

### Question 3.1

Fixed relations:

```
floor(i,j).  
adjacent(i,j,k,l).
```

Dynamic relations:

```
boulder(i,j).  
player(i,j).
```

### Question 3.2

Preconditions:

```
move(i,j,k,l):  
    floor(k,l), ~boulder(k,l), adjacent(i,j,k,l).  
  
push(i,j,k,l,m,n):  
    floor(m,n), ~boulder(m,n), boulder(k,l), adjacent(i,j,k,l),  
    adjacent(k,l,m,n), i - k = k - m, j - l = l - n.
```

Effects:

```
move(i,j,k,l):  
    player(k,l), ~player(i,j).  
push(i,j,k,l,m,n):  
    player(k,l), ~player(i,j), boulder(m,n), ~boulder(k,l).
```

### Question 3.3:

Initial State:

```
floor(1,6),floor(1,7),floor(1,8),floor(1,9),  
floor(2,2),floor(2,3),floor(2,4),floor(2,6),  
floor(2,7),floor(2,8),floor(2,9),floor(3,2),  
floor(3,3),floor(3,4),floor(3,6),floor(4,2),  
floor(4,3),floor(4,4),floor(4,6),floor(4,8),  
floor(5,4),floor(5,8),floor(6,1),floor(6,4),  
floor(6,5),floor(6,6),floor(6,7),floor(6,8),  
floor(7,1),floor(7,3),floor(7,4),floor(7,5),  
floor(7,7),floor(7,8),floor(8,1),floor(8,3),  
floor(8,4),floor(8,5),floor(9,1),floor(9,7),  
floor(9,8),floor(9,9),
```

```
boulder(3,3),boulder(3,4),boulder(4,3),
```

```
player(2,2),
```

```
adjacent(2,2,2,3),adjacent(2,2,3,2)  
''' #for each corner tile
```

```
adjacent(2,3,2,2),adjacent(2,3,2,4),adjacent(2,3,3,3),  
''' #for each wall adjacent tile that is not a corner
```

```
adjacent(3,3,2,3),adjacent(3,3,3,2),adjacent(3,3,3,4),  
adjacent(3,3,4,3)  
''' #for each not wall adjacent tile
```

Question 3.4:

Goal:

boulder(4,8),boulder(5,8),boulder(6,8)

Question 3.5:

The search space can be very large. Without specifying a search algorithm with a distance heuristic (like A\*), an ASP solution can be slower than one where the search algorithm is defined explicitly.