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Image Segmentation



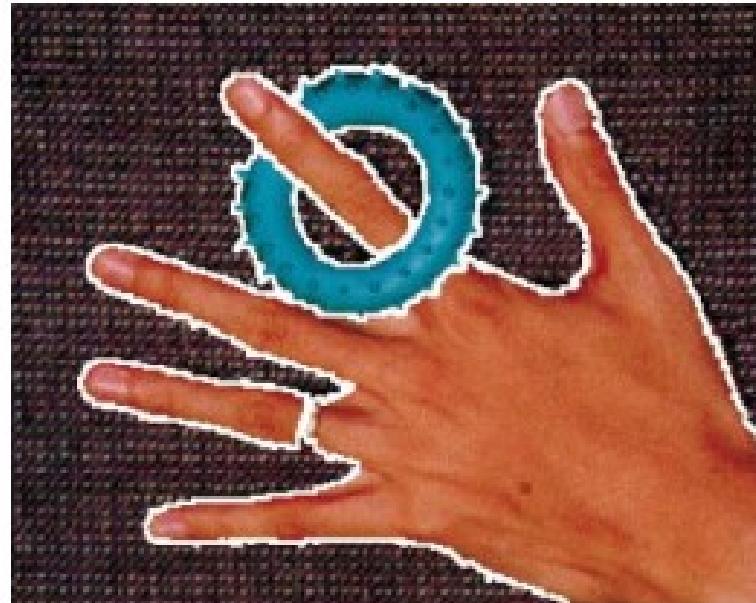
- What does “segmentation” means?
- K-Means
- Mean-shift

- [FP] D. A. Forsyth and J. Ponce. Computer Vision: A Modern Approach (2nd Edition). Prentice Hall, 2011.
- CS231A · Computer Vision: from 3D reconstruction to recognition
 - Prof. Silvio Savarese – Stanford University
- CS131 · Computer Vision: Foundations and Applications
 - Prof. Fei-Fei Li – Stanford University
- Elementi di Analisi per Visione Artificiale
 - Paolo Medici <http://www.ce.unipr.it/people/medici>

What does segmentation means?



- Extraction of homogeneous parts of an image → **components**
- Usually a more compact representation of an image



Why we use segmentation?



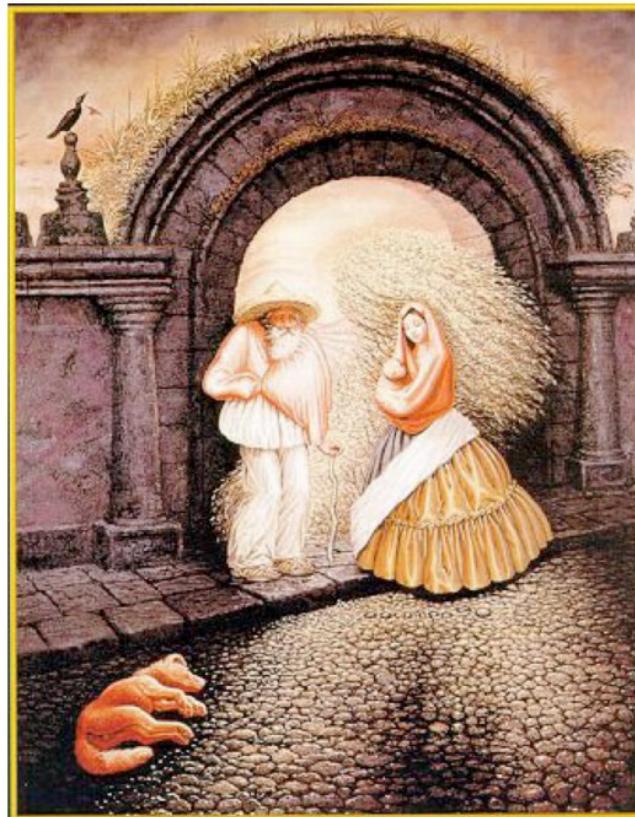
- From image to description
 - Low level → medium level
- Components are often blocks for other algorithms



What does segmentation means?

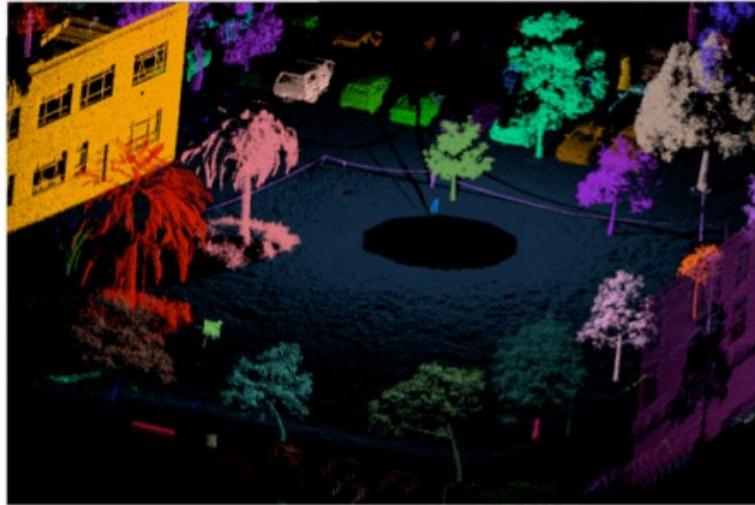
- Extraction of homogeneous parts of an image → **components**
- Usually a more compact representation of an image
- Components share common properties
- Different levels of abstraction for properties

What does segmentation means?

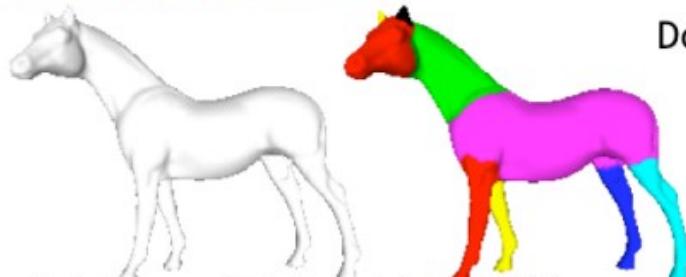


Source: Silvio Savarese

What does segmentation means?



Douillard, et al. ICRA 2011



<http://www-rech.telecom-lille1.eu/shrec2012-segmentation/>

How do humans segment?

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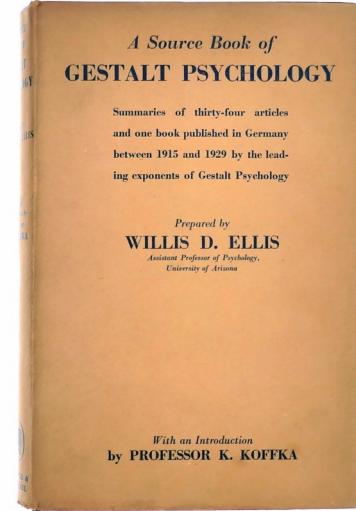
How do humans segment?

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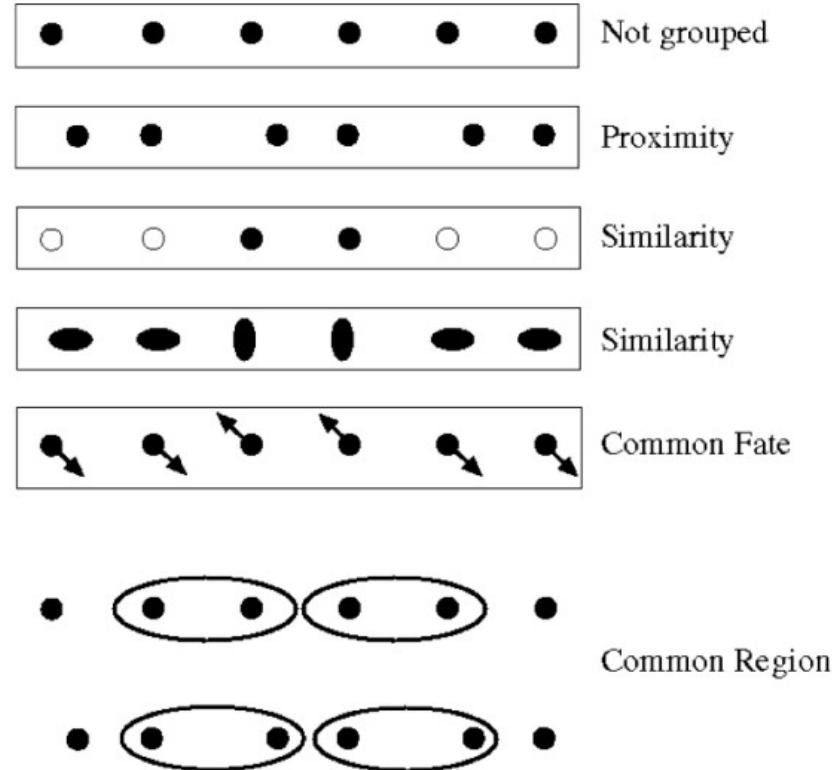


- German word for “shape”, “structure”
- The brain is holistic and parallel
 - Namely no “simple steps” as for algorithms
- Whole is greater than the sum of its parts
 - We perceive objects in their entirety
 - Only after that we perceive details
- What are the principles that allow us to do so?





-A series of factors affect whether elements should be grouped together



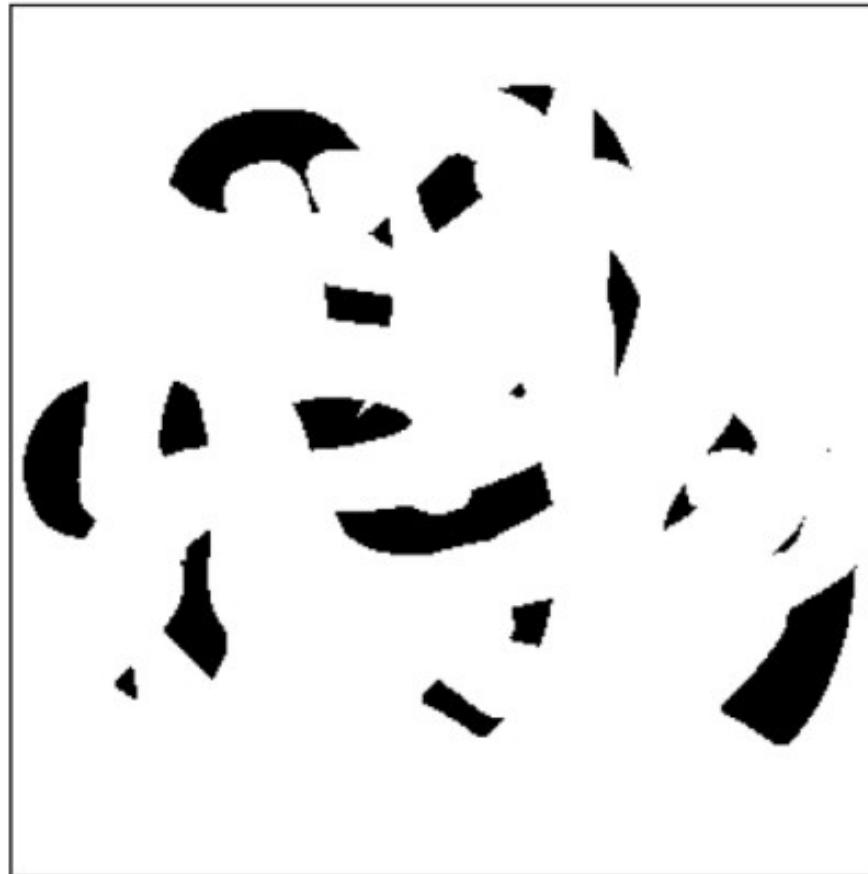


Grouping
by occlusions



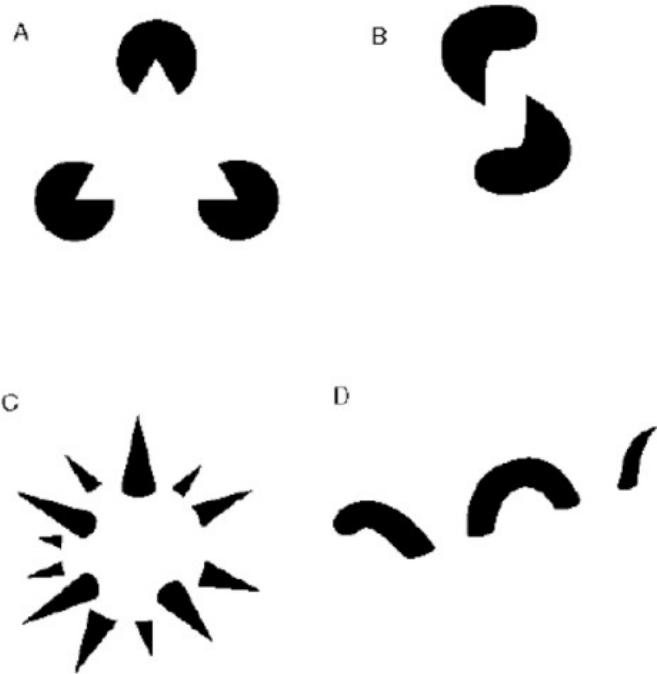


Grouping by occlusions



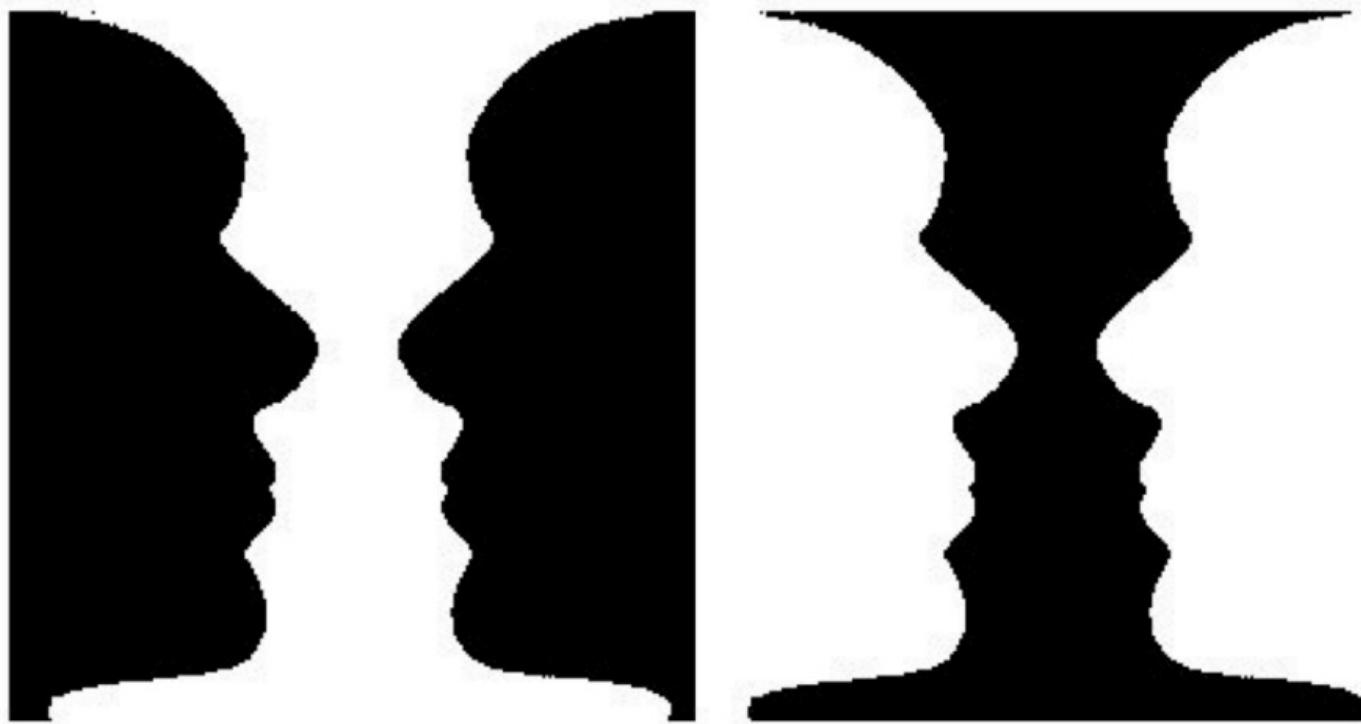


Grouping
by invisible
completions



Gestalt

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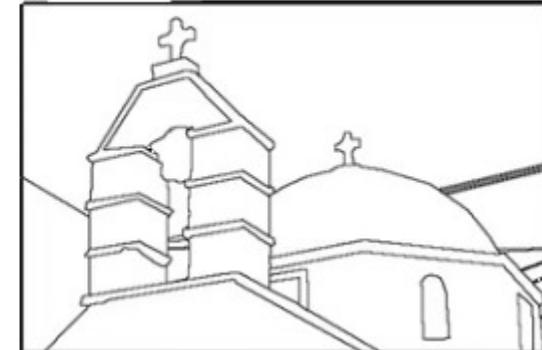
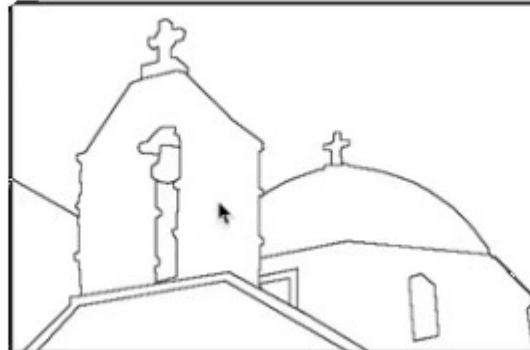
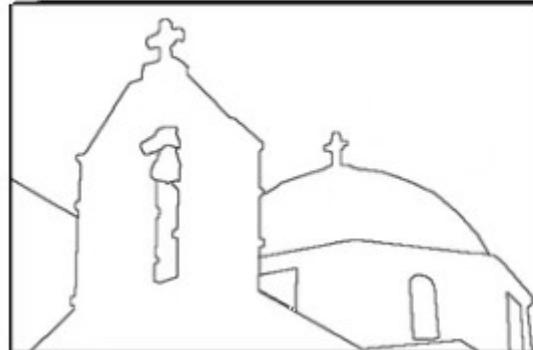




