = object.Zc;
      long double u = uCone (anchor, object.
      direction Vector, normal, gw, ipoint);
      long double v = vCylinder (anchor, object.
3
      direction Vector, ipoint, object.D2 - object.D1);
      struct Color color:
4
      for (int i = 0; i < object.numberTextures; i ++)
5
6
          int xs = object.textures[i].hRes * u;
7
          int ys = object.textures[i].vRes * v;
8
           color = object.textures[i].textureMap[xs][ys];
9
10
      return color;
11
12
13 struct Intersection getFirstIntersection (struct Vector
       anchor, struct Vector direction)
14
15
```

```
rays += 1;
      int k:
      int objectsAmount = numberObjects;
      long double tmin;
4
      struct Intersection intersection;
5
      struct Intersection tempIntersection;
6
      intersection.null = 1;
7
      tmin = 10000000:
8
      tempIntersection.null = 1;
9
      for (k = 0 ; k < objectsAmount ; k ++)
10
11
          tempIntersection = Objects[k].
      intersection Funcion (anchor, direction, Objects [k])
           if (tempIntersection.null != 1 &&
      tempIntersection.distance > e && tempIntersection.
      distance < tmin)
14
15
```

```
tmin = tempIntersection.distance;
               intersection = tempIntersection;
3
          tempIntersection.null = 1;
4
5
      return intersection;
6
7
8 struct Color ponderColor (struct Color baseColor,
      struct Color reflectionColor, long double o1, long
      double o2)
9
      struct Color color:
10
      color.r = baseColor.r * o1 + reflectionColor.r * o2
11
      color.g = baseColor.g * o1 + reflectionColor.g * o2
12
      color.b = baseColor.b * o1 + reflectionColor.b * o2
13
```

```
return color;
2
struct Color getColor (struct Vector anchor, struct
      Vector direction, struct Vector V, int rLevel)
4
      struct Color color;
5
      struct Intersection intersection;
6
7
      struct Intersection * tempIntersection;
      intersection = getFirstIntersection (anchor,
8
      direction);
      if (intersection.null == 1)
9
10
           color = background;
12
      else
13
14
15
```

```
int k;
          int lightsAmount = numberLights;
          struct Object Q = intersection.object;
          struct Vector L:
          struct Vector intersectVector =
5
6
               intersection. Xi, intersection. Yi,
7
      intersection.Zi
          struct Vector N = normalize (Q. normalVector (Q,
9
       intersectVector));
          struct Vector R:
          if (pointProduct (N, direction)> 0)
              N.x *= -1:
13
```

```
N.v *= -1:
              N.z *= -1:
2
          long double Fatt;
          long double I = 0.0;
5
          long double E = 0.0;
6
          for (k = 0 ; k < number Lights ; k ++)
7
               struct Intersection obstacle;
9
               struct Vector light =
                   Lights[k].Xp - intersection.Xi, Lights[
12
      k]. Yp - intersection. Yi, Lights [k]. Zp -
      intersection.Zi
                 };
```

3

4

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13

```
L = light;
        L = normalize (light);
        long double pp = pointProduct (N, L);
        obstacle = getFirstIntersection (
intersectVector, L);
        long double distanceToLight = getNorm (
light);
         if (obstacle.null = 1 \mid \mid (obstacle.
distance > e && obstacle.distance > distanceToLight
))
             Fatt = getAttenuationFactor (Lights[k],
 distanceToLight);
             if (pp > 0.0)
                 R.x = (2 * N.x * pp) - L.x;
                 R.y = (2 * N.y * pp) - L.y;
                 R.z = (2 * N.z * pp) - L.z;
```

```
R = normalize (R);
1
                       I = I + (pp * Q.Kd * Fatt * Lights[
2
      k].lp);
3
                   long double pp2 = pointProduct(R, V);
4
                   if (pp2 > 0.0)
5
6
                       E = E + (pow (pp2, Q.Kn)* Q.Ks *
7
      Lights[k].lp * Fatt);
8
9
           if (Q.numberTextures != 0)
               color = Q.retrieveTextureColor (
13
      intersection, N);
```

```
1
           else
                color = Q.color;
4
5
           if (isnan (color.r))
6
7
                color = Q.color;
8
9
           I = I + Ia * Q.Ka;
10
           I = \min (1.0, I);
11
           color = difusseColor (I, color);
12
           E = \min (1.0, E);
13
```

```
color = specularHighlight (E, color);
           if (rLevel > 0)
2
               long double pNV = pointProduct(N, V);
4
               R.x = (2 * N.x * pNV) - V.x;
               R.v = (2 * N.v * pNV) - V.v;
6
               R.z = (2 * N.z * pNV) - V.z;
               R = normalize (R);
8
               struct Vector otherV =
9
10
                  -R.x.-R.y.-R.z
12
               struct Color reflectionColor = getColor (
13
      intersect Vector, R. other V. rLevel - 1);
```

2

4

5

6

7

8

9

10

12 13

```
color = ponderColor (color, reflectionColor
, Q.o1, Q.o2);
    struct Color transparencyColor = background;
    int levelsAllowed = maxTransparency;
    while (levels Allowed > 0 && intersection.object
.03 > 0)
        transparencyColor = getColor (
intersect Vector, direction, V, maxReflection);
        levelsAllowed --:
        if (transparencyColor.r == background.r &&
transparencyColor.g == background.g &&
transparencyColor.b = background.b
            break:
```

```
color = ponderColor (color, transparencyColor,
1
      1, intersection.object.o3);
2
       return (color);
3
4
  void printPlaneCuts (struct Object objeto)
6
       if (objeto.planeCuts == NULL)
7
8
           printf ("\n Este objeto no tiene planos de
g
      corte asociados. \n");
10
           return:
      else
12
13
14
```

```
int i = 0:
          struct Vector normal:
          struct Vector punto;
          for (i = 0 ; i < objeto.numberPlaneCuts ; i ++)
5
               printf ("Plano %i: \n", i);
               normal = objeto.planeCuts[i].normal;
               punto = objeto.planeCuts[i].point;
8
               printf ("\t Normal unitaria: %LF, %LF, %LF
9
      \n", normal.x, normal.y, normal.z);
               printf ("\t Punto base: %LF, %LF, %LF \n\n"
      , punto.x, punto.y, punto.z);
13
```

```
void printTextures (struct Object objeto, int
      currentTypeObjectReading)
2
      if (objeto.textures = NULL)
4
           printf ("\n Este objeto no tiene texturas
5
      asociados. \n");
           return;
6
7
      else
8
9
          int i = 0:
10
           struct Vector norte;
11
          struct Vector greenwich;
12
          for (i = 0; i < objeto.numberTextures; i ++)
13
14
15
```

2

3

4

5

6

7

8

9

```
printf ("Textura %i: \n", i);
         printf ("Resoluci n Textura: %ix%i \n",
objeto.textures[i].hRes, objeto.textures[i].vRes);
         printf ("Primer texel de la textura: (%LF,
%LF, %LF)", objeto.textures[i].textureMap[0][0].r *
 255, objeto.textures[i].textureMap[0][0].g * 255,
objeto.textures[i].textureMap[0][0].b * 255);
        int last X = objeto.textures[i].hRes - 1;
        int lastY = objeto.textures[i].vRes - 1;
         printf (" Itimo texel de la textura: (%LF,
%LF, %LF)", objeto.textures[i].textureMap[lastX][
lastY ].r * 255, objeto.textures[i].textureMap[lastX
[[lastY].g * 255, objeto.textures[i].textureMap[
lastX | [lastY ].b * 255);
        for (int f = 0; f < objeto.textures[i].
hRes ; f ++)
            for (int j = 0 ; j < objeto.textures[i</pre>
].vRes ; j ++)
```

2

4

5

6

7

8

9

```
if (currentTypeObjectReading = 2 | |
currentTypeObjectReading == 4
currentTypeObjectReading == 5 \mid
currentTypeObjectReading == 8)
             greenwich = objeto.textures[i].
greenwich;
             printf ("\t Greenwich unitario: %LF, %
LF, %LF \n", greenwich.x, greenwich.y, greenwich.z)
             if (currentTypeObjectReading = 2 | |
currentTypeObjectReading == 8)
                 norte = objeto.textures[i].north;
                 printf ("\t Norte unitario: %LF, %
LF, %LF \n", norte.x, norte.y, norte.z);
```

```
void printDraftPlanes (struct Object objeto, int
      currentTypeObjectReading)
2
       if (objeto.draftPlanes = NULL)
3
4
           printf ("\n Este objeto no tiene planos de
5
      calado asociados. \n");
          return;
6
7
       else
8
9
          int i = 0:
10
           struct Vector norte;
11
           struct Vector greenwich;
12
           for (i = 0; i < objeto.numberDraftPlanes; i
13
      ++)
14
15
```

3

4

5

6

7

8

```
printf ("N mero de planos de calado: %i \n
", objeto.numberDraftPlanes);
        printf ("plano de calado %i: \n", i);
        printf ("Resoluci n plano de calado: %ix%i
\n", objeto.draftPlanes[i].hRes, objeto.
draftPlanes[i].vRes);
        printf ("Primer texel del plano de calado:
(%LF, %LF, %LF)", objeto.draftPlanes[i].textureMap
[0][0].r, objeto.draftPlanes[i].textureMap[0][0].g
* 255, objeto.draftPlanes[i].textureMap[0][0].b *
255):
        int lastX = objeto.draftPlanes[i].hRes - 1;
        int lastY = objeto.draftPlanes[i].vRes -1;
        printf (" Itimo texel del plano de calado:
(%LF, %LF, %LF)", objeto.draftPlanes[i].textureMap
[lastX][lastY].r * 255, objeto.draftPlanes[i].
textureMap[lastX][lastY].g * 255, objeto.
draftPlanes[i].textureMap[lastX][lastY].b * 255);
```

Analizador Léxico

```
norte = objeto.draftPlanes[i].north;
                   printf ("\t Norte unitario: %LF, %LF, %
2
      LF \n", norte.x, norte.y, norte.z);
3
4
5
7 void createObjectFromData (long double * data, int
      whichObjectCreate, int quantityData, struct
      PlaneCut * planeCutsFound, struct Texture *
      texturesFound, struct DraftPlane * draftPlanesFound
      , int numberPlaneCuts, int numberTextures, int
      numberDraftPlanes)
8
      switch (whichObjectCreate)
9
10
          case 0:
11
12
               if (debug = 1)
13
```

