This is the k-nearest neighbors workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement k-nearest neighbors.

Please print out the workbook entirely when completed.

We thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu). These are the functions in the cs231n folders and code in the jupyer notebook to preprocess and show the images. The classifiers used are based off of code prepared for CS 231n as well.

The goal of this workbook is to give you experience with the data, training and evaluating a simple classifier, k-fold cross validation, and as a Python refresher.

Import the appropriate libraries

In [1]:
```
import numpy as np # for doing most of our calculations
import matplotlib.pyplot as plt# for plotting
from cs231n.data_utils import load_CIFAR10 # function to load the CIFAR-10 dataset.

# Load matplotlib images inline
%matplotlib inline

# These are important for reloading any code you write in external .py files.
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

In [2]:
```
# Set the path to the CIFAR-10 data
cifar10_dir = './cs231n/CIFAR10' # You need to update this line
X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

# As a sanity check, we print out the size of the training and test data.
print('Training data shape: ', X_train.shape)
print('Training labels shape: ', y_train.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

```
Training data shape:  (50000, 32, 32, 3)
Training labels shape:  (50000,)
Test data shape:  (10000, 32, 32, 3)
Test labels shape:  (10000,)
```

In [3]:
```
# Visualize some examples from the dataset.
# We show a few examples of training images from each class.
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse
', 'ship', 'truck']
num_classes = len(classes)
samples_per_class = 7
for y, cls in enumerate(classes):
    idxs = np.flatnonzero(y_train == y)
    idxs = np.random.choice(idxs, samples_per_class, replace=False)
    for i, idx in enumerate(idxs):
        plt_idx = i * num_classes + y + 1
        plt.subplot(samples_per_class, num_classes, plt_idx)
        plt.imshow(X_train[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls)
plt.show()
```

In [4]:
```
# Subsample the data for more efficient code execution in this exercise
num_training = 5000
mask = list(range(num_training))
X_train = X_train[mask]
y_train = y_train[mask]

num_test = 500
mask = list(range(num_test))
X_test = X_test[mask]
y_test = y_test[mask]

# Reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))
print(X_train.shape, X_test.shape)
```

```
(5000, 3072) (500, 3072)
```

K-nearest neighbors

In the following cells, you will build a KNN classifier and choose hyperparameters via k-fold cross-validation.

In [5]:
```
# Import the KNN class

from nndl import KNN
```

In [6]:
```
# Declare an instance of the knn class.
knn = KNN()

# Train the classifier.
#   We have implemented the training of the KNN classifier.
#   Look at the train function in the KNN class to see what this does.
knn.train(X=X_train, y=y_train)
```

Questions

(1) Describe what is going on in the function knn.train().

(2) What are the pros and cons of this training step?

Answers

(1) X_train and y_train are put in class KNN.

(2) O(1) complexity for training function which is very good. However, it requires lots of space to store data.

KNN prediction

In the following sections, you will implement the functions to calculate the distances of test points to training points, and from this information, predict the class of the KNN.

In [7]:
```
# Implement the function compute_distances() in the KNN class.
# Do not worry about the input 'norm' for now; use the default definitio
n of the norm
#   in the code, which is the 2-norm.
# You should only have to fill out the clearly marked sections.

import time
time_start =time.time()

dists_L2 = knn.compute_distances(X=X_test)

print('Time to run code: {}'.format(time.time()-time_start))
print('Frobenius norm of L2 distances: {}'.format(np.linalg.norm(dists_L
2, 'fro')))
```

```
Time to run code: 25.7061710357666
Frobenius norm of L2 distances: 7906696.077040902
```

In [8]:
```
dists_L2
```

Out[8]:
```
array([[ 3803.92350081,  4210.59603857,  5504.0544147 , ...,
         4007.64756434,  4203.28086142,  4354.20256764],
       [ 6336.83367306,  5270.28006846,  4040.63608854, ...,
         4829.15334194,  4694.09767687,  7768.33347636],
       [ 5224.83913628,  4250.64289255,  3773.94581307, ...,
         3766.81549853,  4464.99921613,  6353.57190878],
       ...,
       [ 5366.93534524,  5062.8772452 ,  6361.85774755, ...,
         5126.56824786,  4537.30613911,  5920.94156364],
       [ 3671.92919322,  3858.60765044,  4846.88157479, ...,
         3521.04515734,  3182.3673578 ,  4448.65305458],
       [ 6960.92443573,  6083.71366848,  6338.13442584, ...,
         6083.55504619,  4128.24744898,  8041.05223214]])
```

Really slow code

Note: This probably took a while. This is because we use two for loops. We could increase the speed via vectorization, removing the for loops.

If you implemented this correctly, evaluating np.linalg.norm(dists_L2, 'fro') should return: ~7906696

KNN vectorization

The above code took far too long to run. If we wanted to optimize hyperparameters, it would be time-expensive. Thus, we will speed up the code by vectorizing it, removing the for loops.

In [12]:
```
# Implement the function compute_L2_distances_vectorized() in the KNN cl
ass.
# In this function, you ought to achieve the same L2 distance but WITHOU
T any for loops.
# Note, this is SPECIFIC for the L2 norm.

time_start =time.time()
dists_L2_vectorized = knn.compute_L2_distances_vectorized(X=X_test)
print('Time to run code: {}'.format(time.time()-time_start))
print('Difference in L2 distances between your KNN implementations (shou
ld be 0): {}'.format(\
                                                                  np.linalg.no
rm(dists_L2 - dists_L2_vectorized, 'fro')))
```

```
Time to run code: 0.21020817756652832
Difference in L2 distances between your KNN implementations (should be
0): 0.0
```

Speedup

Depending on your computer speed, you should see a 10-100x speed up from vectorization. On our computer, the vectorized form took 0.36 seconds while the naive implementation took 38.3 seconds.

Implementing the prediction

Now that we have functions to calculate the distances from a test point to given training points, we now implement the function that will predict the test point labels.

In [13]:
```
# Implement the function predict_labels in the KNN class.
# Calculate the training error (num_incorrect / total_samples)
#   from running knn.predict_labels with k=1

error = 1
pred = knn.predict_labels(dists_L2)
# ================================================================ #
# YOUR CODE HERE:
#   Calculate the error rate by calling predict_labels on the test
#   data with k = 1.  Store the error rate in the variable error.
# ================================================================ #
# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
error = 1 - (pred-y_test).tolist().count(0) / pred.shape[0]
print(error)
```

```
0.726
```

If you implemented this correctly, the error should be: 0.726.

This means that the k-nearest neighbors classifier is right 27.4% of the time, which is not great, considering that chance levels are 10%.

Optimizing KNN hyperparameters

In this section, we'll take the KNN classifier that you have constructed and perform cross-validation to choose a best value of k, as well as a best choice of norm.

Create training and validation folds

First, we will create the training and validation folds for use in k-fold cross validation.

In [14]:
```
from sklearn.model_selection import train_test_split
# Create the dataset folds for cross-valdiation.
num_folds = 5
# Last ones reserved for validation
X_train_folds = [0,0,0,0,0]
y_train_folds = [0,0,0,0,0]
train_data, X_train_folds[0],train_target , y_train_folds[0] = train_tes
t_split(\
                                                                X_train,y_tr
ain,test_size=0.2, random_state=0)
train_data, X_train_folds[1],train_target , y_train_folds[1] = train_tes
t_split(\
                                                                train_data,t
rain_target,test_size=0.25, random_state=0)
train_data, X_train_folds[2],train_target , y_train_folds[2] = train_tes
t_split(\
                                                                train_data,t
rain_target,test_size=0.3333, random_state=0)
X_train_folds[3], X_train_folds[4],y_train_folds[3] , y_train_folds[4] =
\
                                            train_test_split(train_data,tr
ain_target,test_size=0.5, random_state=0)
# ================================================================ #
# YOUR CODE HERE:
#   Split the training data into num_folds (i.e., 5) folds.
#   X_train_folds is a list, where X_train_folds[i] contains the
#      data points in fold i.
#   y_train_folds is also a list, where y_train_folds[i] contains
#      the corresponding labels for the data in X_train_folds[i]
# ================================================================ #



# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
```

Optimizing the number of nearest neighbors hyperparameter.

