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PyExaFMM, an exercise in designing high-performance software with Python and Numba

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Abstract—Numba is a game changing compiler for high performance computing with Python. The machine code it produces runs outside of the single-threaded Python interpreter, and can therefore fully utilize the resources of modern CPUs. This means support for parallel multithreading and auto vectorization if available, just like in a compiled language such as C++ or Fortran. Here we document our attempt to use Numba to develop a fully multithreaded implementation of the Fast Multipole Method, an algorithm which relies on a non-linear data structure and contains a significant amount of data organization that would ordinarily be run through the Python interpreter. We explain how Numba influences the design and structure of software, as well as its major pitfalls when designing implementations of complex algorithms. We find that Numba doesn't live up to its promise due to overhead from the unavoidable interaction between the Python interpreter and Numba compiled code, and that our software remains an order of magnitude slower than ExaFMM-T, the leading C++ implementation of the same algorithm.

PYTHON 1 , is designed for memory safety

¹We use 'Python' to refer to CPython, the popular C language implementation of Python, which is dominant in computational science.

and developer productivity, not speed. Its main selling point being that it allows Computational Scientists to spend more time exploring the science, and less time being confused by strange software quirks, infuriating memory errors, and the nightmare of incompatible dependencies, all of which conspire to drain productivity when working with lower level languages.

The catch is that code is run through an interpreter and restricted to run on a single thread via a software construction called the Global Interpreter Lock [GIL]. However, libraries for high performance computational science have traditionally bypassed the issue of the GIL by using Python's C interface to call extensions built in C or other compiled languages which can be multithreaded or compiled to target special hardware features. Popular examples of this approach include Numpy and SciPy, which together have helped propel Python's popularity in computational science by providing high performance data structures for numerical data as well as interfaces for fast compiled implementations of algorithms for numerical linear algebra, and mathematical solvers for problems from differential equations to statistics and machine learning.

As the actual number-crunching itself happens outside of the interpreter, the GIL only becomes a bottleneck to performance if a program must repeatedly pass control between the interpreter and non-Python code. This is most often an issue when an optimized compiled language implementation of your desired algorithm doesn't exist in the Python Open Source, or if it requires a lot of data organization to form the input for an optimized Numpy or SciPy code, which must unavoidably take place within the interpreter. Previously, an unlucky developer would have been forced to write a compiled implementation to tackle these issues themselves and connect it to their Python package, relegating Python's role to an interface. More problematically, not all Computational Scientists have the necessary software skills or research interest in developing and maintaining complex codebases that couple multiple languages.

This is the context in which Numba was introduced [1]. It is a compiler that specifically targets and optimizes Python code written with Numpy's ndarray data structure. Its power comes from the

ability to generate multithreaded architecture optimized compiled code while only writing Python. The promise of Numba is the ability to develop applications with speed that can rival C++ or Fortran, while retaining the simplicity and productivity of working in Python. We put this promise to the test by developing PyExaFMM², an implementation of the Kernel-Independent Particle Fast Multipole Method [FMM] [2], [3], in three dimensions. Efficient implementations of this algorithm are complicated by a recursively defined tree data structure and a series of operations which each require significant data organization and careful memory allocation. These features made PyExaFMM an excellent test case to see whether Numba could free us as Computational Scientists from the complexities of compiled languages.

We begin with an overview of Numba's design and its major pitfalls when. After introducing the data structures and computations involved in the FMM, we provide an overview of how we implemented our software's data structures, algorithms and application programming interface [API] to optimally use Numba. We conclude benchmarks demonstrating the impact of Numba on vanilla Python implementations of the FMM's operators, the cost of passing between the Python interpreter and Numba compiled code, and performance in terms of memory and runtime in comparison to ExaFMM-T [4], the leading C++ implementation of the same algorithm.

