

(a) a binary image (threshold at 128)

- description:
若 pixel 的數值小於 128，則數值改為 255；其餘則為 0
- algorithm:
拜訪每個 pixel，若 pixel 的數值小於 128，則數值改為 255；其餘則為 0
- principal code fragment:

```
h, w, _ = img.shape
for c in range(w):
    for r in range(h):
        if img[r, c, 0] < 128:
            img[r, c, 0] = 0
            img[r, c, 1] = 0
            img[r, c, 2] = 0
        else:
            img[r, c, 0] = 255
            img[r, c, 1] = 255
            img[r, c, 2] = 255

cv2.imwrite(result_binary_p, img)
```

- result:



(b) a histogram

- description:
劃出 0-255 的分布圖

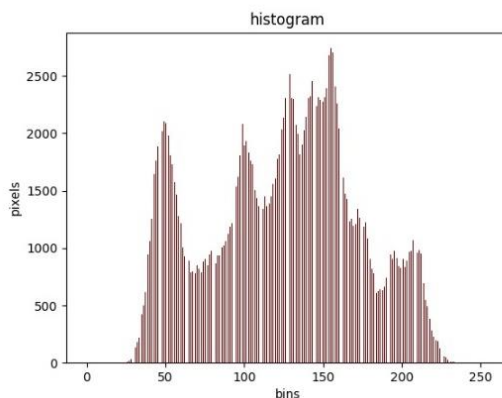
- algorithm:
拜訪每個 pixel，計算 0-255 各自的 pixel 數量並劃出 bar graph
- principal code fragment:

```
for c in range(w):
    for r in range(h):
        histogram[int(img[r, c, 0])] += 1

plt.bar(index, histogram, color = 'maroon', width = 0.4)

plt.xlabel("bins")
plt.ylabel("pixels")
plt.title("histogram")
plt.savefig(result_p)
```

- result:



(c) connected components(regions with + at centroid, bounding box)

- description:
利用 4-connected 來找出對應 component，並劃出面積 ≥ 500 的 bounding box 和 centroid
- algorithm:
 1. 先將影像轉成 binary image
 2. 拜訪每個 pixel，確認該 pixel 上面和左邊 pixel 所屬的 label，若上面和左邊的 label 大於 0，將該 pixel 標示為最小的 label，較大 label 的 component 將其 label 改成較小 label（因為這兩個 component 被連接在一起）。若上面左邊其中一個 label 是 0，則該 pixel 標記成非 0 的 label。若上面左邊皆為 0，則設該 pixel 為新的 label
 3. 拜訪所有紀錄的 components，將該 component 的每個 pixel 的 row 集合取最大最小值為 y_{\max} , y_{\min} ，將該 component 的每個 pixel 的 column 集合取最大最小值為 x_{\max} , x_{\min} ，即可算出 bounding box 的對稱角(x_{\max} , y_{\max})，(x_{\min} , y_{\min})。將該 component 的每個 pixel 的 row 相加取平均為 y ，每個 pixel 的 column 相加取平均為 x ，(x , y)即為重心

- principal code fragment:

```

39 # 4 connected
40 for r in range(h):
41     for c in range(w):
42         if img[r, c, 0] == 255:
43             if c > 0 and r > 0:
44                 if map[r-1, c] * map[r, c-1] > 0:
45                     if map[r-1, c] < map[r, c-1]:
46                         map[r, c] = map[r-1, c]
47                         component_item[map[r, c]].append(r*w+c)
48                         component_item[map[r, c]].extend(component_item[map[r, c-1]])
49                         tmp = map[r, c-1]
50                         change_index(map, component_item[map[r, c-1]], map[r, c])
51                         del component_item[tmp]
52

```

```

53         elif map[r-1, c] > map[r, c-1]:
54             map[r, c] = map[r, c-1]
55             component_item[map[r, c]].append(r*w+c)
56             component_item[map[r, c]].extend(component_item[map[r-1, c]])
57             tmp = map[r-1, c]
58             change_index(map, component_item[map[r-1, c]], map[r, c])
59             del component_item[tmp]
60
61         else:
62             map[r, c] = map[r, c-1]
63             component_item[map[r, c]].append(r*w+c)
64
65         elif map[r-1, c] > 0 or map[r, c-1] > 0:
66             map[r, c] = max(map[r-1, c], map[r, c-1])
67             component_item[map[r, c]].append(r*w+c)
68
69         else:
70             map[r, c] = i
71             component_item[map[r, c]] = [r*w+c]
72             i += 1
73

```

```

74         elif c > 0 and r == 0:
75             if map[r, c-1] > 0:
76                 map[r, c] = map[r, c-1]
77                 component_item[map[r, c]].append(r*w+c)
78
79             else:
80                 map[r, c] = i
81                 component_item[map[r, c]] = [r*w+c]
82                 i += 1
83
84         elif r > 0 and c == 0:
85             if map[r-1, c] > 0:
86                 map[r, c] = map[r-1, c]
87                 component_item[map[r, c]].append(r*w+c)
88
89             else:
90                 map[r, c] = i
91                 component_item[map[r, c]] = [r*w+c]
92                 i += 1
93
94         else:
95             map[r, c] = i
96             component_item[map[r, c]] = [r*w+c]
97             i += 1

```

```

98 # calculate boundingbox and centroid
99 thr_area = 500
100 for key, value in component_item.items():
101
102     if len(value) >= thr_area:
103         # calculate centroid
104         y = np.array(value) // w
105         y = int(np.mean(y))
106         x = np.array(value) % w
107         x = int(np.mean(x))
108
109         # draw a circle
110         cv2.circle(img, (x, y), 5, (0, 0, 255), -1)
111
112         # calculate boundingbox
113         y_max = np.max(np.array(value) // w)
114         y_min = np.min(np.array(value) // w)
115         x_max = np.max(np.array(value) % w)
116         x_min = np.min(np.array(value) % w)
117
118         # draw rectangle
119         cv2.rectangle(img, (x_min, y_min), (x_max, y_max), (255, 0, 0), 3, cv2.LINE_AA)
120
121 cv2.imwrite(result_p, img)

```

• result:

