CENG 384 - Signals and Systems for Computer Engineers Spring 2018-2019

Written Assignment 4

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1. (a)
$$2x[n] = y[n] + \frac{y[n-2]}{8} - \frac{3y[n-1]}{4}$$

(b)
$$H(e^{jw}) = \frac{2}{1 - \frac{3e^{-jw}}{4} + \frac{e^{-2jw}}{8}} = \frac{2}{(1 - \frac{e^{-jw}}{2})(1 - \frac{e^{-jw}}{4})} = \frac{4}{1 - \frac{e^{-jw}}{2}} - \frac{2}{1 - \frac{e^{-jw}}{4}}$$

(c)
$$h[n] = 4\left(\frac{1}{2}\right)^n u[n] - 2\left(\frac{1}{4}\right)^n u[n]$$

$$\begin{split} X(e^{jw}) &= \frac{1}{1 - \frac{e^{-jw}}{4}} \\ Y(e^{jw}) &= H(e^{jw})X(e^{jw}) \\ &= \frac{2}{(1 - \frac{e^{-jw}}{2})(1 - \frac{e^{-jw}}{4})} \cdot \frac{1}{(1 - \frac{e^{-jw}}{4})} \\ Y(e^{jw}) &= \frac{8}{1 - \frac{e^{-jw}}{2}} + \frac{-4}{1 - \frac{e^{-jw}}{4}} + \frac{-2}{\left(1 - \frac{e^{-jw}}{4}\right)^2} \\ y[n] &= 8\left(\frac{1}{2}\right)^n u[n] - 4\left(\frac{1}{4}\right)^n u[n] - 2(n+1)\left(\frac{1}{4}\right)^n u[n] \end{split}$$

2.
$$h[n] = h_1[n] + h_2[n]$$

$$H(e^{jw}) = H_1(e^{jw}) + H_2(e^{jw})$$

$$H_1(e^{jw}) = \frac{1}{\left(1 - \frac{e^{-jw}}{3}\right)}$$

$$H_2(e^{jw}) = \frac{5e^{-jw} - 12}{e^{-2jw} - 7e^{-jw} + 12} - \frac{1}{\left(1 - \frac{e^{-jw}}{3}\right)}$$

$$H_2(e^{jw}) = \frac{-2}{\left(1 - \frac{e^{-jw}}{4}\right)} + \frac{1}{\left(1 - \frac{e^{-jw}}{3}\right)} + \frac{-1}{\left(1 - \frac{e^{-jw}}{3}\right)}$$

$$H_2(e^{-jw}) = \frac{-2}{\left(1 - \frac{e^{-jw}}{4}\right)}$$

$$h_2[n] = -2\left(\frac{1}{4}\right)^n u[n]$$

3.

(a)
$$x(t) = x_1(t) + x_2(t)$$

$$x_1(t) = \frac{\sin(2\pi t)}{\pi t}$$

$$X_1(jw) = \begin{cases} 1 & |w| < 2\pi \\ 0 & |w| > 2\pi \end{cases}$$
 (1)

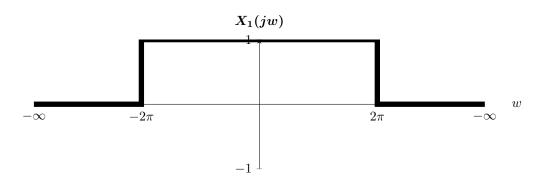


Figure 1: w vs. $X_1(jw)$.

$$x_2(t) = \cos(3\pi t)$$

 $X_2(jw) = \pi[\delta(w - 3\pi) + \delta(w + 3\pi)]$

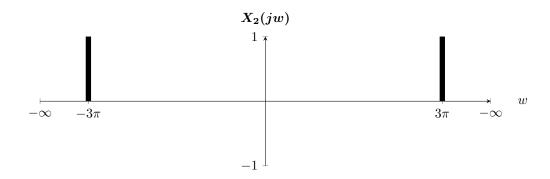


Figure 2: w vs. $X_2(jw)$.

$$X(jw) = X_1(jw) + X_2(jw)$$

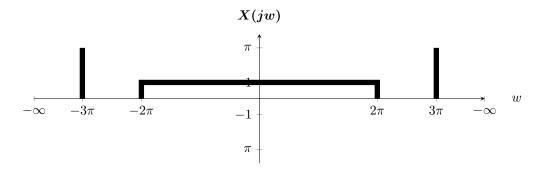


Figure 3: w vs. X(jw).

