$$\vec{A} \cdot \vec{b} = \sum_{i=1}^{n} a_{i}b_{i}$$

$$\vec{a}_{i} \cdot \vec{b} \in \mathbb{R}^{n}$$

$$(C^{n} \vec{a} \cdot \vec{b}_{i}) = \sum_{i=1}^{n} \vec{a}_{i}b_{i}$$

$$\vec{a}_{i} \cdot \vec{b}_{i} = \|\vec{a}\| \|\vec{b}\| \cos \theta$$

$$\vec{b}_{i} = \|\vec{a}\| \|\vec{b}\| \cos \theta$$

$$\vec{b}_{i} = \|\vec{a}\|^{2} + \|\vec{a}\| \|\vec{b}\| \cos \theta + \|\vec{b}\|^{2}$$

$$= a \cdot a + a \cdot b + b \cdot a + 6 \cdot b$$

$$= \|a\|^{2} + \|\vec{a}\| \|\vec{b}\| \cos \theta + \|\vec{b}\|^{2}$$

$$= a \cdot b \cdot a$$

$$a_{1}b \cdot e^{(n)} = a \cdot b \cdot a$$

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$$a_{1}b \cdot e^{(n)} = a \cdot b$$

Vectors
$$\vec{u}, \vec{v} \in \mathbb{R}^n$$
 are "orthogonal"

 $\vec{u} \cdot \vec{v} = 0$
 $\vec{u} \cdot \vec{v} = ||\vec{u}|| ||\vec{v}|| ||\cos\theta||$
 $\vec{u} \cdot \vec{v} = ||\vec{u}|| ||\vec{v}|| ||\cos\theta||$
 $\vec{u} \cdot \vec{v} = ||\vec{u}|| ||\vec{v}|| ||\cos\theta||$
 $\vec{u} \cdot \vec{v} = 0$
 $\vec{u} \cdot \vec{v} = ||\vec{u}|| ||\vec{v}|| ||\cos\theta||$
 $\vec{u} \cdot \vec{v} = 0$
 \vec{u}

Check Rinear =

$$f\left(\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}\right) = f\left(\begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \end{pmatrix}\right)$$

$$= \begin{pmatrix} 3(x_1 + x_2) \\ 2(x_1 + x_2) + (y_1 + y_2) \\ -(y_1 + y_1) \end{pmatrix}$$

$$= \begin{pmatrix} 3x_1 + 3x_2 \\ 2x_1 + y_1 + 2x_2 + y_2 \\ -y_1 - y_2 \end{pmatrix}$$

$$= \begin{pmatrix} 3x_1 \\ 2x_1 + y_1 \end{pmatrix} + \begin{pmatrix} 3x_1 \\ 2x_1 + y_1 \\ -y_1 \end{pmatrix}$$

$$= f\left(\begin{pmatrix} x_1 \\ y_1 \end{pmatrix}\right) + f\left(\begin{pmatrix} x_1 \\ y_2 \end{pmatrix}\right)$$

$$f\left(\begin{pmatrix} C(x) \\ y \end{pmatrix}\right) = \dots = cf\left(\begin{pmatrix} x_1 \\ y \end{pmatrix}\right)$$

$$f\left(\begin{pmatrix} C(x) \\ y \end{pmatrix}\right) = \dots = cf\left(\begin{pmatrix} x_1 \\ y \end{pmatrix}\right)$$

$$\frac{d}{dx} \left(f(x) + g(x)\right) = \frac{d}{dx}f(x) + \frac{d}{dx}g(x)$$

$$\frac{d}{dx} \left(cf(x)\right) = c \frac{d}{dx}f(x)$$

$$g\left(\begin{pmatrix} \mathcal{S} \\ \mathcal{S} \end{pmatrix}\right) = \frac{xy}{2}$$

$$g\left(c\begin{pmatrix} X \\ \mathcal{S} \end{pmatrix}\right) = g\left(\begin{pmatrix} cx \\ cy \end{pmatrix}\right) = (cx)(cy) = c^2xy$$

$$cg\left(\begin{pmatrix} X \\ \mathcal{S} \end{pmatrix}\right) = cxy$$

$$\begin{array}{cccc}
\vec{a} &= & \sum_{i=1}^{m} c_i \vec{u}_i \\
\vec{a} &= & \sum_{i=1}^{m} c_i \vec{u}_i
\end{array}$$

$$\begin{array}{ccccc}
basis vectors \\
\vec{u}_i &= & \\
\vec{u}_i &= & \\
\end{aligned}$$

$$\begin{array}{ccccc}
\vec{a} &= & \sum_{i=1}^{m} c_i Z(\vec{u}_i) \\
\vdots &= & \sum_{i=1}^{m} c_i Z(\vec{u}_i)
\end{array}$$

linear op is determined by its action on the basis vectors

matrix - vector multiplication:

Matrices "column view" M e Rm×n \(\begin{aligned} \begin{alig mxn matrix m rows n columns $\left(\begin{array}{c} u_{1}^{T} \\ \hline \\ u_{2}^{T} \end{array}\right).1 \times h$ \vdots \vdots \vdots \vdots block matrices kxp blocks more generally ... {((0)(1)) $\begin{pmatrix} 1 & 2 \\ -1 & 0 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ $= \begin{pmatrix} (12) \\ (-16) \\ (3.1) \end{pmatrix} = \begin{pmatrix} -u_1' - \\ -u_2' - \\ -u_3' - \end{pmatrix}$

$$\begin{pmatrix}
1 & 0 & \cdots & 0 \\
0 & 1 & \cdots & \vdots \\
\vdots & \vdots & \ddots & \vdots \\
0 & \cdots & 0
\end{pmatrix} = \begin{pmatrix}
1 & \overline{e}_{2} & \cdots & \overline{e}_{n} \\
\overline{e}_{1} & \overline{e}_{2} & \cdots & \overline{e}_{n}
\end{pmatrix}$$

$$= \left(\begin{array}{c} -e_{1}^{T} \\ \vdots \\ -e_{n}^{T} \end{array}\right)$$

Matrix - vector mult

$$P: = \sum_{j=1}^{m} M_{ij} \vec{V}_{j}$$

$$\begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix}$$

Matrix transpose

A E Rmxh

AT E Rnxm transpose of A:

$$\frac{1}{\left(A+B\right)^{T}} = A^{T} + B^{T}$$

$$(A^T)^T = A$$

$$(AB)^T = B^T A^T$$

$$\overrightarrow{X}^{T} \overrightarrow{A} \overrightarrow{B} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\xrightarrow{\mathbb{Z}} \underbrace{\mathbb{Z}}_{x} \underbrace{\mathbb{Z}}$$

$$\left(\mathbf{X}^{\mathsf{T}} \mathbf{A} \mathbf{b}\right)^{\mathsf{T}} = \left(\mathbf{b}^{\mathsf{T}} \mathbf{A}^{\mathsf{T}} \mathbf{X}\right)$$

$$Col(A) = Span(\vec{a}_1, ..., \vec{a}_n)$$

$$A = \begin{pmatrix} \vec{a_1} & \cdots & \vec{a_n} \\ l & & l \end{pmatrix}$$

$$A = \begin{pmatrix} \vec{a}_1 & \cdots & \vec{a}_n \\ 1 & 1 \end{pmatrix} \qquad \begin{cases} \vec{v} \mid \vec{v} = \sum_{i=1}^{n} c_i \vec{a}_i \end{cases}$$

 $\vec{y} = A\vec{x}$ $\vec{y} \in col(A)$

row(A) = Span rows of A