

Midterm 02 - STAT440

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```
set.seed(42)
```

Problem 1 Nelder-Mead

Part a

There are two steps here we need to justify. First there is an equality, then there is an approximation. The equality is simply an expansion of the Kernel Density Estimate function $\hat{f}_\sigma(x)$. Since $\frac{1}{n}$ is a constant and we can sum integrals we pull those two terms out of the integral to get that middle function.

The approximation is done via our Monte Carlo integration. The integral we have in the summation is actually in the form of an expectation $\int g(x)f(x)dx$. In our case the $g(x) = k_\sigma(x, X_i)$ and the $f(x)$ is our true density. Since we have samples $\{X_i\}_{i=1}^n$ from the true density $f(x)$ we can therefore use these samples in our Monte Carlo integration.

In case I did not explain enough the actual integral estimation term is the $\frac{1}{n-1} \sum_{j \neq i} k_\sigma(X_j, X_i)$, which is merely the expected value of our KED function by summing up the sample points and dividing by the sample size, which follows the expected value equation. The beginning part of the term ($\frac{1}{n} \sum_{i=1}^n$) comes from the first step mentioned above expanding $\hat{f}_\sigma(x)$.

Part b

```
# gaussian kernel
k_gauss <- function(x, x_prime, sigma=1) {
  dnorm(x, mean=x_prime, sd=sigma)
}

# error function J
J_gauss <- function(sigma, X) {
  n <- length(X)
  first_term <- 0
  for (i in 1:n) {
    for (j in 1:n) {
      first_term <- first_term + k_gauss(X[i], X[j], sqrt(2)*sigma)
    }
  }
  first_term <- first_term * (1 / n^2)
  second_term <- 0
  for (i in 1:n) {
    inner <- 0
    for (j in 1:n) {
      if (j != i) {
        second_term <- second_term + k_gauss(X[j], X[i], sigma)
      }
    }
  }
}
```

```

    }
    second_term <- second_term + (1 / (n - 1)) * inner
  }
  second_term <- second_term * (2 / n)
  return(first_term - second_term)
}

```

```

# load dataset
scores <- data.matrix(read.csv('./data/score.csv'))
averages <- rowMeans(scores) / 10
averages[0:10]

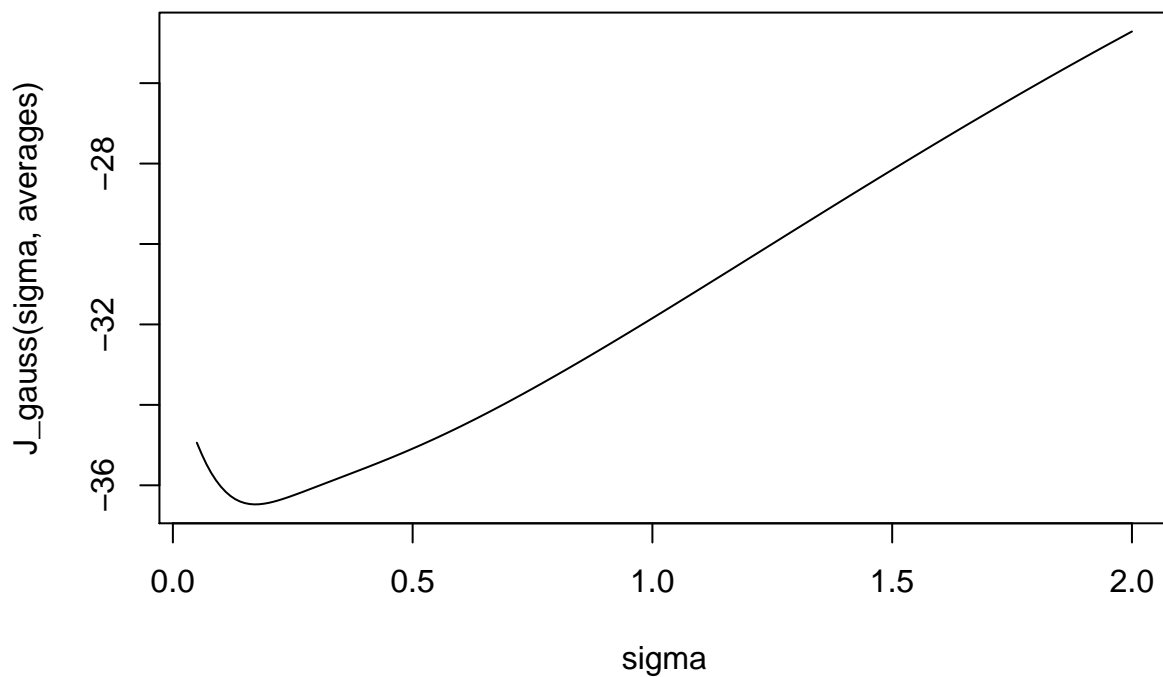
```

```
## [1] 9.04 9.00 8.86 7.92 7.82 7.80 7.62 7.62 7.54 7.30
```

```

sigma <- seq(0.05, 2, 0.01)
plot(sigma, J_gauss(sigma, averages), type="l")

```



Part c

The error curve above is a convex function along this curve. You can draw a line between any two points on this interval that will always be above the line. A minimization algorithm should find the minimum here, since there are no local extrema to draw the algorithm away from the global minimum.

Part d