(b)
$$Nyquist \ rate = 2(3\pi) = 6\pi \\ Nyquist \ frequency = 3\pi \\ Nyquist \ period = \frac{2}{3}$$

(c)
$$x_p(t) = x(t)p(t)$$

$$P(jw) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(w - kw_s)$$

$$x_p(t) = \sum_{k=-\infty}^{\infty} x(nT)\delta(t - kT)$$

$$X_p(jw) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\theta)P(j(w - \theta))d\theta$$

$$= \frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(w - kw_s))$$

$$=\frac{3}{2}\sum_{k=-\infty}^{\infty}X(j(w-k6\pi))$$

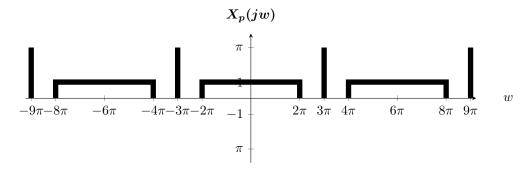


Figure 4: w vs. $X_p(jw)$.

4.

(a)
$$w_s = \pi \qquad T = \frac{2\pi}{\pi} = 2$$

$$X(jw) = \begin{cases} \frac{4w}{\pi} & |w| < \pi/4 \\ 0 & o.w. \end{cases}$$
 (2)

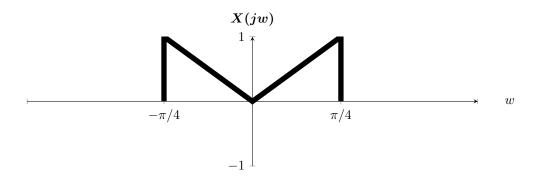


Figure 5: w vs. X(jw).

$$x_p(t) = \sum_{k=-\infty}^{\infty} x(nT)\delta(t - kT)$$
$$X_p(jw) = \frac{1}{2} \sum_{k=-\infty}^{\infty} X(j(w - k\pi))$$

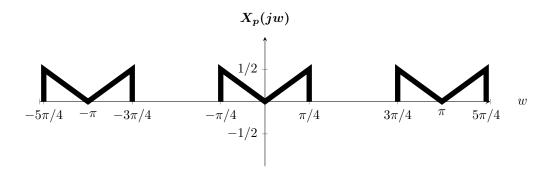


Figure 6: w vs. $X_p(jw)$.

$$X_d(e^{jw}) = \frac{1}{2} \sum_{k=-\infty}^{\infty} X(j(w-2\pi k)/T)$$

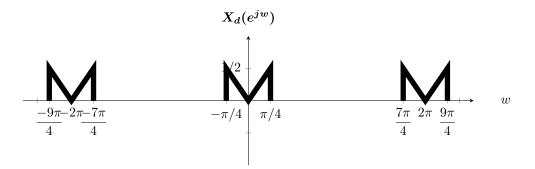


Figure 7: w vs. $X_d(e^{jw})$.

(b)
$$H(e^{jw}) = \pi \sum_{k=-\infty}^{\infty} \delta(w - \pi - 2\pi k) + \delta(w + \pi - 2\pi k)$$

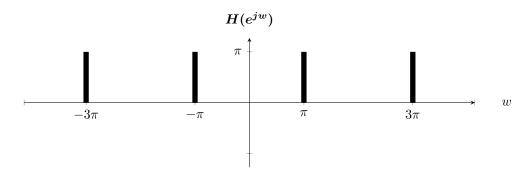


Figure 8: w vs. $H(e^{jw})$.

(c)
$$y_d[n] = x_d[n]h[n]$$

$$Y_d(e^{jw}) = \frac{1}{2\pi}X_d(e^{jw}) * H(e^{jw})$$

$$= \frac{1}{2\pi}\int_{<2\pi>} X_d(e^{j\theta})H(e^{j(w-\theta)})d\theta$$

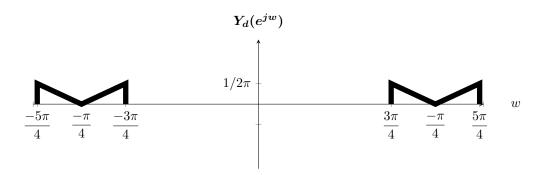


Figure 9: w vs. $Y_d(e^{jw})$.