If we ask to different users to segmentate, different results are obtained



**Segmentation is
HIGHLY
Subjective!**

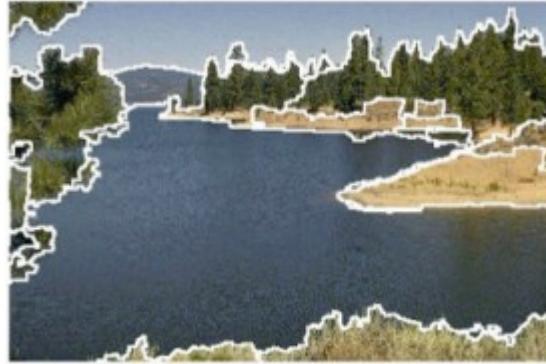


- Segmentation is intuitive for us
 - Even if highly subjective
- Very hard to translate it to an algorithm!
 - If we do not know how it works, how we can write an algorithm?
- Anyway two basic approaches

Strategies



- Bottom-up: components are locally coherent



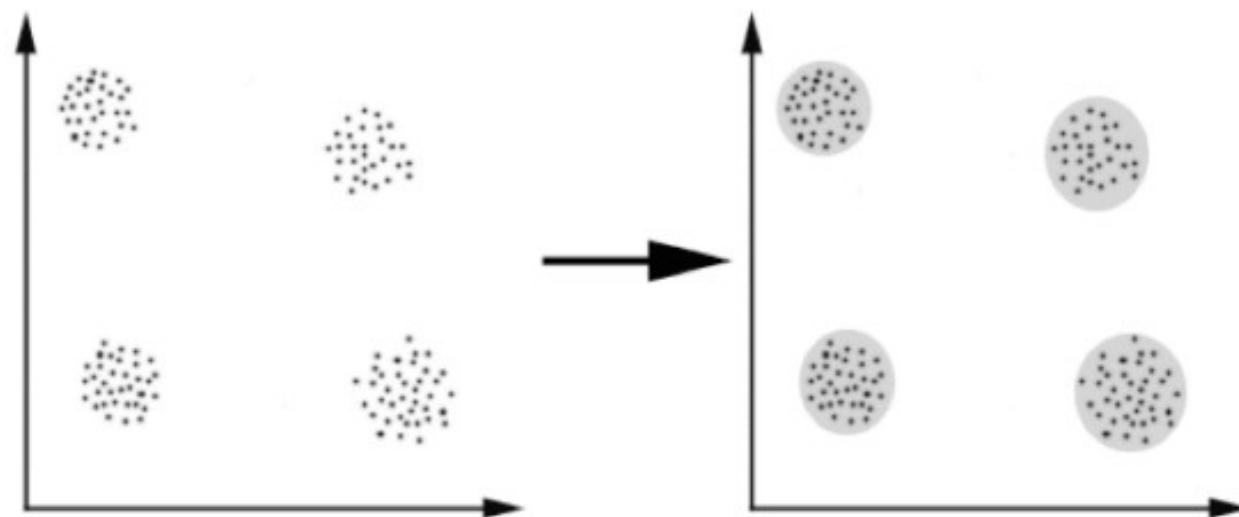
- Top-down: components belong to same entity (object, scene...)



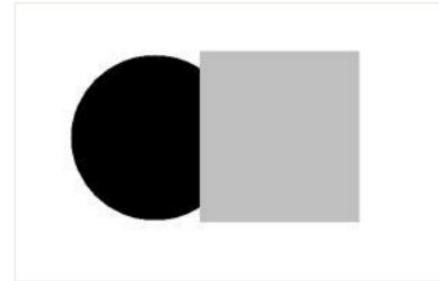
Clustering



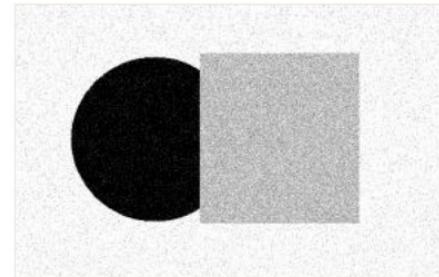
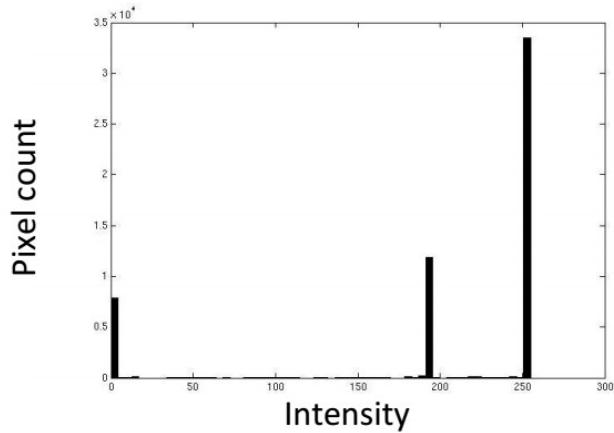
- Each point belongs to a specific “cluster”
- It depends on points visual characteristics
 - A “vector”



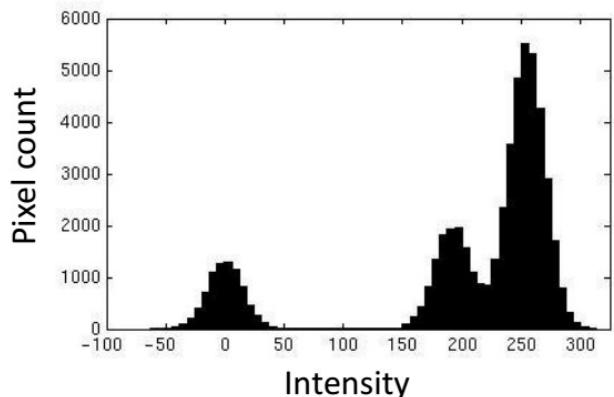
Clustering



Input image



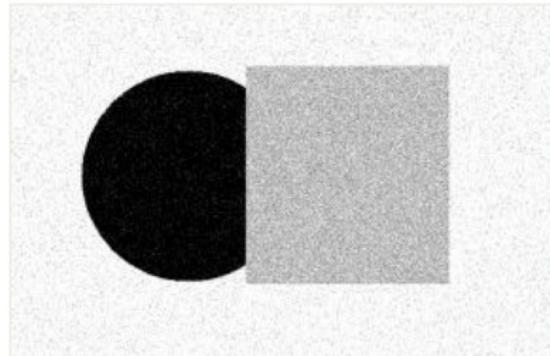
Input image



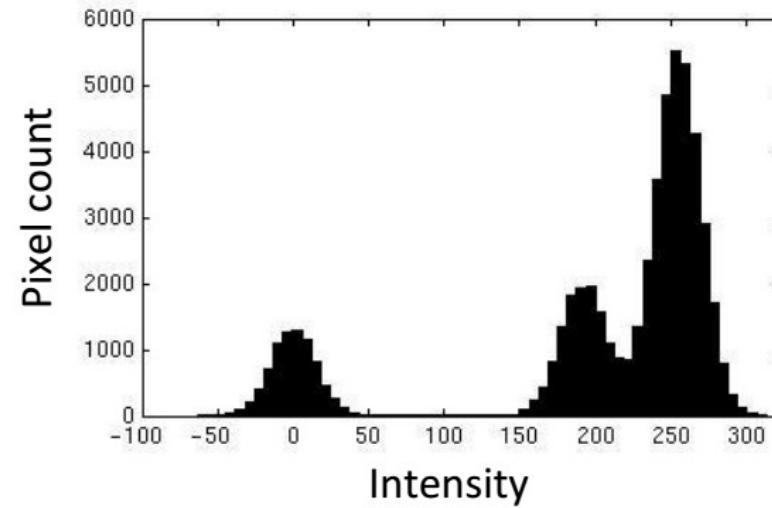
Clustering



- Clustering → identify different luminance levels



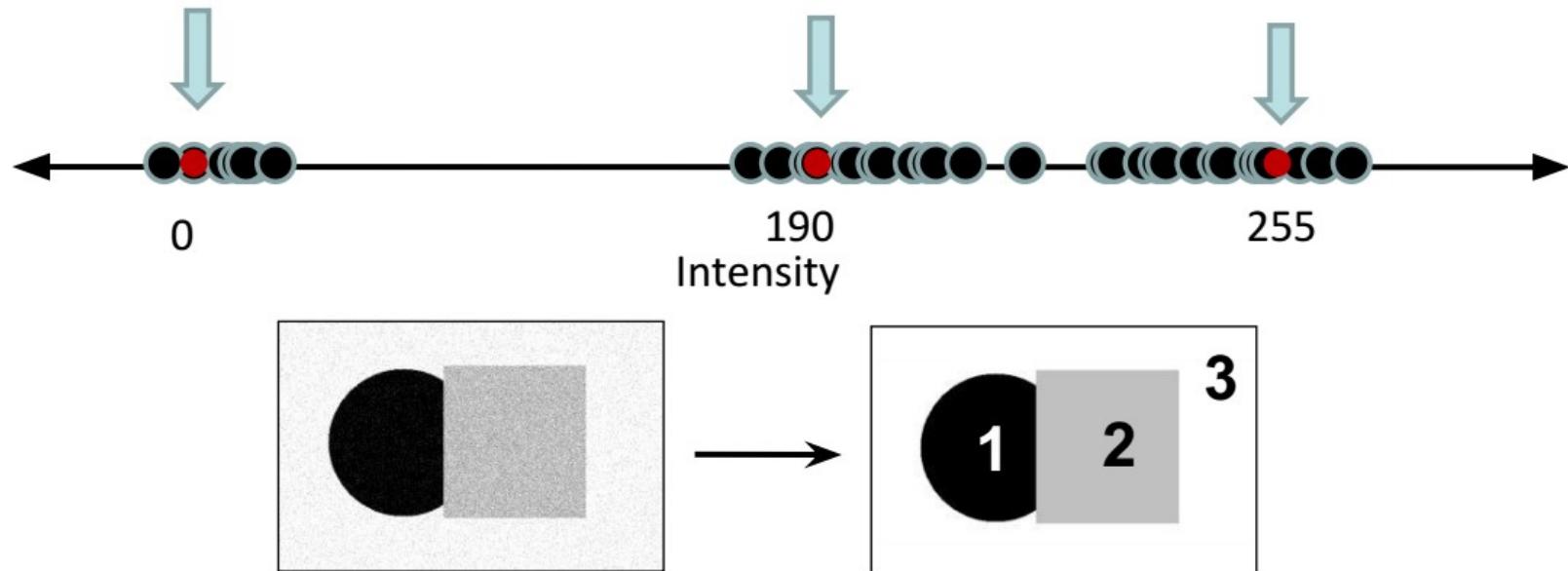
Input image



Clustering



- Clustering → identify different luminance levels
 - Associate each pixel to a specific cluster

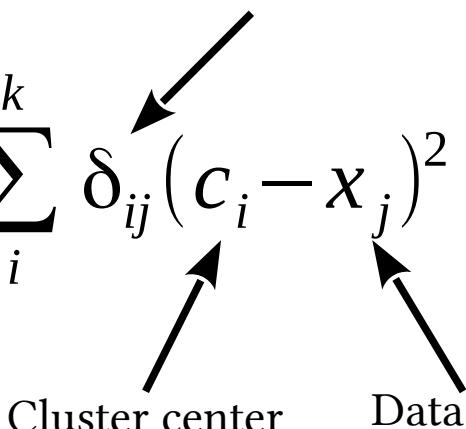




- Underlying idea: minimize “distance” of each “pixel” from cluster center
 - Given N data & k clusters:

$$c^*, \delta^* = \arg \min_{c, \delta} \frac{1}{N} \sum_j^N \sum_i^k \delta_{ij} (c_i - x_j)^2$$

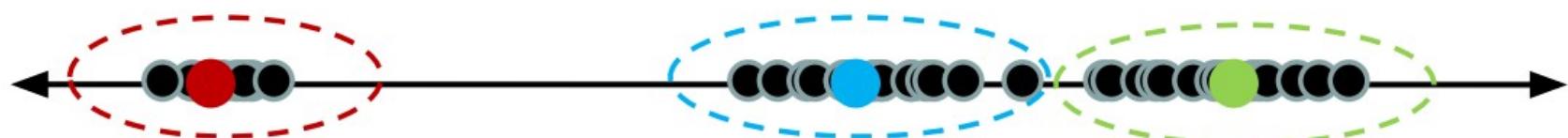
Is x_j belonging to c_i ?



The diagram illustrates the components of the clustering cost function. It shows a mathematical expression where the term δ_{ij} is highlighted with three arrows pointing to its components: "Cluster center" (pointing to c_i), "Data" (pointing to x_j), and "Is x_j belonging to c_i ?".