```
printf ("Insertando datos de escena \n"
     );
                  printf ("Reflexiones: %LF,
2
     Transparencia: %LF, Anti-aliasing: %LF \n", data
     [0], data[1], data[2]);
                  printf ("Iluminaci n ambiente: %LF \n"
3
     , data[3]);
                  printf ("Plano de proyecci n (Xmin,
4
     Ymin) (Xmax, Ymax) : (%LF, %LF) (%LF, %LF) \n",
     data[4], data[5], data[6], data[7]);
                  printf ("Resolucin: %LFx%LF\n",
5
     data[8], data[9]);
                  printf ("Epsilon %LF \n", data[10]);
6
                  printf ("Ojo: (%LF, %LF, %LF) \n", data
7
     [11], data[12], data[13]);
                  printf ("Color background: (%LF, %LF, %
8
     LF) \n", data[14], data[15], data[16]);
9
              maxAA \,=\, data \,[\,0\,]\,;
```

```
Xmin = data[4];
1
               Ymin = data[5];
2
               Xmax = data[6];
               Ymax = data[7];
4
               Hres = data[8];
5
               Vres = data[9];
6
               e = data[10];
7
                eye.x = data[11];
8
                eye.y = data[12];
9
                eye.z = data[13];
10
                background.r = data[14];
11
                background.g = data[15];
12
                background.b = data[16];
13
```

```
Framebuffer [Hres] [Vres];
               Framebuffer = (struct Color * *) malloc (
2
      Vres * sizeof (struct Color *));
               for (int i = 0; i < Vres; i ++)
3
4
                   Framebuffer[i] = (struct Color *) malloc
5
       (Hres * sizeof (struct Color));
6
               return:
7
8
           case 1:
9
               if (debug = 1)
                   printf ("Insertando Luz...\n");
13
```

```
printf ("Pos luz (%LF, %LF, %LF) \n",
      data[0], data[1], data[2]);
                    printf ("c1: %LF, c2: %LF, c3 %LF \n",
      data[3], data[4], data[5]);
                    printf ("lp luz: LF \setminus n", data[6]);
3
4
               struct Object polygon;
5
               struct Color colorPolygon;
6
               struct Light luz;
7
               luz.Xp = data[0];
8
                luz.Yp = data[1];
9
               luz.Zp = data[2];
10
                luz.c1 = data[3];
11
                luz.c2 = data[4]:
12
                luz.c3 = data[5];
13
```

```
luz.lp = data[6];
1
               Lights[lightIndex] = luz;
2
               lightIndex ++;
3
               return:
4
5
          case 2:
6
7
               if (debug = 1)
8
9
                   printf ("Insertando Esfera...");
10
                   printf ("Pos esfera (%LF, %LF, %LF) \n"
11
      , data[0], data[1], data[2]);
                   printf ("o1: %LF, o2: %LF, o3: %LF \n"
      , data[3], data[4], data[5]);
                   printf ("Radio esfera: %LF \n", data
      [6]);
```

```
printf ("Esfera Kd: %LF \n", data[6]);
                   printf ("Esfera Ka: %LF \n", data[8]);
2
                   printf ("Esfera Kn: %LF \n", data[9]);
3
                   printf ("Esfera Ks: %LF \n", data[10]);
4
                   printf ("Color esfera (%LF, %LF, %LF) \
5
      n", data[11], data[12], data[13]);
6
               struct Object polygon;
7
               struct Color colorPolygon;
8
               struct Object esfera;
9
               esfera.Xc = data[0];
10
               esfera.Yc = data[1];
11
               esfera.Zc = data[2];
12
               esfera.o1 = data[3]:
13
```

```
esfera.o2 = data[4];
               esfera.o3 = data[5];
               esfera.other = data[6];
               esfera.Kd = data[7];
               esfera.Ka = data[8];
5
               esfera.Kn = data[9];
               esfera.Ks = data[10];
               esfera.normalVector = sphereNormal;
               esfera.intersectionFuncion =
9
      sphereIntersection;
               esfera.retrieveTextureColor = sphereTexture
               struct Color colorSphere;
11
               colorSphere.r = data[11];
               colorSphere.g = data[12];
13
```

```
colorSphere.b = data[13];
              esfera.color = colorSphere;
2
              esfera.planeCuts = planeCutsFound;
              esfera.numberPlaneCuts = numberPlaneCuts:
4
              esfera.textures = texturesFound;
              esfera.numberTextures = numberTextures;
6
              Objects[objectIndex] = esfera;
              if (debug == 1)
8
9
                  printPlaneCuts (Objects[objectIndex]);
                  printTextures (Objects[objectIndex],
     whichObjectCreate);
              objectIndex ++:
```

```
return;
          case 3:
3
4
               int vertexPolygonIndex = 0;
5
               int numVertexesPolygon = (quantityData - 10)
6
      -12)/3+1:
               int inicio Plano = 10 + (num Vertexes Polygon)
7
     -1)*3;
               if (debug = 1)
8
9
                   printf ("quantityData: %i \n",
      quantity Data);
                   printf ("numVertexesPolygon: %i \n",
11
      numVertexesPolygon);
                   printf ("%i inicioPlano \n",
12
      inicioPlano);
                   printf ("Insertando pol gono...");
13
```

```
printf ("Color pol gono (%LF, %LF, %LF
     ) \n", data[0], data[1], data[2]);
                  printf ("o1: %LF, o2: %LF, o3: %LF \n"
2
      data[3], data[4], data[5]);
                  printf ("Poligono Kd: %LF \n", data[6])
3
                  printf ("Poligono Ka: %LF \n", data[7])
4
                  printf ("Poligono Kn: %LF \n", data[8])
5
                  printf ("Poligono Ks: %LF \n", data[9])
6
                  printf ("Esquina inferior izquierda (%
7
     LF, %LF, %LF) \n", data[inicioPlano], data[
     inicioPlano + 1, data[inicioPlano + 2]);
                  printf ("Esquina inferior derecha (%LF,
8
      %LF, %LF) \n", data[inicioPlano + 3], data[
     inicioPlano + 4], data[inicioPlano + 5]);
                  printf ("Esquina superior derecha (%LF,
9
```

```
struct Object temp;
1
               struct Vector x0v0z0;
2
               x0y0z0.x = data[inicioPlano];
               x0y0z0.y = data[inicioPlano + 1];
4
               x0y0z0.z = data[inicioPlano + 2];
5
               struct Vector x1y1z1;
6
               x1y1z1.x = data[inicioPlano + 3];
7
               x1y1z1.y = data[inicioPlano + 4];
8
               x1y1z1.z = data[inicioPlano + 5];
9
               struct Vector x2y2z2;
10
               x2y2z2.x = data[inicioPlano + 6];
11
               x2y2z2.y = data[inicioPlano + 7];
12
               x2y2z2.z = data[inicioPlano + 8];
13
```

```
struct Vector x3y3z3;
               x3y3z3.x = data[inicioPlano + 9];
2
               x3y3z3.y = data[inicioPlano + 10];
               x3y3z3.z = data[inicioPlano + 11];
4
               temp.points3D = malloc (size of (struct))
5
      Point3D) * 3);
               for (int i = 0; i + 10 < quantityData - 12
6
       ;)
7
                   if (vertexPolygonIndex == 3)
8
9
                        break:
                   vertex.x = data[10 + i];
12
                   i ++:
13
```

```
vertex.y = data[10 + i];
                   i ++:
2
                   vertex.z = data[10 + i];
                   i ++
4
                   temp.points3D[vertexPolygonIndex] =
5
      vertex:
                   vertexPolygonIndex ++;
6
7
               struct Object polygon;
8
               vertexPolygonIndex = 0;
9
               polygon = getABCD (temp);
               if (debug = 1)
12
                   printf ("A del poligono %LF\n", polygon
13
      .Xc);
```

```
printf ("B del poligono %LF\n", polygon
      .Yc);
                   printf ("C del poligono %LF\n", polygon
2
      .Zc);
                   printf ("D del poligono %LF\n", polygon
3
      .other);
4
               polygon.points3D = malloc (size of (struct))
5
      Point3D) * numVertexesPolygon);
               polygon.points2D = malloc (sizeof (struct
6
      Point2D) * numVertexesPolygon);
               struct Color colorPolygon;
7
               colorPolygon.r = data[0];
8
               colorPolygon.g = data[1];
9
               colorPolygon.b = data[2];
10
               polygon.color = colorPolygon;
               polygon.o1 = data[3];
12
               polygon.o2 = data[4];
13
```

```
polygon.o3 = data[5];
               polygon.Kd = data[6];
2
               polygon.Ka = data[7];
3
               polygon.Kn = data[8];
               polygon.Ks = data[9];
5
               polygon.pointAmount = numVertexesPolygon;
6
               polygon.normalVector = polygonNormal;
7
               polygon.intersectionFuncion =
8
      polygonIntersection;
               polygon.retrieveTextureColor = planeTexture
9
               long double u:
10
               long double v;
               long double maxA_B = max (fabs (polygon.Xc)
12
      , fabs (polygon.Yc));
               long double maxA_B_C = max (maxA_B, fabs (
      polygon.Zc));
```

```
int choice = 0:
1
                if (maxA_B_C = fabs (polygon.Xc))
3
                    choice = 0:
4
5
                else if (maxA_B_C = fabs (polygon.Yc))
6
7
                    choice = 1:
8
9
               else if (maxA_B_C = fabs (polygon.Zc))
10
11
                    choice = 2;
12
13
```

```
for (int i = 0; i + 10 < quantityData - 12
1
       ;)
2
                    vertex.x = data[10 + i];
3
                    i ++:
4
                    vertex.y = data[10 + i];
5
                    i ++:
6
                    vertex.z = data[10 + i];
7
                    i ++:
8
                    if (debug = 1)
9
10
                        printf ("Vertice: (%LF,%LF,%LF) \n"
        vertex.x, vertex.y, vertex.z);
12
                    if (choice == 0)
13
14
15
```