In this section, we select different numbers of nearest neighbors and assess which one has the lowest k-fold cross validation error.

In [53]:
```
time_start =time.time()

ks = [1, 2, 3, 5, 7, 10, 15, 20, 25, 30]

# ================================================================ #
# YOUR CODE HERE:
#   Calculate the cross-validation error for each k in ks, testing
#   the trained model on each of the 5 folds.  Average these errors
#   together and make a plot of k vs. cross-validation error. Since
#   we are assuming L2 distance here, please use the vectorized code!
#   Otherwise, you might be waiting a long time.
# ================================================================ #

error = []
for i in range(4):
    knn.train(X_train_folds[i],y_train_folds[i])
    temp = []
    for i1 in range(len(ks)):
        pred = knn.predict_labels(knn.compute_L2_distances_vectorized(X_
train_folds[4]),ks[i1])
        temp.append(1 - (pred-y_train_folds[4]).tolist().count(0) / pre
d.shape[0])
    error.append(temp)
print(error)

# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #

print('Computation time: %.2f'%(time.time()-time_start))
```

```
[[0.762, 0.762, 0.752, 0.753, 0.748, 0.764, 0.759, 0.757, 0.763, 0.771],
[0.752, 0.752, 0.749, 0.755, 0.746, 0.743, 0.749, 0.747, 0.74, 0.748],
[0.769, 0.769, 0.751, 0.748, 0.737, 0.731, 0.732, 0.749, 0.749, 0.752],
[0.759, 0.759, 0.76, 0.747, 0.74, 0.727, 0.722, 0.72, 0.718, 0.735]]
Computation time: 82.21
```

In [54]:
```
error = np.asarray(error).T
avg_error = [sum(error.tolist()[i]) / error.shape[1] for i in range(erro
r.shape[0])]
avg_error.index(min(avg_error))
```

Out[54]: 6

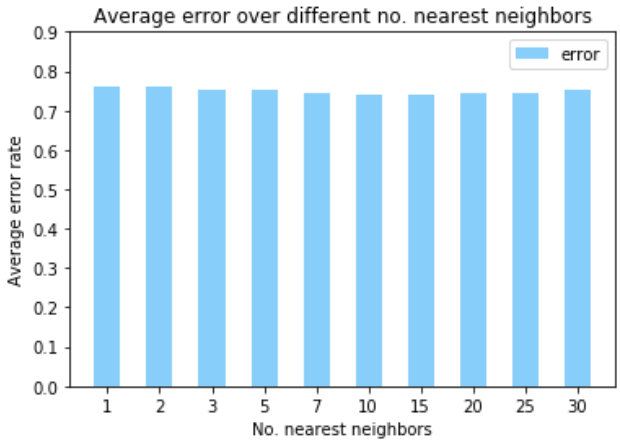
In [66]:
```
best_k = ks[avg_error.index(min(avg_error))]
best_k
```

Out[66]: 15

In [55]:
```
avg_error
```

Out[55]:
```
[0.7605,
 0.7605,
 0.7529999999999999,
 0.75075,
 0.74275,
 0.74125,
 0.7405,
 0.74325,
 0.7425,
 0.7515]
```

In [64]:
```
width = 0.5
p2 = plt.bar(range(len(avg_error)), avg_error, width, label="error", col
or="#87CEFA")
plt.xlabel('No. nearest neighbors')
plt.ylabel('Average error rate')
plt.title('Average error over different no. nearest neighbors')
plt.xticks(range(len(avg_error)), [ks[i] for i in range(len(avg_erro
r))])
plt.yticks(np.arange(0,1.0,0.1))
plt.legend(loc="upper right")
plt.show()
```



Questions:

(1) What value of k is best amongst the tested k's?

(2) What is the cross-validation error for this value of k?

Answers:

(1) 15.

(2) The average cross-validation error for this k is 0.7405.

Optimizing the norm

Next, we test three different norms (the 1, 2, and infinity norms) and see which distance metric results in the best cross-validation performance.

In [67]:
```
time_start =time.time()

L1_norm = lambda x: np.linalg.norm(x, ord=1)
L2_norm = lambda x: np.linalg.norm(x, ord=2)
Linf_norm = lambda x: np.linalg.norm(x, ord= np.inf)
norms = [L1_norm, L2_norm, Linf_norm]

# ================================================================ #
# YOUR CODE HERE:
#   Calculate the cross-validation error for each norm in norms, testing
#   the trained model on each of the 5 folds.  Average these errors
#   together and make a plot of the norm used vs the cross-validation er
ror
#   Use the best cross-validation k from the previous part.
#
#   Feel free to use the compute_distances function.  We're testing just
#   three norms, but be advised that this could still take some time.
#   You're welcome to write a vectorized form of the L1- and Linf- norms
#   to speed this up, but it is not necessary.
# ================================================================ #

error = []
for i in range(4):
    knn.train(X_train_folds[i],y_train_folds[i])
    temp = []
    for i1 in range(len(norms)):
        pred = knn.predict_labels(knn.compute_distances(X_train_folds
[4],norms[i1]),best_k)
        temp.append(1 - (pred-y_train_folds[4]).tolist().count(0) / pre
d.shape[0])
    error.append(temp)
print(error)

# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
print('Computation time: %.2f'%(time.time()-time_start))
```

```
[[0.72, 0.759, 0.841], [0.724, 0.749, 0.839], [0.7150000000000001, 0.732,
0.823], [0.7050000000000001, 0.722, 0.838]]
Computation time: 143.67
```

In [68]:
```
error = np.asarray(error).T
avg_error = [sum(error.tolist()[i]) / error.shape[1] for i in range(erro
r.shape[0])]
avg_error.index(min(avg_error))
```

Out[68]: 0

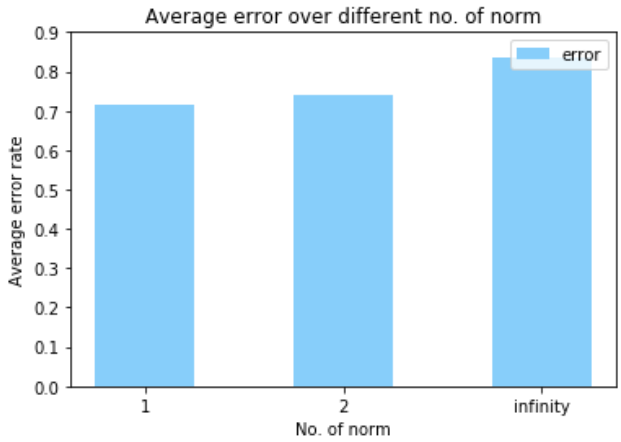
In [69]:
```
best_l = norms[avg_error.index(min(avg_error))]
best_l
```

Out[69]: <function __main__.<lambda>>

In [73]:
```
avg_error
```

Out[73]: [0.716, 0.7405, 0.83525]

In [70]:
```
norms_num = ['1','2','infinity']
width = 0.5
p2 = plt.bar(range(len(avg_error)), avg_error, width, label="error", col
or="#87CEFA")
plt.xlabel('No. of norm')
plt.ylabel('Average error rate')
plt.title('Average error over different no. of norm')
plt.xticks(range(len(avg_error)), [norms_num[i] for i in range(len(avg_e
rror))])
plt.yticks(np.arange(0,1.0,0.1))
plt.legend(loc="upper right")
plt.show()
```



Questions:

(1) What norm has the best cross-validation error?

(2) What is the cross-validation error for your given norm and k?

Answers:

(1) L1-norm.

(2) The average cross-validation error is 0.716.

Evaluating the model on the testing dataset.

Now, given the optimal k and norm you found in earlier parts, evaluate the testing error of the k-nearest neighbors model.

In [72]:
```
error = 1

# ================================================================ #
# YOUR CODE HERE:
#   Evaluate the testing error of the k-nearest neighbors classifier
#   for your optimal hyperparameters found by 5-fold cross-validation.
# ================================================================ #
knn.train(X_train,y_train)
pred = knn.predict_labels(knn.compute_distances(X_test,best_l),best_k)
error = 1 - (pred-y_test).tolist().count(0) / pred.shape[0]
# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #

print('Error rate achieved: {}'.format(error))
```

```
Error rate achieved: 0.7
```

Question:

How much did your error improve by cross-validation over naively choosing $k = 1$ and using the L2-norm?