```
my_loss <- function(sigma) {
  J_gauss(sigma, averages)
}

nm_gauss_kde <- function(par=c(0.05, 2), fn = my_loss, return_points=FALSE) {
  # parameters
  alpha <- 1
  gamma <- 2
  rho <- 0.5
  sigma <- 0.5

  # termination criteria
  max_term <- 100
  sd_threshold <- 0.001

  dim <- 2
  points <- runif(dim, min=par[1], max=par[2])

  point_mat <- NA

  iter <- 1
  while(sd(points) >= sd_threshold & iter <= max_term) {
    # Order points
    points <- points[order(fn(points))]
    if (return_points) {
      if (iter == 1) {
        point_mat <- matrix(points, nrow=1, ncol=dim)
      } else {
        point_mat <- rbind(point_mat, matrix(points, nrow=1, ncol=dim))
      }
    }

    # Compute centroid - this is merely the first point (2 points only)
    centroid <- points[1:dim-1] / (dim-1)

    # Reflect about centroid
    reflected_point <- centroid + alpha * (centroid - points[dim])
    if (reflected_point < 0) {
      reflected_point <- -1 * reflected_point
    }
    val_r <- fn(reflected_point)
    # don't need to check reflected
    # criteria; if better than x_n but not better than x_1; isn't possible
    # since x_1 = x_n here

    # Expand step
    if (val_r < fn(points[1])) {
      expanded <- centroid + gamma * (reflected_point - centroid)
      if (expanded < 0) {
        expanded <- -1*expanded
      }
    }
  }
}
```

```

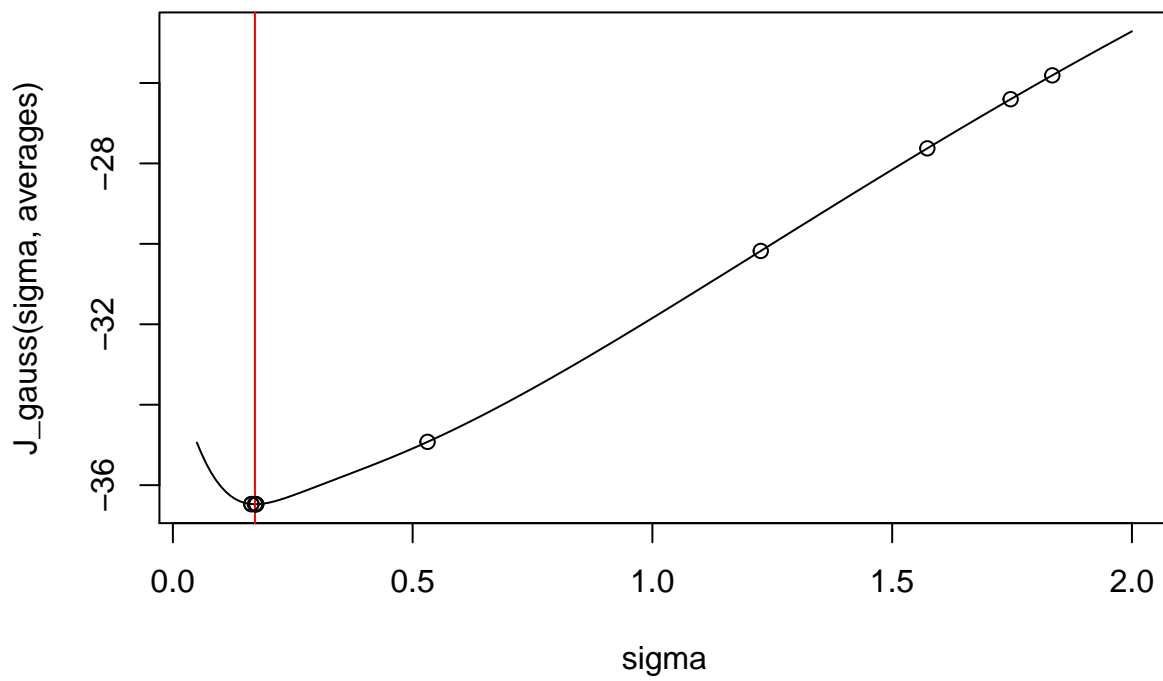
    if (fn(expanded) < val_r) {
      points[dim] <- expanded
    } else {
      points[dim] <- reflected_point
    }
  } else {
    contracted <- centroid + rho * (reflected_point - centroid)
    if (contracted < 0) {
      contracted <- -1*contracted
    }
    if (fn(contracted) < fn(points[dim])) {
      # contract
      points[dim] <- contracted
    } else {
      # shrink
      points <- points[1] + sigma * (points - points[1])
    }
  }
  # next iteration
  iter <- iter + 1
}
if (return_points) {
  return(point_mat)
}
return(points[1])
}

```