- Not well defined...
 - If we know cluster centers → easy points assignment
 - If we know groups → easy to compute centroids



Clustering techniques

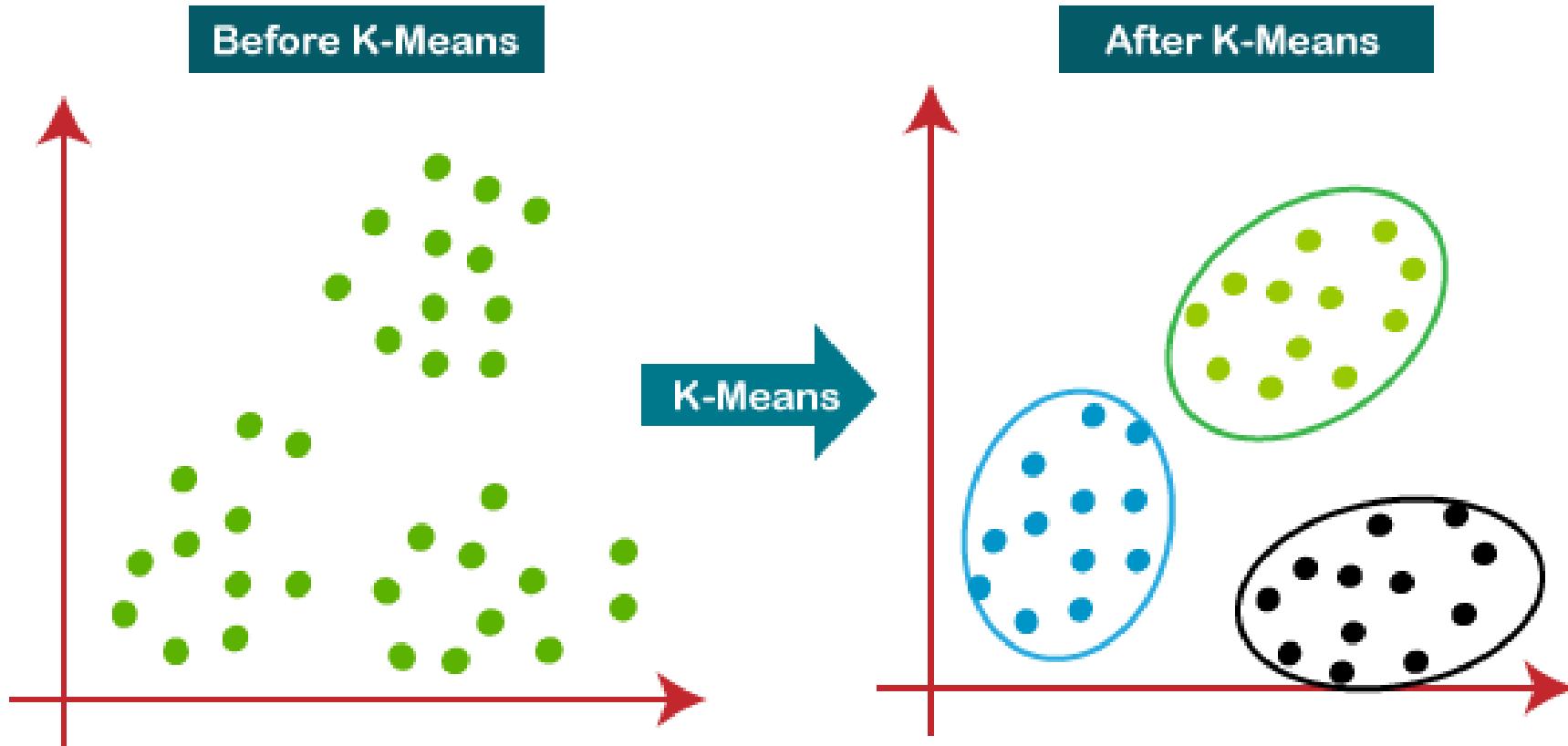
- K-Means
 - Predefined number of clusters
 - “Spherical” clusters
- Mean-shift
 - Variable number of clusters
 - No a priori shape assumptions
 - Slow



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K-means clustering

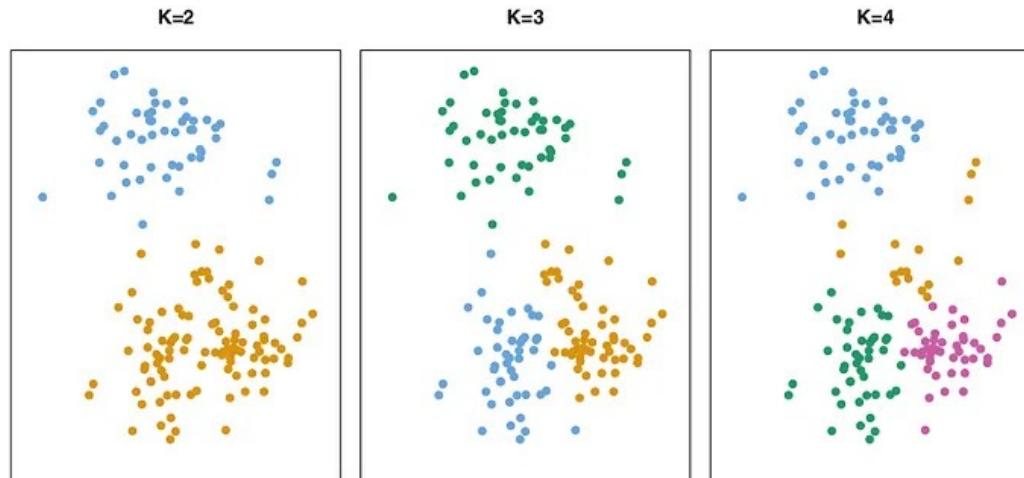
K-Means clustering



K-Means clustering



- The underlying idea under k-means clustering is to guess the number of clusters
 - Namely the “k” in k-means



K-Means clustering

- Initialization
 - Choose k cluster centers
- Repeat
 - Assignment step:
 - For each point find the closest center
 - Update step
 - Update every center as the mean of its points
- Until
 - A maximum number of iterations is reached
 - No or little changes during Assignment step



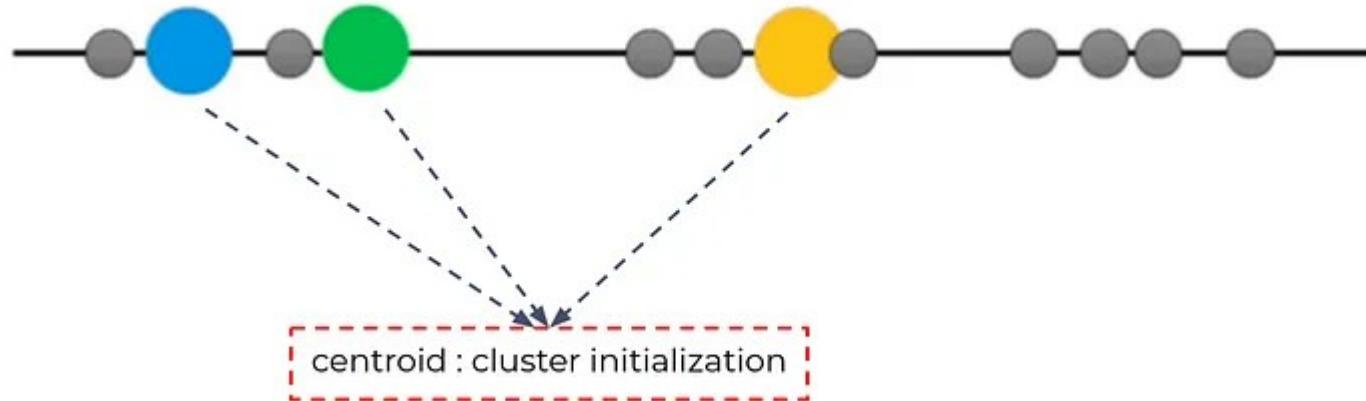
- Initialization
 - Choose k cluster centers
 - The value can be critical, since it can lead to completely different results
- How to select them?
 - randomly
 - k points of the set



K-Means clustering



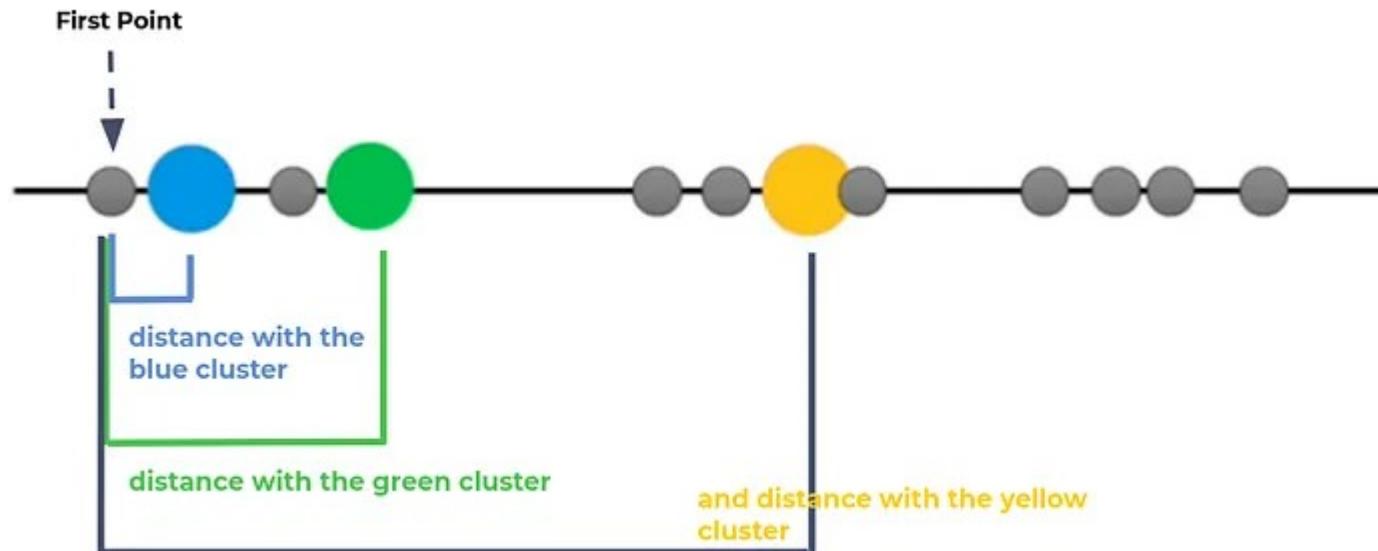
- In our example
 - $k = 3$
 - 3 points are selected as center of clusters



K-Means clustering



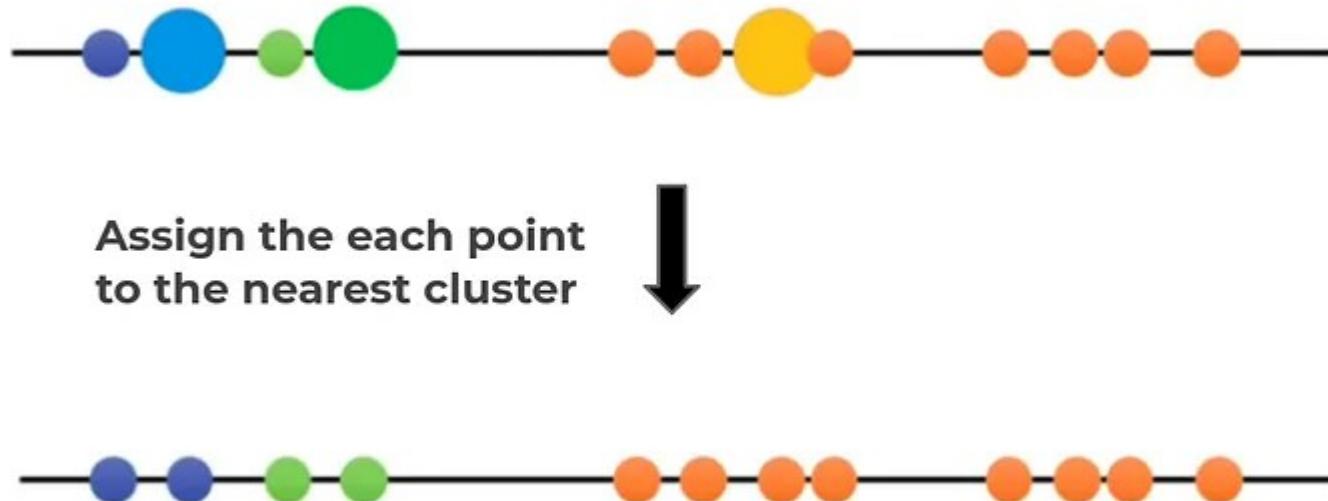
- Assignment
 - For each point find the closest center
 - In our case euclidean distance is used



K-Means clustering



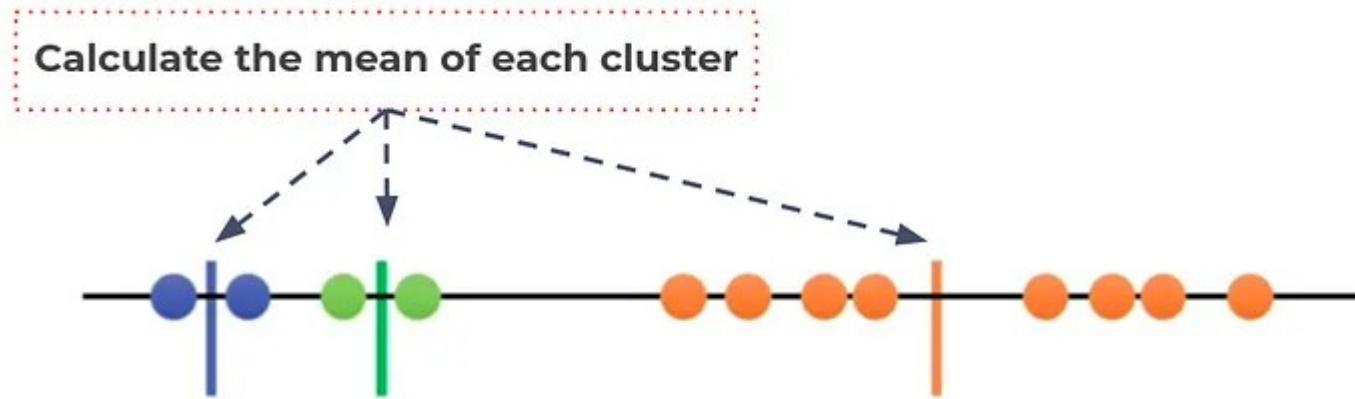
- Assignment
 - For each point find the closest center
 - In our case euclidean distance is used



K-Means clustering



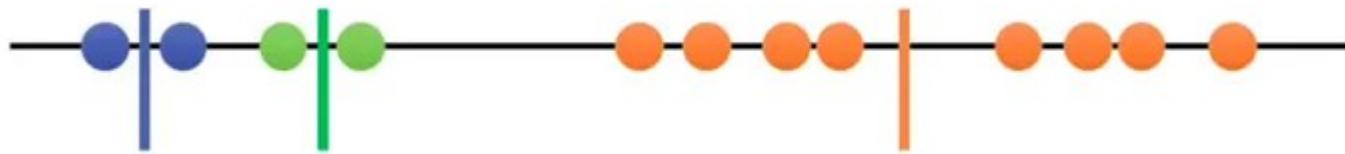
- Update step
 - Update every center as the mean of its points



K-Means clustering



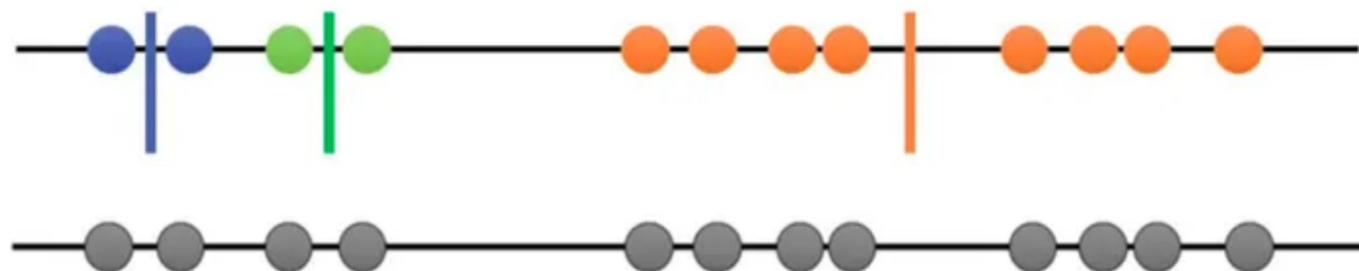
- Repeat
 - Assignment & Update
 - Until no or little changes or a fixed amount of iterations



K-Means clustering



- K-means is extremely sensitive to initialization
- Bad initialization → bad overall clustering
- Potential solutions:
 - K “spread out” points (k-means++)
 - Try multiple initializations



