Graph Convolutional Networks (GCN)

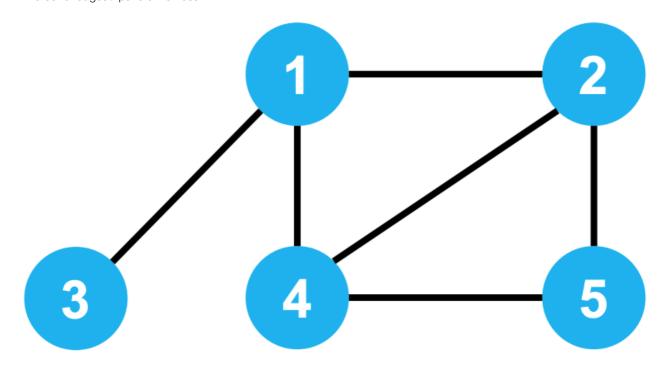
• Semi-Supervised Classification with Graph Convolutional Networks

1. Introduction to Graph

Graph Basics

A Graph is defined as G = (V, E)

- V: a finite, nonempty set of vertices
- E: a set of edges / pairs of vertices

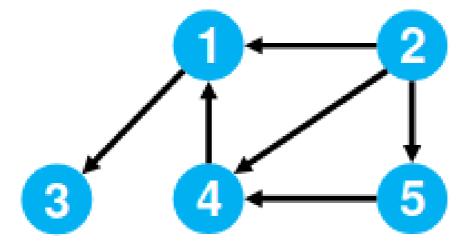


$$V = \{1,2,3,4,5\}$$

 $E = \{(1,2),(1,3),(1,4),(2,4),(2,5),(4,5)\}$

Graph type

- Undirected: edge (u,v) = edge (v,u)
- Directed: edge (u,v) goes from vertex u to vertex v; $(u, v) \neq (v, u)$
- Weighted: edges associate with weights



$$V = \{1,2,3,4,5\}$$

 $E = \{(2,1),(1,3),(4,1),(2,4),(2,5),(5,4)\}$

Terminate

Adjacent

If there is an edge (u,v), then u and v are adjacent.

• Incident

If there id an edge (u,v), the edge (u,v) is incident from u and is incident to v.

• Degree:

The degree of a vertex u is the number of edges incident on u.

- in-degree of u: edges (x,u) in a directed graph.
- out-degree of u: edges (u,x) in a directed graph.
- Degree = in-degree + out-degree
- Isolated vertex: degree = 0
- Connected:
 - Two vertices are connected if there is a path between them.
 - A connected graph has a path from every vertex to every other.

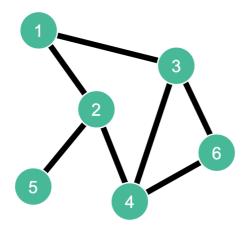
Graph Representations

How to represent a graph in computer programs?

Adjacency Matrix

Adjacency matrix = $N \times N$ matrix A with A[i][j] = 1 if (i,j) is an edge.

$$A_{ij} := \{ 1 \text{ if } (i,j) \in E \text{ 0 otherwise } \}$$



	1	2	3	4	5	6
1		1	1			
2	1			1	1	
3	1			1		1
4		1	1			1
5		1				
6			1	1		

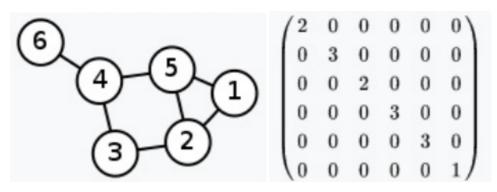
- For undirected graphs, A is symmetric, $A = A^T$
- \bullet If weighted, store weights instead of bits in A

Degree Matrix

Degree matrix is a diagonal matrix wich contains information about the degree of each vertex.

Given a graph G = (V, E) with |V| = n, the degree matrix D for G is a $N \times N$ diagonal matrix defined as:

$$D_{ij} := \{ deg(v_i) \mid \text{if } i = j \ 0 \text{ otherwise} \}$$



2. Spectral Graph Theory

In mathmatics, spectral graph theory is the study of the properties of a graph in relationship to the characteristic polynomial, eigenvalues, and eigenvectors of matrices associated with the graph, such as its adjacency matrix or Laplacian matrix.

Laplacian matrix

Given a simple graph ${\sf G}$ with n vertices, its Laplacian matrix ${\sf L}$ is defined as :

$$L = D - A$$

where D is the degree matrix and A is the adjacency matrix of the graph.

$$L_{ij} := \{ deg(v_i) \mid \text{if } i = j - 1 \mid \text{if } i \neq j \text{ and } v_i \text{is adjaceney to } v_j \text{ 0} \}$$
 otherwise

where $deg(v_i)$ is the degree of the vertex i.

Properties

- L is symmetric matrix.
- L is positive-semidefinite matrix.