NUMBA

Numba³ is a compiler for Python, and was initially developed to optimize a subset of the language that manipulates the *n*-dimensional array, or 'ndarray', data structure from Numpy. Unlike a Python list, where elements can be of any type and are linked by a chain of pointers, ndarrays are homogeneously typed and stored contiguously in memory. This means that adjacent elements are stored in adjacent memory locations. When loading data from a given memory location, modern CPUs cache data located at adjacent locations, therefore algorithms which iterate sequentially over arrays benefit from lower memory loading

²https://github.com/exafmm/pyexafmm

³We use the latest stable release of Numba, 0.53.1 throughout this study.

latencies as the CPU's cache is likely to contain the next element being operated on. This is known as *locality of reference*. This is in contrast to Python lists, where subsequent elements need not be stored in adjacent memory locations and are found by following trails of pointers, this phenomena is known as *indirection*, which doesn't take advantage of CPU caching behavior at all. As ndarrays have fields for data dimensionality, type, and layout, Numba can use this to generate machine code without any indirection. instead it can directly reference the memory locations being referred to by the Python code at runtime. This allows Numba to index into ndarrays with performance that can match compiled languages.

Numba is built with LLVM [5], a frame-work for building custom compilers, that provides an API to generate machine code for different hardware architectures such as CPUs and GPUs. LLVM is also able to analyze the code it's compiling for hardware level optimizations, such as auto vectorization, and apply them automatically if they are available on the target hardware.

From a programmer perspective, using Numba naively doesn't involve a significant rewrite of code. Functions in the Python source code are marked for compilation with a special decorator (see listings (1) (2) and (3) for example syntax). if a marked function is called at runtime from the Python interpreter, program execution is handed to Numba's runtime, which then compiles the function on the fly with a type signature matching the types of the input arguments. This is the origin of the term 'just in time' [JIT] to describe such compilers.

Figure (1) illustrates the program execution path when a Numba decorated function is called from the Python interpreter. We see that Numba doesn't replace the Python interpreter. Instead, a special Numba runtime program interacts with the Python interpreter dynamically and the control of program execution is passed back and forth between Numba and Python. There is an inherent cost to this interaction which from having to 'unbox' Python objects into types compatible with the compiled machine code, and 'box' the outputs of the compiled functions back into Python compatible objects. This process doesn't involve reallocating memory, however pointers to memory locations have to be converted and placed in a

Listing 1. An example of using Numba in a Python function operating on ndarrays.

```
import numba
import numpy as np
# optionally the decorator can take
# the option nopython=True, which
# disallows Numba from running in
# object mode
@numba.jit
def loop_fusion(a):
   An example of loop fusion, an
    optimization that Numba is able
    to perform on a user's behalf.
    When it recognizes that they are
    operating similarly on a single
    data structure
    for i in range (10):
        a[i] += 1
    for i in range (10):
        a[i] *= 5
    return a
```

type compatible with either Numba's compiled code or Python. The cost of this can be seen in Table ([REFERENCE TO BOX BENCHMARK TABLE]), where we illustrate the cost of boxing and unboxing functions of with increasing numbers of array arguments. Table ([REFERENCE BOX BENCHMARK FOR DIFFERENT TYPES]) illustrates the cost of boxing different Python types into Numba compatible types. Software written with Numba has to account for this cost, and minimize the interactions between the Python interpreter and Numba compiled code.

PITFALLS OF NUMBA

Since it was first released, Numba has been extended to compile most functionality from the Numpy library seamlessly, as well as a wide variety of well loved Python language data structures, functions and standard library modules ⁴. However, If Numba isn't able to find a suitable Numba type for each Python type in a decorated function, or it sees a Python feature it doesn't yet support, it runs in 'object' mode, and handles all values as generic Python objects using Python's underlying C implementation to handle operations on these objects. Crucially Numba does

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⁴A full list of supported features for the current release can be found at: https://numba.pydata.org/numba-doc/dev/reference/pysupported.html

this without reporting it to the user, with object mode often no faster than ordinary vanilla Python code. This puts the burden on the programmer to understand when and where Numba might work. Furthermore, to achieve performance, a programmer must be careful to limit the surface of interaction between Python code and Numba code. Therefore, in practice Numba behaves like a framework rather than just a compiler, as it influences the way in which you write Python.

