

Reach-Avoid Derived

Reach-Avoid

Reach

Reach-Avoid with Redemption

Parity

No Op

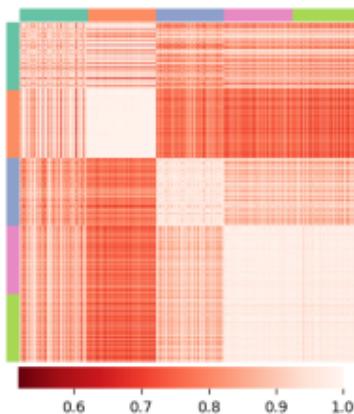
2-Conjunction Collapse

1-Step Advance

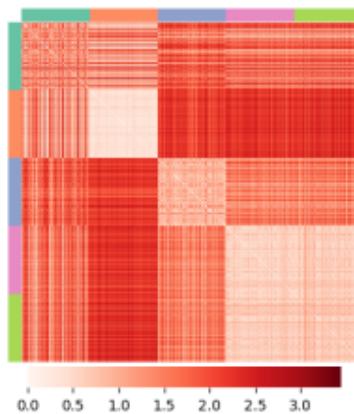
1-Step Advance Leading Accept



(a) GATv2 – 2-D t-SNE



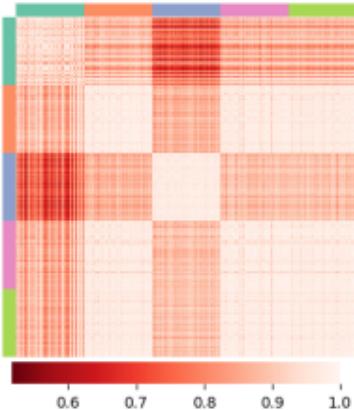
(b) GATv2 – Cosine similarity heat map



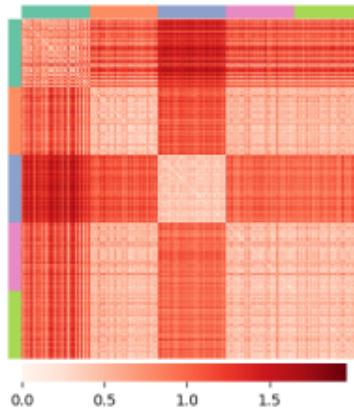
(c) GATv2 – Euclidean distance heat map



(d) RGCN – 2-D t-SNE



(e) RGCN – Cosine similarity heat map



(f) RGCN – Euclidean distance heat map