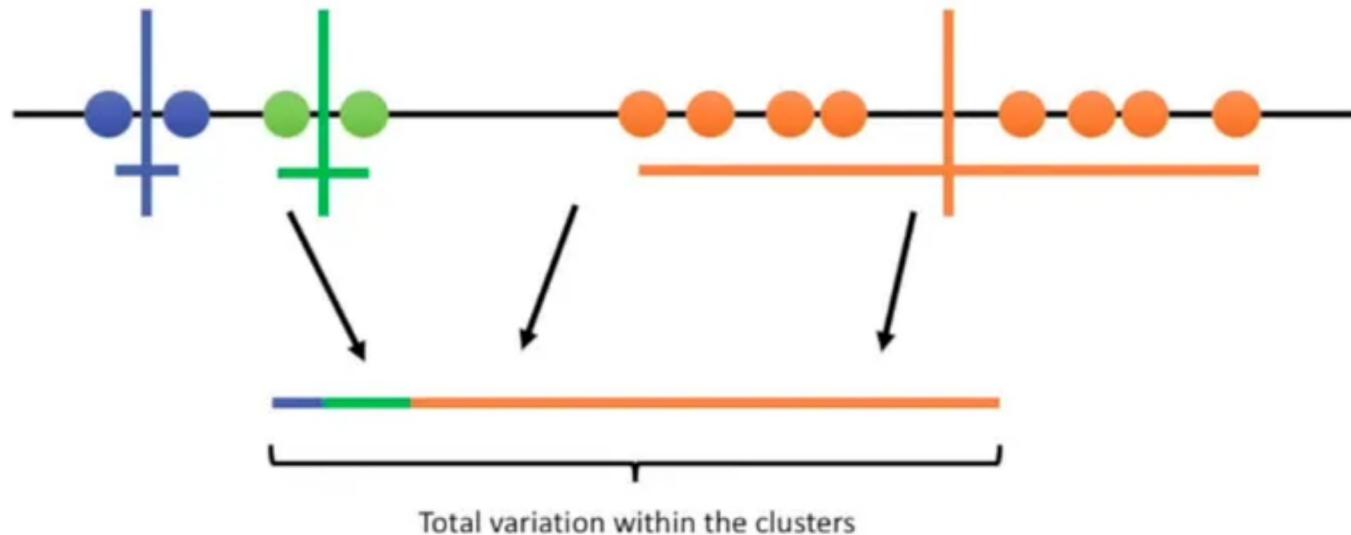
K-Means clustering

- K-means++ approach for initialization
 - Randomly select first center
 - Pick other centers using a probability proportional to $\sum_i (x - c_i)^2$
 - Expected error $\sim \log(k)$

K-Means clustering



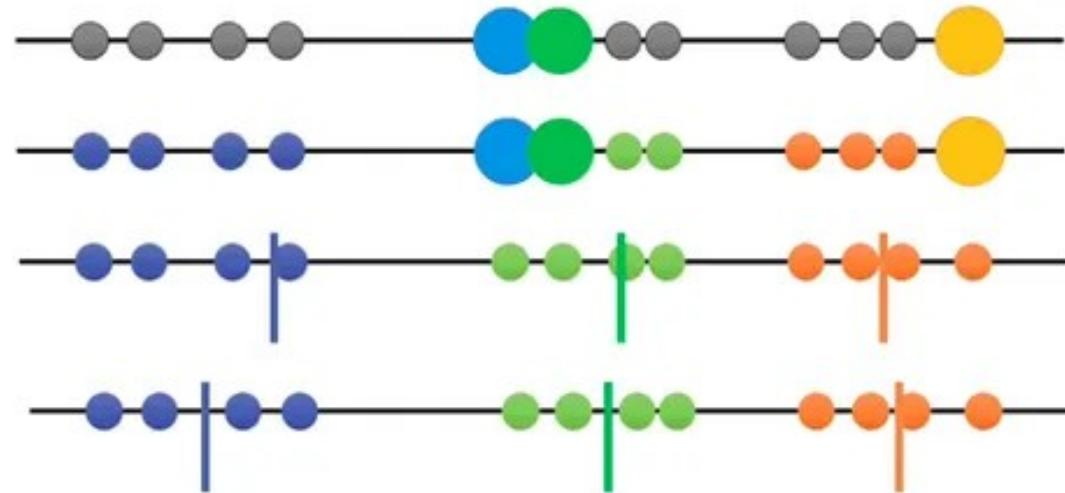
- Multiple initializations
 - Given a first try, asses the quality of the result
 - Compute the variance of each cluster



K-Means clustering



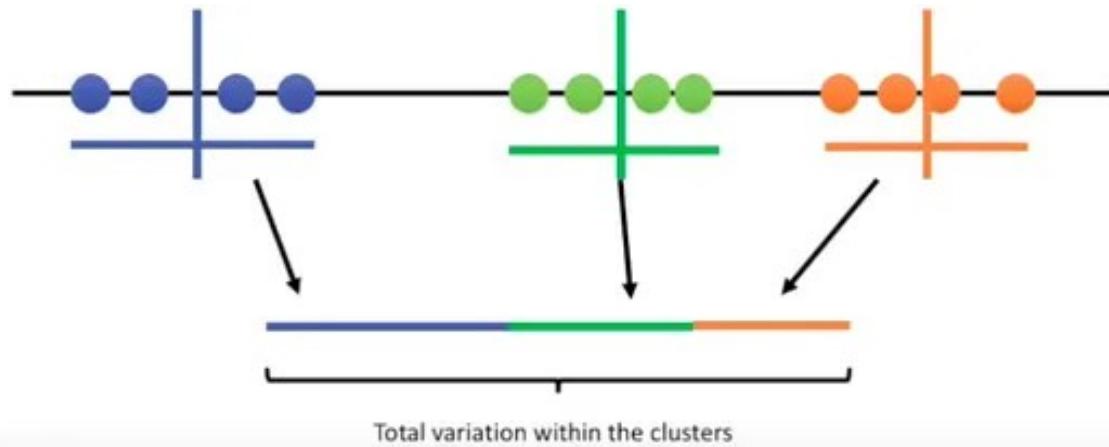
- Repeat again “until” we obtain the minimum variance



K-Means clustering

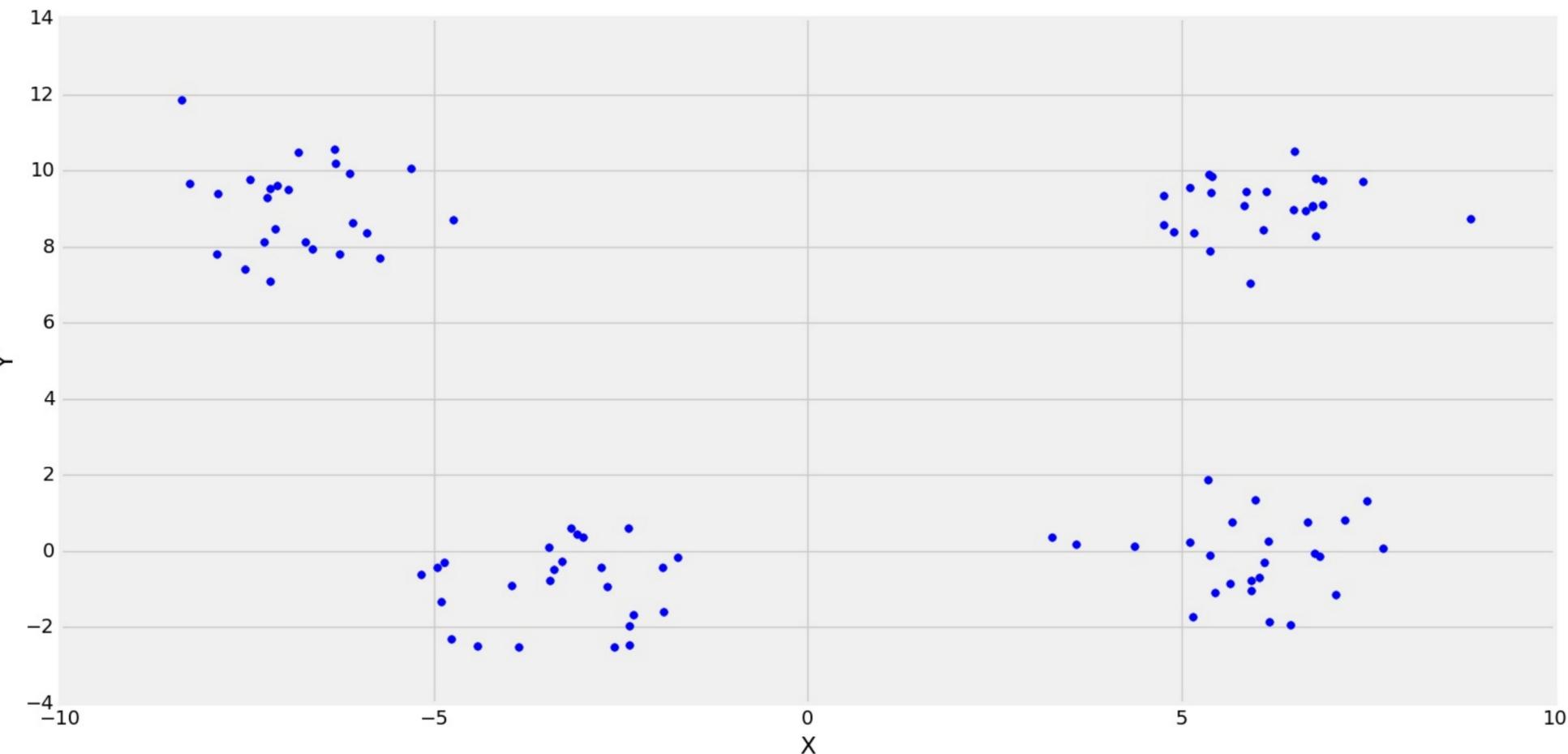


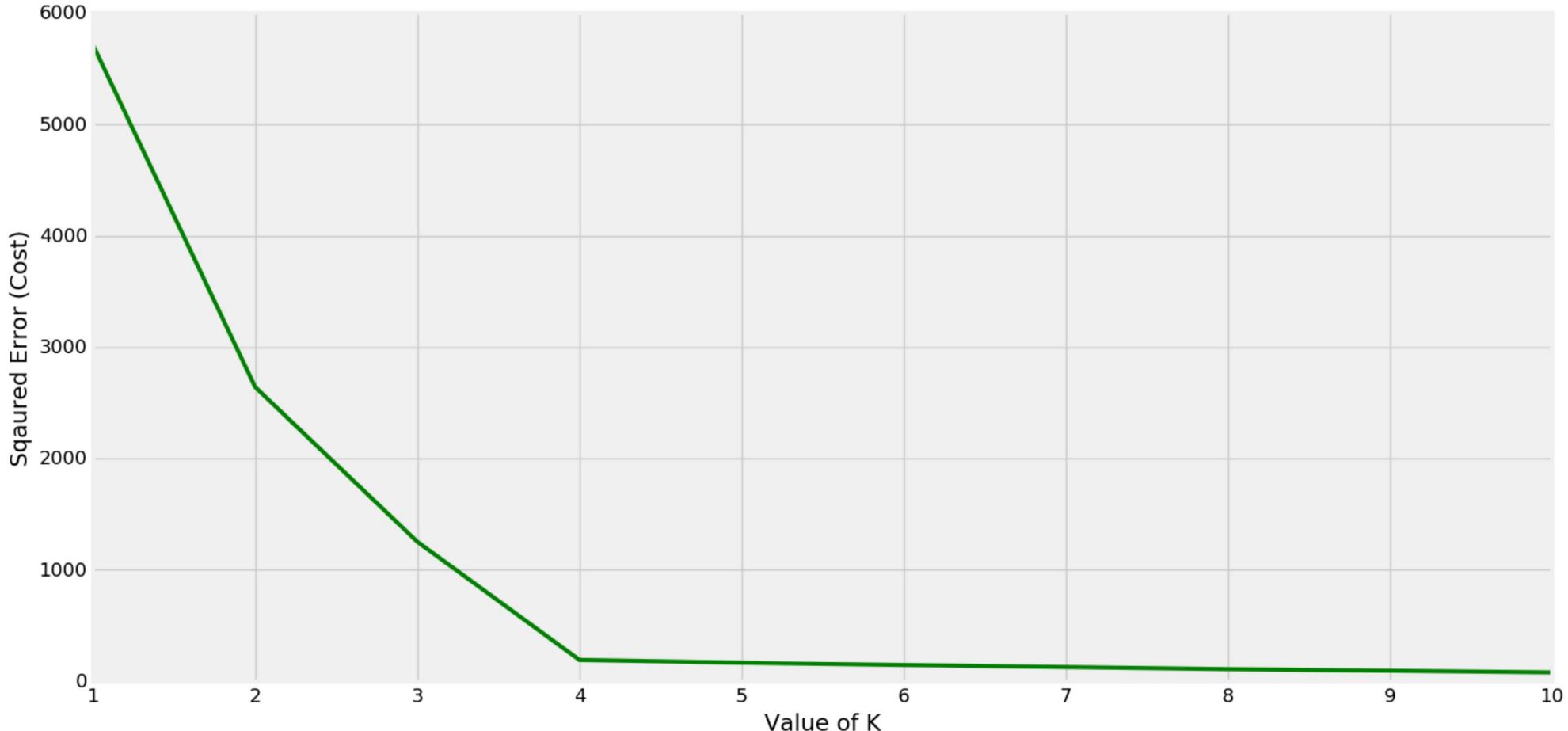
- Repeat again until we obtain the minimum variance



K-Means clustering

- How to choose a proper value for k ?
- Test different ks
 - When k increases → fewer elements in each cluster
 - Also average distortion declines
 - The k value where distortion declines the most is the “elbow” point





Features

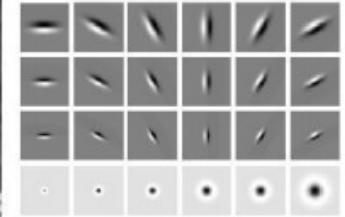


- In previous slides we used Euclidean distance as a cost function
- We can select other approaches
 - Intensity clustering
 - Color clustering
 - Texture clustering
 - ...