Answer:

Naively choosing $k = 1$ and using the L2-norm gives me error rate 0.726. However, choosing $k = 15$ and L1-norm gives me error rate 0.7, which is a considerable improvement.

```
import numpy as np
import pdb
import heapq
import copy
"""
This code was based off of code from cs231n at Stanford University, and modified
for ECE C147/C247 at UCLA.
"""

class KNN(object):

  def __init__(self):
    pass

  def train(self, X, y):
    """
        Inputs:
        - X is a numpy array of size (num_examples, D)
        - y is a numpy array of size (num_examples, )
    """
    self.X_train = X
    self.y_train = y

  def compute_distances(self, X, norm=None):
    """
    Compute the distance between each test point in X and each training point
    in self.X_train.

    Inputs:
    - X: A numpy array of shape (num_test, D) containing test data.
        - norm: the function with which the norm is taken.

    Returns:
    - dists: A numpy array of shape (num_test, num_train) where dists[i, j]
      is the Euclidean distance between the ith test point and the jth training
      point.
    """
    if norm is None:
      norm = lambda x: np.sqrt(np.sum(x**2))
      #norm = 2

    num_test = X.shape[0]
    num_train = self.X_train.shape[0]
    dists = np.zeros((num_test, num_train))
    for i in np.arange(num_test):

      temp = []
      for j in np.arange(num_train):
                # ================================================================
#
        # YOUR CODE HERE:
                #   Compute the distance between the ith test point and the
jth
        #   training point using norm(), and store the result in dists[i, j].
        # ================================================================ #
        temp.append(norm(X[i]-self.X_train[j]))
      dists[i] = temp


                # ================================================================
#
                # END YOUR CODE HERE
                # ================================================================
#

    return dists
```

```
  def compute_L2_distances_vectorized(self, X):
    """
    Compute the distance between each test point in X and each training point
    in self.X_train WITHOUT using any for loops.

    Inputs:
    - X: A numpy array of shape (num_test, D) containing test data.

    Returns:
    - dists: A numpy array of shape (num_test, num_train) where dists[i, j]
      is the Euclidean distance between the ith test point and the jth training
      point.
    """
    num_test = X.shape[0]
    num_train = self.X_train.shape[0]
    dists = np.zeros((num_test, num_train))

        # ========================================================== #
        # YOUR CODE HERE:
        #   Compute the L2 distance between the ith test point and the jth
    #   training point and store the result in dists[i, j].  You may
        #       NOT use a for loop (or list comprehension).  You may only use
        #       numpy operations.
        #
        #       HINT: use broadcasting.  If you have a shape (N,1) array and
        #   a shape (M,) array, adding them together produces a shape (N, M)
        #   array.
        # ========================================================== #

    test_sqr = np.sum(X * X, axis = 1)
    test_sqr_ext = np.asarray([test_sqr] * num_train).T
    train_sqr = np.sum(self.X_train * self.X_train, axis = 1)
    train_sqr_ext = np.asarray([train_sqr] * num_test)
    test_train = X.dot(self.X_train.T)
    dists = np.sqrt(test_sqr_ext + train_sqr_ext - 2 * test_train)


        # ========================================================== #
        # END YOUR CODE HERE
        # ========================================================== #

    return dists


  def predict_labels(self, dists, k=1):
    """
    Given a matrix of distances between test points and training points,
    predict a label for each test point.

    Inputs:
    - dists: A numpy array of shape (num_test, num_train) where dists[i, j]
      gives the distance betwen the ith test point and the jth training point.

    Returns:
    - y: A numpy array of shape (num_test,) containing predicted labels for the
      test data, where y[i] is the predicted label for the test point X[i].
    """

    def max_list(lt):
      temp = 0
      for i in lt:
        if lt.count(i) > temp:
          max_str = i
          temp = lt.count(i)
```

```
      return max_str

    num_test = dists.shape[0]
    y_pred = []
    for i in np.arange(num_test):
      # A list of length k storing the labels of the k nearest neighbors to
      # the ith test point.
      for i1 in range(k):
        temp_ls = copy.deepcopy(dists[i]).tolist()
        min_number = heapq.nsmallest(k,temp_ls)
        min_index = []
        for t in min_number:
          index = temp_ls.index(t)
          min_index.append(index)
          temp_ls[index] = 1000000
      y_pred.append(max_list(self.y_train[min_index].tolist()))
    y_pred = np.asarray(y_pred)
          # ========================================================================= #
          # YOUR CODE HERE:
          #   Use the distances to calculate and then store the labels of
          #   the k-nearest neighbors to the ith test point.  The function
          #   numpy.argsort may be useful.
          #
          #   After doing this, find the most common label of the k-nearest
          #   neighbors.  Store the predicted label of the ith training example
          #   as y_pred[i].  Break ties by choosing the smaller label.
          # ========================================================================= #


          # ========================================================================= #
          # END YOUR CODE HERE
          # ========================================================================= #

    return y_pred
```

This is the svm workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement a linear support vector machine.

Please print out the workbook entirely when completed.

We thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu). These are the functions in the cs231n folders and includes code to preprocess and show the images. The classifiers used are based off of code prepared for CS 231n as well.

The goal of this workbook is to give you experience with training an SVM classifier via gradient descent.

Importing libraries and data setup

In [1]:
```
import numpy as np # for doing most of our calculations
import matplotlib.pyplot as plt# for plotting
from cs231n.data_utils import load_CIFAR10 # function to load the CIFAR-10 dataset.
import pdb

# Load matplotlib images inline
%matplotlib inline

# These are important for reloading any code you write in external .py files.
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

In [2]:
```
# Set the path to the CIFAR-10 data
cifar10_dir = './cs231n/CIFAR10' # You need to update this line
X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

# As a sanity check, we print out the size of the training and test data.
print('Training data shape: ', X_train.shape)
print('Training labels shape: ', y_train.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

```
Training data shape:  (50000, 32, 32, 3)
Training labels shape:  (50000,)
Test data shape:  (10000, 32, 32, 3)
Test labels shape:  (10000,)
```

In [3]:
```
# Visualize some examples from the dataset.
# We show a few examples of training images from each class.
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse
', 'ship', 'truck']
num_classes = len(classes)
samples_per_class = 7
for y, cls in enumerate(classes):
    idxs = np.flatnonzero(y_train == y)
    idxs = np.random.choice(idxs, samples_per_class, replace=False)
    for i, idx in enumerate(idxs):
        plt_idx = i * num_classes + y + 1
        plt.subplot(samples_per_class, num_classes, plt_idx)
        plt.imshow(X_train[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls)
plt.show()
```

In [4]:
```
# Split the data into train, val, and test sets. In addition we will
# create a small development set as a subset of the training data;
# we can use this for development so our code runs faster.
num_training = 49000
num_validation = 1000
num_test = 1000
num_dev = 500

# Our validation set will be num_validation points from the original
# training set.
mask = range(num_training, num_training + num_validation)
X_val = X_train[mask]
y_val = y_train[mask]

# Our training set will be the first num_train points from the original
# training set.
mask = range(num_training)
X_train = X_train[mask]
y_train = y_train[mask]

# We will also make a development set, which is a small subset of
# the training set.
mask = np.random.choice(num_training, num_dev, replace=False)
X_dev = X_train[mask]
y_dev = y_train[mask]

# We use the first num_test points of the original test set as our
# test set.
mask = range(num_test)
X_test = X_test[mask]
y_test = y_test[mask]

print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
print('Dev data shape: ', X_dev.shape)
print('Dev labels shape: ', y_dev.shape)
```

```
Train data shape:  (49000, 32, 32, 3)
Train labels shape:  (49000,)
Validation data shape:  (1000, 32, 32, 3)
Validation labels shape:  (1000,)
Test data shape:  (1000, 32, 32, 3)
Test labels shape:  (1000,)
Dev data shape:  (500, 32, 32, 3)
Dev labels shape:  (500,)
```