Example

Labeled graph	Degree matrix				Adjacency matrix						Laplacian matrix								
<u></u>	/2	0	0	0	0	0)	/0	1	0	0	1	0)	1	2	-1	0	0	-1	0 \
	0	3	0	0	0	0	1	0	1	0	1	0	11	-1	3	-1	0	-1	0
(4)	0	0	2	0	0	0	0	1	0	1	0	0	Ш	0	-1	2	-1	0	0
4 15	0	0	0	3	0	0	0	0	1	0	1	1	Ш	0	0	-1	3	-1	-1
(2)	0	0	0	0	3	0	1	1	0	1	0	0	Η.	-1	-1	0	-1	3	0
3	10	0	0	0	0	1/	10	0	0	1	0	0/	1	0	0	0	-1	0	1/

Other Laplacian matrix

• Random walk normallized Laplacian matrix

$$L^{rw} = D^{-1}L = I - D^{-1}A$$

• Symmetric normalized Laplacian matrix

$$L^{\text{sym}} = D^{-1/2}LD^{-1/2} = I - D^{-1/2}AD^{-1/2}$$

Orthogonal diagonalization

Because L is a real-symmetric matrix, it can be diagonalized by an orthogonal matrix.

$$L = U\Lambda U^T$$

where

- U is a eigenvector of L, and is orthogonally matrix: $UU^T = I, U^{-1} = U^T$.
- Λ is a diagonal matrix that consists of the eigenvalue of L.

$$L = U \left(egin{array}{ccc} \lambda_1 & & & \ & \ddots & & \ & & \lambda_n \end{array}
ight) U^{-1}$$

$$egin{aligned} U^{-1} & L = U egin{pmatrix} \lambda_1 & & & \ & \ddots & & \ & & \lambda_n \end{pmatrix} U^T \end{aligned}$$

3. Laplace operator

The Laplace operator or Laplacian is a differential operator given by the divergence of the gradient of a function on Euclidean space.

It defined as the divergence $(\nabla \cdot)$ of the gradient (∇f) .

The Laplacian of f is defined by:

$$\Delta f = \nabla^2 f = \nabla \cdot \nabla f$$

where

$$\nabla = \left(\frac{\partial}{\partial_{x_1}}, \cdots, \frac{\partial}{\partial_{x_n}}\right)$$

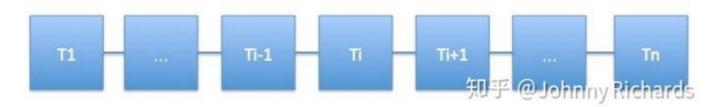
So

$$\Delta f = \sum_{i=1}^{n} \frac{\partial^2 f}{\partial x_i^2}$$

Heat conduction (or thermal conduction) is the movement of heat from one object to another one that has different temperatures when they are touching each other.

Heat flows from the hotter object to the colder one.

Heat Conduction Model on One-dimension



For node i, it's only connected with node i-1 and node i+1, and the temperatures will be changed by these two nodes (receive from node i+1, transfer to node i-1).

If the current temperature of node i is ϕ_i ,

$$\frac{d\phi_i}{dt} = k(\phi_{i+1} - \phi_i) + k(\phi_i - \phi_{i-1})$$

$$\frac{d\phi_i}{dt} - k[(\phi_{i+1} - \phi_i) - (\phi_i - \phi_{i-1})] = 0$$

$$\frac{\partial\phi}{\partial t} - k\frac{\partial^2\phi}{\partial x^2} = 0$$

$$\frac{\partial\phi}{\partial t} - k\frac{\partial^2\phi}{\partial x^2} = 0$$

$$\frac{\partial\phi}{\partial t} - k\Delta\phi = 0$$

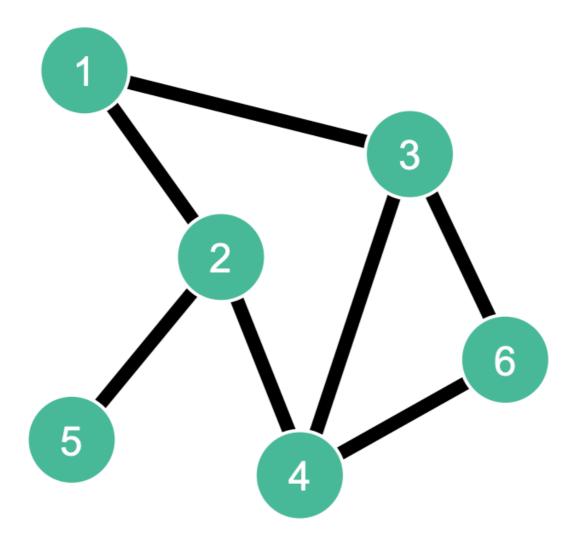
=>

- 1. 在歐式空間中,某溫度升高的速度正比於該點周圍的溫度分佈,用Laplace operator衡量
- 2. Laplace operator是二階導數對高維空間的推廣