.
s.



$$\begin{cases} R=255 \\ G=200 \end{cases}$$



Filter bank of
24 filters

Features



- Not always image space coherence
- As example when using color clustering we have a vector clustering

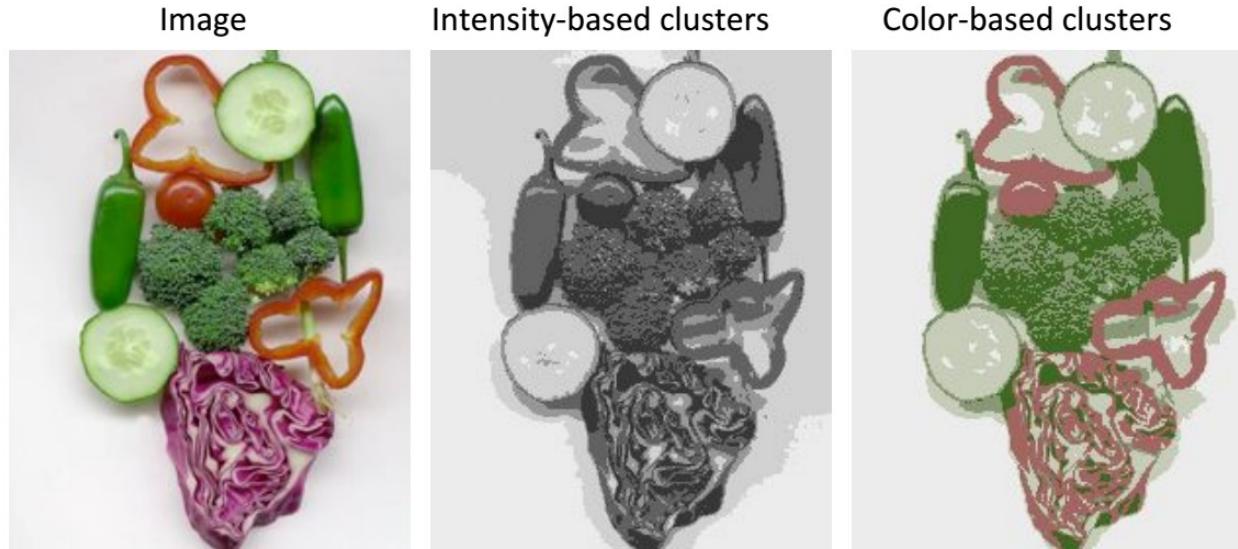
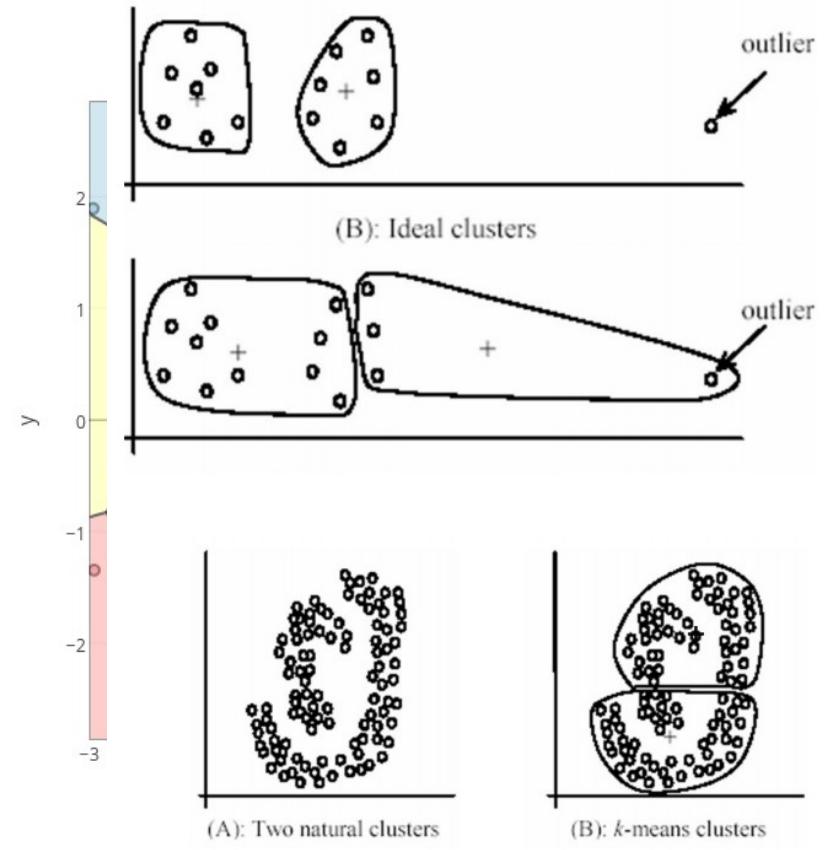


Image source: Forsyth & Ponce

K-means limits

- Each point is assigned to a given cluster
 - No probability function
- Very sensitive to outliers
 - Centroids are affected
 - K-Medians is a K-Means variant to cope with this
- Good with “round shaped” clusters
- Bad with convex distributions
 - Voronoid space



- Images can not be a suitable data for clustering
- We need to extract relevant data → vector
- The output of k-means us then
 - A list of centroids
 - Labelled data
 - Compactness measure (quality of the result)

K-means OpenCV

```
double cv::kmeans  (
    InputArray data,                                // vector of data
    int K,                                         // the K in K-means
    InputOutputArray bestLabels,                     // labels (output/input)
    TermCriteria criteria,                          // termination criteria
    int attempts,                                   // number of tries
    int flags,                                     // flags
    OutputArray centers = noArray()                // centroids list
)
```



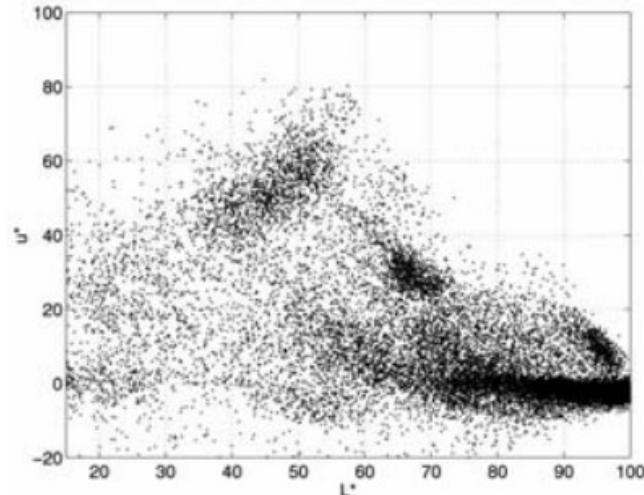
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Mean-shift clustering

Mean shift



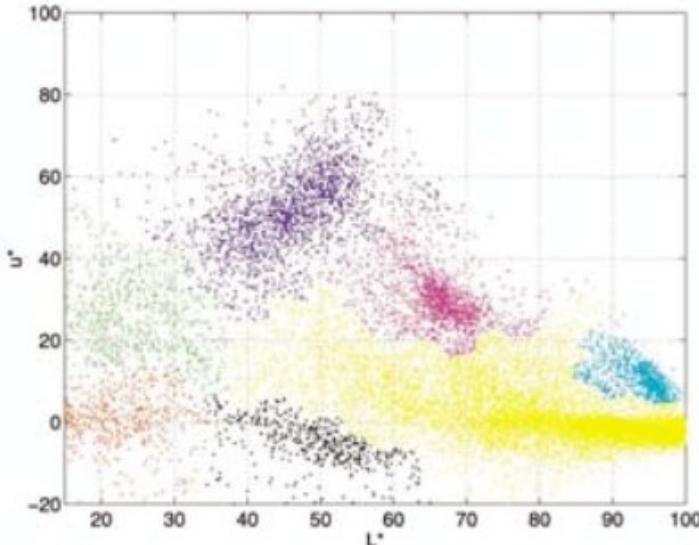
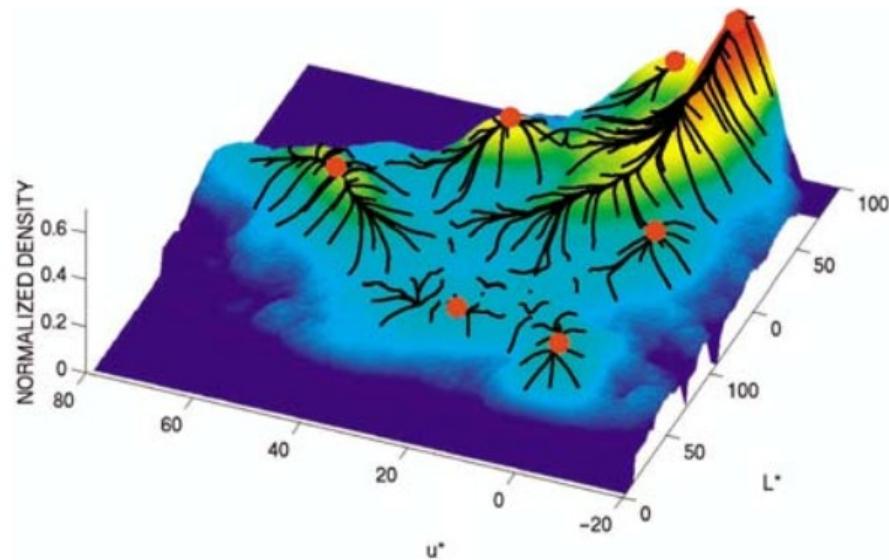
- As for k-means we work on data, not directly on images
 - For simplicity we assume a 2D data
 - Higher dimensionality is anyway possible



Mean shift

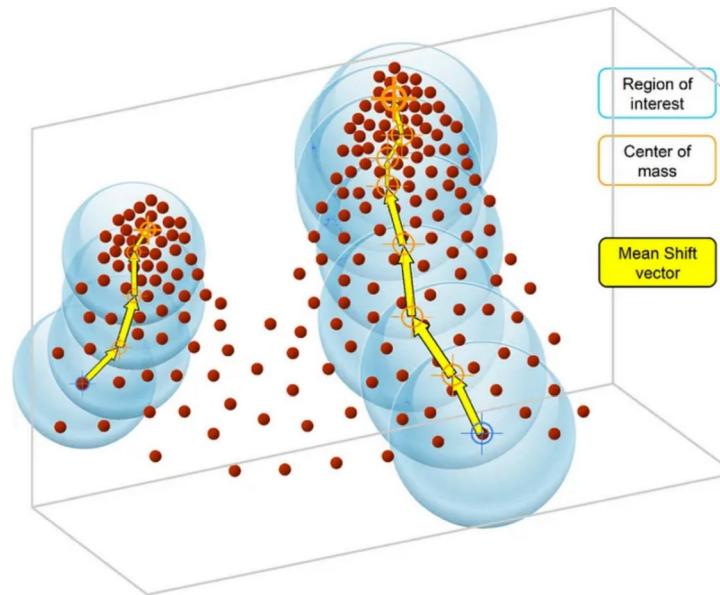
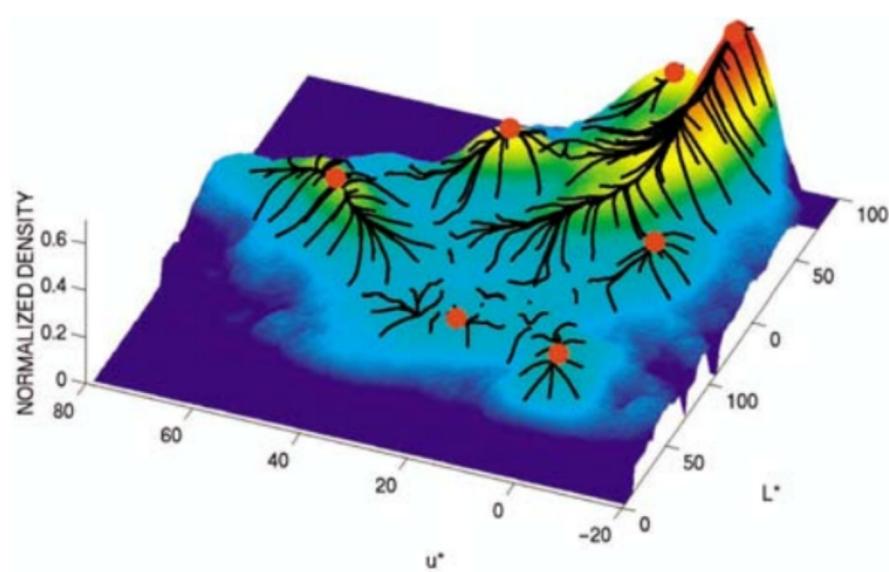


- Looking at data we can imagine a potential clustering
 - Density based
 - Consider density as a third “dimension”



Mean shift

- Iteratively we can have each datum to “climb” the hill
 - Expensive when a large or complex dataset is used
 - The use a reduced set of “seeds” is possible

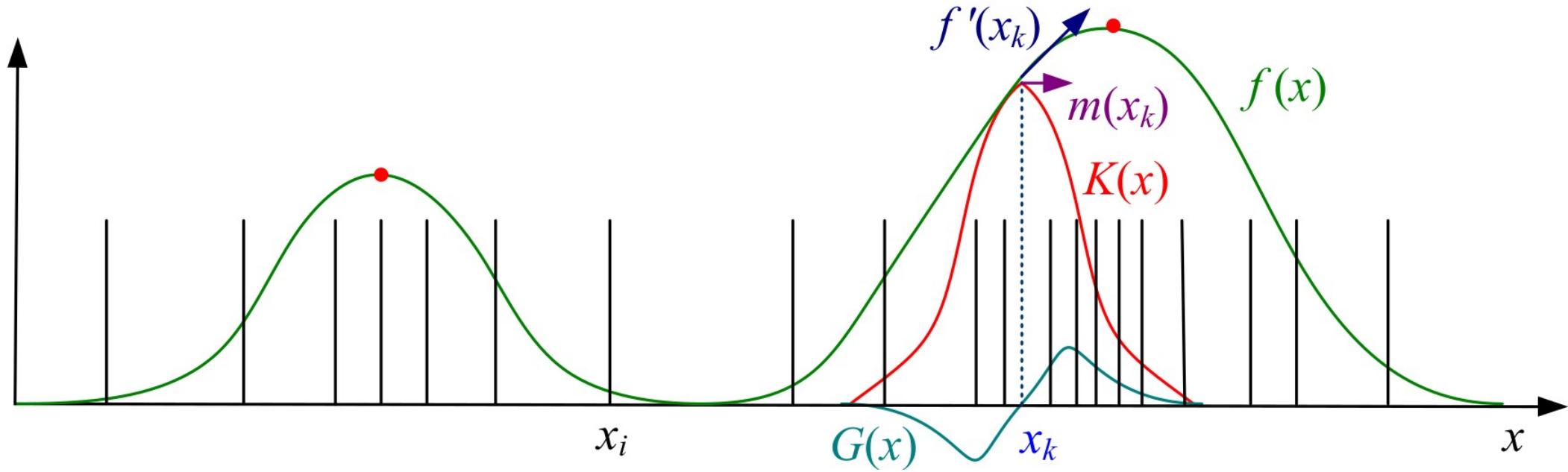


- 1) Initialize random seed and a search window W around it
- 2) Compute center of gravity (the “mean”) of W using a kernel density estimation function $K()$
 - Typically a Gaussian
- 3) Shift W to the mean
- 4) Repeat (2) until convergence

