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import numpy as np
import pdb
This code was originally written for CS 231n at Stanford University
(cs231n.stanford.edu). It has been modified in various areas for use in the ECE 239AS class at UCLA. This includes the descriptions of what code to implement as well as some slight potential changes in variable names to be
consistent with class nomenclature. We thank Justin Johnson & Serena Yeung for
permission to use this code. To see the original version, please visit
cs231n.stanford.edu.
def affine_forward(x, w, b):
  Computes the forward pass for an affine (fully-connected) layer.
 The input x has shape (N, d_1, ..., d_k) and contains a minibatch of N examples, where each example x[i] has shape (d_1, ..., d_k). We will reshape each input into a vector of dimension D = d_1 * ... * d_k, and
  then transform it to an output vector of dimension \overline{M}.
  - x: A numpy array containing input data, of shape (N, d_1, ..., d_k)
  - w: A numpy array of weights, of shape (D, M)
  - b: A numpy array of biases, of shape (M,)
  Returns a tuple of:
  - out: output, of shape (N, M)
  - cache: (x, w, b)
  # ----- #
  # YOUR CODE HERE:
      Calculate the output of the forward pass. Notice the dimensions
      of w are D x M, which is the transpose of what we did in earlier
     assignments.
  # ------ #
  N = x.shape[0]
  D = w.shape[0]
  x inp = x.reshape(N,D)
  out = np.dot(x inp,w) + b
  # END YOUR CODE HERE
  cache = (x, w, b)
  return out, cache
def affine backward(dout, cache):
  Computes the backward pass for an affine layer.
  Inputs:
  - dout: Upstream derivative, of shape (N, M)
  - cache: Tuple of:
    - x: Input data, of shape (N, d_1, ... d_k)
    - w: Weights, of shape (D, M)
  Returns a tuple of:
  - dx: Gradient with respect to x, of shape (N, d1, ..., d_k)
  dw: Gradient with respect to w, of shape (D, M)db: Gradient with respect to b, of shape (M,)
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x, w, b = cache
 dx, dw, db = None, None, None
 # ------ #
 # YOUR CODE HERE:
    Calculate the gradients for the backward pass.
 # dout is N x M
 # dx should be N \times d1 \times ... \times dk; it relates to dout through multiplication with
w, which is D \times M
 # dw should be D \times M; it relates to dout through multiplication with \times, which is
N x D after reshaping
 # db should be M; it is just the sum over dout examples
 N = x.shape[0]
 D = w.shape[0]
 x_{inp} = x.reshape(N,D)
 dx_inp = np.dot(dout,w.T)
 dx = dx_{inp.reshape}(x.shape)
 dw = np.dot(x_inp.T,dout)
 db = np.dot(dout.T,np.ones(N))
 # END YOUR CODE HERE
 # ------ #
 return dx, dw, db
def relu forward(x):
 Computes the forward pass for a layer of rectified linear units (ReLUs).
 - x: Inputs, of any shape
 Returns a tuple of:
 - out: Output, of the same shape as x
  - cache: x
 # YOUR CODE HERE:
 # Implement the ReLU forward pass.
 out = np.maximum(0,x)
 # END YOUR CODE HERE
 cache = x
 return out, cache
def relu backward(dout, cache):
 Computes the backward pass for a layer of rectified linear units (ReLUs).
 Input:
  - dout: Upstream derivatives, of any shape
 - cache: Input x, of same shape as dout
 Returns:
  - dx: Gradient with respect to x
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x = cache
 # YOUR CODE HERE:
     Implement the ReLU backward pass
 # ------ #
 dx = np.asarray(dout)
 dx[x <= 0] = 0
 # END YOUR CODE HERE
 return dx
def svm_loss(x, y):
 Computes the loss and gradient using for multiclass SVM classification.
 Inputs:
  - x: Input data, of shape (N, C) where x[i, j] is the score for the jth class
   for the ith input
  - y: Vector of labels, of shape (N,) where y[i] is the label for x[i] and
   0 \le y[i] < C
 Returns a tuple of:
  - loss: Scalar giving the loss
  - dx: Gradient of the loss with respect to x
 N = x.shape[0]
 correct_class_scores = x[np.arange(N), y]
 margins = np.maximum(0, x - correct_class_scores[:, np.newaxis] + 1.0)
 margins[np.arange(N), y] = 0
 loss = np.sum(margins) / N
 num_pos = np.sum(margins > 0, axis=1)
 dx = np.zeros_like(x)
 dx[margins > 0] = 1
 dx[np.arange(N), y] -= num_pos
 dx /= N
 return loss, dx
def softmax_loss(x, y):
 Computes the loss and gradient for softmax classification.
 Inputs:
  - x: Input data, of shape (N, C) where x[i, j] is the score for the jth class
   for the ith input.
  - y: Vector of labels, of shape (N,) where y[i] is the label for x[i] and
   0 \le y[i] < C
 Returns a tuple of:
 - loss: Scalar giving the loss
  - dx: Gradient of the loss with respect to x
 probs = np.exp(x - np.max(x, axis=1, keepdims=True))
 probs /= np.sum(probs, axis=1, keepdims=True)
 N = x.shape[0]
 loss = -np.sum(np.log(probs[np.arange(N), y])) / N
 dx = probs.copy()
 dx[np.arange(N), y] -= 1
 dx /= N
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return loss, dx