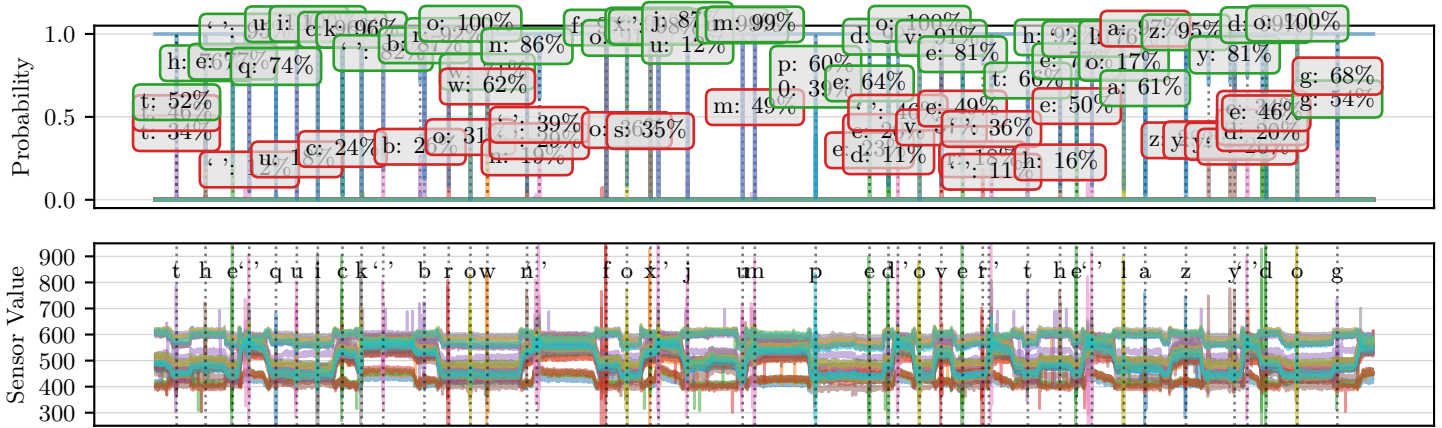
Probability
1.0
0.5
0.0
Sensor Value
900
800
700
600
500
400
300
t h e ‘’ q u i c k ‘’ b r o w n ’’ f o x ’ j u m p e d ’ o v e r ’’ t h e ‘’ l a z y ’ d o g