Mean shift



- Mean shift ($m(x)$) of “sampled” data $f(x)$ using a $K(\cdot)$ window

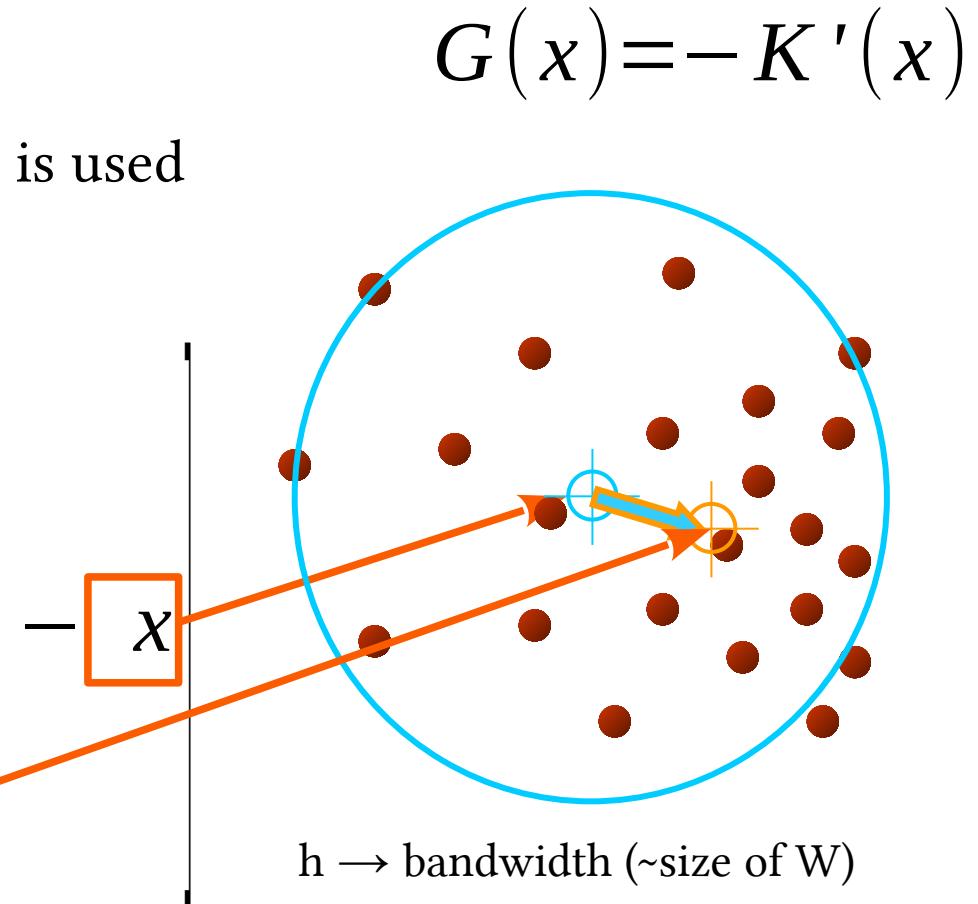


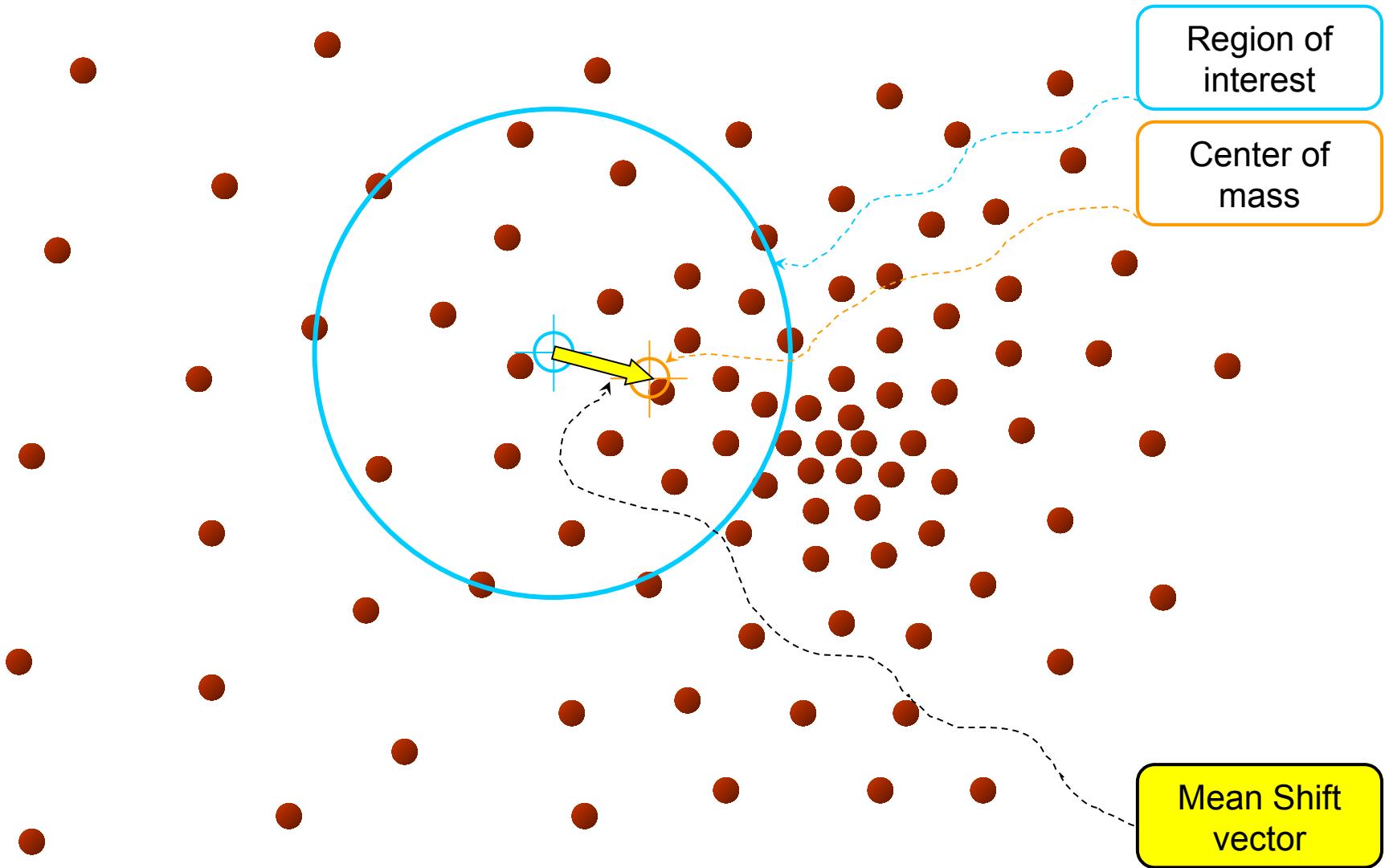
Mean shift

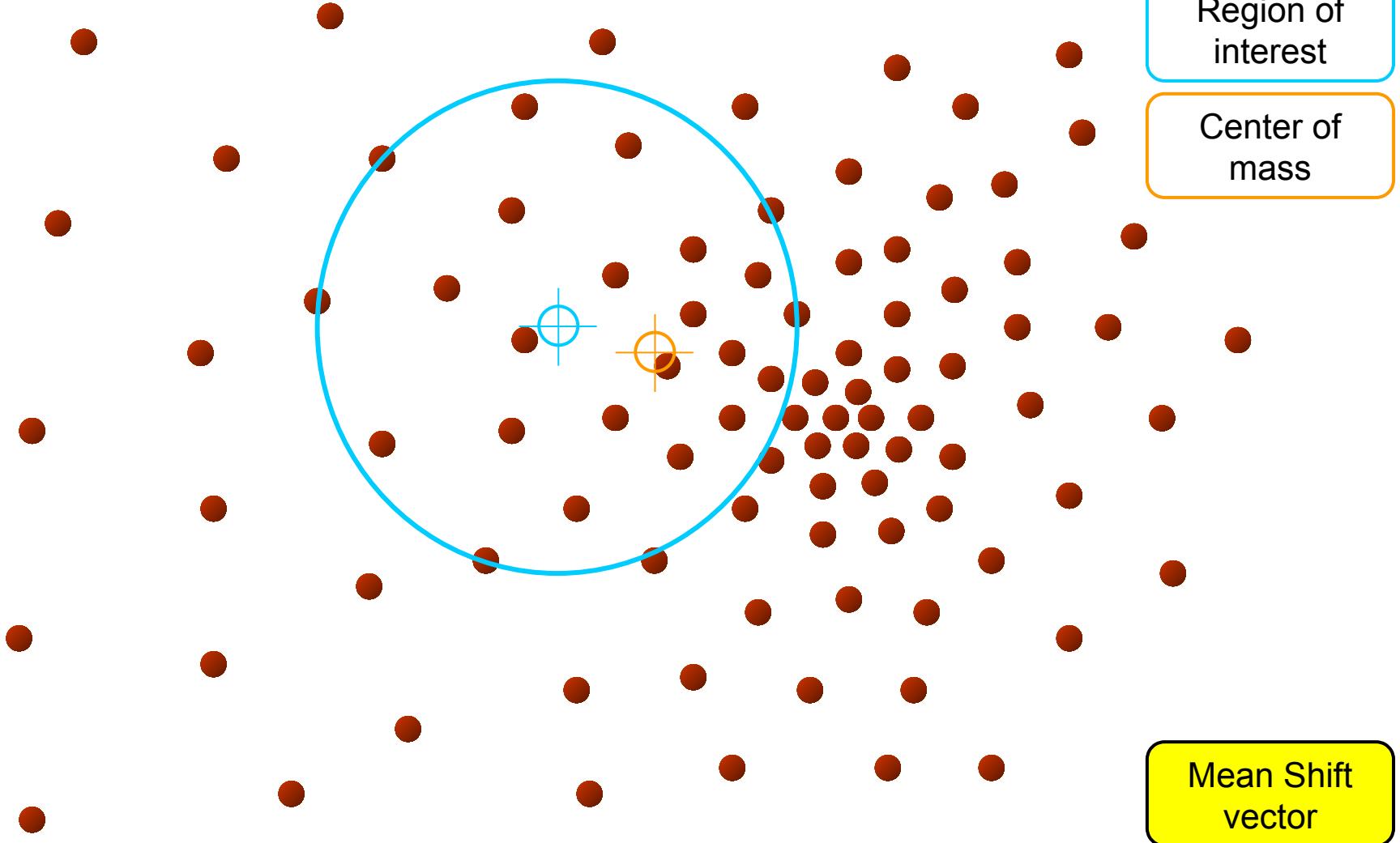


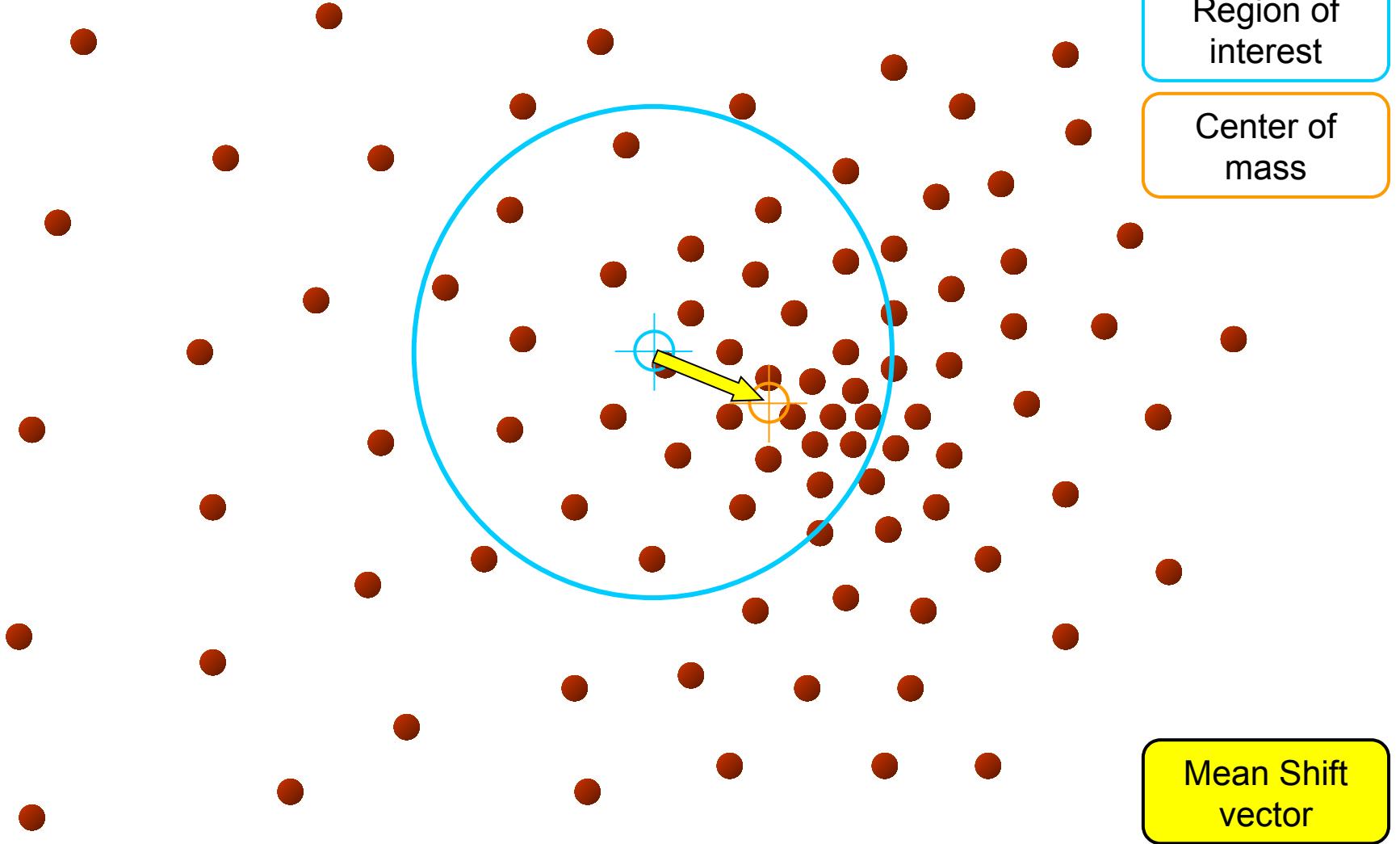
- Compute mean shift
 - Usually a Gaussian approach is used
- Translate W by $m(x)$

$$m(x) = \frac{\sum_{i=1}^n x_i G\left(\frac{\|x - x_i\|^2}{h}\right)}{\sum_{i=1}^n G\left(\frac{\|x - x_i\|^2}{h}\right)}$$





