

$$A = LU$$

$$Ax = b$$

$$\underline{LU}x = b$$

$$\begin{pmatrix} 0 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

row permutations

For nonsingular A , \exists

$$PA = LU$$

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$$

a_{kk}

$$A = \begin{pmatrix} 10^{-20} & 1 \\ 1 & 1 \end{pmatrix}$$

$\overline{a_{kk}}$
tiny pivots are bad

$$\begin{pmatrix} 1 \\ 10^{20} \end{pmatrix}_{l_1} \begin{pmatrix} 10^{-20} & 1 \\ u_1^T \end{pmatrix} = \begin{pmatrix} 10^{-20} & 1 \\ 1 & 10^{20} \end{pmatrix}$$

$$A \cdot l_1 u_1^T = \begin{pmatrix} 0 & 0 \\ 0 & 1 - 10^{-20} \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \begin{pmatrix} 0 & 1 - 10^{-20} \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 10^{20} & 1 \end{pmatrix} \begin{pmatrix} 10^{-20} & 1 \\ 0 & 1-10^{20} \end{pmatrix} = \begin{pmatrix} 10^{-20} & 1 \\ 1 & 1 \end{pmatrix}$$

$L \qquad U \qquad A$

$|x - f(x)| < \frac{\epsilon}{2}$

$$\begin{pmatrix} 1 & 0 \\ 10^{20} & 1 \end{pmatrix} \begin{pmatrix} 10^{-20} & 1 \\ 0 & -10^{20} \end{pmatrix} = \begin{pmatrix} 10^{-20} & 1 \\ 1 & 0 \end{pmatrix}$$

$\tilde{L} \qquad \tilde{U} \qquad \tilde{A}$

backward error

$$A - \tilde{A} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$Ax = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow x = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\tilde{A}\tilde{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow \tilde{x} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

LU factorization is "unstable"
add pivoting to stabilize
(row permutation)

row permutations: $\underline{P}A = LU$

$$A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 3 & 7 \\ 2 & 4 & 8 \end{pmatrix} \quad \boxed{3}$$

$$\begin{pmatrix} 0 \\ 1/2 \\ 1 \end{pmatrix} \quad (2 \ 4 \ 8) \quad = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 2 & 4 \\ 2 & 4 & 8 \end{pmatrix}$$

$l_1 \quad u_1^T$

$$A - l_1 u_1^T = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 2 & 6 \\ 0 & 2 & 6 \end{pmatrix} \quad \boxed{1}$$

$$\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad (0 \ 1 \ 1) \quad = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$l_2 \quad u_2^T$

$$A - l_1 u_1^T - l_2 u_2^T = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \quad 2$$

$$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad (0 \ 0 \ 2) \quad =$$

$l_3 \quad u_3^T$

$$A = l_1 u_1^T + l_2 u_2^T + l_3 u_3^T = LU$$

$$\boxed{P} \begin{pmatrix} 0 & 1 & 1 \\ 1/2 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 4 & 8 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix} = PA$$

$\uparrow \quad \quad \quad u$

$\boxed{3, 1, 2}$
 $\underline{PA = LU}$

$$\underbrace{\begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}}_P A = \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \frac{1}{2} & 1 & 1 \end{pmatrix}}_L \begin{pmatrix} u \end{pmatrix}$$

$$L = P\hat{L}$$

$PA=LU$ partial pivoting = row pivoting
row permutation

complete pivoting

$$\underline{PAQ} = LU$$

$$\underbrace{\begin{pmatrix} | & | & & | \\ a_1 & a_2 & \dots & a_n \\ | & | & & | \end{pmatrix}}_A \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$\begin{pmatrix} | & | & & | \\ a_2 & a_1 & \dots & a_n \\ | & | & & | \end{pmatrix} \begin{pmatrix} x_2 \\ x_1 \\ \vdots \\ x_n \end{pmatrix}$$

$$AQ \underset{\uparrow}{Q^{-1}} \tilde{x} = \sum_{i=1}^n x_i \vec{a}_i$$

$$\underline{Q^{-1}} = Q^T$$

"orthogonal"
matrix

$$\underline{P} = \underline{P_n} \dots \underline{P_2} \underline{P_1}$$

$$\boxed{PAx=Pb}$$

$$(PAQ)Q^{-1}x=Pb$$

$$LU(Q^{-1}x)=Pb$$

$$LU \boxed{\tilde{x}} = Pb$$

$$\boxed{Q^{-1}x = \tilde{x}}$$

$$x = \underbrace{Q\tilde{x}}$$

Summary

Every nonsingular (i.e. invertible)
 $n \times n$ matrix A has

$$PA = LU$$

To solve $Ax = b$

① Find $PA = LU$

$$\underbrace{Lx = c}_{n^2}$$

② $PAx = L(Ux) = Pb$

③ Solve $Ly = Pb$ ($y = Ux$)

④ solve $U\vec{x} = y$

$$Ax = b$$

$$x = A^{-1}b$$

$$\begin{pmatrix} c_{11} & \dots & c_{1n} \\ \vdots & & \vdots \\ c_{n1} & \dots & c_{nn} \end{pmatrix} \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} = \begin{pmatrix} \square \end{pmatrix}$$

$$n(n + n - 1) = \underline{2n^2 - n}$$

Special linear systems

① Symmetric

$$A = A^T$$

$$\begin{pmatrix} 3 & 4 & 5 \\ 4 & 2 & -1 \\ 5 & -1 & 1 \end{pmatrix}$$

Laplacian

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) f$$



② Symmetric positive definite matrix

$$A = A^T$$

S.p.d.

