

# Bertan Karacora

✉ bertan.karacora@gmail.com | 📞 +49 1525 8513315 | 🌐 bertan-karacora.github.io

## EDUCATION

---

### M.Sc. in Computer Science

Oct. 2022 – Present

*University of Bonn*

*Bonn, Germany*

- Current grade average: 1.1/1.0 (degree-relevant modules)
- Focus areas: Image Analysis, Deep Learning, Signal Processing, Intelligent Systems
- Thesis pending, expected completion: April 2026

### B.Sc. in Computer Science

Oct. 2018 – Sep. 2022

*University of Bonn*

*Bonn, Germany*

- Final grade: 1.7/1.0
- Thesis: *Inverse Rendering of Wave Optical BRDFs* (grade: 1.1/1.0)

### General Qualification for University Entrance, "Abitur"

Jul. 2010 – Jun. 2018

*Carl-Fuhlrott-Gymnasium (public secondary school)*

*Wuppertal, Germany*

- Final grade: 1.4/1.0
- Awarded the MINT-EC Certificate with distinction

## EXPERIENCE

---

### Student Teaching Assistant

Oct. 2025 – Mar. 2026

*Computational Analytics Group, University of Bonn*

*Bonn, Germany*

- Tutor for the course *Introduction to High Performance Computing* (Prof. Dr. Estela Suarez)

### Student Research Assistant

Apr. 2024 – Sep. 2025

*Autonomous Intelligent Systems Group, University of Bonn*

*Bonn, Germany*

- Participated with team NimbRo at national and international RoboCup@Home competitions: RoboCup 2024 (Eindhoven, Netherlands, 1st place), RoboCup German Open 2025 (Nuremberg, 1st place), RoboCup 2025 (Salvador, Brazil, 2nd place)
- Integrated a fisheye lens camera system for domestic service robots with efficient dense depth estimation using GPU-based k-NN interpolation in 3D LiDAR pointclouds
- Built training and inference pipelines for DepthAnything V2 on embedded systems (Jetson Orin Nano)
- Integrated and optimized a state-of-the-art 2D LiDAR person detection method (DR-SPAAM)
- Designed and implemented a multi-sensor person detection, re-identification, and tracking pipeline including major adaptations of state-of-the-art methods
- Implemented and deployed the RoboCup@Home task "Help Me Carry" demonstrating person tracking, navigation and following, obstacle avoidance, person re-identification, grasping and carrying of objects

### Student Teaching Assistant

Oct. 2022 – Mar. 2023

*Technical Computer Science Group, University of Bonn*

*Bonn, Germany*

- Tutor for the course *Computer Engineering* (Prof. Dr. Joachim Anlauf)

### Working Student - Full-Stack Developer

Sep. 2020 – Sep. 2022

*Pixelrein GmbH & Co. KG*

*Bonn, Germany*

- Developed and optimized a full-stack web application for an SEO services marketplace, gaining experience in programming, system integration, and project collaboration

## PROJECTS

---

<b>GNN Autoencoder pretraining on 3D Scene Graphs</b> TODO	2024 – 2025
<b>Person Tracking</b> TODO	2024 – 2025
<b>Surface-Aligned Gaussian Splatting for Efficient 3D Mesh Reconstruction and Rendering</b> Seminar project in <i>Recent Advances in Geometry Processing</i> (grade: 1.3/1.0) [report] [slides]	2024 – 2025
<b>Protein Classification Challenge</b> Optional course project in <i>Geometric Deep Learning</i> . Participated in a Kaggle competition on Protein Classification using GNNs. [link]	2025
<b>The Impact of Fiber Orientation Features for Direct White Matter Tract Segmentation</b> Lab project in <i>Visualization and Medical Image Analysis</i> (grade: 1.0/1.0). [report][slides][code]	2023 – 2024
<b>Neural Parametric Models for 3D Deformable Shapes</b> Seminar project in <i>Visual Computing</i> (grade: 1.0/1.0). [report] [slides]	2023
<b>Proteomic Analysis of Stress Granules-Associated Proteins</b> Extracurricular work. Developed a tool for processing, analysis and visualizing multiple datasets of stress granules-associated proteins to explore their role in neurodegenerative diseases. The tool was used by my brother Bilhan Karacora at the Medical Proteome Center, University of Bochum.	2022
<b>Inverse Rendering of Wave Optical BRDFs</b> Bachelor thesis (grade: 1.1/1.0). Developed, implemented and evaluated inverse rendering methods in consideration of wave-optical effects using BRDF slices. [thesis][slides][code]	2021 – 2022
<b>Trön Racing, Computer Animation Festival</b> Course project in <i>Introduction to Computer Graphics and Visualization</i> (ungraded). Developed an OpenGL-based video game prototype from scratch. [video][code]	2021
<b>Lightweight Multi-Branch Network for Animal Re-Identification</b> Bachelor lab project (grade: 1.0/1.0). Prepared a dataset of wild animals dataset captured using camera traps and adapted a person re-identification system for the task of animal re-identification. [report][slides][code]	2021

## PUBLICATIONS

---

Competition papers

**RoboCup@Home 2024 OPL Winner NimbRo: Anthropomorphic Service Robots using Foundation Models for Perception and Planning**, R. Memmesheimer, J. Nogga, B. Pätzold, E. Kruzhkov, S. Bultmann, M. Schreiber, J. Bode, **B. Karacora**, J. Park, A. Savinykh, S. Behnke. In: RoboCup 2024: Robot World Cup XXVII, Lecture Notes in Computer Science (LNCS), vol. 15570, pp. 515–527, Springer, April 2025.

## SKILLS

---

**Programming:** Python (very good), C/C++, Matlab (good)

**Frameworks:** Pytorch (very good), Pytorch Geometric, Tensorflow, CUDA (good), OpenGL (basic)

**Developer Tools:** Git, VS Code, Docker, Bash, Linux system

**Libraries:** NumPy, Matplotlib, pandas, open3d

**Miscellaneous:**  $\text{\LaTeX}$ , ROS 2, ONNX, TensorRT