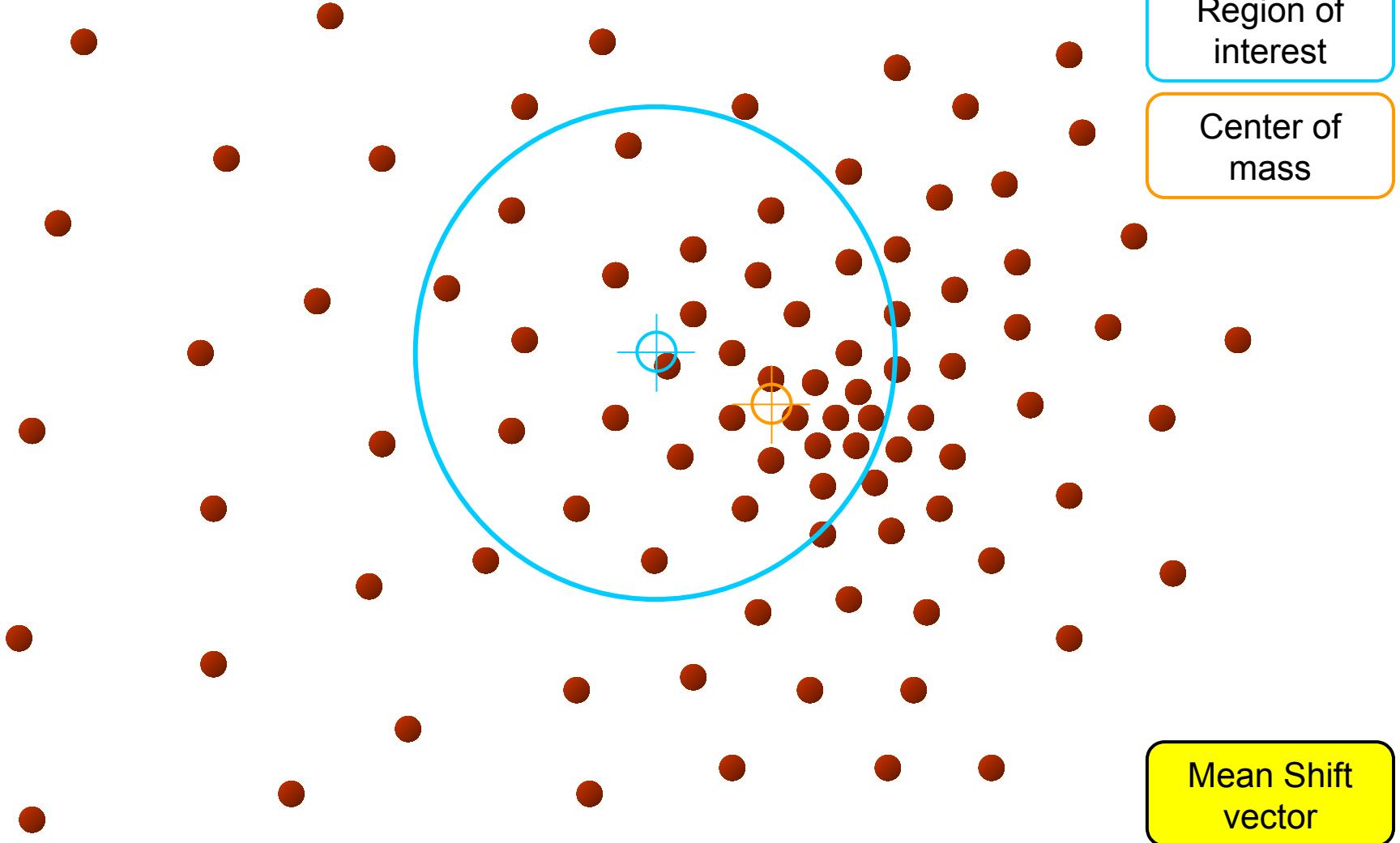


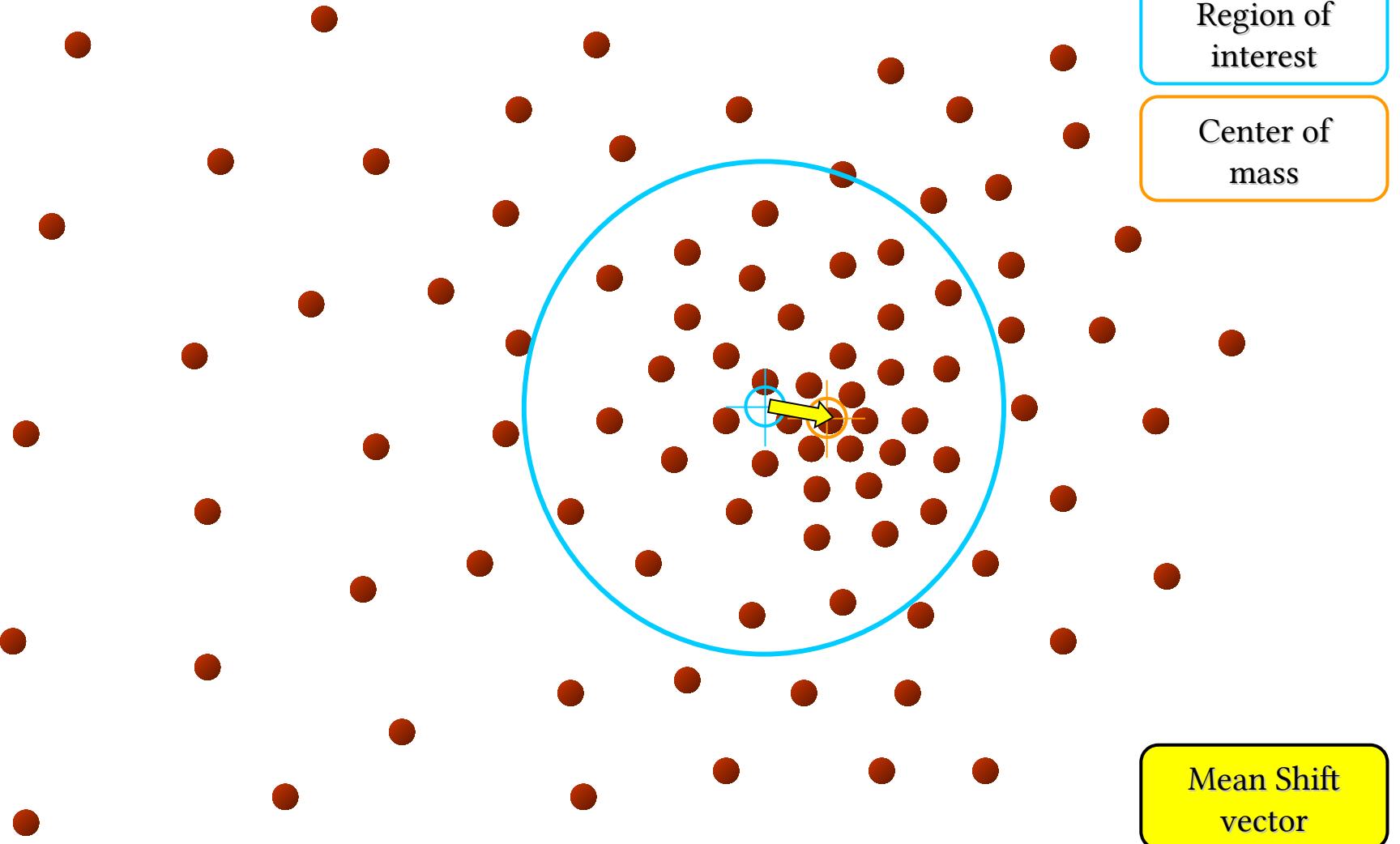


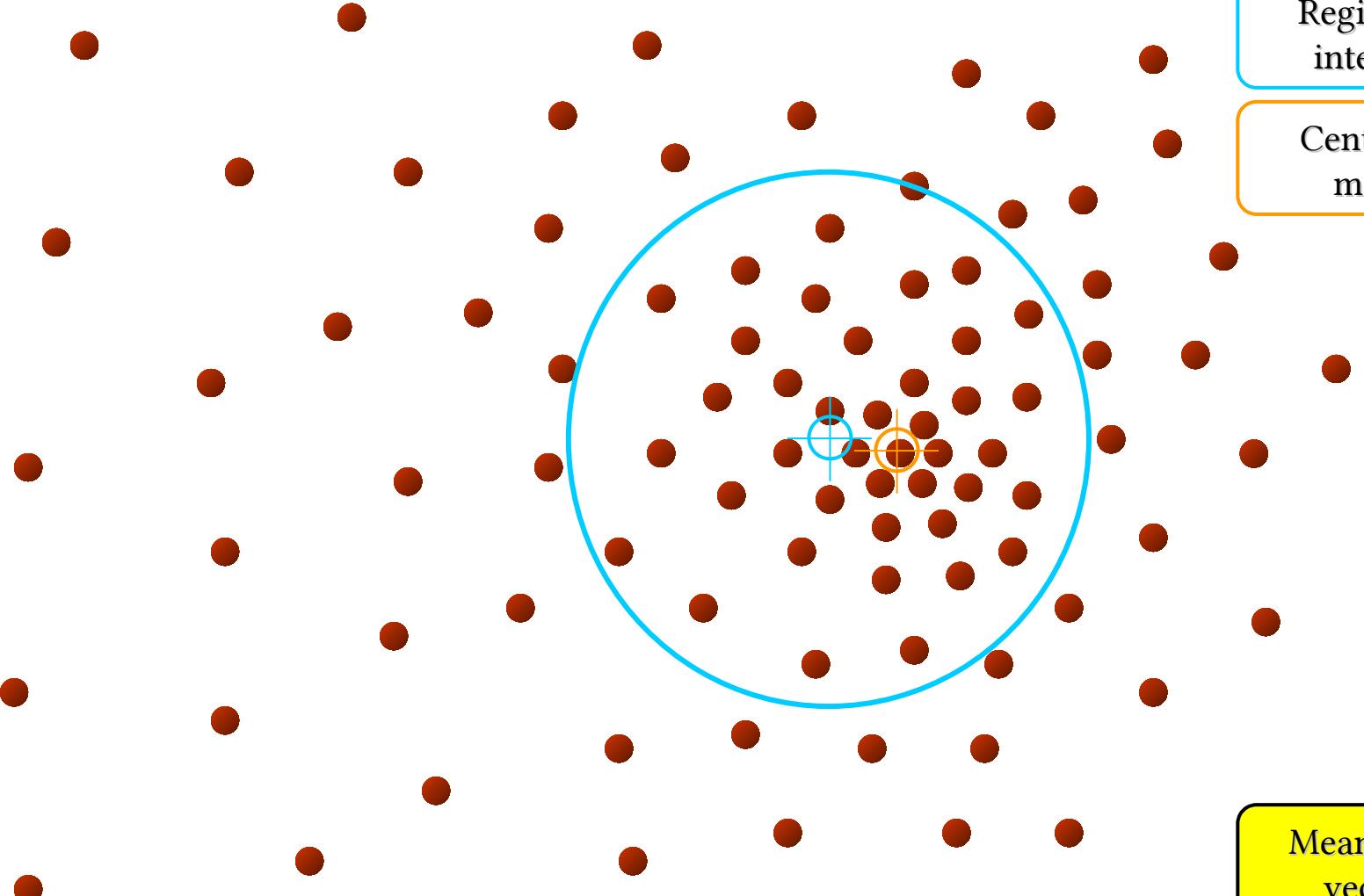
Region of
interest

Center of
mass

Mean Shift
vector



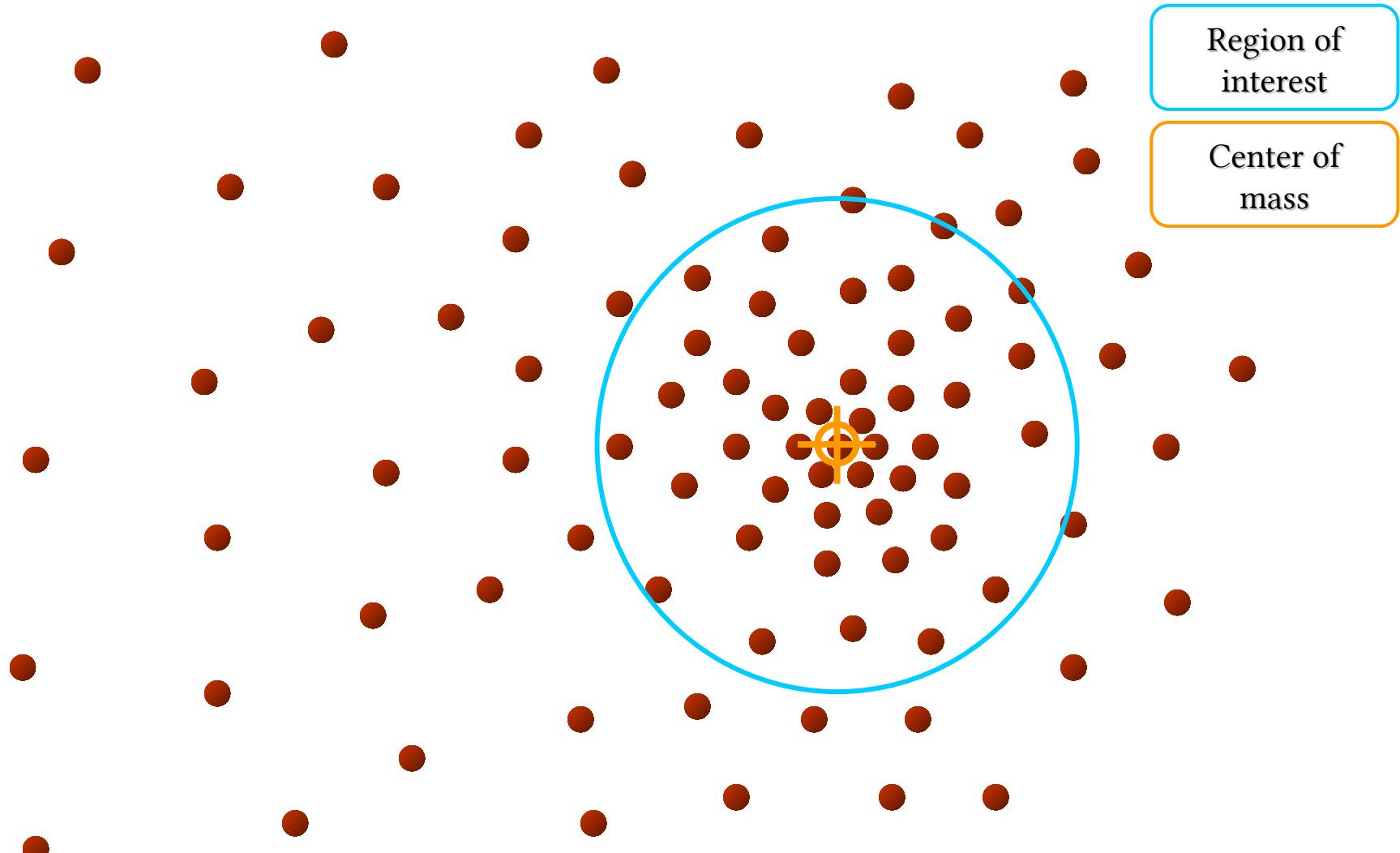


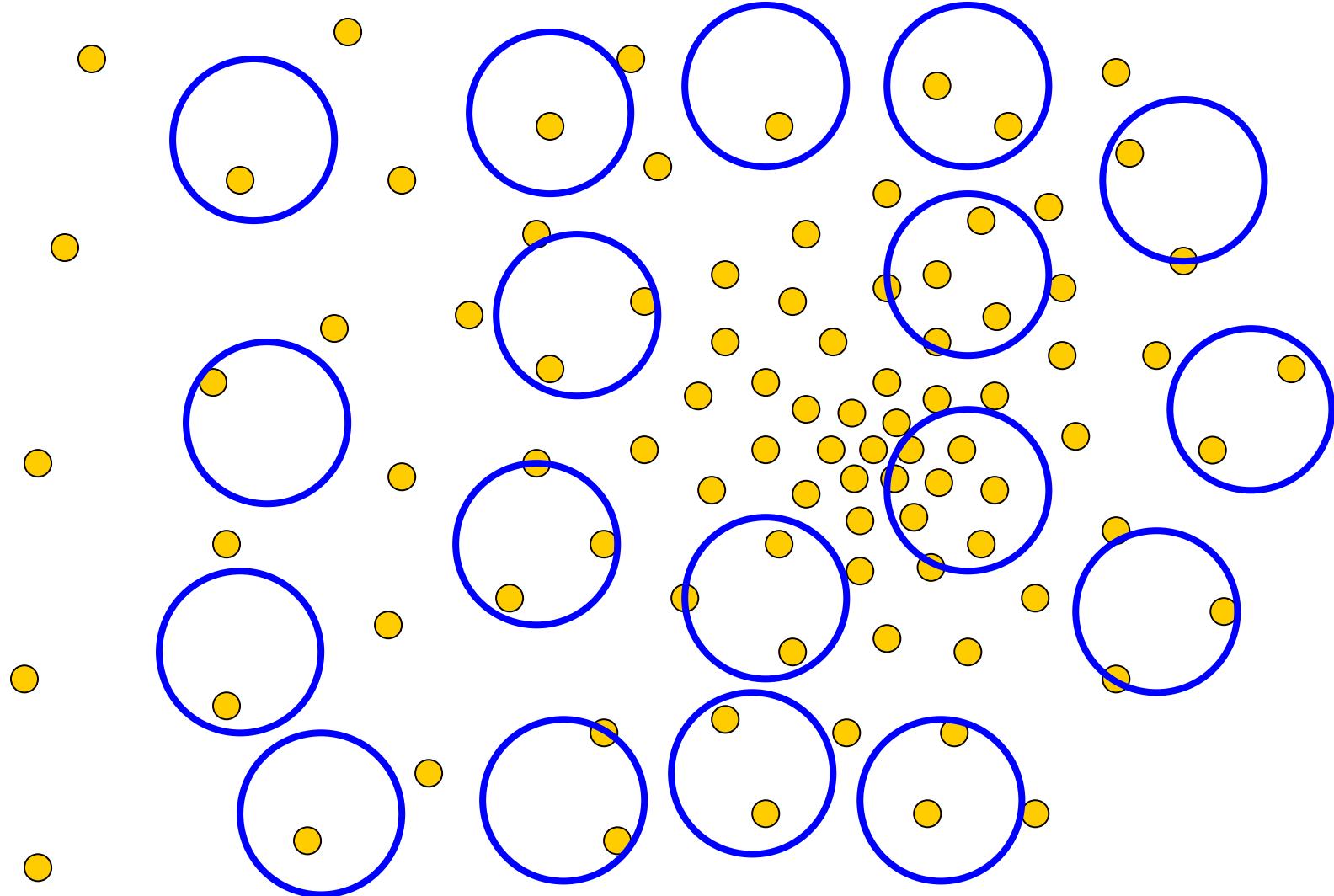


Region of
interest

Center of
mass

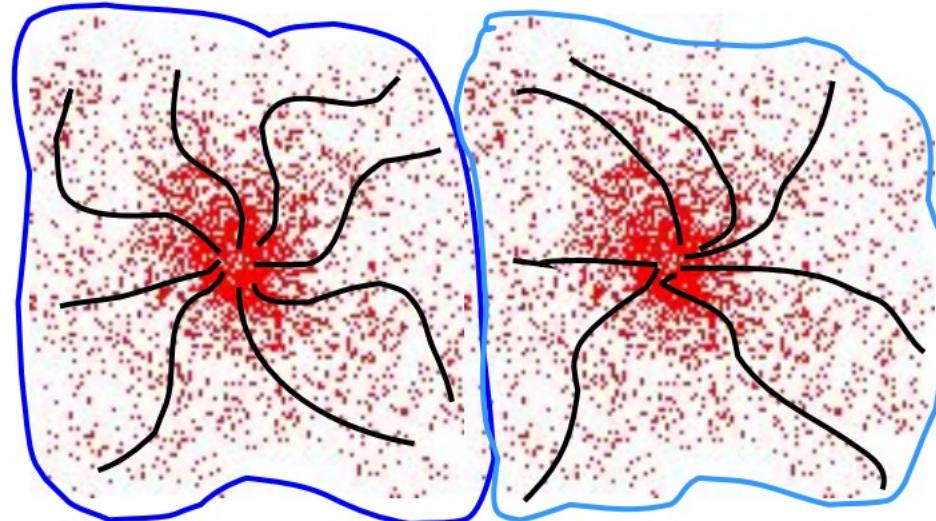
Mean Shift
vector







- Attraction basins → region where all trajectories lead to the same node
- Cluster → all points in the attraction basin of each node