```
u = vertex.z;
1
                         v = vertex.y;
3
                     else if (choice == 1)
4
5
                         u = vertex.x;
6
                         v = vertex.z;
7
8
                     else if (choice = 2)
9
10
                         u = vertex.x;
11
                         v = vertex.y;
12
13
```

```
squashedVertex.u = u;
                   squashedVertex.v = v;
2
                   polygon.points3D[vertexPolygonIndex] =
      vertex:
                   polygon.points2D[vertexPolygonIndex] =
4
      squashed Vertex;
                   vertexPolygonIndex ++;
5
6
               vertex.x = data[10];
7
               vertex.y = data[11];
8
               vertex.z = data[12];
9
               if (choice == 0)
                   u = vertex.z;
                   v = vertex.y;
13
```

```
1
                else if (choice == 1)
3
                    u = vertex.x;
4
5
                    v = vertex.z;
6
                else if (choice = 2)
8
                    u = vertex.x;
9
                    v = vertex.y;
10
11
                squashedVertex.u = u;
12
                squashedVertex.v = v;
13
```

```
polygon.points3D[vertexPolygonIndex] =
      vertex:
               polygon.points2D[vertexPolygonIndex] =
2
      squashed Vertex:
               polygon.planeCuts = planeCutsFound;
3
               polygon.numberPlaneCuts = numberPlaneCuts;
4
               polygon.textures = texturesFound;
5
               polygon.numberTextures = numberTextures;
6
               polygon.x0y0z0 = x0y0z0;
               polygon.x1y1z1 = x1y1z1;
8
               polygon.x2y2z2 = x2y2z2;
9
               polygon.x3y3z3 = x3y3z3;
10
               Objects[objectIndex] = polygon;
               if (debug = 1)
12
13
14
```

```
printPlaneCuts (Objects[objectIndex]);
1
                   printTextures (Objects[objectIndex],
2
      whichObjectCreate);
3
               objectIndex ++;
4
               return:
5
6
          case 4:
7
               if (debug = 1)
9
                   printf ("Insertando cilindro...");
                   printf ("Ancla: (%LF, %LF, %LF) \n",
12
      data[0], data[1], data[2]);
                   printf ("Vector: (%LF, %LF, %LF) \n",
      data[3], data[4], data[5]);
```

```
printf ("o1: %LF, o2: %LF, o3: %LF \n"
      , data[6], data[7], data[8]);
                   printf ("Cilindro Radio: %LF \n", data
2
      [9]);
                   printf ("Cilindro d1: %LF Cilindro d2:
3
     %LF \n", data[10], data[11]);
                   printf ("Cilindro Kd: %LF \n", data
4
      [12]);
                   printf ("Cilindro Ka: %LF \n", data
5
      [13]);
                   printf ("Cilindro Kn: %LF \n", data
6
      [14]);
                   printf ("Cilindro Ks: %LF \n", data
7
      [15]);
                   printf ("RGB Cilindro: (%LF, %LF, %LF)
8
      \n", data[16], data[17], data[18]);
9
               struct Object cilinder;
10
               cilinder.Xc = data[0];
```

```
struct Vector cilinder Vector:
               cilinderVector.x = data[3];
2
               cilinderVector.y = data[4];
3
               cilinderVector.z = data[5];
4
               cilinderVector = normalize (cilinderVector)
5
               cilinder.directionVector = cilinderVector;
6
               cilinder.o1 = data[6]:
7
               cilinder.o2 = data[7];
8
               cilinder.o3 = data[8];
9
               cilinder.other = data[9];
10
               cilinder.D1 = data[10];
11
               cilinder.D2 = data[11];
12
               cilinder.Kd = data[12];
13
```

```
cilinder.Ka = data[13];
1
               cilinder.Kn = data[14];
2
               cilinder.Ks = data[15];
3
               cilinder.height = cilinder.D2 - cilinder.D1
               cilinder.normalVector = cilinderNormal;
5
               cilinder.intersectionFuncion =
6
      cilinderIntersection:
               cilinder.retrieveTextureColor =
7
      cylinderTexture;
               struct Color cilinderColor;
8
               cilinderColor.r = data[16];
9
               cilinderColor.g = data[17];
10
               cilinderColor.b = data[18];
11
               cilinder.color = cilinderColor:
12
               cilinder.planeCuts = planeCutsFound;
13
```

```
cilinder.numberPlaneCuts = numberPlaneCuts;
1
               cilinder.textures = texturesFound;
2
               cilinder.numberTextures = numberTextures:
3
               Objects [objectIndex] = cilinder;
               if (debug = 1)
5
6
                    printPlaneCuts (Objects[objectIndex]);
7
                    printTextures (Objects[objectIndex],
8
      whichObjectCreate);
9
               objectIndex ++;
11
               return:
12
          case 5:
13
14
15
```

2

3

4

5

6

7

8

9

10

11

12

13

```
if (debug == 1)
             printf ("Insertando cono...");
             printf ("Ancla: (%LF, %LF, %LF) \n",
data[0], data[1], data[2]);
             printf ("Vector: (%LF, %LF, %LF) \n",
data[3], data[4], data[5]);
             printf ("o1: %LF, o2: %LF, o3: %LF \n"
, data[6], data[7], data[8]);
             printf ("Cono k1: %LF COno k2: %LF \n",
data[9], data[10]);
             printf ("Cono d1: %LF COno d2: %LF \n",
data[11], data[12]);
             printf ("Cono Kd: \%LF \setminus n", data[13]);
             printf ("Cono Ka: %LF \n", data[14]);
             printf ("Cono Kn: %LF \n", data[15]);
             printf ("Cono Ks: %LF \n", data[16]);
             printf ("RGB Cono: (%LF, %LF, %LF) \n",
data[17], data[18], data[19]);
```

```
1
               struct Object cone;
               cone.Xc = data[0];
               cone.Yc = data[1];
               cone.Zc = data[2];
5
               struct Vector coneVector;
               coneVector.x = data[3];
               coneVector.y = data[4];
               coneVector.z = data[5];
9
               coneVector = normalize (coneVector);
10
               cone.directionVector = coneVector;
11
               cone.o1 = data[6];
12
               cone.o2 = data[7];
13
```

```
cone.o3 = data[8];
               cone.K1 = data[9];
2
               cone.K2 = data[10];
               cone.D1 = data[11];
               cone.D2 = data[12];
               cone.height = cone.D2 - cone.D1;
               cone.Kd = data[13];
               cone.Ka = data[14];
8
               cone.Kn = data[15];
9
               cone.Ks = data[16];
               cone.intersectionFuncion = coneIntersection
               cone.retrieveTextureColor = coneTexture;
               cone.normalVector = coneNormal;
13
```

```
struct Color coneColor:
1
               coneColor.r = data[17];
               coneColor.g = data[18];
               coneColor.b = data[19];
               cone.color = coneColor;
               cone.planeCuts = planeCutsFound;
               cone.numberPlaneCuts = numberPlaneCuts:
               cone.textures = texturesFound;
               cone.numberTextures = numberTextures;
9
               Objects [objectIndex] = cone;
               if (debug = 1)
11
                   printPlaneCuts (Objects[objectIndex]);
13
```

```
printTextures (Objects[objectIndex],
      whichObjectCreate);
2
               objectIndex ++;
               return;
4
5
          case 6:
6
               if (debug = 1)
8
9
                   printf ("Insertando disco...");
10
                   printf ("Punto Central: (%LF, %LF, %LF)
       \n", data[0], data[1], data[2]);
                   printf ("Normal: (%LF, %LF, %LF) \n",
12
      data[3], data[4], data[5]);
                   printf ("Color: (%LF, %LF, %LF) \n",
      data[6], data[7], data[8]);
```

```
printf ("Disco Radio: %LF \n", data[9])
                   printf ("o1: %LF, o2: %LF, o3: %LF \n"
2
       data[10], data[11], data[12]);
                   printf ("Dlsco Kd: LF \setminus n", data[13]);
3
                   printf ("DIsco Ka: %LF \n", data[14]);
4
                   printf ("DIsco Kn: %LF \n", data[15]);
5
                   printf ("Disco Ks: %LF \n", data[16]);
6
                   printf ("Esquina inferior izquierda (%
7
      LF, %LF, %LF) \n", data[17], data[18], data[19]);
                   printf ("Esquina inferior derecha (%LF,
8
      %LF, %LF) \n", data[20], data[21], data[22]);
                   printf ("Esquina superior derecha (%LF,
9
      %LF, %LF) \n", data[23], data[24], data[25]);
                   printf ("Esquina superior izquierda (%
10
      LF, %LF, %LF) \n", data[26], data[27], data[28]);
11
               struct Object disco;
12
               struct Vector x0v0z0;
13
```

```
\times 0y0z0.x = data[17];
1
                 x0y0z0.y = data[18];
2
                 \times 0y0z0.z = data[19];
3
                 struct Vector x1y1z1;
4
                 \times 1y1z1.x = data[20];
5
                 x1y1z1.y = data[21];
6
                 x1y1z1.z = data[22];
7
                 struct Vector x2y2z2;
8
                 x2y2z2.x = data[23];
9
                 \times 2y2z2.y = data[24];
10
                 x2y2z2.z = data[25];
11
                 struct Vector x3y3z3;
12
                 x3y3z3.x = data[26];
13
```

```
x3y3z3.y = data[27];
               x3y3z3.z = data[28];
2
               disco.x0y0z0 = x0y0z0;
               disco.x1y1z1 = x1y1z1;
4
               disco.x2y2z2 = x2y2z2;
               disco.x3v3z3 = x3v3z3;
6
               disco.Xc = data[0];
               disco.Yc = data[1];
8
               disco.Zc = data[2];
9
               disco.intersectionFuncion =
      discIntersection:
               disco.normalVector = discNormal:
11
               disco.retrieveTextureColor = planeTexture;
               struct Vector puntoCentral;
13
```

```
puntoCentral.x = data[0];
               puntoCentral.y = data[1];
2
               puntoCentral.z = data[2];
               struct Vector normalNotNormalized:
               normalNotNormalized.x = data[3];
               normalNotNormalized.y = data[4];
6
               normalNotNormalized.z = data[5];
               struct Color colorDisco;
8
               color Disco.r = data[6];
9
               colorDisco.g = data[7];
               color Disco.b = data[8];
11
               disco.color = colorDisco;
12
               long double dPlano = whatsTheDGeneral (
13
      normalNotNormalized, puntoCentral);
```