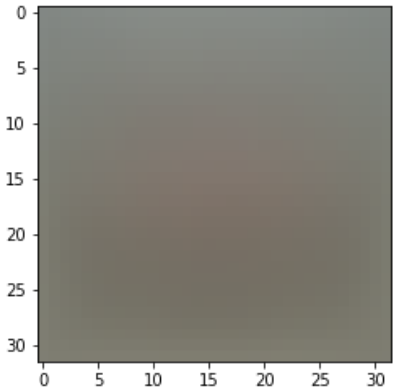
In [5]:
```
# Preprocessing: reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_val = np.reshape(X_val, (X_val.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))
X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))

# As a sanity check, print out the shapes of the data
print('Training data shape: ', X_train.shape)
print('Validation data shape: ', X_val.shape)
print('Test data shape: ', X_test.shape)
print('dev data shape: ', X_dev.shape)
```

```
Training data shape:  (49000, 3072)
Validation data shape:  (1000, 3072)
Test data shape:  (1000, 3072)
dev data shape:  (500, 3072)
```

In [6]:
```
# Preprocessing: subtract the mean image
# first: compute the image mean based on the training data
mean_image = np.mean(X_train, axis=0)
print(mean_image[:10]) # print a few of the elements
plt.figure(figsize=(4,4))
plt.imshow(mean_image.reshape((32,32,3)).astype('uint8')) # visualize th
e mean image
plt.show()
```

```
[130.64189796 135.98173469 132.47391837 130.05569388 135.34804082
 131.75402041 130.96055102 136.14328571 132.47636735 131.48467347]
```



In [7]:
```
# second: subtract the mean image from train and test data
X_train -= mean_image
X_val -= mean_image
X_test -= mean_image
X_dev -= mean_image
```

In [8]:
```
# third: append the bias dimension of ones (i.e. bias trick) so that our
SVM
# only has to worry about optimizing a single weight matrix W.
X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])

print(X_train.shape, X_val.shape, X_test.shape, X_dev.shape)
```

```
(49000, 3073) (1000, 3073) (1000, 3073) (500, 3073)
```

Question:

(1) For the SVM, we perform mean-subtraction on the data. However, for the KNN notebook, we did not. Why?

Answer:

(1) Because simply finding nearest k points does not need to perform mean-subtraction. However, in SVM, mean-subtraction usually gives better performance because it is good for following calculations.

Training an SVM

The following cells will take you through building an SVM. You will implement its loss function, then subsequently train it with gradient descent. Finally, you will choose the learning rate of gradient descent to optimize its classification performance.

In [9]:
```
from nndl.svm import SVM
```

In [10]:
```
# Declare an instance of the SVM class.
# Weights are initialized to a random value.
# Note, to keep people's initial solutions consistent, we are going to u
se a random seed.

np.random.seed(1)

num_classes = len(np.unique(y_train))
num_features = X_train.shape[1]

svm = SVM(dims=[num_classes, num_features])
```

SVM loss

In [11]:
```
## Implement the loss function for in the SVM class(nndl/svm.py), svm.lo
ss()

loss = svm.loss(X_train, y_train)
print('The training set loss is {}.'.format(loss))

# If you implemented the loss correctly, it should be 15569.98
```

```
The training set loss is 15569.977915410187.
```

SVM gradient

In [12]:
```
## Calculate the gradient of the SVM class.
# For convenience, we'll write one function that computes the loss
#   and gradient together. Please modify svm.loss_and_grad(X, y).
# You may copy and paste your loss code from svm.loss() here, and then
#   use the appropriate intermediate values to calculate the gradient.

loss, grad = svm.loss_and_grad(X_dev,y_dev)

# Compare your gradient to a numerical gradient check.
# You should see relative gradient errors on the order of 1e-07 or less
if you implemented the gradient correctly.
svm.grad_check_sparse(X_dev, y_dev, grad)
```

```
numerical: -6.982978 analytic: -6.982978, relative error: 2.161370e-08
numerical: 7.396414 analytic: 7.396414, relative error: 3.141684e-08
numerical: -10.283422 analytic: -10.283422, relative error: 1.358506e-08
numerical: 7.526019 analytic: 7.526019, relative error: 5.046692e-08
numerical: 4.700063 analytic: 4.700064, relative error: 8.993575e-08
numerical: -1.177351 analytic: -1.177350, relative error: 2.551728e-07
numerical: 4.769727 analytic: 4.769727, relative error: 6.581953e-09
numerical: -14.438845 analytic: -14.438845, relative error: 1.330815e-08
numerical: -12.772850 analytic: -12.772850, relative error: 1.456375e-08
numerical: -22.460173 analytic: -22.460174, relative error: 1.358502e-08
```

A vectorized version of SVM

To speed things up, we will vectorize the loss and gradient calculations. This will be helpful for stochastic gradient descent.

In [13]:
```
import time
```

In [14]:
```
## Implement svm.fast_loss_and_grad which calculates the loss and gradie
nt
#    WITHOUT using any for loops.

# Standard loss and gradient
tic = time.time()
loss, grad = svm.loss_and_grad(X_dev, y_dev)
toc = time.time()
print('Normal loss / grad_norm: {} / {} computed in {}s'.format(loss, n
p.linalg.norm(grad, 'fro'), toc - tic))

tic = time.time()
loss_vectorized, grad_vectorized = svm.fast_loss_and_grad(X_dev, y_dev)
toc = time.time()
print('Vectorized loss / grad: {} / {} computed in {}s'.format(loss_vect
orized,\
                                                               np.linal
g.norm(grad_vectorized, 'fro'), toc - tic))

# The losses should match but your vectorized implementation should be m
uch faster.
print('difference in loss / grad: {} / {}'.format(loss - loss_vectorize
d, np.linalg.norm(grad - grad_vectorized)))

# You should notice a speedup with the same output, i.e., differences on
the order of 1e-12
```

```
Normal loss / grad_norm: 15431.809820686762 / 2111.2788185433087 computed
in 0.10197329521179199s
Vectorized loss / grad: 15431.809820686785 / 2111.278818543309 computed i
n 0.05189943313598633s
difference in loss / grad: -2.3646862246096134e-11 / 2.1592099214444736e-
12
```

Stochastic gradient descent

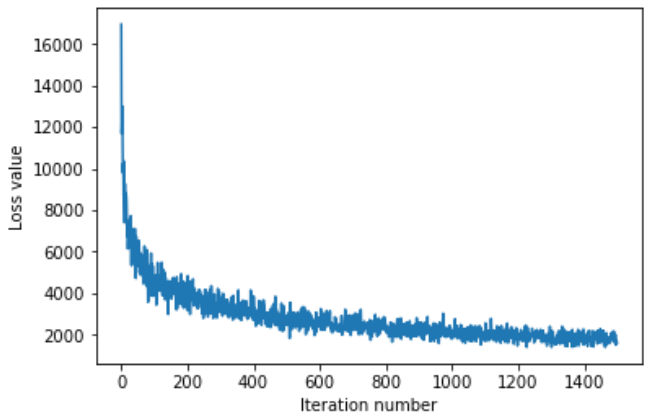
We now implement stochastic gradient descent. This uses the same principles of gradient descent we discussed in class, however, it calculates the gradient by only using examples from a subset of the training set (so each gradient calculation is faster).

In [15]:
```
# Implement svm.train() by filling in the code to extract a batch of dat
a
# and perform the gradient step.

tic = time.time()
loss_hist = svm.train(X_train, y_train, learning_rate=5e-4,
                      num_iters=1500, verbose=True)
toc = time.time()
print('That took {}s'.format(toc - tic))

plt.plot(loss_hist)
plt.xlabel('Iteration number')
plt.ylabel('Loss value')
plt.show()
```

```
iteration 0 / 1500: loss 16943.89523926503
iteration 100 / 1500: loss 4026.806778561375
iteration 200 / 1500: loss 3194.7356097187385
iteration 300 / 1500: loss 3607.13651243476
iteration 400 / 1500: loss 3862.028225076626
iteration 500 / 1500: loss 2946.3366005475436
iteration 600 / 1500: loss 2568.435932806188
iteration 700 / 1500: loss 2599.812650960954
iteration 800 / 1500: loss 2456.028886800395
iteration 900 / 1500: loss 2294.355049022149
iteration 1000 / 1500: loss 2250.7793384243487
iteration 1100 / 1500: loss 1926.2994938989718
iteration 1200 / 1500: loss 2018.962584120033
iteration 1300 / 1500: loss 2174.731930046548
iteration 1400 / 1500: loss 1549.782296147385
That took 649.815535068512s
```



Evaluate the performance of the trained SVM on the validation data.

