

Bernd Accou<sup>1,2</sup>, Jonas Vanthornhout<sup>1</sup>, Hugo Van hamme<sup>2</sup>, Tom Francart<sup>1</sup>

<sup>2</sup> PSI, Department of Electrical Engineering (ESAT), KU Leuven

## Neural tracking

- Finding neural tracking of speech features in the brain
- Can be used as diagnostic tool for speech understanding [Vanthornhout et al., 2018, Accou et al., 2021]

## Problems

- Relatively simple linear models are used
- Subject-specific models, which requires collection of training data for each (test-)subject

**Proposed solution:** A very large augmented auditory inference (VLA AI) network

- Non-linear complex model to decode the envelope from EEG
- Subject-independent model to reduce amount of data needed per subject

## Subjects

- 106 normal hearing native Flemish speakers
- Screened with pure-tone audiogram and Flemish MATRIX test

## Stimuli

- 2-8 children's stories narrated by a single speaker in Dutch
- $\approx$  15 minutes in length

This amounts to  $\approx 195$  hours of EEG data (1 hours and 50 minutes of EEG data per subject on average).

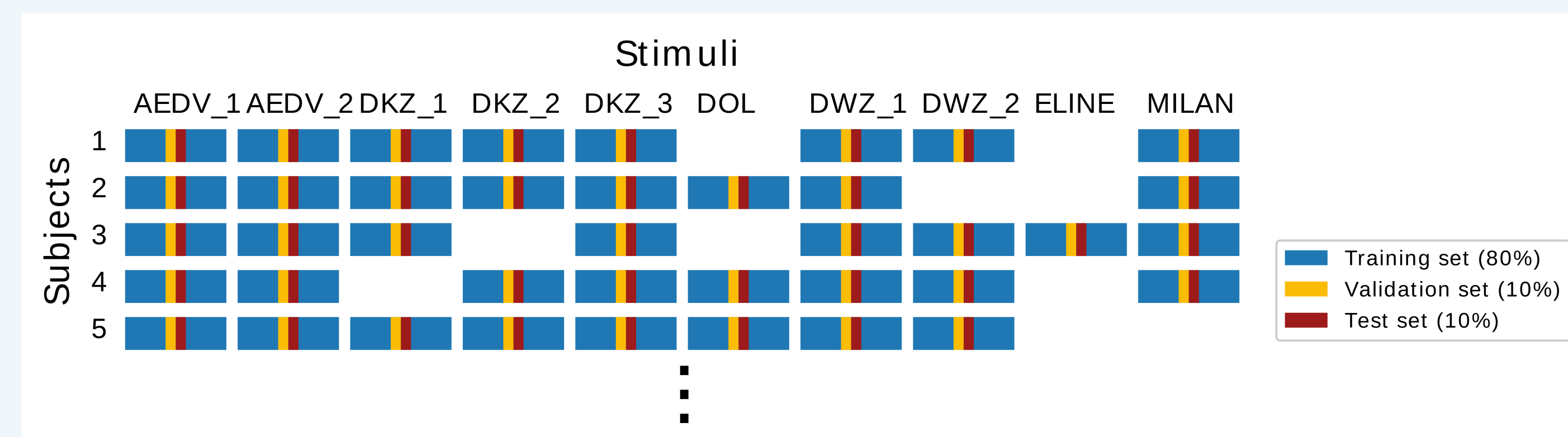


Figure 1: A visualization of the recordings (blue boxes). Test- and validation-set are extracted from the middle of the recording

## Preprocessing steps

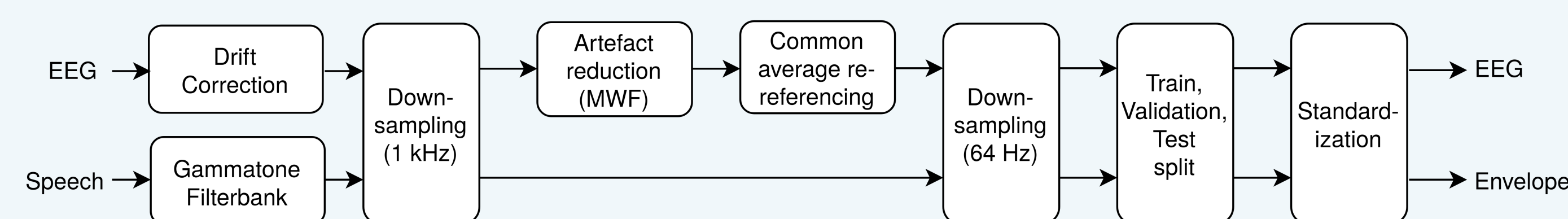


Figure 2: All preprocessing steps performed on the dataset.

To train and evaluate the models in the experiment section, windows of 5 seconds with an overlap of 80% were used

Diagram of the proposed architecture. The input EEG signal is processed by a CNN Stack (N convolutional layers), followed by a Linear layer and an Output context layer. The output of the Output context layer is added to the original EEG input (indicated by a '+' sign in a circle). This sum is then passed through another Linear layer to produce the final Envelope output. The entire process from the CNN Stack to the final Linear layer is repeated N times, as indicated by the 'Nx' label.

Figure 3: The architecture of the new proposed VLAAI network.

The VLAAI network consists of 3 modules which can be repeated  $N_x (= 4)$  times:

1. **CNN stack**  
This module consists of 5 convolutional layers with a kernel size of 8. The first 3 and last 2 layers have 256 and 128 filters respectively. After each convolutional layer, layer normalization, a LeakyReLU activation and zero-padding (7 samples at the end of the sequence) were applied
2. **Linear layer**  
A linear combination of the output filters of the CNN stack.
3. **Output context layer**  
Predicting a better sample based on 31 previous samples + the current sample.

