



# Best Choice Edge Grafting For Efficient Learning of Markov Random Fields

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# Overview

Introduction

Classical Structure Learning Methods

Best Choice Edge Grafting

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# Outline

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# Introduction

## Pairwise Markov Random Fields

A graphical model that represents joint probability distributions.

$G(V, E) : \begin{cases} V : \text{set of } n \text{ nodes (variables);} \\ E : \text{set of edges (parametric interactions).} \end{cases}$

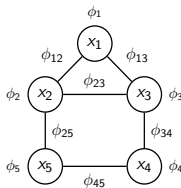
$$p_{\mathbf{w}}(X) = \frac{1}{Z(\mathbf{w})} \prod_{i \in V} \phi_i(x; \mathbf{w}) \prod_{(i,j) \in E} \phi_{ij}(x; \mathbf{w}), \quad (1)$$

where:

$$\phi_c(x; \mathbf{w}) = \exp \left( \sum_{k \in c} w_k f_k(x) \right) = \exp \left( \mathbf{w}^\top f(x) \right). \quad (2)$$

$f_k$  : state indicator functions (assigned one parameter each). For example:

$$f_{k_{\{x_1=1\}}} = \begin{cases} 1 & \text{if } x_1 = 1 \\ 0 & \text{otherwise.} \end{cases} \quad f_{k_{\{x_1=0, x_2=1\}}} = \begin{cases} 1 & \text{if } x_1 = 0 \text{ and } x_2 = 1 \\ 0 & \text{otherwise.} \end{cases}$$



# Introduction

## Structure learning problem:

Given  $N$  observations of  $n$  variables ( $V$ ), find all relevant edges ( $E$ ) and estimate their corresponding parameters.

## Challenges

- $n$  variables  $\Rightarrow O(n^2)$  possible edges.
- Learning requires large datasets.

## This work

- Investigate major computational bottlenecks of  $\ell_1$ -based learning techniques of Markov Random Fields.
- Propose scalable structure learning approach with controllable trade-off between learning speed and quality.



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## $\ell_1$ -Based Learning

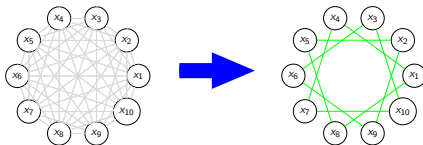
### Minimizing $\ell_1$ -Regularized Negative Log-Likelihood

$$L(\mathbf{w}) = -\frac{1}{N} \sum_{m=1}^N \log p_{\mathbf{w}}(x^{(m)}) = -\frac{1}{N} \sum_{m=1}^N (\mathbf{w}^\top f(x^{(m)})) + \log Z(\mathbf{w}) \quad (3)$$

$$\mathbb{L}(\mathbf{w}) = L(\mathbf{w}) + \lambda \|\mathbf{w}\|_1 \quad (4)$$

$$\min_{\mathbf{w}} \mathbb{L}(\mathbf{w}) \quad (5)$$

$$\delta_k L = -\frac{1}{N} \sum_{m=1}^N f_k(x^{(m)}) + E_{\mathbf{w}}[f_k(x)] = E_{\mathbf{w}}[f_k(x)] - E_D[f_k(x)] \quad (6)$$



### Limitation:

- $E_{\mathbf{w}}[f_k(x)]$  : performs inference at each gradient step (Message passing methods are expensive on fully graphs).
- $E_D[f_k(x)]$  : requires pre-computing data expectations of each possible state (sufficient statistics).

# Feature Grafting<sup>1</sup>

## Idea

Assume that all variables are independent and iteratively activate parameters (introduce dependency).

## Approach

Active-set method: a working set  $S$  and a search set  $F$ .

