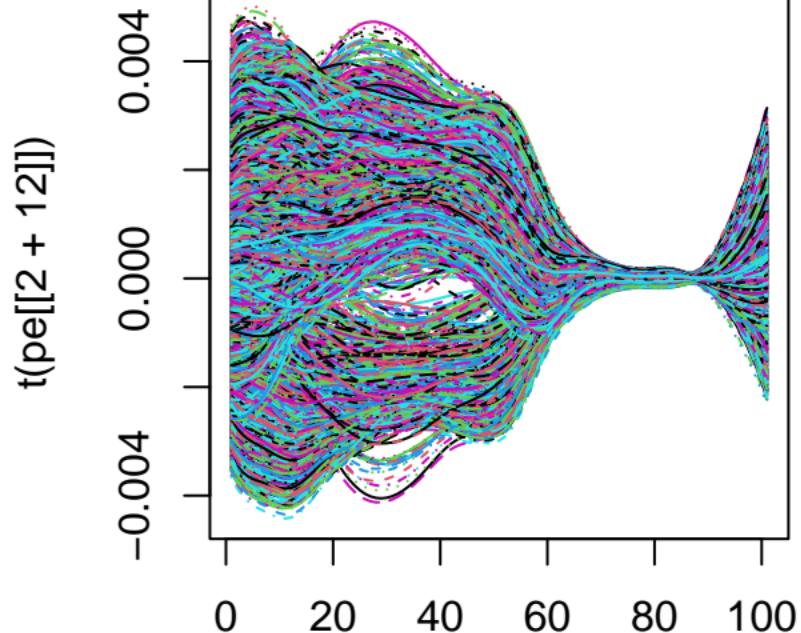


shank.gyro_y



foot.acc_z