```

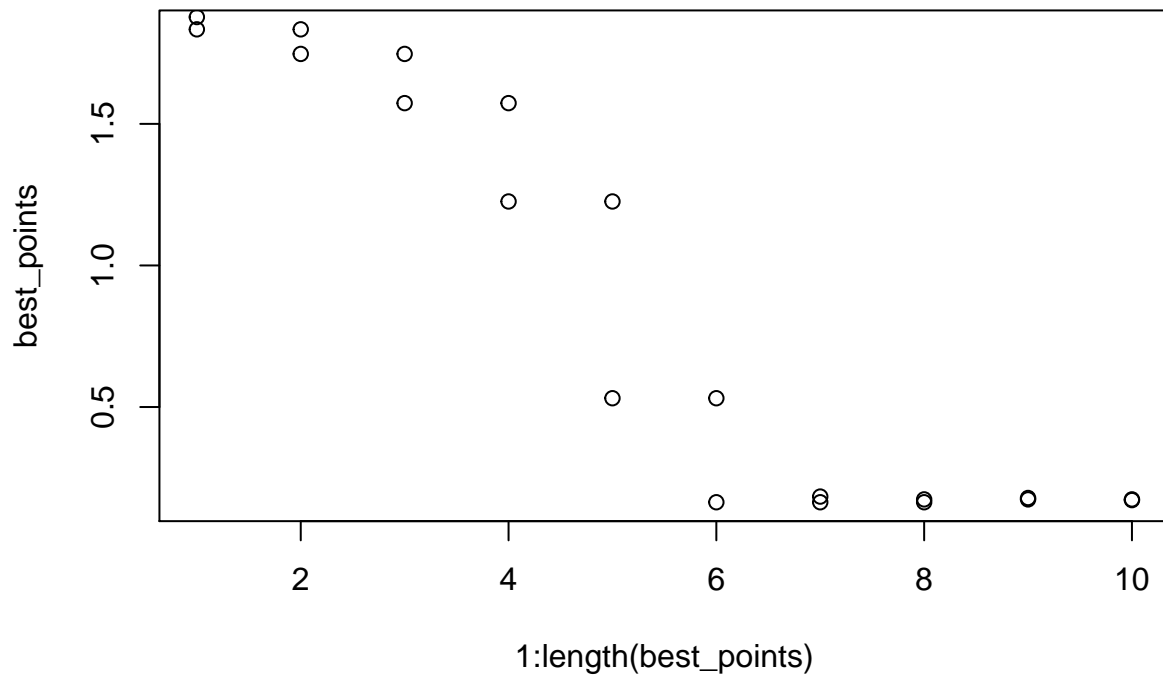
points <- nm_gauss_kde(return_points = TRUE)
best_points <- points[,1]
plot(sigma, J_gauss(sigma, averages), type="l")
abline(v=points[length(best_points),1], col="red")
points(best_points, J_gauss(best_points, averages))

```



Part e

```
plot(1:length(best_points), best_points)
points(1:length(best_points), points[,2])
```



In the first portion, from steps 1 through about 5, the step is almost always a reflect and expand. During this part the algorithm is walking down the large slope to the right of the minimum. After this the reflect and contract happens, so we do not go past 0.05, and then the algorithm pretty much converged through shrinking or some step that is too small to distinguish on this graph.

Problem 2 Permutation Test