In [16]:
```
## Implement svm.predict() and use it to compute the training and testin
g error.

y_train_pred = svm.predict(X_train)
print('training accuracy: {}'.format(np.mean(np.equal(y_train,y_train_pr
ed), )))
y_val_pred = svm.predict(X_val)
print('validation accuracy: {}'.format(np.mean(np.equal(y_val, y_val_pre
d)), ))
```

```
training accuracy: 0.28651020408163264
validation accuracy: 0.303
```

Optimize the SVM

Note, to make things faster and simpler, we won't do k-fold cross-validation, but will only optimize the hyperparameters on the validation dataset (X_val, y_val).

In [17]:
```
from sklearn.model_selection import train_test_split
# ================================================================ #
# YOUR CODE HERE:
#   Train the SVM with different learning rates and evaluate on the
#     validation data.
#   Report:
#     - The best learning rate of the ones you tested.
#     - The best VALIDATION accuracy corresponding to the best VALIDATIO
N error.
#
#   Select the SVM that achieved the best validation error and report
#     its error rate on the test set.
#   Note: You do not need to modify SVM class for this section
# ================================================================ #
learning_rate = [1e-5,3.3e-5,1e-4,3.3e-4,1e-3,3.3e-3,1e-2]
val_acc = []
for i in range(len(learning_rate)):
    X_val_train ,X_val_test, y_val_train, y_val_test = train_test_split
(X_val,y_val,test_size=0.2,\
                                                    random_state=int(np.
random.randint(0,2**32-1,size=1)))
    num_classes = len(np.unique(y_val_train))
    num_features = X_val_train.shape[1]

    svm = SVM(dims=[num_classes, num_features])
    svm.train(X_val_train, y_val_train, learning_rate[i], 1500, 200, Fal
se)
    val_acc.append(np.mean(np.equal(y_val_test, svm.predict(X_val_tes
t))))

val_max = max(val_acc)
index_max = val_acc.index(val_max)
print('The best validation accuracy is ', val_max, ', while the learning
rate is ', learning_rate[index_max])
# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
```

```
The best validation accuracy is  0.31 , while the learning rate is  0.01
```

```python
import numpy as np
import pdb
import copy
from sklearn.model_selection import train_test_split
"""
This code was based off of code from cs231n at Stanford University, and modified
for ECE C147/C247 at UCLA.
"""
class SVM(object):

  def __init__(self, dims=[10, 3073]):
    self.init_weights(dims=dims)

  def init_weights(self, dims):
    """
        Initializes the weight matrix of the SVM.  Note that it has shape (C, D)
        where C is the number of classes and D is the feature size.
        """
    self.W = np.random.normal(size=dims)

  def loss(self, X, y):
    """
    Calculates the SVM loss.

    Inputs have dimension D, there are C classes, and we operate on minibatches
    of N examples.

    Inputs:
    - X: A numpy array of shape (N, D) containing a minibatch of data.
    - y: A numpy array of shape (N,) containing training labels; y[i] = c means
      that X[i] has label c, where 0 <= c < C.

    Returns a tuple of:
    - loss as single float
    """

    # compute the loss and the gradient
    num_classes = self.W.shape[0]
    num_train = X.shape[0]
    loss = 0.0

    for i in np.arange(num_train):
    # ============================================================= #
    # YOUR CODE HERE:
          #   Calculate the normalized SVM loss, and store it as 'loss'.
    #   (That is, calculate the sum of the losses of all the training
    #   set margins, and then normalize the loss by the number of
          #       training examples.)
    # ============================================================= #

      score = np.dot(X[i],self.W.T)
      for j in range(num_classes):
        if j == y[i]:
          continue
        margin = score[j] - score[y[i]] + 1
        loss = loss + max(np.max(margin),0)
    loss = loss / num_train

    # ============================================================= #
    # END YOUR CODE HERE
    # ============================================================= #

    return loss

  def loss_and_grad(self, X, y):
    """
```

```
        Same as self.loss(X, y), except that it also returns the gradient.

        Output: grad -- a matrix of the same dimensions as W containing
                the gradient of the loss with respect to W.
        """

    # compute the loss and the gradient
    num_classes = self.W.shape[0]
    num_train = X.shape[0]
    loss = 0.0
    grad = np.zeros_like(self.W)

    for i in np.arange(num_train):
    # ============================================================= #
    # YOUR CODE HERE:
        #   Calculate the SVM loss and the gradient.  Store the gradient in
    #   the variable grad.
    # ============================================================= #
      score = np.dot(X[i],self.W.T)
      for j in range(num_classes):
        if j != y[i]:
          margin = score[j] - score[y[i]] + 1
          loss = loss + max(np.max(margin),0)
          if margin > 0:
            grad[j] = grad[j] + X[i].T
            grad[y[i]] = grad[y[i]] - X[i].T

    # ============================================================= #
    # END YOUR CODE HERE
    # ============================================================= #

    loss /= num_train
    grad /= num_train

    return loss, grad

  def grad_check_sparse(self, X, y, your_grad, num_checks=10, h=1e-5):
    """
    sample a few random elements and only return numerical
    in these dimensions.
    """

    for i in np.arange(num_checks):
      ix = tuple([np.random.randint(m) for m in self.W.shape])

      oldval = self.W[ix]
      self.W[ix] = oldval + h # increment by h
      fxph = self.loss(X, y)
      self.W[ix] = oldval - h # decrement by h
      fxmh = self.loss(X,y) # evaluate f(x - h)
      self.W[ix] = oldval # reset

      grad_numerical = (fxph - fxmh) / (2 * h)
      grad_analytic = your_grad[ix]
      rel_error = abs(grad_numerical - grad_analytic) / (abs(grad_numerical) + abs
(grad_analytic))
      print('numerical: %f analytic: %f, relative error: %e' % (grad_numerical,
grad_analytic, rel_error))

  def fast_loss_and_grad(self, X, y):
    """
    A vectorized implementation of loss_and_grad. It shares the same
        inputs and ouptuts as loss_and_grad.
    """
    loss = 0.0
    grad = np.zeros(self.W.shape) # initialize the gradient as zero
```

```
    num_classes = self.W.shape[0]
    num_train = X.shape[0]

    # ================================================================ #
    # YOUR CODE HERE:
        #   Calculate the SVM loss WITHOUT any for loops.
    # ================================================================ #

    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    #loss = np.sum([np.sum([1 - ((np.dot(X[i],self.W[y[i]].T) - np.dot(X[i],self.W
[j].T)) if y[i]!=j and (np.dot(X[i],self.W[y[i]].T) - np.dot(X[i],self.W[j].T)) <
1 else 1) for j in range(num_classes)]) for i in range(num_train)])
    score = np.dot(X,self.W.T)
    #y_belong = np.argwhere(y == 0).T.tolist() + np.argwhere(y == 1).T.tolist() +
np.argwhere(y == 2).T.tolist() + np.argwhere(y == 3).T.tolist() + np.argwhere(y ==
4).T.tolist() + np.argwhere(y == 5).T.tolist() + np.argwhere(y == 6).T.tolist() +
np.argwhere(y == 7).T.tolist() + np.argwhere(y == 8).T.tolist() + np.argwhere(y ==
9).T.tolist()
    margin_total = (score + 1 - score[:,y].diagonal().reshape(num_train,1))#.T

    np.put_along_axis(margin_total,y.T.reshape(num_train,1),0,axis=1)
    #for i in range(num_classes):
    #  margin_total[i,y_belong[i]] = 0
    margin_total[margin_total<0] = 0
    loss = np.sum(margin_total)


    margin_total[margin_total>0] = 1
    coef_neg = np.zeros((num_train,num_classes))
    coef_neg[range(num_train),y] = np.sum(margin_total,axis=1)
    grad = np.dot(margin_total.T,X) - np.dot(coef_neg.T,X)

        # ================================================================ #
    # YOUR CODE HERE:
        #   Calculate the SVM grad WITHOUT any for loops.
    # ================================================================ #
    loss /= num_train
    grad /= num_train
    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return loss, grad

  def train(self, X, y, learning_rate=1e-3, num_iters=100,
            batch_size=200, verbose=False):
    """
    Train this linear classifier using stochastic gradient descent.

    Inputs:
    - X: A numpy array of shape (N, D) containing training data; there are N
      training samples each of dimension D.
    - y: A numpy array of shape (N,) containing training labels; y[i] = c
      means that X[i] has label 0 <= c < C for C classes.
    - learning_rate: (float) learning rate for optimization.
    - num_iters: (integer) number of steps to take when optimizing
    - batch_size: (integer) number of training examples to use at each step.
    - verbose: (boolean) If true, print progress during optimization.

    Outputs:
    A list containing the value of the loss function at each training iteration.
    """
    num_train, dim = X.shape
```

```
    num_classes = np.max(y) + 1 # assume y takes values 0...K-1 where K is number
of classes

    self.init_weights(dims=[np.max(y) + 1, X.shape[1]]) # initializes the weights
of self.W

    # Run stochastic gradient descent to optimize W
    loss_history = []

    for it in np.arange(num_iters):
      X_batch = None
      y_batch = None

      # ========================================================================= #
      # YOUR CODE HERE:
      #   Sample batch_size elements from the training data for use in
      #   gradient descent.  After sampling,
      #     - X_batch should have shape: (dim, batch_size)
            #     - y_batch should have shape: (batch_size,)
            #   The indices should be randomly generated to reduce correlations
            #   in the dataset.  Use np.random.choice.  It's okay to sample with
            #   replacement.
      # ========================================================================= #
      _, X_batch,_, y_batch = train_test_split(X,y,test_size=batch_size/num_train,
random_state=int(np.random.randint(0,2**32-1,size=1)))
      # ========================================================================= #
      # END YOUR CODE HERE
      # ========================================================================= #

      # evaluate loss and gradient
      loss, grad = self.fast_loss_and_grad(X_batch, y_batch)
      loss_history.append(loss)

      # ========================================================================= #
      # YOUR CODE HERE:
      #   Update the parameters, self.W, with a gradient step
      # ========================================================================= #
      self.W = self.W - learning_rate * grad
            # ========================================================================= #
      # END YOUR CODE HERE
      # ========================================================================= #

      if verbose and it % 100 == 0:
        print('iteration {} / {}: loss {}'.format(it, num_iters, loss))

    return loss_history

  def predict(self, X):
    """
    Inputs:
    - X: N x D array of training data. Each row is a D-dimensional point.

    Returns:
    - y_pred: Predicted labels for the data in X. y_pred is a 1-dimensional
      array of length N, and each element is an integer giving the predicted
      class.
    """
    y_pred = np.zeros(X.shape[1])


    # ========================================================================= #
    # YOUR CODE HERE:
    #   Predict the labels given the training data with the parameter self.W.
    # ========================================================================= #
    y_pred = np.argmax(X.dot(self.W.T), axis=1)
    # ========================================================================= #
```

```
    # END YOUR CODE HERE
    # ================================================================ #

    return y_pred
```

