Bertan Karacora

■ bertan.karacora@gmail.com | **Q** github.com/bertan-karacora | **⊕** bertan-karacora.github.io

EDUCATION

M.Sc. in Computer Science

Oct. 2022 – Present

University of Bonn

Bonn, Germany

- Current grade average: 1.1/1.0 (degree-relevant modules)
- Focus areas: Image Analysis, Deep Learning, Signal Processing, Intelligent Systems
- Thesis pending, expected completion: April 2026

B.Sc. in Computer Science

Oct. 2018 – Sep. 2022

University of Bonn

Bonn, Germany

• Final grade: 1.7/1.0

• Final grade: 1.7/1.0

• Thesis: Inverse Rendering of Wave Optical BRDFs (grade: 1.1/1.0)

General Qualification for University Entrance, "Abitur"

Jul. 2010 - Jun. 2018

Carl-Fuhlrott-Gymnasium (public secondary school)

Sui. 2010 - Suii. 2018 Wuppertal, Germany

• Final grade: 1.4/1.0

• Awarded the MINT-EC Certificate with distinction

EXPERIENCE

Student Teaching Assistant

Oct. 2025 - Mar. 2026

Computational Analytics Group, University of Bonn

Bonn, Germany

• Tutor for the course Introduction to High Performance Computing (Prof. Dr. Estela Suarez)

Student Research Assistant

Apr. 2024 – Sep. 2025

Autonomous Intelligent Systems Group, University of Bonn

Bonn, Germany

- Participated with team NimbRo at national and international RoboCup@Home competitions: RoboCup 2024 (Eindhoven, Netherlands, 1st place), RoboCup German Open 2025 (Nuremberg, 1st place), RoboCup 2025 (Salvador, Brazil, 2nd place)
- Integrated a fisheye lens camera system for domestic service robots with efficient dense depth estimation using GPU-based k-NN interpolation in 3D LiDAR pointclouds
- Built training and inference pipelines for DepthAnything V2 on embedded systems (Jetson Orin Nano)
- Integrated and optimized a state-of-the-art 2D LiDAR person detection method (DR-SPAAM)
- Designed and implemented a multi-sensor person detection, re-identification, and tracking pipeline including major adaptations of state-of-the-art methods
- Implemented and deployed the RoboCup@Home task "Help Me Carry" demonstrating person tracking, navigation and following, obstacle avoidance, person re-identification, grasping and carrying of objects

Student Teaching Assistant

Oct. 2022 - Mar. 2023

Technical Computer Science Group, University of Bonn

Bonn, Germany

• Tutor for the course Computer Engineering (Prof. Dr. Joachim Anlauf)

Working Student - Full-Stack Developer

Sep. 2020 – Sep. 2022

Pixelrein GmbH & Co. KG

Bonn, Germany

• Developed and optimized a full-stack web application for an SEO services marketplace, gaining experience in programming, system integration, and project collaboration

GNN Autoencoder pretraining on 3D Scene Graphs TODO

2024 - 2025

Person Tracking 2024 – 2025

TODO

Seminar Recent Advances in Geometry Processing

2024 - 2025

Topic: SuGaR: Surface-Aligned Gaussian Splatting for Efficient 3D Mesh Reconstruction and High-Quality Mesh Rendering (grade: 1.3/1.0) [report] [slides]

Protein Classification Challenge

2025

Optional course project. Participated in a Kaggle competition on Protein Classification using GNNs. [link]

Lab Visualization and Medical Image Analysis

2023 - 2024

Topic: The Impact of Fiber Orientation Features for Direct White Matter Tract Segmentation (grade: 1.0/1.0). [report][slides][code]

Seminar in Visual Computing

2023

Topic: Neural Parametric Models for 3D Deformable Shapes (grade: 1.0/1.0). [report] [slides]

Proteomic Analysis of Stress Granules-Associated Proteins

2022

Extracurricular work. Developed a tool for analysis of stress granules as a potential origin of abnormal protein aggregation in neurodegenerative diseases. The tool was used at the Medical Proteome Center, University of Bochum.

Inverse Rendering of Wave Optical BRDFs

2021 - 2022

Bachelor thesis (grade: 1.1/1.0). Implementation and evaluation of inverse rendering methods in consideration of wave-optical effects. [thesis][slides][code]

Trön Racing, Computer Animation Festival

2021

Course project. Developed an OpenGL-based video game prototype from scratch accompanying the lecture *Introduction* to Computer Graphics and Visualization. [video][code]

Lightweight Multi-Branch Network for Animal Re-Identification

2021

Bachelor lab project (grade: 1.0/1.0). Prepared a dataset of wild animals dataset captured using camera traps and adapted a person re-identification system for the task of animal re-identification. [report][slides][code]

Publications

Competition papers

RoboCup@Home 2024 OPL Winner NimbRo: Anthropomorphic Service Robots using Foundation Models for Perception and Planning, R. Memmesheimer, J. Nogga, B. Pätzold, E. Kruzhkov, S. Bultmann, M. Schreiber, J. Bode, B. Karacora, J. Park, A. Savinykh, S. Behnke. In: RoboCup 2024: Robot World Cup XXVII, Lecture Notes in Computer Science (LNCS), vol. 15570, pp. 515–527, Springer, April 2025.

SKILLS

Programming: Python (very good), C/C++, Matlab (good)

Frameworks: Pytorch (very good), Pytorch Geometric, Tensorflow, CUDA (good), OpenGL (basic)

Developer Tools: Git, VS Code, Docker, Bash, Linux system

Libraries: NumPy, Matplotlib, pandas, open3d Miscellaneous: LATEX, ROS 2, ONNX, TensorRT