```
dPlano = dPlano / getNorm (
      normalNotNormalized);
               disco.extraD = dPlano:
2
               normalNotNormalized = normalize (
      normalNotNormalized);
               disco.directionVector = normalNotNormalized
4
               disco.other = data[9];
5
               disco.o1 = data[10];
6
               disco.o2 = data[11];
7
               disco.o3 = data[12];
8
               disco.Kd = data[13];
9
               disco.Ka = data[14];
10
               disco.Kn = data[15];
11
               disco.Ks = data[16];
12
               disco.planeCuts = planeCutsFound;
13
```

```
disco.numberPlaneCuts = numberPlaneCuts;
1
               disco.textures = texturesFound;
2
               disco.numberTextures = numberTextures:
3
               Objects[objectIndex] = disco;
               if (debug = 1)
5
6
                    printPlaneCuts (Objects[objectIndex]);
7
                    printTextures (Objects[objectIndex],
8
      whichObjectCreate);
9
               objectIndex ++;
11
               return:
12
          case 7:
13
14
15
```

```
if (debug = 1)
2
                   printf ("Insertando Elipses...");
3
                   printf ("Foco 1: (%LF, %LF, %LF) \n",
4
      data[0], data[1], data[2]);
                   printf ("Foco 2: (%LF, %LF, %LF) \n",
5
      data[3], data[4], data[5]);
                   printf ("Normal no normalizada: (%LF, %
6
      LF, %LF) \n", data[6], data[7], data[8]);
                   printf ("Color: (%LF, %LF, %LF) \n",
7
      data[9], data[8], data[9]);
                   printf ("K del elipse: %LF \n", data
8
      [12]);
                   printf ("o1: %LF, o2: %LF, o3: %LF \n"
9
      , data[13], data[14], data[15]);
                   printf ("Elipse Kd: %LF \n", data[16]);
10
                   printf ("Elipse Ka: %LF \n", data[17]);
11
                   printf ("Elipse Kn: %LF \n", data[18]);
12
                   printf ("Elipse Ks: LF \setminus n", data[19]);
13
```

```
printf ("Esquina inferior izquierda (%
      LF, %LF, %LF) \n", data[20], data[21], data[22]);
                   printf ("Esquina inferior derecha (%LF,
2
      %LF, %LF) \n", data[23], data[24], data[25]);
                   printf ("Esquina superior derecha (%LF,
3
      %LF, %LF) \n", data[26], data[27], data[28]);
                   printf ("Esquina superior izquierda (%
4
      LF, %LF, %LF) \n", data[29], data[30], data[31]);
5
               struct Object elipse;
6
               struct Vector x0y0z0;
7
               x0y0z0.x = data[20];
8
               x0y0z0.y = data[21];
g
               x0y0z0.z = data[22];
10
               struct Vector x1y1z1;
11
               x1y1z1.x = data[23];
12
               x1y1z1.y = data[24];
13
```

```
x1y1z1.z = data[25];
1
                struct Vector x2y2z2;
2
                x2y2z2.x = data[26];
                x2y2z2.y = data[27];
4
                x2y2z2.z = data[28];
5
                struct Vector x3y3z3;
6
                x3y3z3.x = data[29];
7
                x3y3z3.y = data[30];
8
                x3y3z3.z = data[31];
9
                elipse.\times 0y0z0 = \times 0y0z0;
10
                elipse.x1y1z1 = x1y1z1;
11
                elipse.x2y2z2 = x2y2z2;
12
                elipse.x3y3z3 = x3y3z3;
13
```

```
elipse.intersectionFuncion =
      elipseIntersection;
               elipse.normalVector = elipseNormal;
2
               elipse.retrieveTextureColor = planeTexture;
3
               struct Vector focol:
               foco1.x = data[0];
5
               focol.y = data[1];
               foco1.z = data[2];
7
               elipse.Xc = data[0];
8
               elipse.Yc = data[1];
9
               elipse.Zc = data[2];
10
               elipse.Xother = data[3];
11
               elipse.Yother = data[4];
12
               elipse.Zother = data[5]:
13
```

```
struct Vector normalNotNormalized;
1
               normalNotNormalized.x = data[6];
2
               normalNotNormalized.y = data[7];
3
               normalNotNormalized.z = data[8];
               struct Color colorElipse;
5
               colorElipse.r = data[9];
6
               colorElipse.g = data[10];
               colorElipse.b = data[11];
8
               elipse.color = colorElipse;
9
               long double dPlano = whatsTheDGeneral (
10
      normalNotNormalized, foco1);
               dPlano = dPlano / getNorm (
      normalNotNormalized);
               elipse.extraD = dPlano;
               normalNotNormalized = normalize (
      normalNotNormalized);
```

```
elipse.directionVector =
      normalNotNormalized:
               elipse.other = data[12];
2
               elipse.o1 = data[13];
3
               elipse.o2 = data[14];
               elipse.o3 = data[15]:
5
               elipse.Kd = data[16]:
               elipse.Ka = data[17];
7
               elipse.Kn = data[18];
8
               elipse.Ks = data[19];
9
               elipse.planeCuts = planeCutsFound;
10
               elipse.numberPlaneCuts = numberPlaneCuts;
11
               elipse.textures = texturesFound;
12
               elipse.numberTextures = numberTextures;
13
```

```
Objects [objectIndex] = elipse;
               if (debug = 1)
2
                    printPlaneCuts (Objects[objectIndex]);
                    printTextures (Objects[objectIndex],
5
      whichObjectCreate);
6
               objectIndex ++;
               return:
8
          case 8:
               if (debug = 1)
12
13
14
```

```
printf ("Insertando Cuadr tica...");
                 printf ("Coeficientes: \n\t A: %LF \n\t
2
      B: %LF \n\t C: %LF\n\t D: %LF\n\t E: %LF \n\t F: %
     [1], data[2], data[3], data[4], data[5], data[6],
     data[7], data[8], data[9]);
                  printf ("Constante K: %LF \n", data
3
     [10]);
                 printf ("o1: %LF, o2: %LF, o3: %LF \n"
4
     , data[11], data[12], data[13]);
                 printf ("Elipse Kd: %LF \n", data[14]);
5
                 printf ("Elipse Ka: %LF \n", data[15]);
6
                 printf ("Elipse Kn: %LF \n", data[16]);
7
                 printf ("Elipse Ks: %LF \n", data[17]);
8
                 printf ("Color: (%LF, %LF, %LF) \n",
9
     data[18], data[19], data[20]);
10
             struct Object cuadratica;
11
             cuadratica.A = data[0];
12
```

```
cuadratica.C = data[2];
1
               cuadratica.D = data[3];
2
               cuadratica.E = data[4];
               cuadratica.F = data[5];
4
               cuadratica.G = data[6];
5
               cuadratica.H = data[7];
6
               cuadratica.l = data[8];
7
               cuadratica.J = data[9];
               cuadratica.other = data[10];
9
               cuadratica.o1 = data[11];
10
               cuadratica.o2 = data[12];
11
               cuadratica.o3 = data[13];
12
               cuadratica.Kd = data[14];
13
```

```
cuadratica.Ka = data[15];
              cuadratica.Kn = data[16];
              cuadratica.Ks = data[17];
              struct Color colorCuadratica:
              colorCuadratica.r = data[18];
5
              colorCuadratica.g = data[19];
              colorCuadratica.b = data[20];
              cuadratica.color = colorCuadratica;
              cuadratica.intersectionFuncion =
9
     quadraticIntersection;
              cuadratica.normalVector = quadraticNormal;
              cuadratica.planeCuts = planeCutsFound;
              cuadratica numberPlaneCuts =
     numberPlaneCuts:
              cuadratica.textures = texturesFound:
```

```
cuadratica.numberTextures = numberTextures;
               Objects [objectIndex] = cuadratica;
2
               if (debug = 1)
                   printPlaneCuts (Objects[objectIndex]);
                   printTextures (Objects[objectIndex],
6
      whichObjectCreate);
                   printf ("sup");
7
8
               objectIndex ++;
9
               return:
13
```

```
long double obtainSingleValueFromLine (char line[])
2
      char * token;
3
      char * search = "=":
4
      long double numericValue;
5
      token = strtok (line, search);
6
      token = strtok (NULL, search);
7
      sscanf (token, "%LF", &numericValue);
8
      return numericValue;
9
10
  long double * obtainPointFromString (char stringPoint
      [])
12
      char * token:
13
```

```
char * search = "=";
      long double numericValue;
      token = strtok (stringPoint, search);
3
      token = strtok (NULL, search);
4
      char * pch;
5
      long double * pointDimensions = malloc (sizeof (
6
      long double)* 3);
      int current Dimension = 0:
7
      pch = strtok (token, ",");
8
      while (pch != NULL)
9
10
           sscanf (pch, "%LF", &pointDimensions[
      currentDimension]);
          pch = strtok (NULL, ",");
12
          current Dimension ++:
13
```

```
return pointDimensions;
3
4 void strip (char * s)
5
      char * p2 = s;
6
       while (* s != ' \setminus 0')
7
           if (* s != '\t' && * s != '\n')
10
               * p2 +++ = * s ++:
12
          else
13
14
15
```

```
++ s:
1
3
      * p2 = ' \ 0';
  char * obtainFilenameTexture (char stringLine[])
7
      char * token = malloc (size of (char) * 200);
8
      char * search = "=":
9
      token = strtok (stringLine, search);
10
      token = strtok (NULL, search);
11
       strip (token);
12
       return token;
13
```

```
2 struct PlaneCut * readPlaneCuts (long int pos, int *
      numberPlanes, long int * posAfterReading)
3
      char temporalBuffer[300];
4
      struct PlaneCut * planeCutsFound = NULL;
5
      long double * datosPlanos;
6
      int indexPlaneCut = -1;
7
      FILE * file:
8
      if (file = fopen (escenaFile, "r"))
9
10
          fseek (file, pos, SEEK_SET);
          while (fgets (temporalBuffer, 300, file)!= NULL
12
13
14
```