This is the softmax workbook for ECE C147/C247 Assignment #2

Please follow the notebook linearly to implement a softmax classifier.

Please print out the workbook entirely when completed.

We thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu). These are the functions in the cs231n folders and code in the jupyer notebook to preprocess and show the images. The classifiers used are based off of code prepared for CS 231n as well.

The goal of this workbook is to give you experience with training a softmax classifier.

In [1]:
```
import random
import numpy as np
from cs231n.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

%matplotlib inline
%load_ext autoreload
%autoreload 2
```

In [2]:
```
def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1
000, num_dev=500):
    """
    Load the CIFAR-10 dataset from disk and perform preprocessing to pre
pare
    it for the linear classifier. These are the same steps as we used fo
r the
    SVM, but condensed to a single function.
    """
    # Load the raw CIFAR-10 data
    cifar10_dir = './cs231n/CIFAR10' # You need to update this line
    X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

    # subsample the data
    mask = list(range(num_training, num_training + num_validation))
    X_val = X_train[mask]
    y_val = y_train[mask]
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]
    mask = np.random.choice(num_training, num_dev, replace=False)
    X_dev = X_train[mask]
    y_dev = y_train[mask]

    # Preprocessing: reshape the image data into rows
    X_train = np.reshape(X_train, (X_train.shape[0], -1))
    X_val = np.reshape(X_val, (X_val.shape[0], -1))
    X_test = np.reshape(X_test, (X_test.shape[0], -1))
    X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))

    # Normalize the data: subtract the mean image
    mean_image = np.mean(X_train, axis = 0)
    X_train -= mean_image
    X_val -= mean_image
    X_test -= mean_image
    X_dev -= mean_image

    # add bias dimension and transform into columns
    X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
    X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
    X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
    X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])

    return X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev


# Invoke the above function to get our data.
X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev = get_CIFAR
10_data()
print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
print('dev data shape: ', X_dev.shape)
print('dev labels shape: ', y_dev.shape)
```

```
Train data shape:  (49000, 3073)
Train labels shape:  (49000,)
Validation data shape:  (1000, 3073)
Validation labels shape:  (1000,)
Test data shape:  (1000, 3073)
Test labels shape:  (1000,)
dev data shape:  (500, 3073)
dev labels shape:  (500,)
```

Training a softmax classifier.

The following cells will take you through building a softmax classifier. You will implement its loss function, then subsequently train it with gradient descent. Finally, you will choose the learning rate of gradient descent to optimize its classification performance.

In [3]:
```
from nndl import Softmax
```

In [4]:
```
# Declare an instance of the Softmax class.
# Weights are initialized to a random value.
# Note, to keep people's first solutions consistent, we are going to use
a random seed.

np.random.seed(1)

num_classes = len(np.unique(y_train))
num_features = X_train.shape[1]

softmax = Softmax(dims=[num_classes, num_features])
```

Softmax loss

In [5]:
```
## Implement the loss function of the softmax using a for loop over
#  the number of examples

loss = softmax.loss(X_train, y_train)
```

In [6]:
```
print(loss)
```

```
2.327760702804886
```

Question:

You'll notice the loss returned by the softmax is about 2.3 (if implemented correctly). Why does this make sense?

Answer:

A random weight can lead to the probability of one class out of 10 classes as $1/10$, so $loss = -log(1/10)$.

Softmax gradient

In [7]:
```
## Calculate the gradient of the softmax loss in the Softmax class.
# For convenience, we'll write one function that computes the loss
#   and gradient together, softmax.loss_and_grad(X, y)
# You may copy and paste your loss code from softmax.loss() here, and th
en
#   use the appropriate intermediate values to calculate the gradient.

loss, grad = softmax.loss_and_grad(X_dev,y_dev)

# Compare your gradient to a gradient check we wrote.
# You should see relative gradient errors on the order of 1e-07 or less
if you implemented the gradient correctly.
softmax.grad_check_sparse(X_dev, y_dev, grad)
```

```
numerical: -0.667767 analytic: -0.667767, relative error: 2.043087e-08
numerical: -0.991149 analytic: -0.991149, relative error: 1.683765e-08
numerical: -0.534692 analytic: -0.534692, relative error: 4.168893e-08
numerical: 1.252677 analytic: 1.252677, relative error: 3.261767e-08
numerical: 1.957190 analytic: 1.957190, relative error: 2.990491e-08
numerical: 0.925873 analytic: 0.925873, relative error: 2.330969e-08
numerical: -1.246938 analytic: -1.246938, relative error: 5.963844e-08
numerical: -0.435818 analytic: -0.435818, relative error: 2.526776e-08
numerical: 1.204972 analytic: 1.204972, relative error: 1.065681e-08
numerical: -3.007804 analytic: -3.007804, relative error: 1.299631e-08
```

A vectorized version of Softmax

To speed things up, we will vectorize the loss and gradient calculations. This will be helpful for stochastic gradient descent.

