

# Machine Learning

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# Outline

- Most common learning setting: supervised learning
- Empirical risk minimization
- Generalization and generalization error

# Supervised Learning

- Draw data set  $D = \{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$  from distribution  $\mathbb{D}$
- Algorithm  $A$  learns hypothesis  $h \in H$  from set  $H$  of possible hypotheses  $A(D) = h$
- We measure the quality of  $h$  as the expected **loss**:  $E_{(x,y) \in \mathbb{D}} [\ell(y, h(x))]$ 
  - This quantity is known as the **risk**
  - E.g., loss could be the Hamming loss  $\ell_{\text{Hamming}}(a, b) = \begin{cases} 0 & \text{if } a = b \\ 1 & \text{otherwise} \end{cases}$

# Supervised Learning

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$$E_{(x,y) \in \mathbb{D}} [\ell(y, h(x))]$$

Risk

$$\frac{1}{n} \sum_{i=1}^n \ell(y_i, x_i)$$

Empirical Risk

# Examples

- Maximum likelihood estimation. Loss = negative log likelihood
- Support vector machines. Loss = hinge loss
- Neural networks. Loss = any differentiable loss

# Empirical Risk Minimization

- Algorithm  $A$  solves

$$\min_{h \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \ell(y_i, h(x_i)) \quad := \min_{h \in \mathcal{H}} \hat{R}(h)$$

- **Generalization error** compares **risk** to **empirical risk**

$$E_{x \sim \mathbb{D}} [\ell(y, h(x))] - \sum_{i=1}^n \ell(y_i, h(x_i)) \quad := \quad R(h) - \hat{R}(h)$$

# Example Generalization Error Bound

Diagram illustrating the Generalization Error Bound:

$$R(h) \leq \hat{R}(h) + \sqrt{\frac{VC(H) \left( \log \frac{2n}{VC(H)} + 1 \right) - \log \frac{\delta}{4}}{n}}$$

The diagram includes the following annotations:

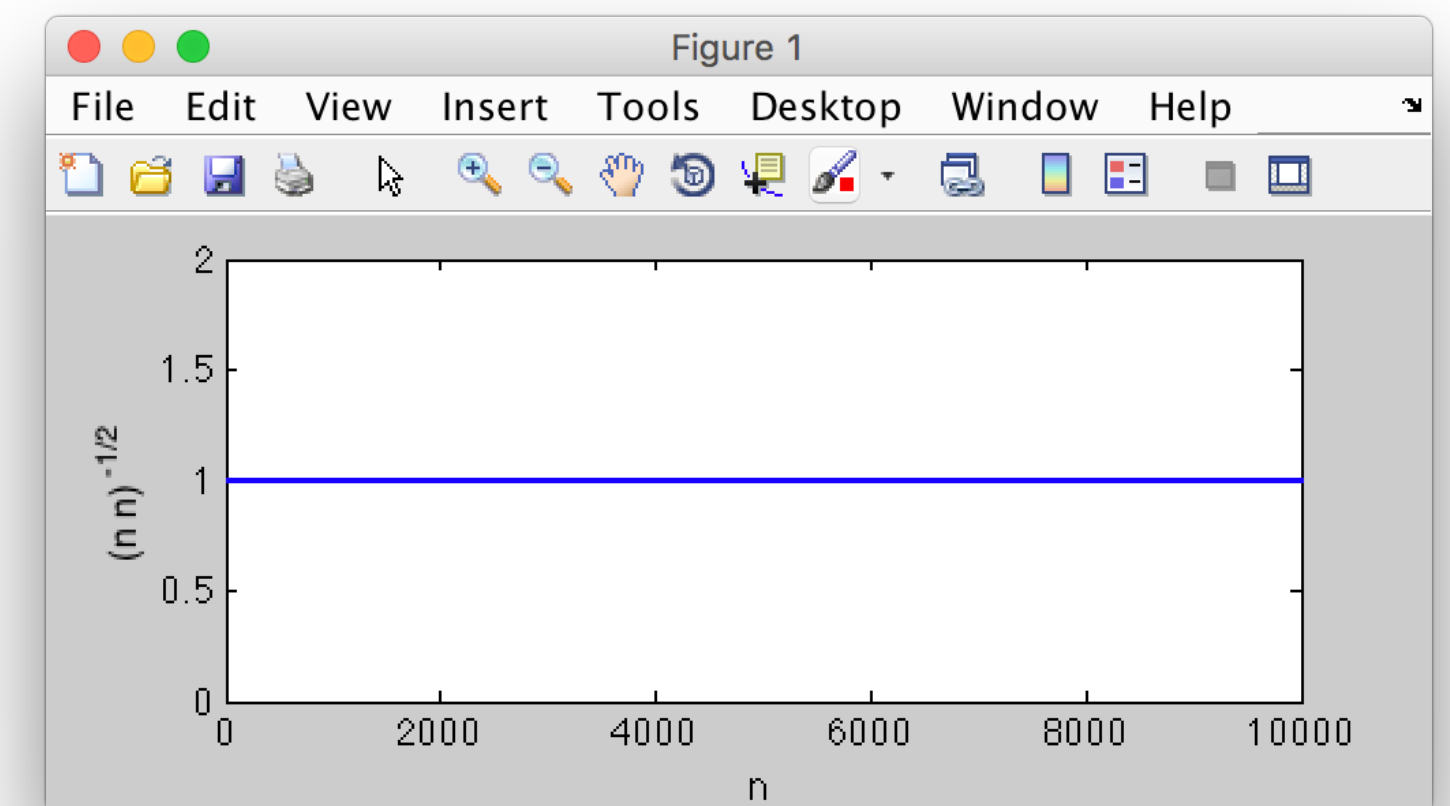
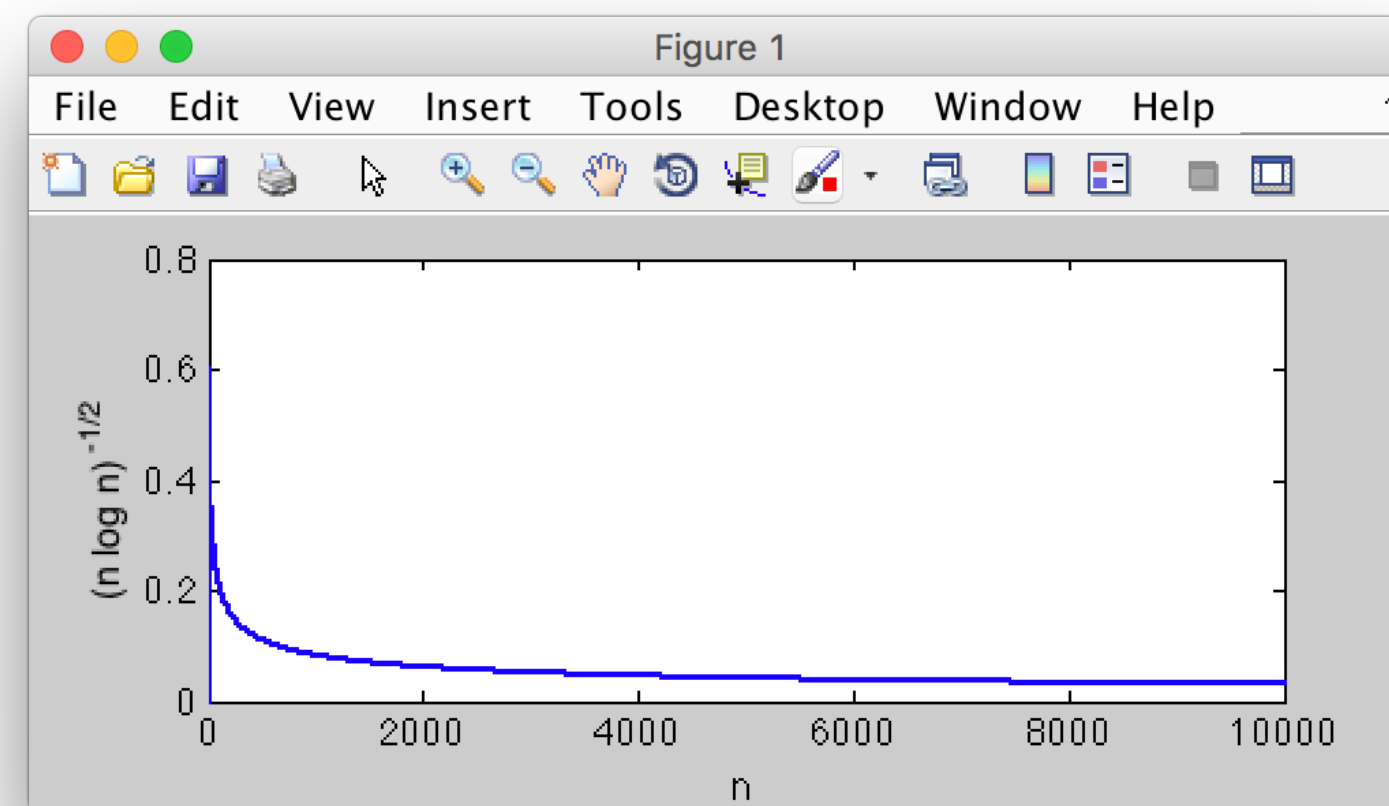
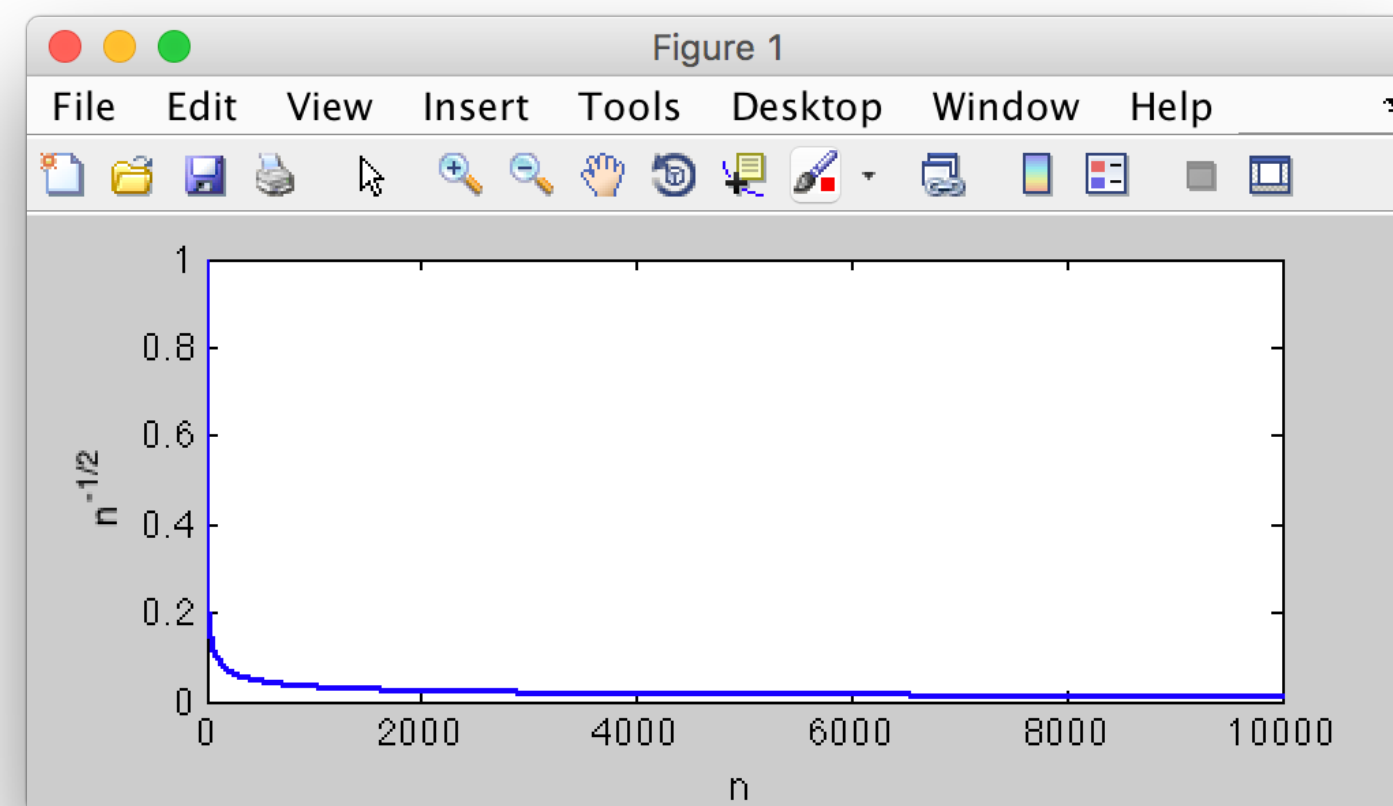
- true risk**: Points to  $R(h)$ .
- empirical risk**: Points to  $\hat{R}(h)$ .
- Vapnik-Chervonenkis dimension (model complexity)**: Points to  $VC(H)$ .
- size of training data**: Points to  $n$ .
- failure probability**: Points to  $\delta$ .

$$R(h) \leq \hat{R}(h) + \sqrt{\frac{VC(H) \left( \log \frac{2n}{VC(H)} + 1 \right) - \log \frac{\delta}{4}}{n}}$$

if complexity is fixed

$$\approx \sqrt{\frac{\text{complexity}(H)}{n}}$$

if complexity is  $O(n)$





# Takeaway Points

- Supervised learning trains from labeled examples
- Empirical risk minimization finds **hypothesis** in **hypothesis class** that scores lowest empirical risk
- But usually we care about **true risk**
- Difference between **true risk** and **empirical risk** is the **generalization error**
- **Generalization error** shrinks with more data (and simpler models)