```
if (temporalBuffer[0] = ' n')
1
2
                   continue;
3
4
               if (strstr (temporalBuffer, "#")!= NULL)
5
6
                   continue:
8
               if (strstr (temporalBuffer, "NumberPlanes")
9
      != NULL)
                   long double numberPlanes =
      obtainSingleValueFromLine (temporalBuffer);
                   planeCutsFound = malloc (sizeof (struct
       PlaneCut) * numberPlanes);
                   continue:
13
```

```
else if (strstr (temporalBuffer, "Plano_")
      != NULL)
3
                   indexPlaneCut ++:
4
                   continue;
5
6
               else if (strstr (temporalBuffer, "
7
      END_Planos")!= NULL)
8
                   * numberPlanes = indexPlaneCut + 1:
9
                   * posAfterReading = ftell (file);
                   return planeCutsFound;
               else if (strstr (temporalBuffer, "Punto")!=
13
       NULL)
14
15
```

```
datosPlanos = obtainPointFromString (
      temporalBuffer);
                   struct Vector temp;
2
                   temp.x = datosPlanos[0];
                   temp.y = datosPlanos[1];
4
                   temp.z = datosPlanos[2];
5
                   planeCutsFound[indexPlaneCut]. point =
6
      temp;
                   free (datosPlanos);
7
                   continue:
9
               else if (strstr (temporalBuffer, "Normal")
10
      != NULL)
                   datosPlanos = obtainPointFromString (
      temporalBuffer);
                   struct Vector temp;
13
```

```
temp.x = datosPlanos[0];
                   temp.y = datosPlanos[1];
2
                   temp.z = datosPlanos[2];
3
                   long double dEquation =
4
      whatsTheDGeneral (temp, planeCutsFound[
      indexPlaneCut].point);
                   dEquation = dEquation / getNorm (temp);
5
                   temp = normalize (temp);
6
                   planeCutsFound[indexPlaneCut].normal =
7
      temp;
                   planeCutsFound[indexPlaneCut].d =
8
      dEquation;
                   free (datosPlanos);
9
                   continue;
10
11
               continue;
12
13
```

```
struct Color * * getTexels (char * pFile, int * hRes,
      int * vRes)
4
      int counter, x, y, i, j;
5
      char dump[100];
6
      time_t t:
7
      struct Color * * temp;
8
      srand ((unsigned)time (&t));
9
      FILE * file;
10
       if (file = fopen (pFile, "r"))
11
12
           for (i = 0 ; i < 11 ; ++ i)
13
14
15
```

```
fscanf (file, "%s", &dump[0]);
1
               if (i = 8 | | i = 9)
                   if (i = 8)
4
5
                        sscanf (&dump[0], "%i", hRes);
6
7
                    else
8
9
                        sscanf (&dump[0], "%i", vRes);
10
12
13
```

```
temp = malloc (sizeof (struct Color *)* (* hRes
1
      ));
          for (int r = 0; r < (* hRes); r ++)
2
              temp[r] = malloc (sizeof (struct Color)* (*
4
       vRes));
5
          if (temp = NULL)
6
7
               printf ("Devolvi NULL \n");
9
          char temporalBuffer[2000];
10
          int i = 0, x = 0, y = 0, counter = 0;
11
          while (fgets (temporalBuffer, 200, file)!= NULL
12
13
14
```

```
if (temporalBuffer[0] = ' n')
2
                   continue:
               struct Color texel:
5
               long double number;
6
               sscanf (temporalBuffer, "%LF", &number);
7
               int xs = * hRes - x - 1;
8
               if (i = 0)
9
                   temp[y][xs].r = (number)/255;
12
               else if (i == 1)
13
14
15
```

```
temp[y][xs].g = (number)/255;
2
               else if (i = 2)
3
                   temp[y][xs].b = (number)/255;
5
6
               i = (i + 1)\% 3;
               if (i = 0)
8
9
                   y = (y + 1);
10
                   y = y \% (* vRes);
                   if (y == 0)
12
14
```

```
x = (x + 1);
                        x = x \% (* hRes);
2
                        if (x = 0)
3
                             break;
5
               counter = 1:
10
        y = 0;
11
       x = 0;
12
          while (counter != 5)
13
14
15
```

```
counter ++:
2
               v ++:
4
      else
6
            (* vRes) = 128;
           (* hRes) = 128;
8
           temp = malloc (sizeof (struct Color *)* 128);
9
           for (int r = 0; r < (* hRes); r ++)
10
               temp[r] = malloc (sizeof (struct Color)*
12
      128);
13
```

```
if (temp = NULL)
               printf ("Devolvi NULL \n");
3
4
          printf ("La textura de %s no pudo abrirse. Se
5
      sustituir por est tica\n", pFile);
          for (x = 0 ; x < 128 ; x ++)
6
7
               for (y = 0 : y < 128 : y ++)
8
9
                   struct Color estatica:
10
                   estatica.r = ((long double) (rand ()\%)
      255))/ 255;
                   estatica.g = ((long double) (rand ()\%)
12
      255))/ 255:
                   estatica.b = ((long double) (rand ()\%)
13
      255))/ 255;
```

```
temp[x][y] = estatica;
2
4
      return temp;
5
  struct Texture * readTextures (int currentTypeReading,
      long int pos, int * numberTextures, long int *
      posAfterReading)
8
      char temporalBuffer[300];
9
      struct Texture * texturesFound = NULL:
      long double * datosTexture;
      int indexTexture = -1;
12
      FILE * file:
13
```

```
if (file = fopen (escenaFile, "r"))
2
           fseek (file, pos, SEEK_SET);
           while (fgets (temporalBuffer, 300, file)!= NULL
4
5
               if (temporalBuffer[0] = ' \ n')
6
7
                    continue;
8
9
               if (temporalBuffer[0] = ' \ t')
11
                    continue:
13
```

2

4

5

6

7

8

9

11

12

```
if (strstr (temporalBuffer, "#")!= NULL)
            continue:
        if (strstr (temporalBuffer, "NumberTextures
")!= NULL || strstr (temporalBuffer,
NumberTexturas" )!= NULL)
            long double numberTextures =
obtainSingleValueFromLine (temporalBuffer);
            texturesFound = malloc (sizeof (struct
Texture)* numberTextures);
             continue;
        else if (strstr (temporalBuffer, "Texture_"
)!= NULL || strstr (temporalBuffer, "Textura_")!=
NULL)
             indexTexture ++:
```

2

3

4

5

6

7

9

11

```
continue:
         else if (strstr (temporalBuffer, "
END_Textures")!= NULL || strstr (temporalBuffer, "
END_Texturas" )!= NULL)
             * numberTextures = indexTexture + 1:
             * posAfterReading = ftell (file);
             return textures Found;
        else if (strstr (temporalBuffer, "Filename"
)!= NULL || strstr (temporalBuffer, "filename")!=
NULL)
             char * filename = obtainFilenameTexture
 (temporalBuffer);
             int hRes, vRes;
             texturesFound[indexTexture].filename =
filename:
```

2

4

5

7

8

```
struct Color * * textureMap = getTexels
 (texturesFound[indexTexture].filename, &hRes, &
vRes);
             texturesFound[indexTexture].textureMap
= textureMap;
             texturesFound[indexTexture].hRes = hRes
             texturesFound[indexTexture].vRes = vRes
             continue;
         if (currentTypeReading == 2 ||
currentTypeReading == 4 || currentTypeReading == 5
  currentTypeReading == 8)
             if (strstr (temporalBuffer, "Greenwich"
)!=NULL)
                 datosTexture =
```

```
temp.y = datosTexture[1];
                       temp.z = datosTexture[2];
                       temp = normalize (temp);
3
                       texturesFound[indexTexture].
      greenwich = temp;
                       free (datosTexture);
5
                       continue:
6
                   if (currentTypeReading = 2 | |
8
      currentTypeReading == 8)
9
                       if (strstr (temporalBuffer, "Norte"
10
      )!= NULL || strstr (temporalBuffer, "North")!= NULL
                           datosTexture =
      obtainPointFromString (temporalBuffer);
                           struct Vector temp;
13
```

```
temp.x = datosTexture[0];
1
                             temp.y = datosTexture[1];
2
                             temp.z = datosTexture[2];
                             temp = normalize (temp);
4
                             texturesFound[indexTexture].
5
      north = temp;
                             free (datosTexture);
6
                             continue:
7
8
9
10
                continue;
11
12
13
```

```
2 struct DraftPlane * readDraftPlanes (int
      currentTypeReading, long int pos, int *
      numberDraftPlanes, long int * posAfterReading)
3
      char temporalBuffer[300];
4
      struct DraftPlane * draftPlanesFound = NULL;
5
      long double * datosDraftPlane;
6
      int indexDraftPlane = -1;
7
      FILE * file:
8
      if (file = fopen (escenaFile, "r"))
9
10
          fseek (file , pos , SEEK_SET);
          while (fgets (temporalBuffer, 300, file)!= NULL
12
13
14
```

3

5

7

9

11 12

13

```
if (temporalBuffer[0] = ' n')
            continue;
         if (temporalBuffer[0] = ' \ t')
            continue:
         if (strstr (temporalBuffer, "#")!= NULL)
            continue;
        if (strstr (temporalBuffer, "
NumberPlanosCalado")!= NULL || strstr (
temporalBuffer, "NumberDraftPlanes")!= NULL)
```

2

3

5

6

7

8

```
long double numberDraftPlanes =
obtainSingleValueFromLine (temporalBuffer);
            draftPlanesFound = malloc (sizeof (
struct DraftPlane)* numberDraftPlanes);
            continue;
        else if (strstr (temporalBuffer, "
Plano_Calado_")!= NULL || strstr (temporalBuffer,
PlanoCalado_")!= NULL)
             indexDraftPlane ++:
             continue;
        else if ((strstr (temporalBuffer, "
END_Planos_Calado")!= NULL)|| (strstr (
temporalBuffer, "END_PlanosCalado")!= NULL) || (
strstr (temporalBuffer, "END_DraftPlanes")!= NULL)
|| (strstr (temporalBuffer, "END_Draft_Planes")!=
NULL))
```

2

3

4

5

6

7

8