VLAAL is trained with negative Pearson coefficient as a loss function

All models utilized in this section were trained with EEG data of all participants (i.e. **subject-independent** models).

The proposed VLAAI network is compared to 3 baseline models:

1. **Linear decoder**  
A linear decoder with an integration window of 500 ms, trained with negative pearson coefficient as loss.
2. **CNN**  
The CNN model of Thornton et al. [2022], which was based on the EEGNET architecture [Lawhern et al., 2018]
3. **FCNN**  
The FCNN model of Thornton et al. [2022], which was based on the architecture of de Taillez et al. [2017].

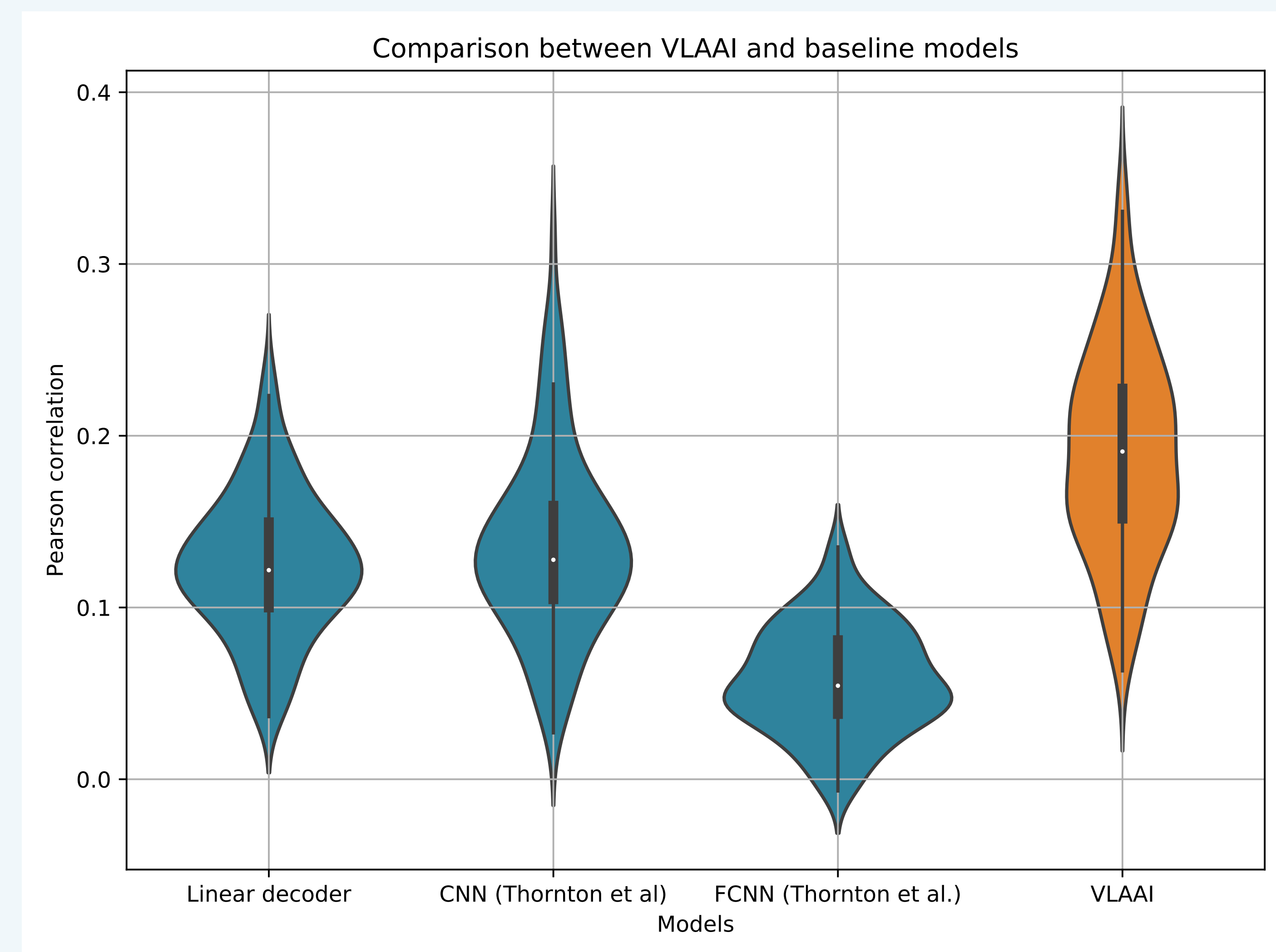


Figure 4: Comparison between the VLAAL network with 3 baseline models for 5 second segments. Each point in the boxplot represents the reconstruction score for a subject, averaged across stimuli.

Models were compared using a Wilcoxon signed-rank test using Holm-Bonferroni correction. All models performed significantly different ( $p < 0.05$ ). The VLAAl network significantly outperforms all baseline models

- While Thornton et al. [2022] could be replicated using their own provided data, the FCNN model performed worse when trained/applied on the datasets presented here (see Figure 4). A possible explanation is that the hyperparameters for regularizing the population models in Thornton et al. [2022] are not optimal for our dataset
- The VLAAI network outperforms the baseline models substantially (a relative improvement in median accuracy of 56.74% compared to the linear decoder baseline). A better decoder model, such as VLAAI, might reveal neural tracking and/or effects that were hidden previously

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