- $S = \{\text{unary parameters}\}$ ;  $F = \{\text{pairwise parameters}\}$ .
- Alternate between two steps until convergence:
  - *Step 1*: Optimizing over the active set  $S$  using a sub-gradient method.
  - *Step 2*: Select top violating parameter from  $F$  and add to  $S$ .
- Feature Activation Condition:

$$\text{KKT optimality condition: } \begin{cases} \delta_k L = 0 & \text{if } w_k \neq 0 \\ |\delta_k L| \leq \lambda & \text{if } w_k = 0 \end{cases} \quad (7)$$

$$\Rightarrow C_1 : j = \arg \max_k |\delta_k L| \text{ s.t. } |\delta_k L| > \lambda \quad (8)$$

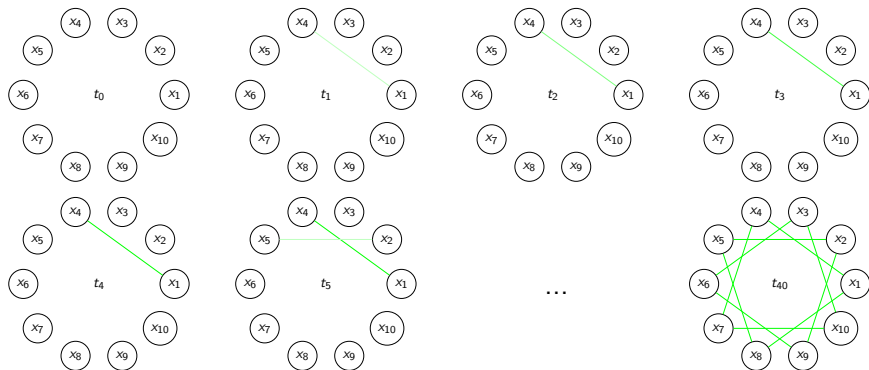
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<sup>1</sup>Lee et al, 2007





## Feature Grafting



$$t_0 : S = \emptyset$$

$$t_1 : S = \{w_{x_1=0, x_4=1}\}$$

$$t_2 : S = \{w_{x_1=0, x_4=1}, w_{x_1=1, x_4=1}\}$$

$$t_3 : S = \{w_{x_1=0, x_4=1}, w_{x_1=1, x_4=1}, w_{x_1=1, x_4=0}\}$$

$$t_4 : S = \{w_{x_1=0, x_4=1}, w_{x_1=1, x_4=1}, w_{x_1=1, x_4=0}, w_{x_1=0, x_4=0}\}$$

$$t_5 : S = \{w_{x_1=0, x_4=1}, w_{x_1=1, x_4=1}, w_{x_1=1, x_4=0}, w_{x_1=0, x_4=0}, w_{x_2=1, x_5=0}\}$$

$$t_{40} : S = S^*$$



## Feature Grafting

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### Algorithm 1 Grafting

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- 1: Initialize  $\mathcal{F} = \{\text{set of all pairwise parameters}\}$
  - 2: Compute sufficient statistics of  $f \ \forall f \in \mathcal{F}$  # cost:  $O(n^2 N s_{\max}^2)$
  - 3: **repeat**
  - 4:   Select the top violating feature  $f^*$  # cost:  $O(n^2 s_{\max}^2)$
  - 5:   Activate  $f^*$
  - 6:   Optimize the  $\ell_1$ -regularized  $L$  over the active set
  - 7: **until** convergence
- 

### Limitations:

- Parameters are treated as one homogeneous group. No structure information is used.
- Requires computing  $O(n^2 N s_{\max}^2)$  sufficient statistics and performing  $O(n^2 s_{\max}^2)$  parameter activation tests.



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- Edge Grafting

- Best Choice Edge Grafting

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## Edge Grafting

### Problem reformulation: Grafting Edges

- Redefine the search space:  $F = \{\text{Edge-wise parameter groups}\}$
- Introduce groups sparsity regularization in the loss function.

$$\mathbb{L}(\mathbf{w}) = L(\mathbf{w}) + \sum_{g \in G} \lambda d_g \|\mathbf{w}_g\|_2 + \lambda_2 \|\mathbf{w}\|_2^2, \quad (9)$$

where  $g$  refers to either a node or an edge and  $d_g$  compensates for different groups' cardinalities.

$$\min_{\mathbf{w}} \mathbb{L}(\mathbf{w}) \quad (10)$$

$$\text{KKT optimality condition: } \begin{cases} \frac{\|\delta_g L\|_2}{d_g} + \lambda_2 \|\mathbf{w}_g\|_2^2 = 0 \text{ if } \|\mathbf{w}_g\|_2 \neq 0 \\ \frac{\|\delta_g L\|_2}{d_g} \leq \lambda \text{ if } \|\mathbf{w}_g\|_2 = 0 \end{cases} \quad (11)$$