Heat Conduction Model on Graph

現在讓我們將熱傳播模型推廣到Graph上

如下圖中所示,點1只和點2跟點3發生熱交換,點5的熱量要通過點2間接傳過來,而沒有直接熱交換。



根據一維熱傳播模型,這Graph上溫度隨時間的變化可以寫成以下:

$$\frac{d\phi_i}{dt} = -k \sum_i A_{ij} (\phi_i - \phi_j)$$

where A is adjacency matrix

=>

$$\frac{d\phi_i}{dt} = -k \sum_j A_{ij} (\phi_i - \phi_j) \qquad = -k [\phi_i \sum_j A_{ij} - \sum_j A_{ij} \phi_j] = -k [deg(i)\phi_i - \sum_j A_{ij} \phi_j]$$

=>

kA

$$\left[\phi_1 \phi_2 \cdots \phi_n\right]$$

\$\$

define $\phi = [\phi_1, \phi_2, \cdots, \phi_n]^T$, then

$$\frac{d\phi}{dt} = -kD\phi + kA\phi \qquad = -k(D-A)\phi$$

=>

$$\frac{d\phi}{dt} + kL\phi = 0$$

=>

$$L = D - A$$

推廣到GCN

假設在圖中各個節點流動的東西不是熱量,而是特徵(Feature),而是訊息(Message),那問題就自然被推廣到了GCN。 所以GCN就是在一張Graph Network中特徵(Feature)和訊息(Message)中的流動傳播。

4. Convolution and Forurier Transfornm

Convolution

The convolution of f and g is written f * g,

$$(f * g)(t) = \int_{-\infty}^{\infty} f(\tau)g(t - \tau)d\tau$$

• Fourier Transform

$$Ff(w) = \int_{-\infty}^{\infty} f(x)e^{-iwx}dx$$

• Inverse Fourier transform

$$F^{-1}f(x) = \int_{-\infty}^{\infty} f(w)e^{iwx}dx$$

推導

$$h(z) = \int_{-\infty}^{\infty} f(x)g(z - x)dx$$

$$Ff * g(z) = Fh(z) \qquad = \int_{-\infty}^{\infty} h(z)e^{-iwz}dz = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x)g(z - x)e^{-iwz}dxdz \qquad = \int_{-\infty}^{\infty} f(x)(\int_{-\infty}^{\infty} g(z - x)e^{-iwz}dz)dx$$

Let y = z - x, dy = dz

$$Ff * g = \int_{-\infty}^{\infty} f(x) \left(\int_{-\infty}^{\infty} g(y) e^{-iw(y+x)} dy \right) dx \qquad = \int_{-\infty}^{\infty} f(x) e^{-iwx} dx \int_{-\infty}^{\infty} g(y) e^{-iwy} dy = Ff \cdot Fg$$
$$f * g = F^{-1} Ff \cdot Fg$$

5. Graph Fourier

• Traditional Fourier

$$F(W) = \hat{f}(w) = \int_{-\infty}^{\infty} f(x)e^{-iwx}dx$$

• Graph Fourier

$$F(\lambda_i) = \hat{f}(\lambda_i) = \sum_{k=1}^{N} f(k)u_i^*(k)$$

$$\begin{pmatrix} \hat{f}(\lambda_1) \\ \hat{f}(\lambda_2) \\ \vdots \\ \hat{f}(\lambda_N) \end{pmatrix} = \begin{pmatrix} u_1(1) & u_1(2) & \dots & u_1(N) \\ u_2(1) & u_2(2) & \dots & u_2(N) \\ \vdots & \vdots & \ddots & \vdots \\ u_N(1) & u_N(2) & \dots & u_N(N) \end{pmatrix} \begin{pmatrix} f(1) \\ f(2) \\ \vdots \\ f(N) \end{pmatrix}$$

$$=>\hat{f}=U^Tf$$

• Traditional Inverse Fourier

$$F^{-1}[F(w)] = f(x) = \int_{-\infty}^{\infty} F(w)e^{iwx}dx$$

• Graph Inverse Fourier

$$f(i) = \sum_{k=1}^{N} \hat{f}(\lambda_i) u_k(i)$$

$$\Rightarrow f = U\hat{f}$$

6. Graph Convolution

• Traditional Convolution

$$f * h = F^{-1}Ff \cdot Fh$$

· Graph convolution

$$(f * h)_G = U((U^T f) \odot (U^T h))$$

where \odot is the element-wised product (as known as Hadamard product).

Let $\hat{h}(\lambda_i) = \sum_{k=1}^N h(k) u_i^*(k)$, then:

$$(f*h)_G = U egin{pmatrix} \hat{h}(\lambda_1) & & & & \ & \ddots & & \ & & \hat{h}(\lambda_n) \end{pmatrix} U^T f$$