4	CE
	$\mathbf{c}\mathbf{o}$

Register No.:	

## **April 2019**

<u>Time - Three hours</u> (Maximum Marks: 75)

- [N.B: (1) Q.No. 8 in PART A and Q.No. 16 in PART B are compulsory.

  Answer any FJUR questions from the remaining in each PART A and PART B
  - (2) Answer division (a) or division (b) of each question in PART C.
  - (3) Each question carries 2 marks in PART A, 3 marks in Part B and 10 marks in PART C. J

## PART - A

- 1. What are the types of CAD system?
- 2. What is meant by scaling?
- 3. What are the functions of CAM?
- 4. What is meant by coding structure?
- 5. List out the methods of NC part programming.
- 6. List out the benefits of CIM.
- Define AGV.
- 8. Write the need of CE.

## PART - B

- 9. Write about the two types of geometric modelling.
- 10. Write short notes on JIT.
- 11. What are the advantages of CAPP?
- 12. Describe the coordinate system.
- 13. List out the benefits of FMS.
- 14. What are the types of robot sensors?
- Define DFMA and list out it's benefits.
- 16. List out M codes.

## PART - C

17. (a) Explain Shigley's design process.

(Or

- (b) Explain the various types of solid modelling.
- 18. (a) Describe optiz system and MICLASS system.

(Or)

- (b) Explain the variant and generative type CAPP.
- 19. (a) Explain the concept of mirroring using sub program.

(Or)

- (b) Explain about the canned cycle programming using in peck drilling.
- 20. (a) Explain in detail about the working principle of AGV.

(Or)

- (b) Explain about the robot configuration.
- 21. (a) Discuss in detail about sequential engineering Vs concurrent engineering.

(Or)

(b) Explain in detail about the FMEA process.

185/22-2