# Edge Grafting

## Grafting Edges

- Edge score:

$$s_e = \frac{||\delta_e L||_2}{d_e} \quad (12)$$

- Group-wise gradient (pairwise probability error between model and data observations):

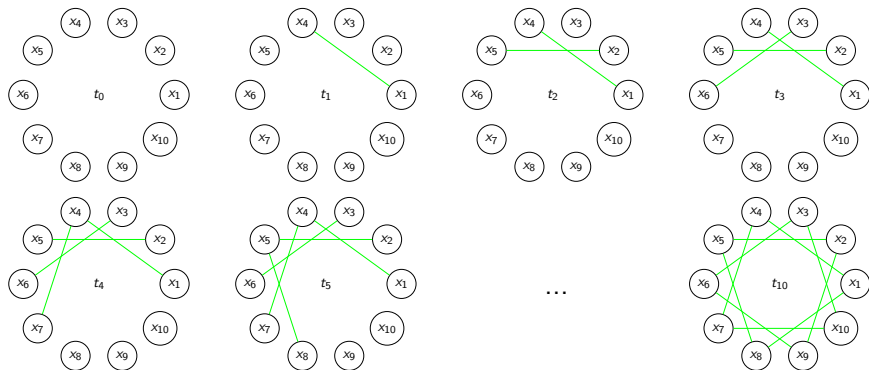
$$\delta_e L = \hat{p}_{\mathbf{w}}(e) - p_D(e) \quad (13)$$

- Necessary edge activation condition:

$$C_2 : \arg \max_e |s_e| \text{ s.t. } s_e > \lambda \quad (14)$$

**Limitations:** Requires computing  $O(n^2 N s_{\max}^2)$  sufficient statistics and performing  $O(n^2)$  edge activation tests.

# Edge Grafting



$$t_0 : S = \emptyset$$

$$t_1 : S = \{w_{x_1=0, x_4=1}, w_{x_1=1, x_4=1}, w_{x_1=1, x_4=0}, w_{x_1=0, x_4=0}\}$$

$$t_2 : S = \{w_{x_1=0, x_4=1}, w_{x_1=1, x_4=1}, w_{x_1=1, x_4=0}, w_{x_1=0, x_4=0}, w_{x_2=0, x_5=1}, w_{x_2=1, x_5=1}, w_{x_2=1, x_5=0}, w_{x_2=0, x_5=0}\}$$

$$t_{10} : S = S^*$$

## Best Choice Edge Grafting

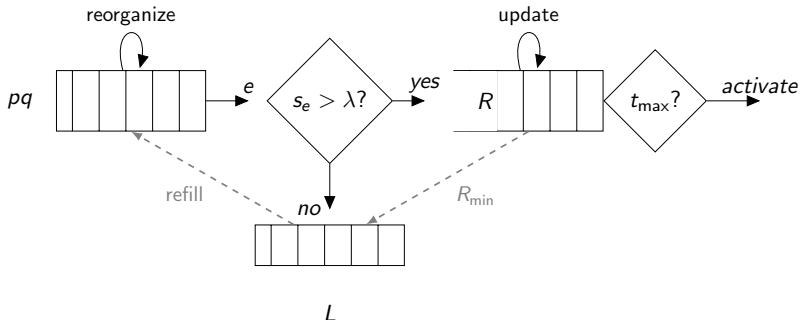
### Best Choice Problem

Given a set of streaming candidates, make a decision without testing all possible ones. Similar to a hiring process.

### Best Choice Edge Grafting Mechanism

- On-demand edge sufficient statistics computation.
- Reduced number of activation tests

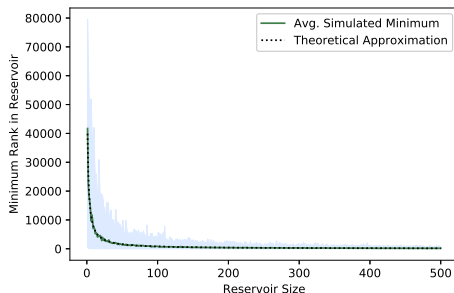
Figure: High-level operational scheme of the edge activation mechanism.