Additionally, though a large number of Python features are supported, not everything is supported in a way a Python programmer would expect which can have impacts on program design. An example this situation arises when using Python dictionaries, which are partially supported by Numba. As they are untyped, and can have any Python objects as members, they don't neatly fit into a Numba compatible type. Programmers can declare a Numba compatible 'typed dictionary', where the keys and values are constrained to Numba compatible types, and pass it to a Numba decorated function at low cost. However, using a Numba dictionary from the Python interpreter is always slower than an ordinary Python dictionary due to the (un)boxing cost when getting and setting any item. A natural use case for a dictionary is as a place to store results during an algorithm. To avoid the (un)boxing cost in algorithms that involve multiple steps that operate on shared data, programmers are forced write a nested functions as in listing (2) that are called as minimally as possible. These nested functions have the tendency to grow long in highly-performant Numba code, in order to keep the interaction surface between Numba and Python small. Therefore when pursuing performance with Numba, code can end up looking quite un-Pythonic, with few user created objects, performance critical sections written in terms of loops over simple array based data structures reminiscent of C, and many long nested functions which are uncommonly used in standard Python and are more difficult to unit test.

Though Numba is advertised as an easy way of injecting performance into your program via a simple decorator, achieving performance in practice may require a programmer to be familiar with the internals of its implementation (fig. 1), and potentially have to radically change the design of their algorithms and data structures to avoid

Listing 2. An example of using typed dictionaries in

```
import numpy as np
import numba
import numba.core
import numba.typed
# Dictionary instance created at runtime
results = numba.typed.Dict.empty(
    key_type=numba.core.types.unicode_type,
    value_type=numba.core.types.float64[:]
@numba.niit
def nested(arg, results):
    # This function expects a
    # typed dictionary as an
    # argument to store results
    def step1(a):
        # first step of algorithm
        # store results in dictionary
    def step2(a):
        # second step of algorithm
        # store results in dictionary
    # Interpreter doesn't know about
    # the changes in the dictionary
    # until Numba runtime hands back
    # control
    return results
```

back and forth between the Numba runtime and the Python interpreter. A significant proportion of Numba's intended target audience who are not software specialists may find it easier to stick with their C or Fortran implementations where performance is generally guaranteed regardless of implementation details.

THE FAST MULTIPOLE METHOD

The particle FMM is an approximation algorithm for N-body problems in which N source particles interact with N target particles [3]. Without loss of generality we can consider the sources and targets to correspond to the same set of particles. An example of this is the calculation of electrostatic potentials from a set of charged particles, and we use this as our reference problem to test our software. Consider a three-dimensional domain, with a set of N charged particles at positions x_i . The potential, ϕ_j , at a given target particle at x_j due to all other particles, excluding self interaction, can be written

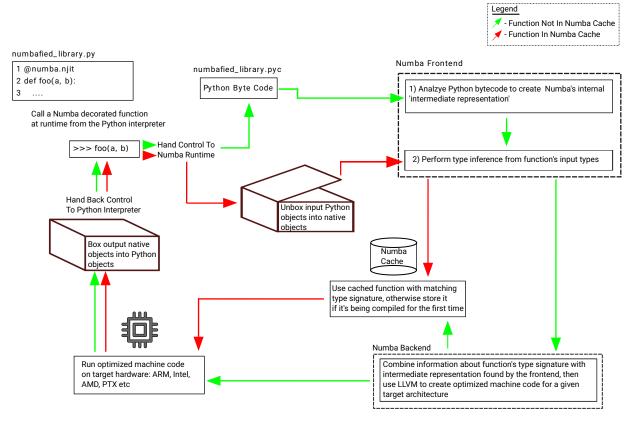


Figure 1. Simplified execution path when calling a Numba compiled function from the Python interpreter. The green path is only taken if the function hasn't been called before. The red path is taken if a compiled version with the correct type signature already exists in the Numba cache.

as.

$$\phi_j = \sum_{i=1, i \neq j}^{N} \frac{q_i}{4\pi |x_i - x_j|} \tag{1}$$

where $\frac{1}{4\pi|x_i-x_j|}$ is called the kernel, or the Green's function, and q_i is the charge at x_i . The naive computation over all particles is $O(N^2)$, however the FMM compresses groups of interactions far away from a given particle using expansions to reduce the overall complexity to just O(N) with a well described error bound for a chosen level of discretization. Expansions are ways of describing the charge contained within subregions of the octree, and can be truncated with a given accuracy, described by a parameter called the expansion order, p. The value of p is equal to the number of digits of precision of the final solution. Problems with this structure appear frequently in science and engineering and are made tractable using the FMM, as a result it's

been described as one of the ten most important algorithms of the twentieth century [6].