```
return draftPlanesFound:
         else if (strstr (temporalBuffer, "Filename"
)!= NULL || strstr (temporalBuffer, "filename")!=
NULL)
             char * filename = obtainFilenameTexture
 (temporalBuffer);
             int hRes, vRes;
             draftPlanesFound[indexDraftPlane].
filename = filename:
             struct Color * * textureMap = getTexels
 (draftPlanesFound[indexDraftPlane].filename, &hRes
, &vRes);
             draftPlanesFound[indexDraftPlane].
textureMap = textureMap;
             draftPlanesFound[indexDraftPlane].hRes
= hRes;
             draftPlanesFound[indexDraftPlane].vRes
```

```
if (currentTypeReading = 2 \mid |
currentTypeReading == 4 || currentTypeReading == 5
  currentTypeReading == 8)
             if (strstr (temporalBuffer, "Greenwich"
)!=NULL)
                 datosDraftPlane =
obtainPointFromString (temporalBuffer);
                 struct Vector temp;
                 temp.x = datosDraftPlane[0];
                 temp.y = datosDraftPlane[1];
                 temp.z = datosDraftPlane[2];
                 temp = normalize (temp);
                 draftPlanesFound[indexDraftPlane].
greenwich = temp;
                 free (datosDraftPlane);
                 continue:
```

4

5

6

7

9

12

```
if (currentTypeReading == 2 ||
currentTypeReading == 8)
                 if (strstr (temporalBuffer, "Norte"
)!= NULL || strstr (temporalBuffer, "North")!= NULL
                     datosDraftPlane =
obtainPointFromString (temporalBuffer);
                     struct Vector temp;
                    temp.x = datosDraftPlane[0];
                    temp.y = datosDraftPlane[1];
                    temp.z = datosDraftPlane[2];
                    temp = normalize (temp);
                     draftPlanesFound[
indexDraftPlane].north = temp;
                     free (datosDraftPlane);
```

4

5

6

7

8

9

```
continue;
1
2
3
                continue;
5
6
7
8
  long double * readValueFromLine (int state, int *
      counterValueSegment, char * lineRead, int *
      numberValuesRead)
10
      long double * values;
      switch (state)
12
13
14
```

```
case 0:
               if ((* counterValueSegment)>= 0 && (*
      counterValueSegment) <= 10)
3
                   values = malloc (sizeof (long double));
4
                   values[0] = obtainSingleValueFromLine (
5
      lineRead);
                   (* counterValueSegment)++;
6
                   * numberValuesRead = 1;
                   return values;
9
               else if ((* counterValueSegment)>= 11 && (*
       counterValueSegment) <= 12)
                   long double * point =
      obtainPointFromString (lineRead);
                   values = malloc (sizeof (long double)*
13
      3);
```

```
values[0] = point[0];
                    values[1] = point[1];
2
                    values[2] = point[2];
                    * numberValuesRead = 3;
4
                    free (point);
5
                    if ((* counterValueSegment) == 12)
6
                         (* counterValueSegment)= 0;
8
9
                    else
                         (* counterValueSegment)++;
12
13
```

```
return values:
2
          case 1:
               if ((* counterValueSegment)== 0)
5
                   long double * positionLight =
6
      obtainPointFromString (lineRead);
                   values = malloc (sizeof (long double)*
7
      3);
                   values[0] = positionLight[0];
8
                   values[1] = positionLight[1];
9
                   values[2] = positionLight[2];
                   (* counterValueSegment)++;
                   * numberValuesRead = 3:
                   free (positionLight);
13
```

```
return values:
2
              else if ((* counterValueSegment)>= 1 && (*
     counterValueSegment <= 4))
4
                  values = malloc (sizeof (long double));
5
                  values[0] = obtainSingleValueFromLine (
6
     lineRead);
                  if ((* counterValueSegment)== 4)
7
8
                        (* counterValueSegment)= 0;
9
                  else
                        (* counterValueSegment)++;
```

```
1
                   * numberValuesRead = 1;
2
                   return values;
3
           case 2:
5
               if ((* counterValueSegment)== 0 || (*
6
      counterValueSegment) == 9)
7
                   long double * positionSphere =
8
      obtainPointFromString (lineRead);
                    values = malloc (sizeof (long double)*
9
      3);
                   values[0] = positionSphere[0];
                    values[1] = positionSphere[1];
11
                    values [2] = position Sphere [2];
12
                    free (positionSphere);
13
```

```
* numberValuesRead = 3:
                   if ((* counterValueSegment)== 9)
                        (* counterValueSegment)= 0;
5
                   else
                         (* counterValueSegment)++;
9
                   return values;
               else if ((* counterValueSegment) >= 1 \&\& (*
      counterValueSegment) <= 8)
14
```

```
values = malloc (sizeof (long double));
1
                   values[0] = obtainSingleValueFromLine (
2
      lineRead);
                   (* counterValueSegment)++;
3
                   * numberValuesRead = 1;
4
                   return values;
5
6
          case 3:
7
               if ((* counterValueSegment) == 0)
                   values = malloc (sizeof (long double)*
      3);
                   long double * rgbColors =
      obtainPointFromString (lineRead);
                   values[0] = rgbColors[0];
12
                   values[1] = rgbColors[1];
13
```

```
values[2] = rgbColors[2];
                  free (rgbColors);
2
                  * numberValuesRead = 3:
                  (* counterValueSegment)++;
                  return values:
5
6
              else if ((* counterValueSegment)>= 1 && (*
7
     counterValueSegment) <= 7)
                  values = malloc (sizeof (long double));
9
                  values [0] = obtainSingleValueFromLine (
     lineRead);
                  (* counterValueSegment)++;
                  * numberValuesRead = 1;
                  return values:
```

```
1
               else if ((* counterValueSegment)== 8)
2
3
                   if (strstr (lineRead, "END_Vertices")!=
4
       NULL)
5
                         (* counterValueSegment)++;
6
                        return values;
7
8
                   else
9
                        values = malloc (sizeof (long
      double)* 3);
                        long double * vertexPolygon =
      obtainPointFromString (lineRead);
                        values [0] = vertexPolygon [0];
13
```

```
values[1] = vertexPolygon[1];
1
                       values[2] = vertexPolygon[2];
2
                       free (vertexPolygon);
                       * numberValuesRead = 3;
4
                        if ((* counterValueSegment)== 12)
                             (* counterValueSegment)= 0;
                            return values;
8
9
                        if ((* counterValueSegment)!= 8)
                             (* counterValueSegment)++;
12
13
```

```
return values;
2
3
               else if ((* counterValueSegment)>= 9)
5
                    values = malloc (sizeof (long double)*
6
      3);
7
                    long double * vertexPolygon =
      obtainPointFromString (lineRead);
                    values [0] = vertexPolygon [0];
8
                    values [1] = vertexPolygon [1];
9
                    values [2] = vertexPolygon [2];
10
                    free (vertexPolygon);
                    * numberValuesRead = 3;
12
                    if ((* counterValueSegment) == 12)
13
14
15
```

```
(* counterValueSegment)= 0;
                        return values;
2
3
                    (* counterValueSegment)++;
                    return values:
5
           case 4:
7
                if (* counterValueSegment = 0 \mid \mid *
8
      counterValueSegment = 1 \mid \mid * counterValueSegment
      == 12)
9
                    long double * positionCilinder =
10
      obtainPointFromString (lineRead);
                    values = malloc (sizeof (long double)*
      3);
                    values [0] = position Cilinder [0];
12
                    values [1] = position Cilinder [1];
```

```
values [2] = position Cilinder [2];
                    if (* counterValueSegment == 12)
                         (* counterValueSegment)= 0;
4
5
                    else
6
                         (* counterValueSegment)++;
8
9
                    * numberValuesRead = 3:
                    free (positionCilinder);
                    return values;
12
13
```

3

4

5

6

7

9

10

```
else if (* counterValueSegment >= 2 && *
counterValueSegment <= 11)
             values = malloc (sizeof (long double));
             values[0] = obtainSingleValueFromLine (
lineRead);
             (* counterValueSegment)++;
             * numberValuesRead = 1;
             return values;
    case 5:
         if (* counterValueSegment == 0 \mid \mid *
counterValueSegment = 1 \mid \mid * counterValueSegment
== 13)
             long double * positionCone =
obtainPointFromString (lineRead);
             values = malloc (sizeof (long double)*
3);
```

```
values[0] = positionCone[0];
1
                   values[1] = positionCone[1];
2
                   values[2] = positionCone[2];
                   if (* counterValueSegment == 13)
4
5
                         (* counterValueSegment)= 0;
6
                   else
8
9
                         (* counterValueSegment)++;
                   * numberValuesRead = 3;
12
                   free (positionCone);
13
```

3

4

5

6

7

9

```
return values:
         else if (* counterValueSegment >= 2 && *
counterValueSegment <= 12)
             values = malloc (sizeof (long double));
             values [0] = obtainSingleValueFromLine (
lineRead);
             (* counterValueSegment)++;
             * numberValuesRead = 1;
             return values:
     case 6:
         if ((* counterValueSegment >= 0 \&\& *
counterValueSegment <= 2) || (* counterValueSegment
>= 11 \&\& * counterValueSegment <= 14))
```

```
long double * tripleta =
      obtainPointFromString (lineRead);
                   values = malloc (sizeof (long double)*
      3);
                   values[0] = tripleta[0];
3
                   values[1] = tripleta[1];
                   values[2] = tripleta[2];
5
                   if (* counterValueSegment == 14)
7
                        (* counterValueSegment)= 0;
8
9
                   else
                        (* counterValueSegment)++;
13
```

```
* numberValuesRead = 3:
                  free (tripleta);
2
                  return values;
              else if ((* counterValueSegment >= 3 && *
5
     counterValueSegment <= 10))
6
                  values = malloc (sizeof (long double));
7
                  values [0] = obtainSingleValueFromLine (
8
     lineRead);
                  (* counterValueSegment)++;
                  * numberValuesRead = 1;
                  return values;
          case 7:
```