In [8]:
```
import time
```

In [9]:
```
## Implement softmax.fast_loss_and_grad which calculates the loss and gr
adient
#    WITHOUT using any for loops.

# Standard loss and gradient
tic = time.time()
loss, grad = softmax.loss_and_grad(X_dev, y_dev)
toc = time.time()
print('Normal loss / grad_norm: {} / {} computed in {}s'.format(loss, n
p.linalg.norm(grad, 'fro'), toc - tic))

tic = time.time()
loss_vectorized, grad_vectorized = softmax.fast_loss_and_grad(X_dev, y_d
ev)
toc = time.time()
print('Vectorized loss / grad: {} / {} computed in {}s'.format(loss_vect
orized, np.linalg.norm(grad_vectorized, 'fro'), toc - tic))

# The losses should match but your vectorized implementation should be m
uch faster.
print('difference in loss / grad: {} /{} '.format(loss - loss_vectorize
d, np.linalg.norm(grad - grad_vectorized)))

# You should notice a speedup with the same output.
```

```
Normal loss / grad_norm: 2.3365011463447702 / 342.32056865654664 computed
in 0.10150647163391113s
Vectorized loss / grad: 2.3365011463447725 / 342.32056865654664 computed
in 0.02950000762939453s
difference in loss / grad: -2.220446049250313e-15 /3.758474133615425e-13
```

Stochastic gradient descent

We now implement stochastic gradient descent. This uses the same principles of gradient descent we discussed in class, however, it calculates the gradient by only using examples from a subset of the training set (so each gradient calculation is faster).

Question:

How should the softmax gradient descent training step differ from the svm training step, if at all?

Answer:

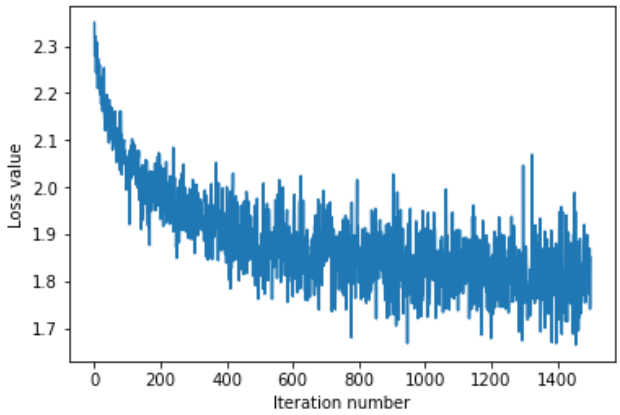
The only difference is the loss and gradient calculation.

In [10]:
```
# Implement softmax.train() by filling in the code to extract a batch of
data
# and perform the gradient step.
import time


tic = time.time()
loss_hist = softmax.train(X_train, y_train, learning_rate=1e-7,
                          num_iters=1500, verbose=True)
toc = time.time()
print('That took {}s'.format(toc - tic))

plt.plot(loss_hist)
plt.xlabel('Iteration number')
plt.ylabel('Loss value')
plt.show()
```

```
iteration 0 / 1500: loss 2.349798657251204
iteration 100 / 1500: loss 2.015830811582698
iteration 200 / 1500: loss 1.9321500072895117
iteration 300 / 1500: loss 1.9957457355380566
iteration 400 / 1500: loss 2.0006236556576704
iteration 500 / 1500: loss 1.8564504580161476
iteration 600 / 1500: loss 1.7678840661488393
iteration 700 / 1500: loss 1.896439357817373
iteration 800 / 1500: loss 1.8209576593256567
iteration 900 / 1500: loss 1.8298248793945795
iteration 1000 / 1500: loss 1.8257647092319849
iteration 1100 / 1500: loss 1.857539082214287
iteration 1200 / 1500: loss 1.8158592538807803
iteration 1300 / 1500: loss 1.8200186008174413
iteration 1400 / 1500: loss 1.7800642179886326
That took 341.6465744972229s
```



Evaluate the performance of the trained softmax classifier on the validation data.

In [11]:
```
## Implement softmax.predict() and use it to compute the training and te
sting error.

y_train_pred = softmax.predict(X_train)
print('training accuracy: {}'.format(np.mean(np.equal(y_train,y_train_pr
ed), )))
y_val_pred = softmax.predict(X_val)
print('validation accuracy: {}'.format(np.mean(np.equal(y_val, y_val_pre
d)), ))
```

```
training accuracy: 0.38224489795918365
validation accuracy: 0.403
```

Optimize the softmax classifier

You may copy and paste your optimization code from the SVM here.