```
weather <- read.csv('./data/Szeged_Weather_Summary.csv')
weather[1:5,]
```

```
##   Year Month Temperature ApparentTemp Humidity WindSpeed WindBearing
## 1 2006     1 -1.67428315   -4.170818 0.8346505  8.902067   160.7769
## 2 2006     2 -0.06128472   -2.986136 0.8433929 10.958278   197.8914
## 3 2006     3  4.53346792    1.940272 0.7786541 14.416716   195.0619
## 4 2006     4 12.62587191   12.083819 0.7295278 10.926802   192.1569
## 5 2006     5 15.66531511   15.555600 0.7209677 10.201839   208.9583
##   Visibility Pressure
## 1   7.900988 1021.1935
## 2   7.421214  995.2108
## 3   9.577225  976.3727
## 4  10.626760 1013.4965
## 5  11.748066 1016.6247
```

Part a

Null Hypothesis:

$$H_0 : \rho = 0$$

Alternative Hypothesis:

$$H_A : \rho \neq 0$$

We can use the following test statistic:

$$T = |r - \rho_0| = |r|$$

This test statistic we are using here translates to the absolute value of the sample correlation coefficient between Temperature and Humidity. Our null hypothesis states that ρ_0 is zero, which is why we only need $|r|$. Our extreme set would be test statistics that are greater than our observed test statistic T_{obs} where $T_{obs} = |r_{obs}|$. Explicitly our extreme set is $T \geq T_{obs}$. We can calculate our P value by calculating the proportion of test statistics that fall within our extreme set.

Part b

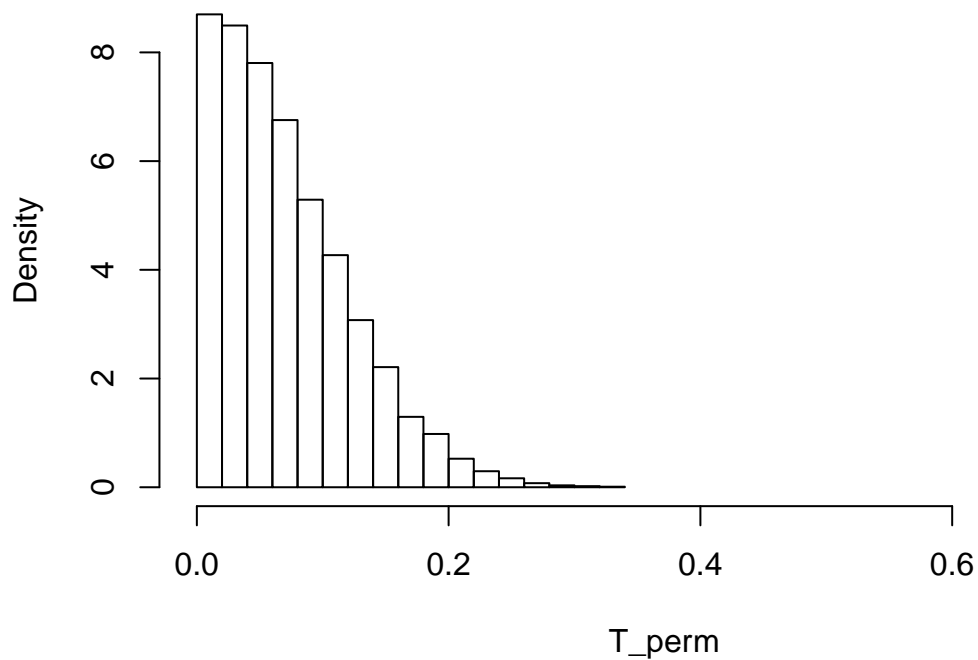
```
K <- 10000

T_obs <- abs(cor(weather$Temperature, weather$Humidity))

T_perm <- vector('numeric', K)
temp_df <- weather
for (i in 1:K) {
  temp_df$Humidity <- sample(weather$Humidity)
  T_perm[i] <- abs(cor(temp_df$Temperature, temp_df$Humidity))
}

x_end <- max(c(T_obs, max(T_perm)))
hist(T_perm, freq=FALSE, xlim = c(0,x_end))
abline(v=T_obs, col='red')
```

Histogram of T_perm



```
print(mean(T_perm >= T_obs))
```

```
## [1] 0
```

We would reject the null hypothesis here with a p-value of zero in our permutation test.

Problem 3 Cross-Validation

```
# size of data
n <- nrow(weather)
# error caches
error1 <- numeric(n)
error2 <- numeric(n)
error3 <- numeric(n)

for (i in 1:n) {
  # create models
  m1_i <- lm(Temperature~Humidity, data=weather)
  m2_i <- lm(Temperature~WindSpeed, data=weather)
  m3_i <- lm(Temperature~Humidity+WindSpeed, data=weather)

  # predicted values
```



```

y1 <- predict(m1_i, weather[i,])
y2 <- predict(m2_i, weather[i,])
y3 <- predict(m3_i, weather[i,])

# compute squared error
error1[i] <- (weather$Temperature[i] - y1)^2
error2[i] <- (weather$Temperature[i] - y2)^2
error3[i] <- (weather$Temperature[i] - y3)^2
}

print(mean(error1))

```

```
## [1] 28.85106
```

```
print(mean(error2))
```

```
## [1] 51.06846
```

```
print(mean(error3))
```

```
## [1] 20.29997
```

The linear regression model that had the minimal error through the leave-one-out cross-validation was using both Humidity and WindSpeed to predict Temperature. Since the model with just Humidity did much better than just WindSpeed we can also infer that Humidity is likely more correlated with Temperature than WindSpeed is.

Problem 4 Bootstrap and Regression

Problem 5 Extra Points

Part a

Part b

Part c