Gaussian linear models are often insufficient in practical applications, where noise can be heavy-tailed. In this problem, we consider a linear model of the form  $y_i = a \cdot x_i + b + e_i$ . The  $(e_i)$  are independent noise from a distribution that depends on x as well as on global parameters; however, the noise distribution has conditional mean zero given x. The goal is to derive a good estimator for the parameters a and b based on a sample of observed (x, y) pairs.

## 1.1 Instructions:

- 1. Load the data, which is provided as (x, y) pairs in CSV format. Each file contains a data set generated with different values of a and b. The noise distribution, conditional on x, is the same for all data sets.
- 2. Formulate a model for the data-generating process.
- 3. Based on your model, formulate a loss function for all parameters: *a*, *b*, and any additional parameters needed for your model.
- 4. Solve a suitable optimization problem, corresponding to your chosen loss function, to obtain point estimates for the model parameters.
- 5. Formulate and carry out an assessment of the quality of your parameter estimates.
- 6. Try additional models if necessary, repeating steps 2-5.

## 1.2 Deliverables:

- 1. A CSV file containing your point estimates of the linear model parameters a and b for each of the input files. The output CSV file will have three columns: input file name, a, and b corresponding to your solution for that data set.
- A brief report on your approach. Discuss modeling assumptions you made as well as any hand-picked numerical constants. Please submit the report in pdf format; include any necessary figures and equations.
- 3. Your code for deriving and assessing the estimates. We will evaluate your code for correctness, conciseness, and readability (comments and documentation). We prefer R or Python, but feel free to use any high-level programming language you are comfortable with. You are allowed to use any publicly available software packages.