In [12]:
```
np.finfo(float).eps
```

Out[12]:
```
2.220446049250313e-16
```

In [13]:
```
from sklearn.model_selection import train_test_split
# ================================================================ #
# YOUR CODE HERE:
#   Train the SVM with different learning rates and evaluate on the
#     validation data.
#   Report:
#     - The best learning rate of the ones you tested.
#     - The best VALIDATION accuracy corresponding to the best VALIDATIO
N error.
#
#   Select the SVM that achieved the best validation error and report
#     its error rate on the test set.
#   Note: You do not need to modify SVM class for this section
# ================================================================ #
learning_rate = [1e-5,3.3e-5,1e-4,3.3e-4,1e-3,3.3e-3,1e-2]
val_acc = []
for i in range(len(learning_rate)):
    X_val_train ,X_val_test, y_val_train, y_val_test = train_test_split
(X_val,y_val,test_size=0.2,\
                                                    random_state=int(np.
random.randint(0,2**32-1,size=1)))
    num_classes = len(np.unique(y_val_train))
    num_features = X_val_train.shape[1]

    softmax = Softmax(dims=[num_classes, num_features])
    softmax.train(X_val_train, y_val_train, learning_rate[i], 1500, 200,
False)
    val_acc.append(np.mean(np.equal(y_val_test, softmax.predict(X_val_te
st))))

val_max = max(val_acc)
index_max = val_acc.index(val_max)
print('The best validation accuracy is ', val_max, ', while the learning
rate is ', learning_rate[index_max])
# ================================================================ #
# END YOUR CODE HERE
# ================================================================ #
```

```
/home/dennis/Documents/PY_PROGRAM/UCLA_C247/HW2-code/HW2-code/nndl/softma
x.py:139: RuntimeWarning: divide by zero encountered in log
  loss = -np.sum(np.log(np.true_divide(np.exp(np.sum(X * self.W[y],axis=
1) - np.max(np.dot(X,self.W.T),axis=1)),np.sum(np.exp(np.dot(X,self.W.T)
- np.max(np.dot(X,self.W.T),axis=1).reshape(num_train,1)),axis=1))))

The best validation accuracy is  0.335 , while the learning rate is  1e-0
5
```

```python
import numpy as np
from sklearn.model_selection import train_test_split
class Softmax(object):

  def __init__(self, dims=[10, 3073]):
    self.init_weights(dims=dims)

  def init_weights(self, dims):
    """
        Initializes the weight matrix of the Softmax classifier.
        Note that it has shape (C, D) where C is the number of
        classes and D is the feature size.
        """
    self.W = np.random.normal(size=dims) * 0.0001

  def loss(self, X, y):
    """
    Calculates the softmax loss.

    Inputs have dimension D, there are C classes, and we operate on minibatches
    of N examples.

    Inputs:
    - X: A numpy array of shape (N, D) containing a minibatch of data.
    - y: A numpy array of shape (N,) containing training labels; y[i] = c means
      that X[i] has label c, where 0 <= c < C.

    Returns a tuple of:
    - loss as single float
    """

    # Initialize the loss to zero.
    loss = 0.0

    # ============================================================= #
    # YOUR CODE HERE:
        #   Calculate the normalized softmax loss.  Store it as the variable loss.
    #   (That is, calculate the sum of the losses of all the training
    #   set margins, and then normalize the loss by the number of
        #       training examples.)
    # ============================================================= #
    num_train = X.shape[0]
    for i in range(num_train):
      score = np.dot(X[i],self.W.T)
      score = score - np.max(score)
      loss = loss - score[y[i]]

      sm = 0
      for s in score:
        sm = sm + np.exp(s)
      loss = loss + np.log(sm)
    loss = loss / num_train

    # ============================================================= #
    # END YOUR CODE HERE
    # ============================================================= #

    return loss

  def loss_and_grad(self, X, y):
    """
        Same as self.loss(X, y), except that it also returns the gradient.

        Output: grad -- a matrix of the same dimensions as W containing
                the gradient of the loss with respect to W.
        """
```

```
    # Initialize the loss and gradient to zero.
    loss = 0.0
    grad = np.zeros_like(self.W)

    num_train = X.shape[0]
    num_class = self.W.shape[0]
    for i in range(num_train):
      score = np.dot(X[i],self.W.T)
      score = score - np.max(score)
      loss = loss - score[y[i]]

      sm = 0
      for s in score:
        sm = sm + np.exp(s)
      loss = loss + np.log(sm)
      for j in range(num_class):
        sftmx = np.exp(score[j]) / np.sum(np.exp(score))
        if j == y[i]:
          grad[j,:] = grad[j,:] + (sftmx - 1) * X[i]
        else:
          grad[j,:] = grad[j,:] + sftmx * X[i]
    loss = loss / num_train
    grad = grad / num_train
    # ============================================================= #
    # YOUR CODE HERE:
        #   Calculate the softmax loss and the gradient. Store the gradient
        #   as the variable grad.
    # ============================================================= #


    # ============================================================= #
    # END YOUR CODE HERE
    # ============================================================= #

    return loss, grad

  def grad_check_sparse(self, X, y, your_grad, num_checks=10, h=1e-5):
    """
    sample a few random elements and only return numerical
    in these dimensions.
    """

    for i in np.arange(num_checks):
      ix = tuple([np.random.randint(m) for m in self.W.shape])

      oldval = self.W[ix]
      self.W[ix] = oldval + h # increment by h
      fxph = self.loss(X, y)
      self.W[ix] = oldval - h # decrement by h
      fxmh = self.loss(X,y) # evaluate f(x - h)
      self.W[ix] = oldval # reset

      grad_numerical = (fxph - fxmh) / (2 * h)
      grad_analytic = your_grad[ix]
      rel_error = abs(grad_numerical - grad_analytic) / (abs(grad_numerical) + abs
(grad_analytic))
      print('numerical: %f analytic: %f, relative error: %e' % (grad_numerical,
grad_analytic, rel_error))

  def fast_loss_and_grad(self, X, y):
    """
    A vectorized implementation of loss_and_grad. It shares the same
        inputs and ouptuts as loss_and_grad.
    """
    loss = 0.0
```

```
    grad = np.zeros(self.W.shape) # initialize the gradient as zero
    num_train = X.shape[0]
    num_class = self.W.shape[0]
    # ============================================================= #
    # YOUR CODE HERE:
        #   Calculate the softmax loss and gradient WITHOUT any for loops.
    # ============================================================= #

    loss = -np.sum(np.log(np.true_divide(np.exp(np.sum(X * self.W[y],axis=1) -
np.max(np.dot(X,self.W.T),axis=1)),np.sum(np.exp(np.dot(X,self.W.T) - np.max(np.dot
(X,self.W.T),axis=1).reshape(num_train,1)),axis=1))))
    #loss = np.sum([np.log(np.sum([np.exp(np.dot(X[i],self.W.T) - np.max(np.dot(X
[i],self.W.T)))])) - np.dot(X[i],self.W[y[i]].T) + np.max(np.dot(X[i],self.W.T))
for i in range(num_train)])
    loss = loss / num_train
    y_belong = np.argwhere(y == 0).T.tolist() + np.argwhere(y == 1).T.tolist() +
np.argwhere(y == 2).T.tolist() + np.argwhere(y == 3).T.tolist() + np.argwhere(y ==
4).T.tolist() + np.argwhere(y == 5).T.tolist() + np.argwhere(y == 6).T.tolist() +
np.argwhere(y == 7).T.tolist() + np.argwhere(y == 8).T.tolist() + np.argwhere(y ==
9).T.tolist()
    grad = np.dot(np.true_divide(np.exp(np.dot(X,self.W.T) - np.max(np.dot
(X,self.W.T),axis=1).reshape(num_train,1)),np.sum(np.exp(np.dot(X,self.W.T) -
np.max(np.dot(X,self.W.T),axis=1).reshape(num_train,1)),axis=1).reshape
(num_train,1)).T,X) - [np.sum(X[y_belong[i]],axis=0) for i in range(num_class)]
    #grad = [sum([(np.exp(np.dot(X[i],self.W.T)[j] - np.max(np.dot(X
[i],self.W.T))) / np.sum(np.exp(np.dot(X[i],self.W.T) - np.max(np.dot(X
[i],self.W.T)))) - (0 if j != y[i] else 1)) * X[i] for i in range(num_train)]) for
j in range(num_class)]
    grad = np.asarray(grad) / num_train

    # ============================================================= #
    # END YOUR CODE HERE
    # ============================================================= #

    return loss, grad

  def train(self, X, y, learning_rate=1e-3, num_iters=100,
            batch_size=200, verbose=False):
    """
    Train this linear classifier using stochastic gradient descent.

    Inputs:
    - X: A numpy array of shape (N, D) containing training data; there are N
      training samples each of dimension D.
    - y: A numpy array of shape (N,) containing training labels; y[i] = c
      means that X[i] has label 0 <= c < C for C classes.
    - learning_rate: (float) learning rate for optimization.
    - num_iters: (integer) number of steps to take when optimizing
    - batch_size: (integer) number of training examples to use at each step.
    - verbose: (boolean) If true, print progress during optimization.

    Outputs:
    A list containing the value of the loss function at each training iteration.
    """
    num_train, dim = X.shape
    num_classes = np.max(y) + 1 # assume y takes values 0...K-1 where K is number
of classes

    self.init_weights(dims=[np.max(y) + 1, X.shape[1]]) # initializes the weights
of self.W

    # Run stochastic gradient descent to optimize W
    loss_history = []

    for it in np.arange(num_iters):
      X_batch = None
```

```
      y_batch = None

      # ================================================================ #
      # YOUR CODE HERE:
      #   Sample batch_size elements from the training data for use in
      #   gradient descent.  After sampling,
      #     - X_batch should have shape: (dim, batch_size)
          #     - y_batch should have shape: (batch_size,)
          #   The indices should be randomly generated to reduce correlations
          #   in the dataset.  Use np.random.choice.  It's okay to sample with
          #   replacement.
      # ================================================================ #
      _, X_batch,_, y_batch = train_test_split(X,y,test_size=batch_size/num_train,
random_state=int(np.random.randint(0,2**32-1,size=1)))
      # ================================================================ #
      # END YOUR CODE HERE
      # ================================================================ #

      # evaluate loss and gradient
      loss, grad = self.fast_loss_and_grad(X_batch, y_batch)
      loss_history.append(loss)

      # ================================================================ #
      # YOUR CODE HERE:
      #   Update the parameters, self.W, with a gradient step
      # ================================================================ #
      self.W = self.W - learning_rate * grad

          # ================================================================ #
      # END YOUR CODE HERE
      # ================================================================ #

      if verbose and it % 100 == 0:
        print('iteration {} / {}: loss {}'.format(it, num_iters, loss))

    return loss_history

  def predict(self, X):
    """
    Inputs:
    - X: N x D array of training data. Each row is a D-dimensional point.

    Returns:
    - y_pred: Predicted labels for the data in X. y_pred is a 1-dimensional
      array of length N, and each element is an integer giving the predicted
      class.
    """
    y_pred = np.zeros(X.shape[1])
    # ================================================================ #
    # YOUR CODE HERE:
    #   Predict the labels given the training data.
    # ================================================================ #
    y_pred = np.argmax(np.dot(X,self.W.T),axis=1)
    # ================================================================ #
    # END YOUR CODE HERE
    # ================================================================ #

    return y_pred
```