```
//write LPC1768 c to blionk LED CONNECTED TO p1.19PIN
//FOREVER
#include <LPC17xx.h>
#define LED1 (0x01 << 19)
int main()
{
int i;
//CONFIGURE p1.19 PIN AS OUTPUT PIN
LPC_GPIO1->FIODIR |= LED1;
 //
while(1){
  LPC_GPIO1->FIOSET=LED1; //turn on LED
  for(i=0;i<100000;i++){}
  LPC GPIO1->FIOCLR=LED1; //turn off LED
 for(i=0;i<100000;i++){}
}
}
#include <LPC17xx.h>
#define LED1 (0x01 << 19) // Define LED1 connected to P1.19
#define ALL_LED (0xFF << 19) // Define all LEDs connected from P1.19 to P1.26
void delay_ms(uint32_t millis);
int main(void)
  // Configure P1.19 - P1.26 as output pins
  LPC_GPIO1->FIODIR |= ALL_LED; // Set P1.19 to P1.26 as outputs
  LPC_GPIO1->FIOCLR = ALL_LED; // Turn off all LEDs initially
```

```
while (1) {
    LPC GPIO1->FIOSET = ALL LED; // Turn on all LEDs
    delay ms(1000);
                      // 1-second delay
    LPC_GPIO1->FIOCLR = ALL_LED; // Turn off all LEDs
    delay_ms(1000); // 1-second delay
 }
}
void delay_ms(uint32_t millis)
{
  uint32_t i, j;
  for (i = 0; i < millis; i++) {
    for (j = 0; j < 1250; j++) {
      // Small time delay loop
    }
  }
}
#include <LPC17xx.h>
#define ALL_LED (0xFF << 19) // Define all LEDs connected from P1.19 to P1.26
void delay_ms(uint32_t millis);
int main(void)
{
  uint32_t i; // Declare the loop variable at the beginning of the block
  // Configure P1.19 - P1.26 as output pins
```

```
LPC_GPIO1->FIODIR |= ALL_LED; // Set P1.19 to P1.26 as outputs
  LPC_GPIO1->FIOCLR = ALL_LED; // Turn off all LEDs initially
  while (1) {
    for (i = 19; i <= 26; i++) \{ // Iterate through LEDs from P1.19 to P1.26
      LPC_GPIO1->FIOSET = (1 << i); // Turn on the current LED
      delay_ms(500);
                                // 500 ms delay
      LPC_GPIO1->FIOCLR = (1 << i); // Turn off the current LED
    }
  }
}
void delay_ms(uint32_t millis)
{
  uint32_t i, j;
  for (i = 0; i < millis; i++) {
    for (j = 0; j < 1250; j++) {
      // Small time delay loop
    }
  }
}
#include <LPC17xx.h>
#define ALL_LED (0xFF << 19) // Define all LEDs connected from P1.19 to P1.26
void delay_ms(uint32_t millis);
int main(void)
{
```

```
// Configure P1.19 - P1.26 as output pins
  LPC GPIO1->FIODIR |= ALL LED; // Set P1.19 to P1.26 as outputs
  LPC GPIO1->FIOCLR = ALL LED; // Turn off all LEDs initially
  while (1) {
    // First phase: Sequentially light up LEDs from P1.19 to P1.26
    for (i = 19; i <= 26; i++) {
      LPC_GPIO1->FIOSET = (1 << i); // Turn on the current LED
      delay_ms(200); // 200 ms delay
    }
    // Second phase: Sequentially light up LEDs from P1.26 to P1.19
    for (i = 26; i >= 19; i--)
      LPC GPIO1->FIOSET = (1 << i); // Turn on the current LED
      delay ms(200); // 200 ms delay
    }
    // Brief pause before restarting the cycle
    LPC_GPIO1->FIOCLR = ALL_LED;
    delay_ms(500); // 500 ms delay before starting again
 }
void delay_ms(uint32_t millis)
  uint32_t i, j;
  for (i = 0; i < millis; i++) {
    for (j = 0; j < 1250; j++) {
      // Small time delay loop
```