# Reservoir Sampling

**Benefits of reservoir sampling** We simulate the behavior in finite settings, sampling  $|R|$  ranks from the list of all possible numbers from 1 to  $\binom{n}{2}$  and taking the minimum.

**Figure:** Simulated edge ranks using the reservoir. (50 nodes).



## Two extremes

- **First Hit** ( $|R| = 1$ )  $\rightarrow$  Bad quality edges.
- **Edge Grafting** (using an unlimited reservoir)  $\rightarrow$  Negligible gains over a small reservoir.





# Reservoir Sampling

## Reservoir management

- Before  $t_{\max}$  is reached:
  - If reservoir full: replace minimum scoring edge  $R_{\min}$  with incoming edge  $e$  if  $s_{R_{\min}} < s_e$ .
- When  $t_{\max}$  is reached:
  - Compute mean reservoir scores:

$$\mu = \frac{1}{|R|} \sum_{e \in R} s_e \quad (15)$$

- Activation threshold as:

$$\tau_\alpha = (1 - \alpha)\mu + \alpha \max_{e \in R} s_e, \quad (16)$$

where  $\alpha \in [0, 1]$  controls a trade-off between quality of added edges and speed of edge activation.



# Search Space Reorganization

## Reorganizing search space

- Search History:

- Edge violation offset  $v_e$ :

$$v_e = 1 - \frac{s_e}{\lambda} . \quad (17)$$

- Store failing edges in  $L$  and refill  $pq$  when it is empty:

$$pq[e] = v_e \quad (18)$$

- Partial structure information:

- Idea: Promote a scale-free structure.
- Detect hubs using degree centrality:

$$c_i = \frac{|\mathcal{N}_i|}{|V| - 1} \quad (19)$$

- Construct Hub set:

$$H = \{i \in V \text{ such that } c_i > \hat{c}\} \quad (20)$$

- Prioritizing edges incident to hubs such that  $\forall h \in H$  and  $\forall n \in V$ :

$$pq[(h, n)] = pq[(h, n)] - 1 \quad (21)$$

## Summary of Complexities

Algorithm	Suff. stats. at $j^{th}$ edge	Activation step
Feature grafting	$O(n^2 N s_{\max}^2)$	$O(n^2 s_{\max}^2)$
Edge grafting	$O(n^2 N s_{\max}^2)$	$O(n^2 s_{\max}^2)$
Best choice edge grafting	$O((n + j t_{\max}) N s_{\max}^2)$	$O(t_{\max} s_{\max}^2)$

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# Synthetic Experiments

## Synthetic Data

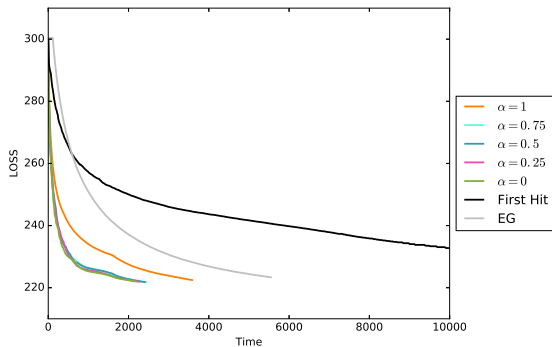
Number of nodes	200	400	600
Number of states per variable	5	5	5
Number of parameters	498,500	1,997,000	4,495,500

- Scale-free-structures: Few dominant hubs.
- Data generated using Gibbs sampler: 20,000 data points from each network, randomly split into train and held-out testing sets.

# Synthetic Experiments

## Synthetic results

Figure: Full convergence of different methods (200 nodes).



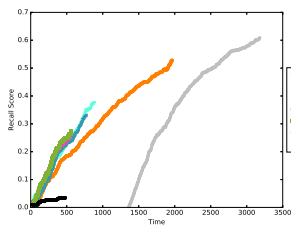
$$\tau_{\alpha} = (1 - \alpha)\mu + \alpha \max_{e \in R} s_e$$



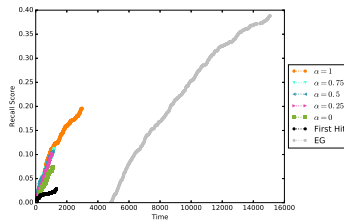
# Synthetic Experiments

## Synthetic results

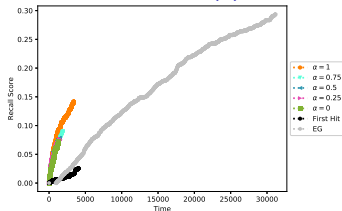
Figure: Learning objectives vs time for varying MRFs sizes.



