

QR

$$A = QR$$

$n \times n$

Q  $n \times n$  orthogonal matrix

R  $n \times n$  upper triangular

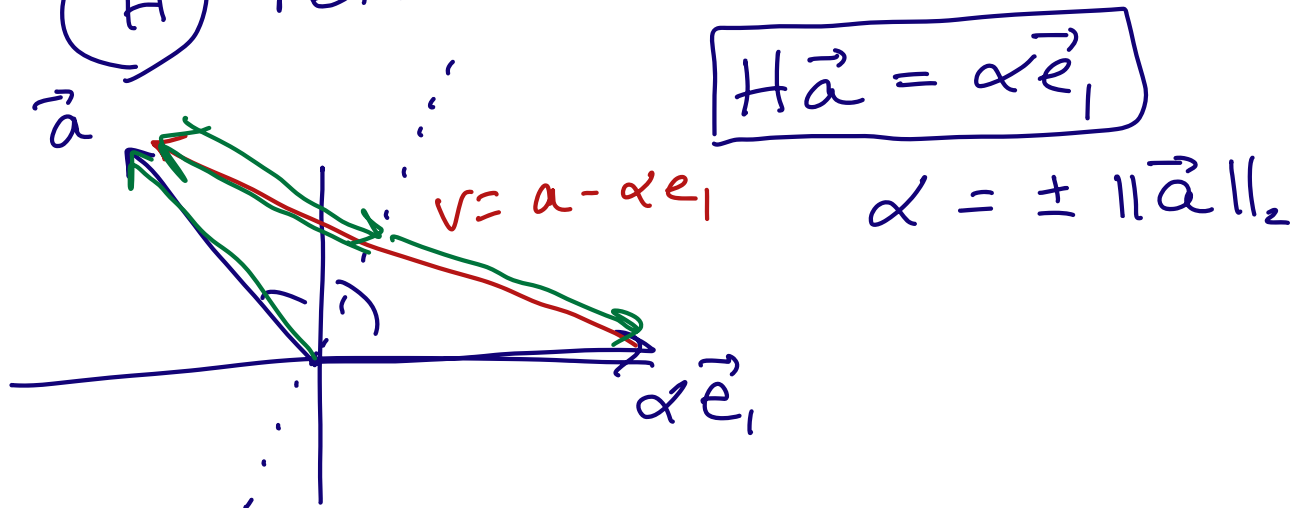
- classical Gram-Schmidt algorithm
- modified Gram-Schmidt
- Householder

Householder matrix  $(H^{-1} = H^T)$

$H$   $n \times n$  orthogonal matrix:

$$H^T H = H H^T = I$$

(H) reflection matrix  $\det(H) = -1$



$$Ha = a - 2 \frac{v v^T}{v^T v} a$$

$$Ha = \underbrace{\left( I - 2 \frac{v v^T}{v^T v} \right)}_H a$$

$$\vec{a} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$$

$$H \vec{a} = \begin{pmatrix} \alpha \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \alpha \vec{e}_1$$

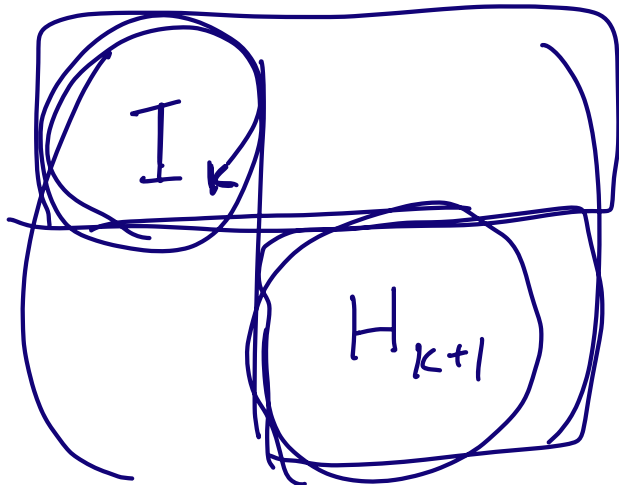
$$\vec{C} = \begin{pmatrix} C_1 \\ C_2 \\ C_3 \\ \vdots \\ C_n \end{pmatrix} \rightarrow \vec{C}_2 \quad \begin{matrix} \textcircled{H_2} \vec{C}_2 \\ (n-1) \times (n-1) \end{matrix} = \begin{pmatrix} \beta \\ 0 \\ \vdots \\ 0 \end{pmatrix}_{n-1}$$