The algorithm relies on a hierarchical octree data structure to discretize the problem domain in three dimensions (see fig. 1 [7]) and consists of eight operators: P2M, P2L, M2M, M2L, L2L, L2P, M2P and the 'near field', applied once to each applicable node over the course of two consecutive traversals of the octree (bottom-up and then top-down). An operator is read as 'X to Y', where 'P' stands for particle(s), 'M' for multipole expansion and 'L' for local expansion. The direct calculation of (1) is referred to as the P2P operator, and is used as a subroutine during the calculation of the other operators. The Kernel Independent FMM [KIFMM] [2], implemented by PyExaFMM and ExaFMM-T, is a re-formulation of the FMM with a structure that favours parallelization. Indeed all of the operators can be decomposed into matrix-vector products, or multithreaded implementations of (1), which

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fit well with Numba's programming framework.

The computational complexities of operators in the KIFMM are defined by n_{crit} , which is the maximum allowed number of particles in a leaf node, n_e and n_c which are the numbers of quadrature points on the *check* and *equivalent* surfaces respectively, and are quadratically related to the desired expansion order, i.e. $p \sim n_c^2$ (see sec. 3 [2]). Typical values used for n_{crit} are ~ 100 , The depth of the octree is defined n_{crit} and hence defined by the distribution of particles. We defer to the FMM literature for a more detailed discussion on the mathematical significance of these operators [2], [3].

The inputs to the M2L, M2P and P2L, operators are defined by 'interaction lists' [2], called the V, W and X lists respectively. These interaction lists define the nodes with which a given target node, to which the operator is being applied, interacts with. We can restrict the size of these interaction lists by demanding that neighboring nodes are at most twice as large as each other. Using this 'balance condition', the V, X and W lists contains at most 189, 19 and 148 nodes in three dimensions, respectively. The near field operator uses the P2P operator for calculating interactions directly with particles in nodes neighboring a given target node, where taking expansions no longer works. The neighbors are defined by the U list, which contains 60 nodes at most in three dimensions.

COMPUTATIONAL STRUCTURE OF FMM OPERATORS

Here we review the computational structure of each operator, to see where it's possible to insert parallelism into an KIFMM implementation.

The inputs to the P2P operator are vectors for the source and target positions, and the source charges, with the expected output being a vector of potentials. It's an embarrassingly parallel problem over each target particle, and can be used as a measure of raw performance of the Numba compiled code.

The near field, L2P, M2P, P2L and P2M operators act over all leaf nodes independently, and all rely on the P2P operator with different inputs. The M2L operator acts independently on all nodes at a given level during the top-down traversal, for nodes between level two and the

leaf level of the octree.

The near field operator applied to a target node applies the P2P operator between the charges contained within the target, and the source particles for nodes in its U list. This results in $O(60 \cdot n_{crit}^2)$ calculations. The M2P operator applied to a target node, applies the P2P operator between multipole expansion coefficients of source nodes in the target's W list the charges the target contains. Similarly, the L2P operator applied to a target node, applies the P2P operator between it's own local expansion coefficients and the charges it contains. This results in $O(148 \cdot n_e \cdot n_{crit})$ and $O(n_e \cdot n_{crit})$ calculations respectively.

The P2L, P2M and M2L involve creating local and multipole expansions, and rely on a matrix vector product related to the number of source nodes being compressed, which for the P2L and M2L are defined by the size of the target node's interaction lists. These matrix vector products have complexities of the form $O(k \cdot n_e^2)$ where k = |X| = 19 for the P2L operator, k = |V| = 189 for the M2L operator, and k = 1 for the P2M operator. Additionally, the P2L and P2M operators have to calculate 'check potentials' (see sec. 3 [2]) which require $O(19 \cdot n_{crit} \cdot n_c)$ and $O(n_{crit} \cdot n_c)$ calculations respectively.

The M2M operator is applied to each node during the bottom-up traversal, and the L2L operator is applied to each node during the top-down traversal. They both involve translating expansions between nodes their eight children, and rely on a matrix vector product of $O(n_e^2)$.

