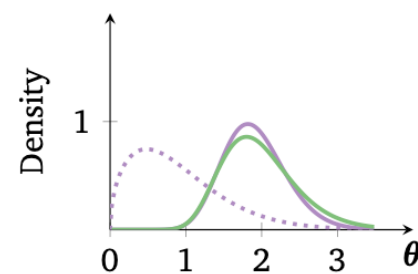


one-to-one differential transform

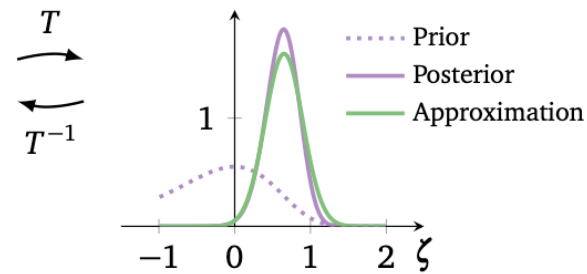
$$\zeta = T(\theta)$$

Mean-field Gaussian approximation

$$q(\zeta; \phi) = \mathcal{N}(\zeta; \mu, \text{diag}(\sigma^2)) = \prod_{k=1}^K \mathcal{N}(\zeta_k; \mu_k, \sigma_k^2)$$



(a) Latent variable space



(b) Real coordinate space

$$\phi^* = \arg \min_{\phi \in \Phi} \text{KL}(q(\theta; \phi) \| p(\theta | \mathbf{x}))$$

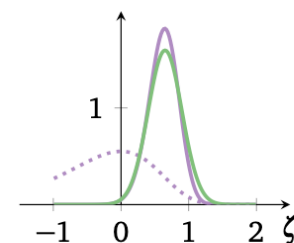
Minimize the KL divergence: maximize the ELBO

$$\phi^* = \arg \max_{\phi \in \Phi} \mathcal{L}(\phi) \quad \text{such that} \quad \text{supp}(q(\theta; \phi)) \subseteq \text{supp}(p(\theta | \mathbf{x}))$$

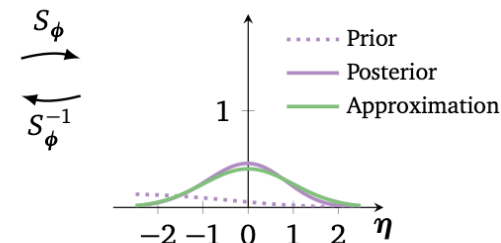
ELBO $\mathcal{L}(\phi) = \mathbb{E}_{q(\theta)} [\log p(\mathbf{x}, \theta)] - \mathbb{E}_{q(\theta)} [\log q(\theta; \phi)]$

$$\mathcal{L}(\phi) = \mathbb{E}_{q(\zeta; \phi)} \left[\log p(\mathbf{x}, T^{-1}(\zeta)) + \log |\det J_{T^{-1}}(\zeta)| \right] + \mathbb{H}[q(\zeta; \phi)]$$

Reparameterization



(a) Real coordinate space



(b) Standardized space

$$\phi^* = \arg \max_{\phi} \mathbb{E}_{\mathcal{N}(\eta; 0, I)} \left[\log p(\mathbf{x}, T^{-1}(S_{\phi}^{-1}(\eta))) + \log |\det J_{T^{-1}}(S_{\phi}^{-1}(\eta))| \right] + \mathbb{H}[q(\zeta; \phi)]$$

step size

$$\rho_k^{(i)} = \eta \times i^{-1/2+\epsilon} \times \left(\tau + \sqrt{s_k^{(i)}} \right)^{-1}$$

adapts to the curvature of the ELBO

$$s_k^{(i)} = \alpha g_k^{2(i)} + (1 - \alpha) s_k^{(i-1)}$$