

Data Structures and Algorithms Homework 5

Due Wednesday Oct 2; Joseph Sepich (jps6444)

1 Problem 1

A back edge in a BFS algorithm would designate a cycle in a directed graph. This cycle would include the ancestor through the descendant in the tree. This means all one has to do is run a BFS algorithm, which takes $O(|V| + |E|)$ time and look for edges (v, w) that have $\text{depth}(v) > \text{depth}(w)$ (back edge). If this edge has $\text{depth}(w) - \text{depth}(v) \% 2 == 1$ then you can increment the count of number of odd-length cycles. This second part of the algorithm looking for the odd-length cycle is a single loop through the edges so the algorithm takes $O(|V| + 2|E|)$ time or $O(|V| + |E|)$ time, which is linear.

2 Problem 2

2.1 Part a

In BFS it is impossible to have a forward edge, because the algorithm searches breadth first. This means if you start at root node A, then the algorithm will look at all of A's outgoing edges and add the nodes at the other side as children of A. This means the algorithm could not find a node that has an edge with A that is not a child of A, so there cannot be any forward edges in the BFS tree. All edges from A, must a child, so it cannot fulfill the definition we gave for a forward edge: a BFS forward edge leads from a node to a nonchild descendant in the BFS tree. All edges must be a child descendant.

2.2 Part b

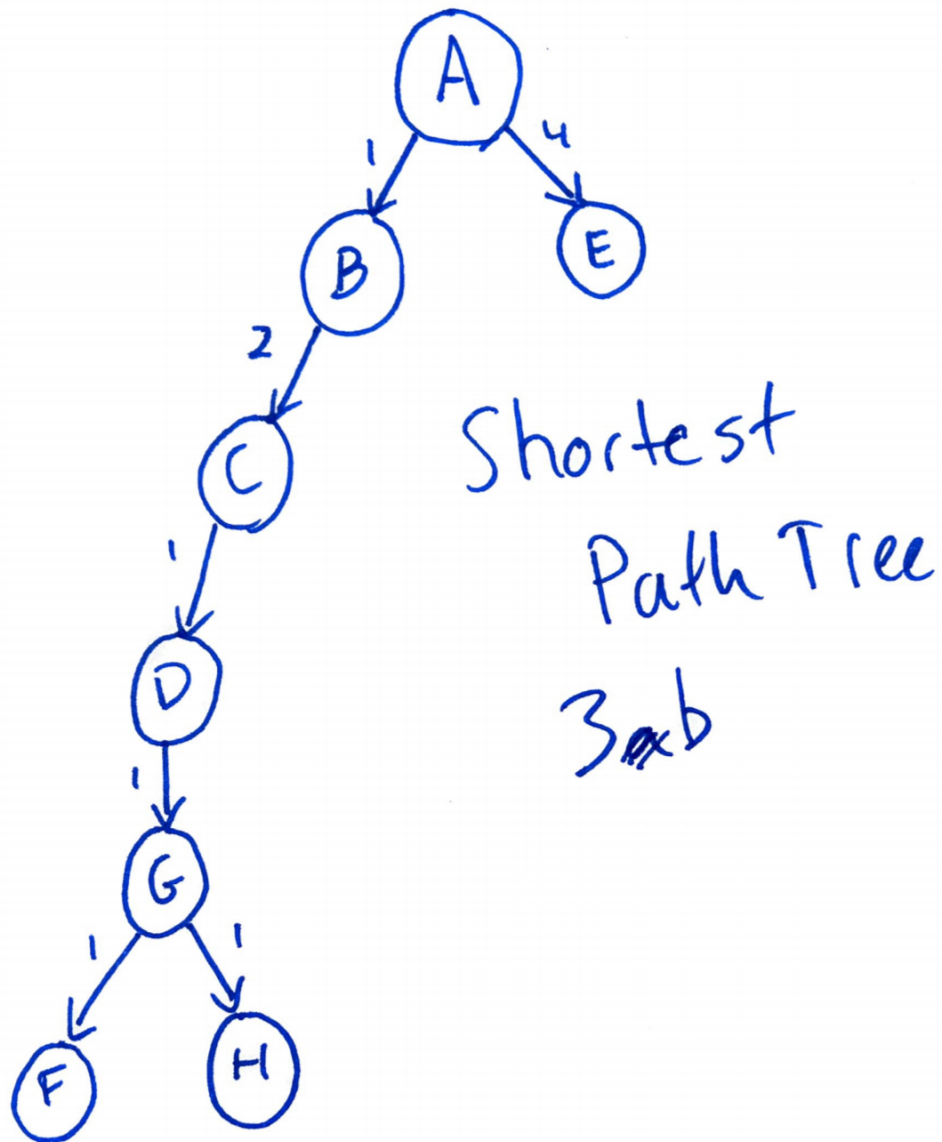
To determine edge type in the BFS tree you can run BFS and use the edges and depth values from the algorithm. If there exists an edge (v, w) and $\text{depth}(v) + 1 = \text{depth}(w)$, then (v, w) is a tree edge, which can be classified as such during the run of the BFS algorithm. Any edge (v, w) with $\text{depth}(v) = \text{depth}(w)$ or $\text{depth}(v) + 1 = \text{depth}(w)$ is a cross edge, if it was not designated a tree edge during the running of the BFS algorithm. A back edge is any of the remaining edges or when the edge (v, w) has $\text{depth}(v) > \text{depth}(w)$. Since we have a BFS portion in $O(|V| + |E|)$ and portion where we go through the edges in $O(|E|)$ we have a running time of $O(|V| + 2|E|)$ or $O(|V| + |E|)$ running time. A crucial part to differentiating between cross and tree edge is making sure to designate the tree edges while the standard BFS algorithm is running.

3 Problem 3

3.1 Part a

A	B	C	D	E	F	G	H
0*	∞	∞	∞	∞	∞	∞	∞
0	1*	∞	∞	4	8	∞	∞
0	1	3*	∞	4	7	7	∞
0	1	3	4*	4	7	5	∞
0	1	3	4	4*	7	5	8
0	1	3	4	4	7	5*	8
0	1	3	4	4	6*	5	6
0	1	3	4	4	6	5	6*

3.2 Part b



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4 Problem 4

The method suggested by Prof F. Lake surely works. We can prove this by induction. At a base case we have standard Dijkstra where all edge weights are greater than or equal to 1. We know that Dijkstra works in this case. For our inductive hypothesis let's assume the min edge weight is $1 - k < 0$ works with Dijkstra's algorithm if we add k so our min edge weight is $1 - k + k = 1$. If we then have an edge weight of $1 - (k + 1) < 0$, we would have to add $k + 1$, which still preserves the relative weights of each edge, therefore the claim that you can transform all the edge weights by a constant to make them positive so Dijkstra will work is a valid method.