

# boolean\_dsgrn

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```
[1]: import ginsim
import biolqm
import boolsim
import pandas as pd
from colomoto_jupyter import tabulate
from colomoto.minibn import BooleanNetwork
from colomoto.temporal_logics import *
```

This notebook has been executed using the docker image colomoto/colomoto-docker:2025-03-01

## 0.1 boolsim

```
[2]: ## Define network
# network = {
#     "ATM": "!Wip1",
#     "Chk2": "ATM & !Wip1",
#     "Mdm2": "p53",
#     "p53": "(ATM | Chk2) & !Mdm2",
#     "Wip1": "p53"
# }
network = {
    "x" : "!y",
    "y" : "!x"}
bn = BooleanNetwork(network)
```

```
[3]: ## Tabulate the attractors using boolsim
%time A = boolsim.attractors(bn)
tabulate(A)
```

CPU times: user 24.7 ms, sys: 5.11 ms, total: 29.8 ms

Wall time: 116 ms

```
[3]:   x  y
0  0  1
1  1  0
```

```
[4]: ## Print attractors. The asterisk means "complex" attractors
for att in A:
    print(att)
```

```
{'x': 0, 'y': 1}
{'x': 1, 'y': 0}
```

## 1 bioLQM

```
[5]: ## Convert from boolsim to biolqm
lqm = bn.to_biolqm()
```

```
[6]: ## Save for future reference
biolqm.save(lqm, "network.net", "boolsim")
```

```
[6]: 'network.net'
```

```
[7]: # Influence graph from biolqm
biolqm.influence_graph(lqm)
```

```
# computing graph layout...
```

```
[7]: <networkx.classes.multidigraph.MultiDiGraph at 0x7fffcbb1cf010>
```

### 1.0.1 Identification of stable states (fixed points)

```
[8]: fps = biolqm.fixpoints(lqm)
pd.DataFrame(fps)
```

```
[8]:   x  y
0  0  1
1  1  0
```

### 1.0.2 Identification of stable motifs (trapspaces)

A stable motif (also called symbolic steady state) is a partially assigned state such that all possible successors of all states which belong to the motif also belong to the motif.

```
[9]: traps = biolqm.trapspace(lqm)
pd.DataFrame(traps)
```

```
[9]:   x  y
0  1  0
1  0  1
```

### 1.0.3 Stable (states?)

```
[10]: states = biolqm.stable(lqm)
print(states)
```

```
[{'x': 0, 'y': 1}, {'x': 1, 'y': 0}]
```

There are some functionalities regarding “simulation” of deterministic paths (and non-deterministic by doing random walks).

#### 1.0.4 Model perturbation

the `biolqm.perturbation` function enables the construction of a variant of the model, where the logical function of one (or several) component has been modified. A textual parameter describes the modification:

`component%0` defines a knockout of a component `component%1` defines an ectopic expression `component%1:2` restricts the range of values for multi-valued components `regulator:component%0` allows to remove a regulator In the following, we show the impact of the ectopic expression of the CycD component on the stable states and trapsaces on the model.

```
[11]: pert = biolqm.perturbation(lqm, "y%1")
```

```
[12]: fps = biolqm.fixpoints(pert)
      pd.DataFrame(fps)
```

```
[12]:   x  y
      0  0  1
```

```
[13]: traps = biolqm.trapspace(pert, "terminal")
      pd.DataFrame(traps)
```

```
[13]:   x  y
      0  0  1
```

## 2 GINsim

```
[14]: ## Convert from biolqm to ginsim
      lrg = biolqm.to_ginsim(lqm)
      ginsim.show(lrg)
```

```
[14]: <IPython.core.display.HTML object>
```

```
[15]: ## Fixed points
      fps = biolqm.fixpoints(lqm)
      print(len(fps), "fixpoints")
```

```
2 fixpoints
```

```
[16]: # First fixed point
      ginsim.show(lrg, fps[0])
```

```
[16]: <IPython.core.display.HTML object>
```

```
[17]: # Second fixed point
      ginsim.show(lrg, fps[1])
```

```
[17]: <IPython.core.display.HTML object>
```

```
[ ]:
```