Midterm 02 - STAT440

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set.seed(42)

Problem 1 Nelder-Mead

Part a

There are two steps here we need to justify. First there is an equality, then there is an approximation. The equality is simply an expansion of the Kenel Density Estimate function $\hat{f}_{\sigma}(x)$. Since $\frac{1}{n}$ is a constant and we can sum integrals we pull those two terms out of the integral to get that middle function.

The approximation is done via our Monte Carlo integration. The integral we have in the summation is actually in the form of an expectation $\int g(x)f(x)dx$. In our case the $g(x)=k_{\sigma}(x,X_i)$ and the f(x) is our true density. Since we have samples $\{X_i\}_{i=1}^n$ from the true density f(x) we can therefore use these samples in our Monte Carlo integration.

In case I did not explain enough the actual integral estimation term is the $\frac{1}{n-1}\Sigma_{j\neq i}k_{\sigma}(X_j,X_i)$, which is merely the expected value of our KED function by summing up the sample points and dividing by the sample size, which is follows the expected value equation. The beginning part of the term $(\frac{1}{n}\Sigma_{i=1}^n)$ comes from the first step mentioned above expanding $\hat{f}_{\sigma}(x)$.

Part b

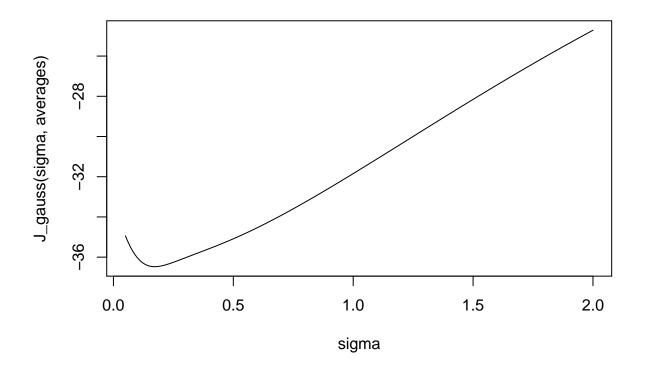
```
# gaussian kernel
k_gauss <- function(x, x_prime, sigma=1) {</pre>
    dnorm(x, mean=x_prime, sd=sigma)
# error function J
J_gauss <- function(sigma, X) {</pre>
    n <- length(X)
    first_term <- 0
    for (i in 1:n) {
        for (j in 1:n) {
            first_term <- first_term + k_gauss(X[i], X[j], sqrt(2)*sigma)
    first_term <- first_term * (1 / n^2)
    second_term <- 0
    for (i in 1:n) {
        inner <- 0
        for (j in 1:n) {
            if (j != i) {
                 second_term <- second_term + k_gauss(X[j], X[i], sigma)</pre>
```

```
}
    second_term <- second_term + (1 / (n - 1)) * inner
}
second_term <- second_term * (2 / n)
    return(first_term - second_term)
}

# load dataset
scores <- data.matrix(read.csv('./data/score.csv'))
averages <- rowMeans(scores) / 10
averages[0:10]

## [1] 9.04 9.00 8.86 7.92 7.82 7.80 7.62 7.62 7.54 7.30

sigma <- seq(0.05, 2, 0.01)
plot(sigma, J_gauss(sigma, averages), type="l")</pre>
```



Part c

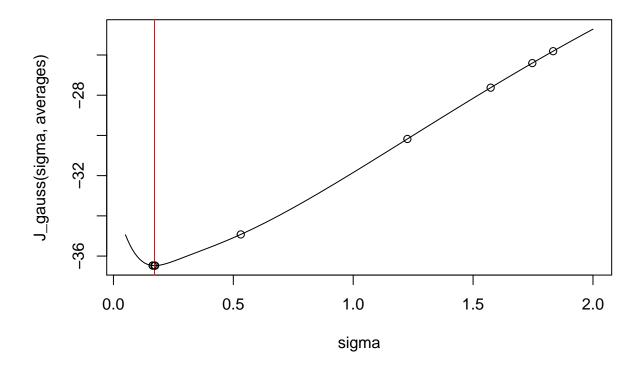
The error curve above is a convex function along this curve. You can draw a line between any two points on this interval that will always be above the line. A minimiziation algorithm should find the minimum here, since there are no local extrema to draw the algorithm away from the global minimum.

Part d

```
my_loss <- function(sigma) {</pre>
    J_gauss(sigma, averages)
nm_gauss_kde <- function(par=c(0.05, 2), fn = my_loss, return_points=FALSE) {
    # parameters
    alpha <- 1
    gamma <- 2
    rho <- 0.5
    sigma <- 0.5
    # termination criteria
    max term <- 100
    sd_threshold <- 0.001
    dim <- 2
    points <- runif(dim, min=par[1], max=par[2])</pre>
    point_mat <- NA
    iter <- 1
    while(sd(points) >= sd_threshold & iter <= max_term) {</pre>
        # Order points
        points <- points[order(fn(points))]</pre>
        if (return_points) {
            if (iter == 1) {
                 point_mat <- matrix(points, nrow=1, ncol=dim)</pre>
                 point_mat <- rbind(point_mat, matrix(points, nrow=1, ncol=dim))</pre>
        }
        # Compute centroid - this is merely the first point (2 points only)
        centroid <- points[1:dim-1] / (dim-1)</pre>
        # Reflect about centroid
        reflected_point <- centroid + alpha * (centroid - points[dim])</pre>
        if (reflected_point < 0) {</pre>
             reflected_point <- -1 * reflected_point</pre>
        val_r <- fn(reflected_point)</pre>
        # don't need to check reflected
        \# criteria; if better than x_n but not better than x_1; isn't possible
        \# since x_1 = x_n here
        # Expand step
        if (val_r < fn(points[1])) {</pre>
             expanded <- centroid + gamma * (reflected_point - centroid)</pre>
             if (expanded < 0) {</pre>
                 expanded <- -1*expanded
```