$$\begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & & & & \\ \vdots & & \textcircled{H_2} & & \\ 0 & & & & \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \\ \vdots \\ C_n \end{pmatrix} = \begin{pmatrix} C_1 \\ 1 \\ H_2 C_2 \\ \vdots \end{pmatrix} = \begin{pmatrix} C_1 \\ \beta \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & H_2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & H_2^T \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & \textcircled{H_2 H_2^T} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & I_{n-1} \end{pmatrix}$$

$$= I_n$$



orthogonal

$$\begin{pmatrix} 1 \\ H_2 \end{pmatrix}$$

$$\left( \begin{array}{c|c} 1 & \\ \hline 1 & H_3 \end{array} \right)$$

# Householder QR

$$\boxed{A} = \boxed{Q} \boxed{R}$$

$$\begin{array}{c} \textcircled{H_1} \\ \uparrow \end{array} \underbrace{\begin{pmatrix} a_{11} & | & | \\ a_{21} & | & | \\ a_{31} & | & | \\ \vdots & | & | \\ a_{n1} & | & | \end{pmatrix}}_A = \begin{array}{c} \overline{Q^T A = R} \\ \uparrow \end{array} \begin{pmatrix} \alpha_1 & | & | \\ 0 & | & | \\ \vdots & | & | \\ 0 & | & | \end{pmatrix} \begin{pmatrix} | & | & | \\ H_1 a_2 & \dots & H_1 a_n \\ | & | & | \end{pmatrix}$$

$$H_2 H_1 A = \begin{pmatrix} | & | & | \\ \hline & \hat{H}_2 & \end{pmatrix} H_1 A = \begin{pmatrix} \alpha_1 & \cdot & \cdot & \cdot \\ 0 & \times & \times & \dots \times \\ \vdots & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot \end{pmatrix}$$

$$H_3 H_2 H_1 A = \begin{pmatrix} 1 & | & | \\ \hline & \hat{H}_3 & \end{pmatrix} H_2 H_1 A = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

$$\underbrace{\begin{array}{c} \downarrow \\ H_{n-1} \end{array} \dots \begin{array}{c} \downarrow \\ H_1 \end{array}}_A A = \begin{pmatrix} \times & \times & \times & \times \\ & \times & \times & \times \\ & & \times & \times \\ & & & \times \end{pmatrix}$$

$$Q^T A = R$$

$$\boxed{A = QR}$$

$$\underline{H}a = \underbrace{\left( I - 2 \frac{vv^T}{v^T v} \right)}_{\text{cheaper than gen. matrix-vec}} a \quad \underline{O(n)}$$

$$\boxed{(A)x \quad O(n^2)}$$

$$= a - 2 v \boxed{v^T a} \quad O(n)$$

$$= a - \underbrace{\left( \frac{2}{v^T v} \right) (v^T a)}_{\text{scalar}} v \quad O(n)$$

$$a \ominus \quad O(n)$$

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Q ?

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yet 1 more approach:

Givens rotations

SVD = Singular Value Decomposition

T&B: What if we take the SVD?

$$\underset{m \times n}{A} = \underset{m \times m}{U} \underset{m \times n}{\Sigma} \underset{n \times n}{V^T}$$

it exists for all matrices!

$U$ :  $m \times m$  orthogonal (unitary)

$V$ :  $n \times n$  orthogonal (unitary)

$\Sigma$ :  $m \times n$  diagonal with real positive entries s.t.

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > \sigma_{r+1} = \dots = \sigma_n = 0$$

$3 \times 2$

$$\begin{pmatrix} 100 & 0 \\ 0 & .01 \\ 0 & 0 \end{pmatrix}$$

$$\Sigma_{ii} \geq 0$$

$$\begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$r = \text{rank}(A)$$

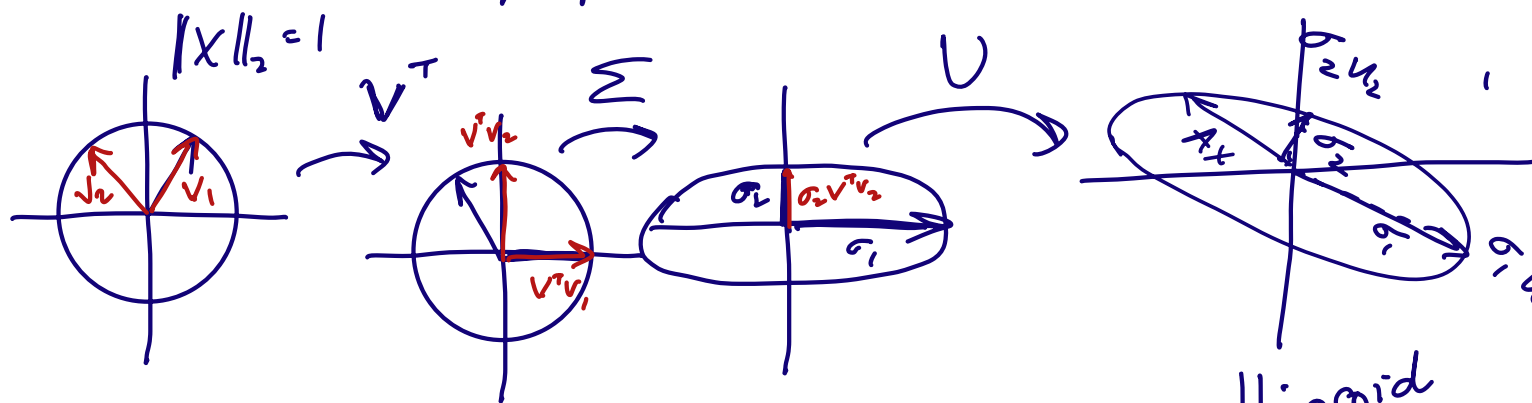
$$\sigma_1 \geq \sigma_2 > \sigma_3 = 0$$

$\sigma_i$ 's singular values of  $A$

$u_1, \dots, u_m$  left singular vectors  
 $v_1, \dots, v_n$  right " "

$$Ax = \underbrace{U}_{\uparrow} \underbrace{\Sigma}_{\uparrow} \underbrace{V^T}_{\uparrow} x$$

$$Ax \quad \forall \|x\|_2 = 1$$



$$\Sigma = \begin{pmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$V^T v_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$V^T v_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}$$

$$A = U \Sigma V^T$$

$$A v_i = U \Sigma V^T v_i = U \Sigma e_i$$

$$= U \sigma_i e_i$$

$$= \sigma_i \underbrace{U e_i}_{\vec{u}_i}$$

$$= \sigma_i \vec{u}_i$$



$$A = U \Sigma V^T$$

$$\underbrace{A}_{m \times n} \underbrace{V}_{n \times n} = \underbrace{U \Sigma}_{m \times m \quad m \times n} \underbrace{\quad}_{m \times n}$$

$$\boxed{(A v_i) = \sigma_i u_i} \quad i = 1, \dots, n$$

$$n \leq m$$

$$\begin{aligned} A_{m \times n} &= \begin{pmatrix} | & | & & | \\ u_1 & u_2 & \dots & u_m \\ | & | & & | \end{pmatrix} \begin{pmatrix} \boxed{\sigma_1} & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_n \end{pmatrix} \begin{pmatrix} - & v_1^T & - \\ - & v_2^T & - \\ & \vdots & \\ - & v_n^T & - \end{pmatrix} \\ &= \begin{pmatrix} | & | & & | \\ \sigma_1 u_1 & \sigma_2 u_2 & \dots & \sigma_n u_n \\ | & | & & | \end{pmatrix} \begin{pmatrix} - & v_1^T & - \\ - & v_2^T & - \\ & \vdots & \\ - & v_n^T & - \end{pmatrix} \end{aligned}$$

$$A = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \underbrace{\sigma_n u_n v_n^T}_{\nearrow 0}$$

$$\text{rank}(A) = r \leq \min(m, n)$$

$$A = \sum_{i=1}^r \sigma_i u_i v_i^T$$

$$r = \text{rank}(A)$$

reduced SVD

$$A = \begin{pmatrix} | & & | \\ u_1 & \dots & u_r \\ | & & | \end{pmatrix} \begin{pmatrix} \sigma_1 & \dots & \sigma_r \end{pmatrix} \begin{pmatrix} \text{---} v_1^T \text{---} \\ \vdots \\ \text{---} v_r^T \text{---} \end{pmatrix}$$

$m \times r \qquad r \times r$