}

{

```
}
  }
}
#include <LPC17xx.h>
#define ALL LED (0xFF << 19) // Define all LEDs connected from P1.19 to P1.26
void delay_ms(uint32_t millis);
int main(void)
{
  uint32_t i, mid = 22; // Center LED index (P1.22 is the midpoint for P1.19 to P1.26)
  // Configure P1.19 - P1.26 as output pins
  LPC GPIO1->FIODIR |= ALL LED; // Set P1.19 to P1.26 as outputs
  LPC GPIO1->FIOCLR = ALL LED; // Turn off all LEDs initially
  while (1) {
    // Converging effect: LEDs light up from outer edges to the center
    for (i = 0; i \le (mid - 19); i++) {
      LPC_GPIO1->FIOSET = (1 << (19 + i)) | (1 << (26 - i)); // Turn on symmetrical LEDs
      delay_ms(50); // Delay for convergence
    }
    delay_ms(50); // Hold all LEDs ON at the center
    // Diverging effect: LEDs light up from the center outward (reverse of converging)
    for (i = 0; i \le (mid - 19); i++) {
       \label{localization} LPC\_GPIO1->FIOCLR = (1 << (mid - i)) \mid (1 << (mid + i)); // Turn off LEDs symmetrically inward
       delay_ms(50); // Delay for divergence (moving outward)
```

```
}
    delay_ms(300); // Hold all LEDs OFF after divergence
    // Reset LEDs to OFF before restarting the cycle
    LPC_GPIO1->FIOCLR = ALL_LED;
    delay_ms(50); // Brief pause before the next cycle
  }
}
void delay_ms(uint32_t millis)
{
  uint32_t i, j;
  for (i = 0; i < millis; i++) {
    for (j = 0; j < 1250; j++) {
      // Small time delay loop
    }
  }
}
#include <LPC17xx.h>
// LEDs connected from P1.19 to P1.26
#define ALL_LED (0xFF << 19)
#define GROUP1 (0x0F << 19)
#define GROUP2 (0x0F << 23)
void delay_ms(uint32_t millis);
int main(void)
{
  //uint32_t i;
```

```
// Configure P1.19 - P1.26 as output pins
  LPC_GPIO1->FIODIR |= ALL_LED; // Set P1.19 to P1.26 as outp
  LPC_GPIO1->FIOCLR = ALL_LED;
  while (1) {
      LPC_GPIO1->FIOSET = GROUP1;
      LPC_GPIO1->FIOCLR = GROUP2;
    delay_ms(5);
   LPC_GPIO1->FIOSET = GROUP2;
   LPC_GPIO1->FIOCLR = GROUP1;
   delay_ms(5);
  }
}
void delay_ms(uint32_t millis)
{
  uint32_t i, j;
  for (i = 0; i < millis; i++) {
    for (j = 0; j < 1250; j++) {
      // Small time delay loop
    }
  }
}
# include <LPC17xx.h>
#define BUZZER (0x01 << 27)
void delay_ms(uint32_t mls){
uint32_t i, j;
```

```
for (i = 0; i < mls; i++){
for (j = 0; j < 1250; j++){}
}
}
int main(){
LPC_GPIO1 -> FIODIR |= BUZZER;
LPC_GPIO1 -> FIOCLR = BUZZER;
while(1){
    LPC_GPIO1 -> FIOSET = BUZZER;
    delay_ms(250);
    LPC_GPIO1 -> FIOCLR = BUZZER;
    delay_ms(250);
  }
}
# include <LPC17xx.h>
# include <stdlib.h>
# include <time.h>
#define BUZZER (0x01 << 27)
void delay_ms(uint32_t mls){
uint32_t i, j;
for (i = 0; i < mls; i++){
for (j = 0; j < 1250; j++){}
}
}
int main(){
```

```
uint32_t i;
LPC_GPIO1 -> FIODIR |= BUZZER;
LPC GPIO1 -> FIOCLR = BUZZER;
for (i = 0; i < 10; i++){
    int rand_val = (rand() \% (1000 - 100 + 1));
    LPC_GPIO1 -> FIOSET = BUZZER;
    delay_ms(rand_val);
    LPC_GPIO1 -> FIOCLR = BUZZER;
    delay_ms(rand_val);
 }
}
# include <LPC17xx.h>
# include <stdint.h>
#define BUZZER (1 << 27)
#define SWITCH (1 << 11)
void delay(uint32_t ms){
uint32_t i, j;
  for(i = 0; i < ms; i++){
    for(j = 0; j < 1250; j++)\{\}
}
}
int main(){
  LPC_GPIO1 -> FIODIR |= BUZZER; //OUTPUT KE LIYE OR
  LPC_GPIO2 -> FIODIR &= ~SWITCH;//INPUT KE LIYE AND
```

```
LPC_GPIO1 -> FIOCLR = BUZZER;
  while(1){
    if ((LPC_GPIO2 -> FIOPIN & SWITCH) != 0){
      LPC_GPIO1 -> FIOSET = BUZZER;
    }
    else{
      LPC_GPIO1 -> FIOCLR = BUZZER;
    }
  }
}
# include <LPC17xx.h>
# include <stdint.h>
#define BUZZER (1 << 27)
#define SW1 (1 << 11)
#define SW2 (1 << 12)
#define ALL_LED (0xFF << 19)
void delay(uint32_t ms){
uint32_t i, j;
  for(i = 0; i < ms; i++){
    for(j = 0; j < 1250; j++){}
}
}
int main(){
  LPC_GPIO1 -> FIODIR |= BUZZER;
  LPC_GPIO1 -> FIODIR |= ALL_LED;
```

```
LPC_GPIO2 -> FIODIR &= ~SW1;
LPC_GPIO2 -> FIODIR &= ~SW2;
LPC_GPIO1 -> FIOCLR = ALL_LED;
LPC_GPIO1 -> FIOCLR = BUZZER;
while(1){
  if ((LPC_GPIO2 -> FIOPIN & SW1) != 0){
    LPC_GPIO1 -> FIOSET = BUZZER;
  }
  else{
    LPC_GPIO1 -> FIOCLR = BUZZER;
  }
  if ((LPC_GPIO2 -> FIOPIN & SW2) != 0){
    LPC_GPIO1 -> FIOSET = ALL_LED;
  }
  else{
    LPC_GPIO1 -> FIOCLR = ALL_LED;
  }
}
```

SS

}