$$\vec{x} \neq 0, \quad \underline{\vec{x}^T A \vec{x}} > 0 \quad A \text{ pos. def.}$$

$$x \neq 0 \quad x a x = \underbrace{a}_{\uparrow} x^2 > 0$$

A spd

(rotating) \Rightarrow

Cholesky
factorization

LU (no pivoting)
for $k=1, \dots, n$

if $a_{kk} \leq 0$ stop

$$l_{kk} = (a_{kk})^{1/2}$$

$$(l_{kk}=1)$$

for $i=k+1, \dots, n$

$$l_{ik} = a_{ik} / l_{kk}$$

end

for $i=k+1, \dots, n$

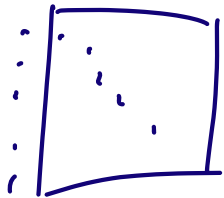
for $j=k+1, \dots, i$

$$a_{ij} \leftarrow a_{ij} - l_{ik} l_{jk}$$

end

end

end

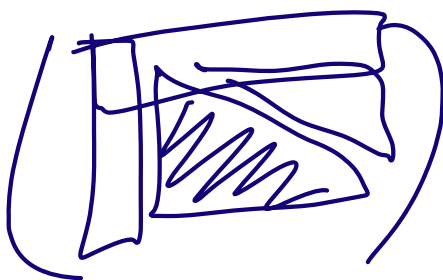
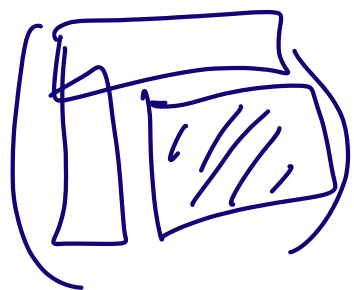


update
only
lower
tri
 $1/2$ ops

Cuts work
down by
 $1/2$

$$A = \underline{L} \underline{U}^T = \underline{L}_1 \underline{U}_1^T$$

~~$$\frac{2}{3} n^3$$~~

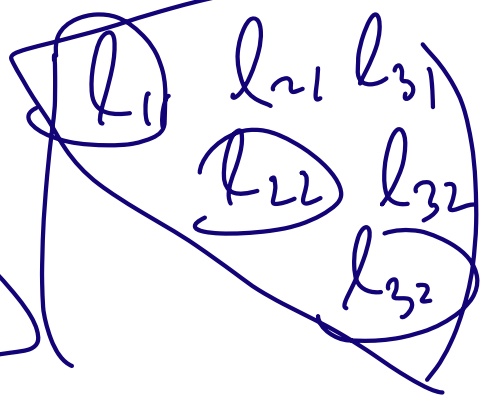
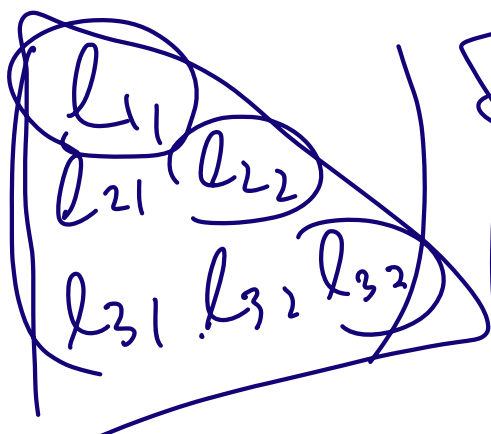


$$\frac{1}{3} n^3$$

LU

$$\begin{pmatrix} 1 & & \\ & 1 & \\ x & x & 1 \end{pmatrix} \begin{pmatrix} x & x & x \\ & x & x \\ & & x \end{pmatrix}$$

Cholesky



L

$$U = L^T$$

A

=

$$\underline{L} \underline{L}^T$$

$$\underline{R}^T \underline{R}$$

=

$$\underline{\tilde{L}} \underline{D} \underline{\tilde{L}}^T$$

\sim
L

unit tri

$$\begin{pmatrix} \boxed{3} & & \\ 1 & \boxed{4} & \\ & -1 & \boxed{2} \end{pmatrix}$$

$$\begin{pmatrix} & 1 & \\ 3 & & \\ & 1 & -1 \\ & & 2 \end{pmatrix}$$

L



L^T

$$\begin{pmatrix} 1 & & \\ 1/3 & 1 & \\ 1/3 & -1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} \boxed{3} & & \\ 0 & 1 & \\ 0 & 0 & 2 \end{pmatrix}$$

$$\begin{pmatrix} & 1 & \\ 3 & & \\ & & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1/3 & 1/3 \\ & 1 & -1 \\ & & 1 \end{pmatrix}$$

$D^{1/2}$

$D^{1/2}$

$$\begin{pmatrix} 1 & & \\ 1/3 & 1 & \\ 1/3 & -1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 9 & & \\ & 1 & \\ & & 4 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1/3 & 1/3 \\ & 1 & -1 \\ & & 1 \end{pmatrix}$$

$$LL^T$$

$$\tilde{L}D\tilde{L}^T \quad \text{symm.}$$

Cholesky factorization

A s.p.d.

① $\exists A = LL^T$

② stable w/o pivoting

③ $\frac{n^3}{3}$

④ can use Chol. fact.

to answer

A is SPD?

LDL^T