(a) 200 nodes and 600 edges



(b) 400 nodes and 1,200 edges



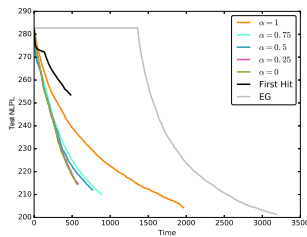
(c) 600 nodes and 1,800 edges



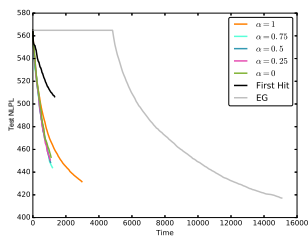
# Synthetic Experiments

## Synthetic results

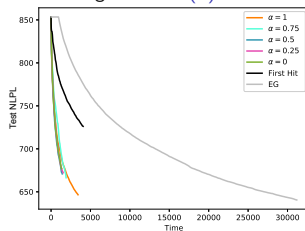
Figure: Negative Log Pseudo-Likelihood vs time for varying MRFs sizes.



(a) 200 nodes and 600 edges



(b) 400 nodes and 1,200 edges



(c) 600 nodes and 1,800 edges



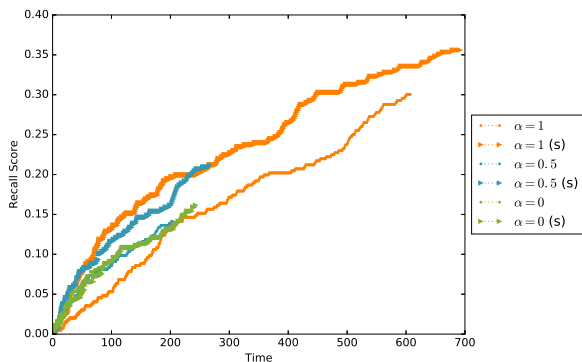




# Synthetic Experiments

## Synthetic results

**Figure:** Role of structure heuristics in improving the quality of the learned MRF.(200 nodes)





## Real Data Experiments

### Real data

Dataset	Jester	Yummly recipes
Number of variables	100	153
Number of States per variable	5	2
Number of parameters	124,250	36,450
Dataset size	73,421	10,000

- Jester<sup>2</sup>: user ratings of jokes.
- Yummly recipes<sup>3</sup>: recipes with different ingredients.

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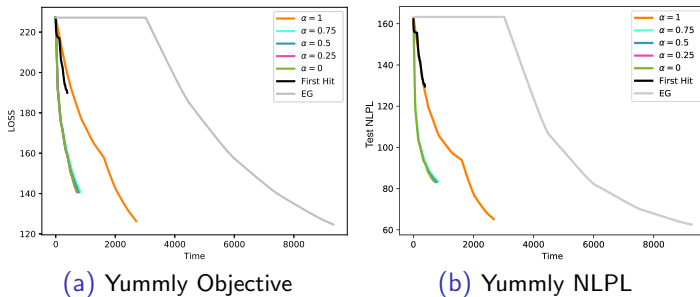
<sup>2</sup><http://goldberg.berkeley.edu/jester-data/>

<sup>3</sup><https://www.kaggle.com/c/whats-cooking>

# Real Data Experiments

## Real data results

Figure: Negative Log Pseudo-Likelihood vs time for varying MRFs sizes.



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# Conclusion

## Proposed work

- Reformulate learning problem by introducing structure information.
- Avoid costly batch  $\ell_1$ -learning on the entire problem space. Informed edge search through reservoir sampling and search space reorganization.

## Result

- Faster edge activation and convergence.
- Controllable trade-off between learning speed and quality.
- Achieved better scalability.

## Limitations and future work

- Assumption of scale free structure: Investigate better structure heuristics for a more efficient search space reorganization.
- Applied on pairwise MRFs: Generalize approach for higher order MRFs.