The FMM's operators expose natural parallelism. The M2L, M2P, P2L and near field operators operate independently over their interaction lists. Furthermore, the near field, L2P, M2P, P2L and P2M operators also operate independently over all the leaf nodes, and the M2L operates independently over the nodes at a given level. Finally, The M2M and L2L operators operate independently over sibling nodes. We note that some parallelizations incur a cost in the form of writing to shared memory locations, an operator parallelized over its interaction list will write to a shared vector for the target node's expansions or potentials. This also applies to the M2M and L2L operators, when parallelized over sibling nodes.

Listing 3. An example of parallel multithreading.

```
import numba
import numpy as np
@numba.njit(cache=True, parallel=True)
def multithreading(a):
    for i in numba.prange(10):
        a[i] *= 10
```

MULTITHREADING IN NUMBA

Numba is interoperable with OpenMP and Intel's TBB, listing (3) shows the syntax synonymous using OpenMP's parallel range function from within Numba.

- Thread oversubscription issues and their origin and how to avoid this in Numba. Comment on the quality of this solution the py multithreading papers from intel group have good information and experiments regarding this.
- how kernels are multithreaded bearing in mind issues raise in Numba section, and data oriented design section.
- Optimal design of multithreading approach relies on the actual constraints of the kernel in question, will need to get into specifics here of how each kernel was approached.
- metric for portion of code that is run on single vs multiple threads, can actually time this at least roughly.

M2M - serial. cannot parallelize over leaves, there are parallel writes to parent multipole expansion from siblings. Parallelizing over sibling leaves is hard due to linear representation of tree - have to perform expensive neighbours searches to find siblings to perform group by. equivalent charge = $O(8^l \cdot n_e \cdot n_c)$ at a given level l.

DATA ORIENTED DESIGN

- what is data oriented design? Why is it necessary? Why does Numba demand this?
- we implement it in two ways: (1) the simplicity of our containers, few abstractions (2) Our thin API in Python.
 - long nested operator functions
- multipole and local expansions of whole tree stored as long 1D arrays
 - API designed
- Minimize the impact of running code in the interpreter.
 - Software design diagram

DIFFERENCES WITH EXAFMM-T

- tree design is linear.
- things this makes hard neighbor searches.
- things it makes easy easy interoperability with numba A strict like-for-like comparison between the two implementations isn't possible. The softwares take different approaches to the implementation of some of their operations and data structures. However, as the differences in the design of PyExaFMM are heavily influenced by Numba and Python, it remains useful as an illustration of what can be achieved with Python in comparison to a compiled language to solve the same problem.
- Main differences are tree design, and the replacement of FFT with rSVD.
- A short note on the decision for M2l via SVD, and the expected impact on performance condense discussion from MSc thesis section 2.4 pg 28

BENCHMARKS

- contrast multithreading impact for each kernel
 - boxing cost for each kernel
- compare and contrast pyexafmm vs exafmm for a given accuracy, try and find optimum compression parameter.(?)

CONCLUSION

In this paper we've shown how to use Numba to create a performant application for an algorithm with a complex data structure. We've shown how Numba can constrain software design, and that developers must be careful in designing methods and data structures in order to experience a performance benefit. Furthermore, performance debugging for more complex applications may require more knowledge than non-software specialists can be expected to have. Numba can be seen to have its own learning curve for achieving performance. Numba is a remarkable tool despite this, with a great deal of functionality. It allows one to develop fast, heterogenous, cross-platform numerical applications, using only Python, and offers good performance while retaining the benefits of working in Python.

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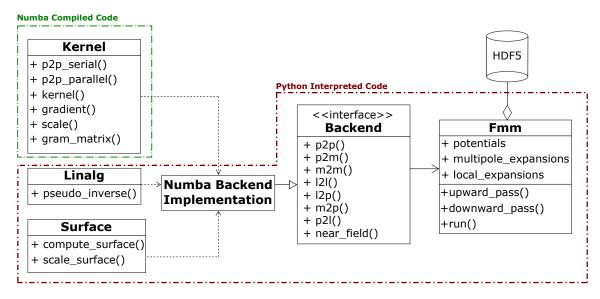


Figure 2. Simplified UML model of all PyExaFMM components. Trees and operators are precomputed and stored in the HDF5 database. The 'Fmm' object which acts as the user interface, all other components are modules consisting of methods on operating on arrays.

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