```
if ((* counterValueSegment >= 0 \&\& *
      counterValueSegment <= 3) || (* counterValueSegment
     >= 12 \&\& * counterValueSegment <= 15)
                   long double * tripleta =
      obtainPointFromString (lineRead);
                   values = malloc (sizeof (long double)*
4
      3);
                   values[0] = tripleta[0];
5
                   values[1] = tripleta[1];
6
                   values[2] = tripleta[2];
                   if (* counterValueSegment == 15)
9
                         (* counterValueSegment)= 0;
11
                   else
13
14
```

```
(* counterValueSegment)++;
2
                  * numberValuesRead = 3:
                  free (tripleta);
                  return values;
5
6
              else if ((* counterValueSegment \geq 4 && *
7
     counterValueSegment <= 11))
                   values = malloc (sizeof (long double));
9
                   values [0] = obtainSingleValueFromLine (
     lineRead);
                   (* counterValueSegment)++;
                  * numberValuesRead = 1;
                  return values:
```

```
case 8:
               if ((* counterValueSegment) == 18)
                   long double * tripleta =
5
      obtainPointFromString (lineRead);
                   values = malloc (sizeof (long double)*
6
      3);
                   values[0] = tripleta[0];
7
                   values[1] = tripleta[1];
8
                   values [2] = tripleta [2];
9
                   (* counterValueSegment)= 0;
                   * numberValuesRead = 3;
                   free (tripleta);
                   return values:
13
```

```
1
               else if ((* counterValueSegment >= 0 && *
2
      counterValueSegment <= 17))
3
                   values = malloc (sizeof (long double));
4
                   values [0] = obtainSingleValueFromLine (
5
      lineRead);
                   (* counterValueSegment)++;
6
                   * numberValuesRead = 1;
                   return values;
8
9
  int plainCutsFound (long int pos)
13
14
```

```
char temporalBuffer[300];
      FILE * file:
      if (file = fopen (escenaFile, "r"))
4
           fseek (file, pos, SEEK_SET);
5
           while (fgets (temporalBuffer, 300, file)!= NULL
6
7
               if (temporalBuffer[0] = ' \ n')
8
9
                   continue:
               if (temporalBuffer[0] = ' \ t')
12
13
14
```

```
continue:
2
               if (strstr (temporalBuffer, "#")!= NULL)
                    continue;
5
6
               else if (strstr (temporalBuffer, "
7
      Planos_Corte:")!= NULL)
8
                   return 1;
9
10
               else if (strstr (temporalBuffer, "Texturas:
11
      ")!= NULL)
                    return 0:
13
```

```
1
               else if (strstr (temporalBuffer, "
2
      Planos_Calado:")!= NULL)
3
                   return 0;
4
5
               else if (strstr (temporalBuffer, "
6
      Sphere_Object")!= NULL)
7
                   return 0;
8
9
               else if (strstr (temporalBuffer, "
10
      Polygon_Object")!= NULL)
                    return 0;
12
13
```

```
else if (strstr (temporalBuffer, "
Cylinder_Object")!= NULL)
            return 0:
        else if (strstr (temporalBuffer, "
Cone_Object")!= NULL)
            return 0;
        else if (strstr (temporalBuffer, "
Disc_Object")!= NULL)
            return 0:
        else if (strstr (temporalBuffer, "
Elipse_Object")!= NULL)
```

3

5

6

7

9

10

11 12

13

```
return 0:
1
2
               else if (strstr (temporalBuffer, "
3
      Quadratic_Object")!= NULL)
4
                    return 0:
5
6
               else if (strstr (temporalBuffer, "
7
      Scene_Data")!= NULL)
8
g
                    return 0;
10
               else if (strstr (temporalBuffer, "
      Light_Object")!= NULL)
12
                    return 0:
13
```

```
1
2
3
      return 0:
5
  int texturesFound (long int pos)
      char temporalBuffer[300];
8
      FILE * file:
9
       if (file = fopen (escenaFile, "r"))
10
11
           fseek (file, pos, SEEK_SET);
12
           while (fgets (temporalBuffer, 300, file)!= NULL
13
14
15
```

```
if (temporalBuffer[0] = ' n')
                    continue;
3
4
                if (temporalBuffer[0] = ' \ t')
5
6
                    continue:
7
8
                if (strstr (temporalBuffer, "#")!= NULL)
9
10
                    continue;
11
12
               else if (strstr (temporalBuffer, "Texturas:
13
      ")!= NULL || strstr (temporalBuffer, "Textures:")!=
       NULL)
14
15
```

```
return 1:
1
2
               else if (strstr (temporalBuffer, "
3
      Planos_Calado:")!= NULL)
4
                    return 0:
5
6
               else if (strstr (temporalBuffer, "
7
      Sphere_Object")!= NULL)
8
g
                    return 0;
10
               else if (strstr (temporalBuffer, "
      Polygon_Object")!= NULL)
12
                    return 0:
13
```

```
1
               else if (strstr (temporalBuffer, "
2
      Cylinder_Object")!= NULL)
3
                    return 0;
4
5
               else if (strstr (temporalBuffer, "
6
      Cone_Object")!= NULL)
7
8
                    return 0;
9
               else if (strstr (temporalBuffer, "
10
      Disc_Object")!= NULL)
                    return 0;
12
13
```

```
else if (strstr (temporalBuffer, "
Elipse_Object")!= NULL)
             return 0:
        else if (strstr (temporalBuffer, "
Quadratic_Object")!= NULL)
            return 0:
        else if (strstr (temporalBuffer, "
Scene_Data")!= NULL)
             return 0:
        else if (strstr (temporalBuffer, "
Light_Object")!= NULL)
```

3

5

6

7

9

10

11 12

13

```
return 0;
1
3
4
       return 0:
5
  int draftPlanesFound (long int pos)
8
      char temporalBuffer[300];
9
      FILE * file:
10
       if (file = fopen (escenaFile, "r"))
11
12
           fseek (file, pos, SEEK_SET);
13
```

```
while (fgets (temporalBuffer, 300, file)!= NULL
               if (temporalBuffer[0] = ' \ n')
3
                    continue:
6
               if (temporalBuffer[0] = ' \ t')
7
8
                    continue;
9
10
               if (strstr (temporalBuffer, "#")!= NULL)
11
12
                    continue:
13
```

```
else if ((strstr (temporalBuffer, "
2
      Planos_Calado:")!= NULL)|| (strstr (temporalBuffer,
       "PlanosCalado:")!= NULL)|| (strstr (temporalBuffer
      , "DraftPlanes:")!= NULL)|| (strstr (temporalBuffer
      , "Draft_Planes")!= NULL))
3
                   return 1:
4
5
               else if (strstr (temporalBuffer, "
6
      Sphere_Object")!= NULL)
7
                   return 0:
8
9
               else if (strstr (temporalBuffer, "
10
      Polygon_Object")!= NULL)
                   return 0;
12
13
```

```
else if (strstr (temporalBuffer, "
Cylinder_Object")!= NULL)
            return 0:
        else if (strstr (temporalBuffer, "
Cone_Object")!= NULL)
            return 0;
        else if (strstr (temporalBuffer, "
Disc_Object")!= NULL)
            return 0:
        else if (strstr (temporalBuffer, "
Elipse_Object")!= NULL)
```

3

5

6

7

9

10

11 12

13

```
return 0:
1
2
               else if (strstr (temporalBuffer, "
3
      Quadratic_Object")!= NULL)
4
                    return 0:
5
6
               else if (strstr (temporalBuffer, "
7
      Scene_Data")!= NULL)
8
g
                    return 0;
10
               else if (strstr (temporalBuffer, "
      Light_Object")!= NULL)
12
                    return 0:
13
```

```
1
3
       return 0;
4
5
  void getSceneObjects ()
7
       int i, j, c;
8
      int state = 0:
9
      int counterValueSegment = 0;
10
      char temporalBuffer[300];
11
      long double * valuesRead;
12
       int indexValuesRead = 0:
13
```

```
int currentTypeObjectReading = 1;
      struct PlaneCut * arrayPlaneCuts = NULL;
2
      struct Texture * arrayTextures = NULL;
      struct DraftPlane * arrayDraftPlanes = NULL;
4
      FILE * file:
5
      if (file = fopen (escenaFile, "r"))
6
7
          while (fgets (temporalBuffer, 300, file)!= NULL
8
9
               if (temporalBuffer[0] = ' \ n')
10
                   continue:
13
```

```
if (temporalBuffer[0] = ' \ t')
2
                    continue;
4
               if (strstr (temporalBuffer, "#")!= NULL)
6
                    continue;
8
               if (strstr (temporalBuffer, "Scene_Data")!=
9
       NULL)
                    state = 0;
11
                    counterValueSegment = 0;
12
                    indexValuesRead = 0;
13
```

```
valuesRead = NULL;
1
                   valuesRead = malloc (sizeof (long
2
      double) * 22);
                   currentTypeObjectReading = 0;
3
                    continue;
4
5
               else if (strstr (temporalBuffer, "
6
      Light_Object")!= NULL)
7
8
                    state = 1:
                   counterValueSegment = 0;
9
                    indexValuesRead = 0;
10
                    free (valuesRead);
                   valuesRead = malloc (sizeof (long
      double) * 7);
                   currentTypeObjectReading = 1;
13
```

```
continue;
               else if (strstr (temporalBuffer, "
3
      Sphere_Object")!= NULL)
4
                    state = 2:
5
                    indexValuesRead = 0;
6
                    free (valuesRead);
                    valuesRead = malloc (sizeof (long
8
      double) * 22);
                    counterValueSegment = 0;
9
                    currentTypeObjectReading = 2;
10
                    continue:
11
               else if (strstr (temporalBuffer, "
13
      Polygon_Object")!= NULL)
14
15
```

```
state = 3:
                   counterValueSegment = 0;
2
                   indexValuesRead = 0;
                   free (valuesRead);
                   valuesRead = malloc (sizeof (long
5
      double) * 2000000);
                   currentTypeObjectReading = 3;
6
                   continue:
8
               else if (strstr (temporalBuffer, "
9
      Cylinder_Object")!= NULL)
                   state = 4:
                   counterValueSegment = 0;
                   indexValuesRead = 0:
13
```

