

Aufgabe 1

```
roscore http://RoboBox:11311/
Press Ctrl-C to interrupt
Done checking log file disk usage. Usage is <1GB.

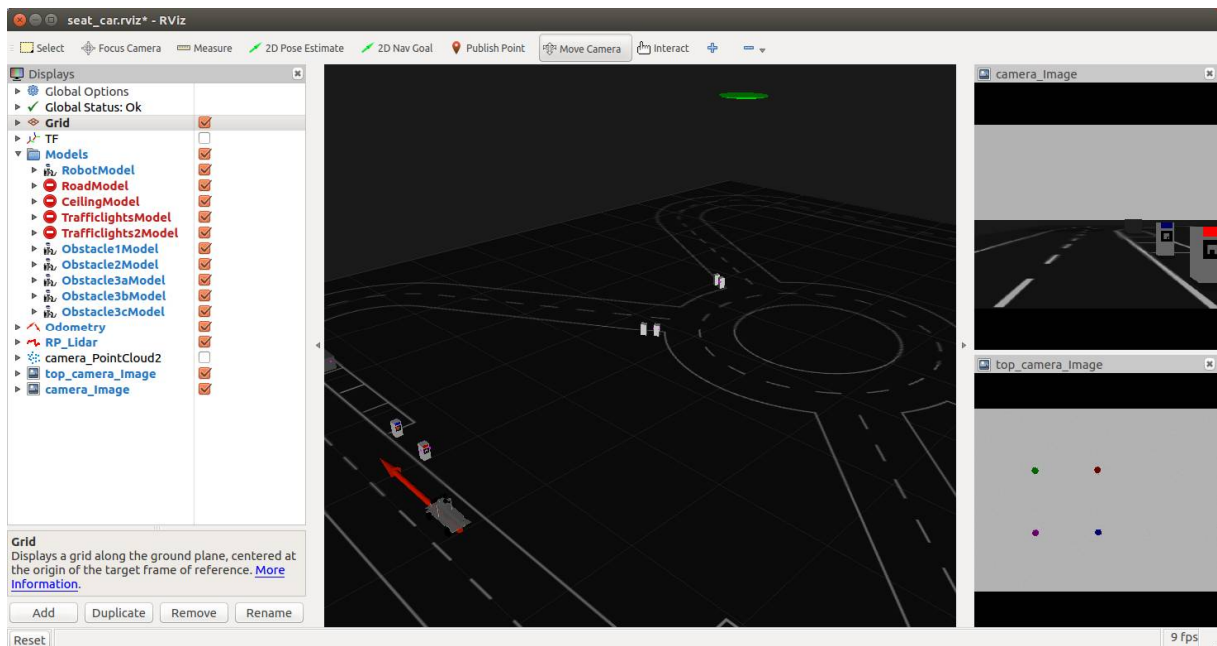
started roslaunch server http://RoboBox:45835/
ros_comm version 1.12.7

SUMMARY
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PARAMETERS
* /roslistro: kinetic
* /rosversion: 1.12.7

NODES
auto-starting new master
process[master]: started with pid [2470]
ROS_MASTER_URI=http://RoboBox:11311/

setting /run_id to f9201a7a-ba67-11e7-8de8-0800273bea71
process[roscout-1]: started with pid [2487]
started core service [/roscout]
```

Aufgabe 2



Aufgabe 3

a)

```
$ /opt/ros/kinetic/bin/rostopic list /camera
/camera/depth/camera_info
/camera/depth/image_raw
/camera/depth/points
/camera/parameter_descriptions
/camera/parameter_updates
/camera/rgb/camera_info
/camera/rgb/image_raw
/camera/rgb/image_raw/compressed
/camera/rgb/image_raw/compressed/parameter_descriptions
/camera/rgb/image_raw/compressed/parameter_updates
/camera/rgb/image_raw/compressedDepth
/camera/rgb/image_raw/compressedDepth/parameter_descriptions
/camera/rgb/image_raw/compressedDepth/parameter_updates
/camera/rgb/image_raw/theora
/camera/rgb/image_raw/theora/parameter_descriptions
/camera/rgb/image_raw/theora/parameter_updates
```

c)