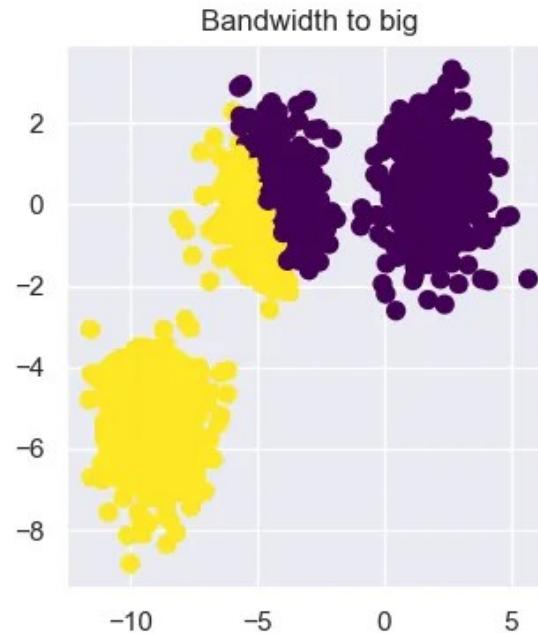
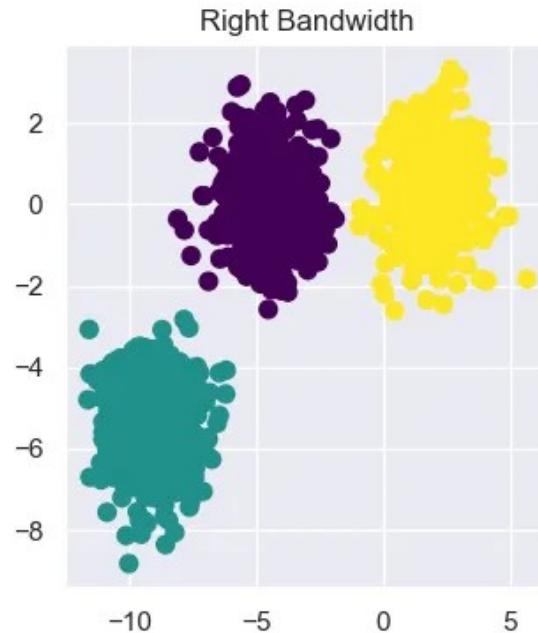
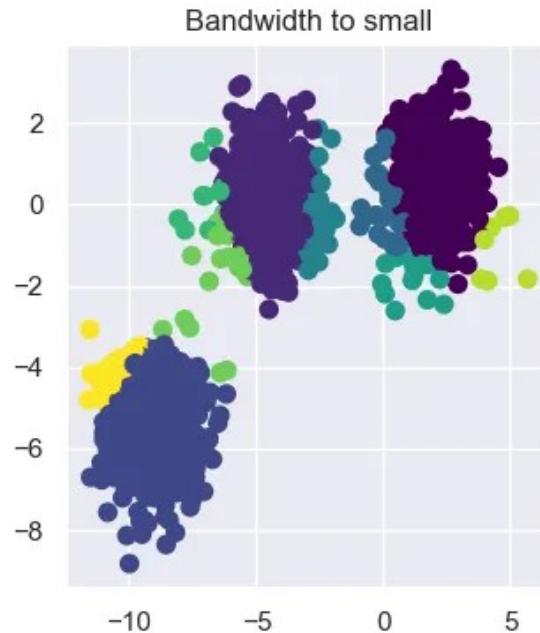


Mean Shift examples



- Pros
 - Good results
 - Flexible
 - Robust to outliers
- Cons
 - We have to choose kernel size
 - Not suitable for high dimensional features
 - Slow

Mean shift: bandwidth selection

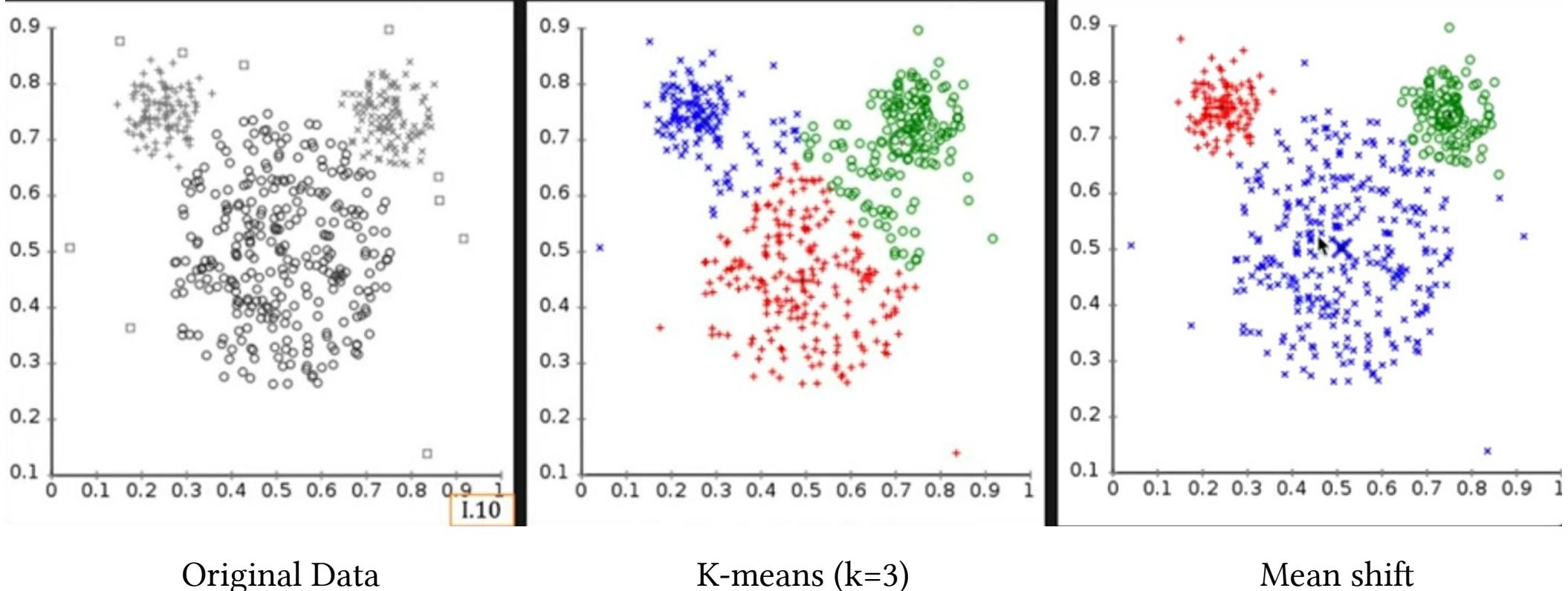




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K-means vs mean shift

K-means vs mean shift



K-means vs mean shift



Original Data



K-means ($k=16$)



Mean shift



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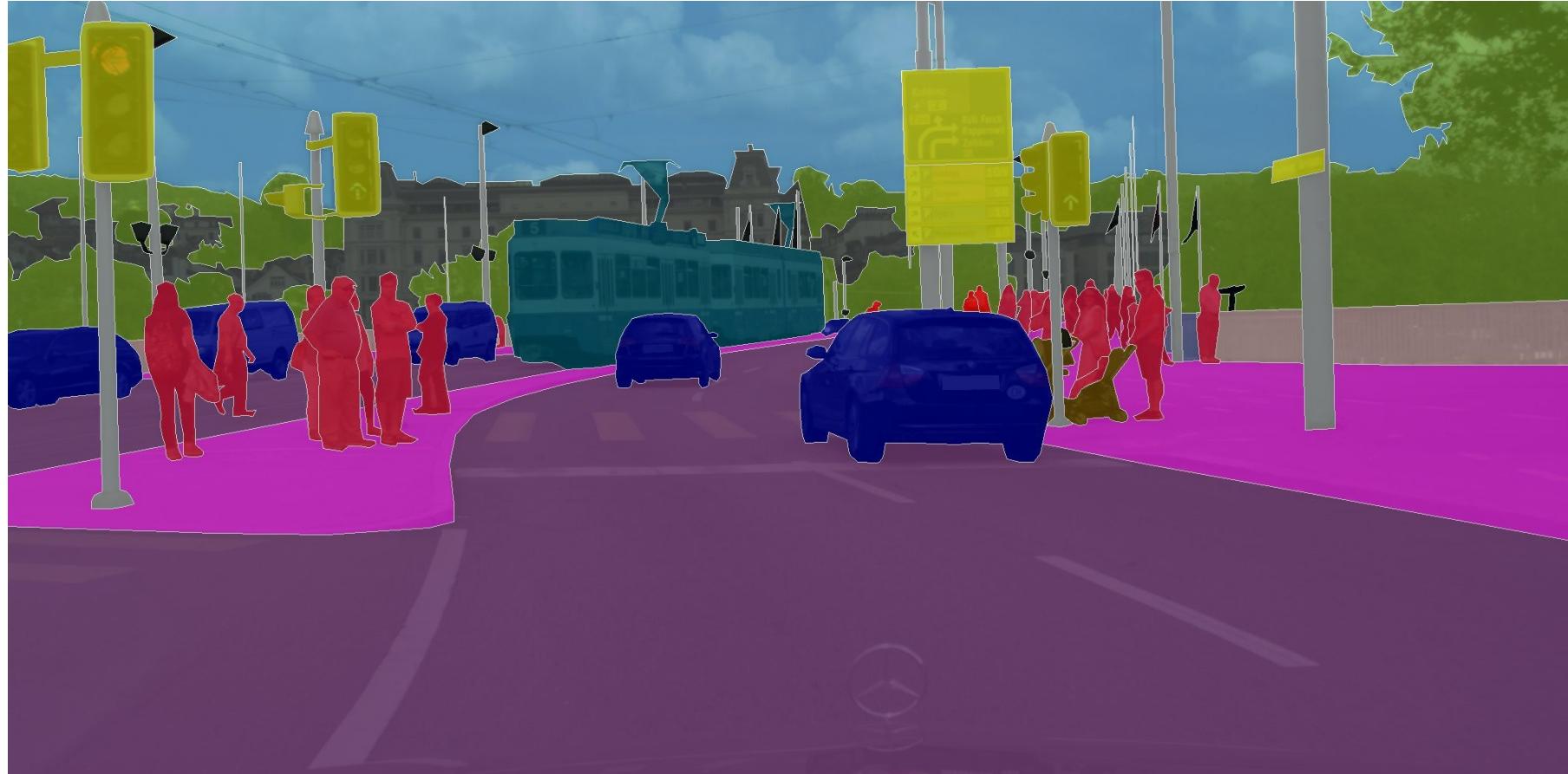
Other clustering approaches

Other clustering approaches

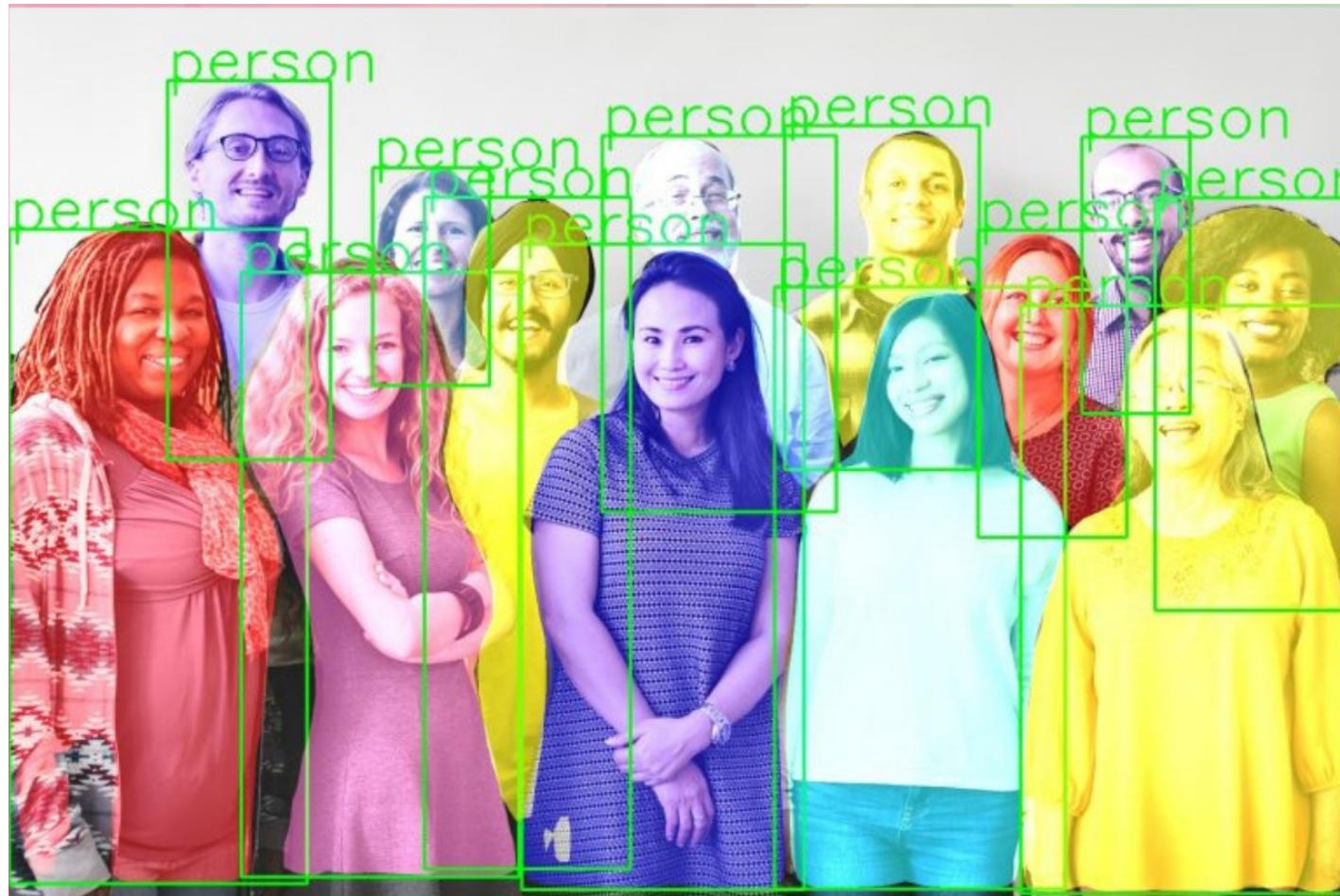


- Spectral clustering
- Agglomerative clustering
- Graph cut
- ...
- All bottom-up approaches!

Semantic segmentation (DL)



Instance segmentation (DL)





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Image Segmentation

Question time!