```
free (valuesRead);
1
                   valuesRead = malloc (sizeof (long
2
      double) * 55);
                   currentTypeObjectReading = 4;
3
                    continue;
4
5
               else if (strstr (temporalBuffer, "
6
      Cone_Object")!= NULL)
7
                    state = 5:
8
                   counterValueSegment = 0;
9
                    indexValuesRead = 0;
10
                    free (valuesRead);
                   valuesRead = malloc (sizeof (long
      double) * 55);
                   currentTypeObjectReading = 5;
13
```

3

4

5

6

8

9

10

11

13

```
continue;
         else if (strstr (temporalBuffer, "
Disc_Object")!= NULL)
             state = 6:
             counterValueSegment = 0;
             indexValuesRead = 0;
             free (valuesRead);
             valuesRead = malloc (sizeof (long
double) * 55);
             currentTypeObjectReading = 6;
             continue:
         else if (strstr (temporalBuffer, "
Elipse_Object")!= NULL)
```

```
state = 7:
                   counterValueSegment = 0;
2
                   indexValuesRead = 0;
                   free (valuesRead);
                   valuesRead = malloc (sizeof (long
5
      double) * 55);
                   currentTypeObjectReading = 7;
6
                   continue:
8
               else if (strstr (temporalBuffer, "
9
      Quadratic_Object")!= NULL)
                   state = 8:
11
                   counterValueSegment = 0;
                   indexValuesRead = 0:
13
```

```
free (valuesRead);
            valuesRead = malloc (sizeof (long
double) * 55):
            currentTypeObjectReading = 8;
             continue:
        int numberValuesRead = 0:
        long double * valuesReadTemp =
readValueFromLine (state, &counterValueSegment,
temporalBuffer, &numberValuesRead);
         if (valuesReadTemp = NULL)
             continue:
        int i = 0:
        for (i = 0 ; i < numberValuesRead ; i ++)
```

3

4

6

7

8

12

```
valuesRead[indexValuesRead + i] =
      valuesReadTemp[i];
2
               indexValuesRead += numberValuesRead;
               if (counterValueSegment = 0)
5
                   int numberPlaneCuts = 0;
6
                   int numberTextures = 0;
                   int numberDraftPlanes = 0;
8
                   long int posAfterReading;
9
                   long int pos;
                   pos = ftell (file);
                   int areTherePlainCuts = plainCutsFound
12
      (pos);
                   if (areTherePlainCuts == 1)
14
15
```

2

3

4

5

6

7

9

10

12

```
pos = ftell (file);
                 arrayPlaneCuts = readPlaneCuts (pos
, &numberPlaneCuts, &posAfterReading);
                 fseek (file, posAfterReading,
SEEK_SET);
             pos = ftell (file);
             int areThereTextures = texturesFound (
pos);
             if (areThereTextures == 1)
                 pos = ftell (file);
                 arrayTextures = readTextures (
currentTypeObjectReading, pos, &numberTextures, &
posAfterReading);
                 fseek (file, posAfterReading,
SEEK_SET);
             int areThereDraftPlanes =
```

2

4

5

6

7

8

10 11

12

```
if (areThereDraftPlanes == 1)
                 pos = ftell (file);
                 arrayDraftPlanes = readDraftPlanes
(currentTypeObjectReading, pos, &numberDraftPlanes,
&posAfterReading);
                 fseek (file, posAfterReading,
SEEK_SET);
            createObjectFromData (valuesRead.
currentTypeObjectReading, indexValuesRead,
arrayPlaneCuts, arrayTextures, arrayDraftPlanes,
numberPlaneCuts, numberTextures, numberDraftPlanes)
    free (valuesRead);
fclose (file):
```

```
void howManyObjectsLights ()
2
      char temporalBuffer[100];
3
      FILE * file:
4
       if (file = fopen (escenaFile, "r"))
5
6
           while (fgets (temporalBuffer, 100, file)!= NULL
7
8
               if (temporalBuffer[0] = ' \ n')
9
10
                    continue:
12
               if (strstr (temporalBuffer, "#")!= NULL)
13
14
15
```

```
continue;
               if (strstr (temporalBuffer, "Light_Object")
3
      != NULL)
4
                    numberLights ++;
5
                    continue:
6
7
               else if (strstr (temporalBuffer, "
8
      Sphere_Object")!= NULL)
9
                    numberObjects ++;
10
                    continue:
               else if (strstr (temporalBuffer, "
13
      Polygon_Object")!= NULL)
14
15
```

```
numberObjects ++;
                    continue;
2
               else if (strstr (temporalBuffer, "
4
      Cone_Object")!= NULL)
5
                   numberObjects ++;
6
                    continue:
8
               else if (strstr (temporalBuffer, "
9
      Cylinder_Object")!= NULL)
                   numberObjects ++;
                    continue:
13
```

```
else if (strstr (temporalBuffer,
1
      Disc_Object")!= NULL)
2
                   numberObjects ++;
                    continue;
4
5
               else if (strstr (temporalBuffer,
6
      Elipse_Object")!= NULL)
7
                   numberObjects ++;
8
                    continue;
9
10
               else if (strstr (temporalBuffer, "
      Quadratic_Object")!= NULL)
12
                   numberObjects ++;
13
```

```
continue:
2
4
      fclose (file);
5
      Objects = malloc (sizeof (struct Object)*
6
      numberObjects);
      Lights = malloc (sizeof (struct Light)*
7
      numberLights);
8
  struct Vector throwRay (long double x, long double y)
10
      struct Vector direction;
      long double Xw, Yw;
12
      Xw = (long double) ((x)* Xdif) / Hres + Xmin;
13
```

```
Yw = (long double) ((y)* Ydif) / Vres + Ymin;
1
      direction.x = Xw - eye.x;
2
      direction.y = Yw - eye.y;
3
      direction.z = - eye.z;
4
      direction = normalize (direction);
5
      return direction;
6
7
8 struct Color ponderAAcolors (struct Color c1, struct
      Color c2, struct Color c3, struct Color c4)
9
      struct Color color:
10
      color.r = (c1.r + c2.r + c3.r + c4.r)/4;
11
      color.g = (c1.g + c2.g + c3.g + c4.g)/4;
12
      color.b = (c1.b + c2.b + c3.b + c4.b)/4;
13
```

```
return color;
3 long double getDistanceColors (struct Color c1, struct
      Color c2)
4
    return sqrt (pow (c1.r - c2.r, 2)+ pow (c1.g - c2.g
5
      , 2) + pow (c1.b - c2.b, 2));
7 int theyOK (struct Color c1, struct Color c2, struct
      Color c3, struct Color c4)
8
      long double dist, dist1, dist2, dist3, dist4, dist5
9
      , dist6;
      dist1 = getDistanceColors (c1, c2);
10
      dist2 = getDistanceColors (c1, c3);
11
      dist3 = getDistanceColors (c1, c4);
12
      dist4 = getDistanceColors (c2, c3);
13
```

```
dist5 = getDistanceColors (c2, c4);
1
       dist6 = getDistanceColors (c3, c4);
2
       dist = (dist1 + dist2 + dist3 + dist4 + dist5 +
3
      dist6)/6;
       if (dist <= similar)</pre>
4
5
           return 1:
6
7
       else
8
9
           return 0;
10
11
12
  struct Color getAAColor (long double x, long double y,
      int aaLevel)
14
15
```

```
int areOK;
1
      int level = aaLevel:
2
      struct Color color, color1, color2, color3, color4;
3
      struct Vector direction . V:
4
      long double sum = 1 / pow (2, level);
5
      level ++:
6
      long double nextSum = 1 / pow (2, level);
7
      direction = throwRay(x, y):
8
      V.x = - direction.x:
9
      V.y = - direction.y;
10
      V.z = - direction.z:
11
      color1 = getColor (eye, direction, V, maxReflection
12
      );
      direction = throwRay (x, y + sum);
13
```

```
V.x = - direction.x:
      V.y = - direction.y;
2
      V.z = - direction.z;
3
      color2 = getColor (eye, direction, V, maxReflection
4
      direction = throwRay (x + sum, y);
5
      V.x = - direction.x:
6
      V.v = - direction.v;
7
      V.z = - direction.z:
8
      color3 = getColor (eye, direction, V, maxReflection
9
      direction = throwRay (x + sum, y + sum);
10
      V.x = - direction.x:
      V.v = - direction.v;
12
      V.z = - direction.z;
13
```

```
color4 = getColor (eye, direction, V, maxReflection
1
      ):
      areOK = theyOK (color1, color2, color3, color4);
2
       if (areOK == 0 && level <= maxAA)</pre>
4
           color1 = getAAColor(x, y, level);
5
           color2 = getAAColor (x, y + nextSum, level);
6
           color3 = getAAColor (x + nextSum, y, level);
7
           color4 = getAAColor (x + nextSum, y + nextSum,
8
      level):
           color = ponderAAcolors (color1, color2, color3,
9
       color4);
10
       else
11
12
           color = ponderAAcolors (color1, color2, color3,
13
       color4):
```

```
return color:
3
  void * runRT (void * x)
5
    int start, i, j;
6
      struct Color color;
7
       i = * ((int *)x);
       printf ("%i \setminus n", i);
      for (i ; i < Vres ; i += 4)
10
11
           for (j = 0 ; j < Hres ; j ++)
12
13
14
```

```
color = getAAColor ((long double)j, (long
      double)i, 0);
               Framebuffer[i][j] = color;
3
4
       return NULL:
5
  int main (int argc, char * arcgv[])
8
      howManyObjectsLights ();
9
       printf ("Lights: %i \n", numberLights);
10
       printf ("Objects: %i \n", numberObjects);
11
      getSceneObjects ();
12
      int i:
13
```

```
pthread_t threads [4];
      Xdif = Xmax - Xmin:
2
      Ydif = Ymax - Ymin;
3
      similar = sqrt(3)/32;
4
      printf ("\nRay Tracing\n...\n");
5
      for (i = 0 ; i < 4 ; i ++)
6
7
           pthread_create (& (threads[i]), NULL, &runRT, &
8
      i);
           sleep (1);
9
10
      for (i = 0 ; i < 4 ; i ++)
11
12
           pthread_join (threads[i], NULL);
13
```

```
printf ("Rays: %LF\n", rays);
saveFile ();
free (Objects);
free (Lights);
free (Framebuffer);
printf ("\nDONE.\n");
}
```