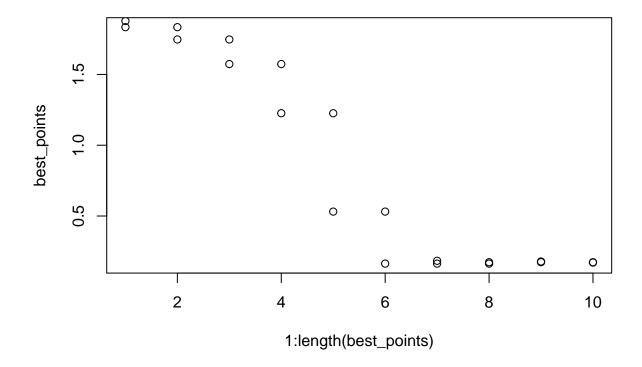
```
if (fn(expanded) < val_r) {</pre>
                  points[dim] <- expanded</pre>
             } else {
                  points[dim] <- reflected_point</pre>
             }
        } else {
             contracted <- centroid + rho * (reflected_point - centroid)</pre>
             if (contracted < 0) {</pre>
                  contracted <- -1*contracted</pre>
             if (fn(contracted) < fn(points[dim])) {</pre>
                  # contract
                  points[dim] <- contracted</pre>
             } else {
                  # shrink
                  points <- points[1] + sigma * (points - points[1])</pre>
        }
         # next iteration
         iter <- iter + 1
    if (return_points) {
        return(point_mat)
    return(points[1])
}
```

```
points <- nm_gauss_kde(return_points = TRUE)
best_points <- points[,1]
plot(sigma, J_gauss(sigma, averages), type="l")
abline(v=points[length(best_points),1], col="red")
points(best_points, J_gauss(best_points, averages))</pre>
```



Part e

```
plot(1:length(best_points), best_points)
points(1:length(best_points), points[,2])
```



In the first portion, from steps 1 through about 5, the step is almost always a reflect and expand. During thi part the algorithm is walking down the large slope to the right of the minimum. After this the reflect and contract happens, so we do not go past 0.05, and then the algorithm pretty much converged through shrinking or some step that is too small to distinguish on this graph.

Problem 2 Permutation Test

```
weather <- read.csv('./data/Szeged_Weather_Summary.csv')</pre>
weather[1:5,]
     Year Month Temperature ApparentTemp
                                           Humidity WindSpeed WindBearing
##
## 1 2006
              1 -1.67428315
                                -4.170818 0.8346505 8.902067
                                                                   160.7769
## 2 2006
              2 -0.06128472
                                -2.986136 0.8433929 10.958278
                                                                   197.8914
## 3 2006
                 4.53346792
                                 1.940272 0.7786541 14.416716
                                                                   195.0619
## 4 2006
              4 12.62587191
                                12.083819 0.7295278 10.926802
                                                                   192.1569
## 5 2006
              5 15.66531511
                                15.555600 0.7209677 10.201839
                                                                   208.9583
##
     Visibility
                 Pressure
## 1
       7.900988 1021.1935
##
       7.421214
                 995.2108
  3
       9.577225
##
                 976.3727
      10.626760 1013.4965
      11.748066 1016.6247
## 5
```

Part a

Null Hypothesis:

$$H_0: \rho = 0$$

Alternative Hypothesis:

$$H_A: \rho \neq 0$$

We can use the following test statistic:

$$T = |r - \rho_0| = |r|$$

This test statistic we are using here translates to the absolute value of the sample correlation coefficient between Temperature and Humidity. Our null hypothesis states that ρ_0 is zero, which is why we only need |r|. Our extreme set would be test statistics that are greater than our observed test statistic T_{obs} where $T_{obs} = |r_{obs}|$. Explicitly our extreme set is $T \geq T_{obs}$. We can calculate our P value by calculating the proportion of test statistics that fall within our extreme set.

Part b

```
K <- 10000

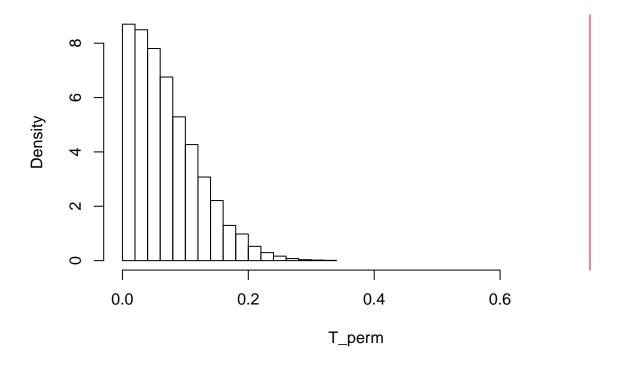
T_obs <- abs(cor(weather$Temperature, weather$Humid))

T_perm <- vector('numeric', K)

temp_df <- weather
for (i in 1:K) {
    temp_df$Humid <- sample(weather$Humid)
    T_perm[i] <- abs(cor(temp_df$Temperature, temp_df$Humid))
}

x_end <- max(c(T_obs, max(T_perm)))
hist(T_perm, freq=FALSE, xlim = c(0,x_end))
abline(v=T_obs, col='red')</pre>
```

Histogram of T_perm



print(mean(T_perm >= T_obs))

[1] 0

We would reject the null hypothesis here with a p-value of zero in our permutation test.

Problem 3 Cross-Validation

Problem 4 Bootstrap and Regression

Problem 5 Extra Points

Part a

Part b

 $\mathbf{Part}\ \mathbf{c}$