

Finite Difference Methods: Differentiation, Interpolation and Integration (I)

Differentiation: Finite Differences

The definition of derivative is:

$$\left. \frac{df}{dx} \right|_{x=x_0} = f'(x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

Therefore, it is reasonable to think that:

For small enough h :

$$f'(x_0) \approx \frac{f(x_0 + h) - f(x_0)}{h}$$

In this way, we approximate the differential operator $D = \frac{d}{dx}$ by an expression involving the values of the function at a discrete set of points. This kind of formula is called a **Finite Difference Formula**. The discrete set of points is called the **Stencil** of the formula.

All *finite difference formulas* are based on the concept of the *Taylor Series*:

A function $f(x)$ continuous and differentiable in the interval $[x_0, x]$ can be approximated by:

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k = \sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k + R_n$$

Where $R_n = \frac{1}{(n+1)!} (x - x_0)^{n+1} f^{(n+1)}(\xi)$, usually abbreviated as $O(h^{n+1})$.

The exponent of $O(h^{n+1})$ is the order of the finite difference formula. It means that the error made when approximating the derivative with a certain formula with $O(h^p)$ will have an error of the order of h^p . As we normally use $h \ll 1$, the error will be smaller for larger order formulas.

The choice of stencil is very important. Normally we use equispaced stencils, which means that all consecutive points are spaced by a constant amount ($x_{i+n} = x_i + nh$). A general stencil would be:

x	x_{i-n}	\cdots	x_{i-1}	x_i	x_{i+1}	\cdots	x_{i+m}
$y = f(x)$	y_{i-n}	\cdots	y_{i-1}	y_i	y_{i+1}	\cdots	y_{i+m}

In order to derive the finite difference formulas, it is useful to define a set of linear differential operators:

Difference Operators:

Forward Difference:

$$\Delta u = u_{i+1} - u_i$$

Backward Difference:

$$\nabla u = u_i - u_{i-1}$$

Central Difference:

$$\delta u = u_{i+1/2} - u_{i-1/2}$$

Finite Forward Difference Formulas

Forward difference formulas are those that enable us to compute the value y'_i of the derivative of a function y at a certain point x_i based on the value y_i of the function at that same point x_i and a certain number of points larger than x_i (y_{i+1}, y_{i+2}, \dots).

These formulas derive from the Taylor expansion of y around x_i up to order N :

$$y_{i+n} = \sum_{k=0}^N \frac{(x_{i+n} - x_i)^k}{k!} y_i^{(k)} + O(h^{N+1})$$

The order up to which the expansion is used, N , is the order of the finite difference formula. If we consider $x_{i+1} - x_i = h$, then $x_{i+n} - x_i = nh$, and the formula is simplified to:

$$y_{i+n} = \sum_{k=0}^N \frac{(nh)^k}{k!} y_i^{(k)} + O(h^{N+1})$$

If we want to find the expression of the derivative $y_i^{(r)}$, then we need to find the previous expansion up to $N \geq r$ and evaluate it at $n = 0, 1, \dots, N$. This will allow us to build a system of equations with enough equations to find the coefficients a_n of:

$$y_i^{(r)} = a_0 y_i + a_1 y_{i+1} + \dots + a_N y_{i+N} + O(h^N)$$

The order of forward finite difference formulas is usually equal to $k - 1$, where k is the number of points of the function y on which the formula depends.

Example: Second Order Finite Forward Difference Formula for the First Derivative

We want to find the second order finite difference formula, so $N = 2$. We know this is possible because, as we want the first derivative ($r = 1$), we can verify that $N = 2 > 1 = r$.

As $N = 2$, we need to expand y_{i+n} up to the second order and evaluate for $n = 0, 1, 2$:

$$y_{i+n} = \sum_{k=0}^2 \frac{(nh)^k}{k!} y_i^{(k)} + O(h^3) = y_i + nh y'_i + \frac{1}{2} (nh)^2 y''_i + O(h^3)$$

Then:

$$y_i = y_i$$

$$y_{i+1} = y_i + hy'_i + \frac{1}{2}h^2 y''_i + O(h^3)$$

$$y_{i+2} = y_i + 2hy'_i + 2h^2 y''_i + O(h^3)$$

Now we have a system of equations to solve:

$$y'_i = a_0 y_i + a_1 y_{i+1} + a_2 y_{i+2} + O(h^2)$$

Substituting:

$$\begin{aligned} y'_i &= a_0 y_i + a_1 \left(y_i + hy'_i + \frac{1}{2}h^2 y''_i + O(h^3) \right) + \\ &\quad a_2 \left(y_i + 2hy'_i + 2h^2 y''_i + O(h^3) \right) + O(h^2) = \\ &= (a_0 + a_1 + a_2)y_i + h(a_1 + 2a_2)y'_i + \frac{h^2}{2}(a_1 + 4a_2)y''_i \end{aligned}$$

Finally, $y'_i = (a_0 + a_1 + a_2)y_i + h(a_1 + 2a_2)y'_i + \frac{h^2}{2}(a_1 + 4a_2)y''_i$ requires:

$$a_0 + a_1 + a_2 = 0$$

$$h(a_1 + 2a_2) = 1$$

$$\frac{h^2}{2}(a_1 + 4a_2) = 0$$

yielding $a_0 = -\frac{3}{2h}$, $a_1 = \frac{2}{h}$ and $a_2 = -\frac{1}{2h}$:

The *Second Order Finite Forward Difference Formula for the First Derivative* is:

$$y'_i = \frac{-3y_i + 4y_{i+1} - y_{i+2}}{2h} + O(h^2)$$

Finite Backward Difference Formulas

Backward difference formulas are those that enable us to compute the value y'_i of the derivative of a function y at a certain point x_i based on the value y_i of the function at that same point x_i and a certain number of points smaller than x_i (y_{i-1}, y_{i-2}, \dots).

Again, these formulas derive from the Taylor expansion of y around x_i up to order N that we simplified before to:

$$y_{i+n} = \sum_{k=0}^N \frac{(nh)^k}{k!} y_i^{(k)} + O(h^{N+1})$$

If we want to find the expression of the derivative $y_i^{(r)}$, then we need to find the previous expansion up to $N \geq r$ and evaluate it at $n = 0, -1, \dots, -N$. This will allow us to build a system of equations with enough equations to find the coefficients a_n of:

$$y_i^{(r)} = a_0 y_i + a_1 y_{i-1} + \cdots + a_N y_{i-N} + O(h^N)$$

The order of backward finite difference formulas is usually equal to $k - 1$, where k is the number of points of the function y on which the formula depends.

Example: Second Order Finite Backward Difference Formula for the First Derivative

We want to find the second order finite difference formula, so $N = 2$. We know this is possible because, as we want the first derivative ($r = 1$), we can verify that $N = 2 > 1 = r$.

As $N = 2$, we need to expand y_{i+n} up to the second order and evaluate for $n = 0, 1, 2$:

$$y_{i+n} = \sum_{k=0}^2 \frac{(nh)^k}{k!} y_i^{(k)} + O(h^3) = y_i + nh y_i' + \frac{1}{2} (nh)^2 y_i'' + O(h^3)$$

Then:

$$y_i = y_i$$

$$y_{i-1} = y_i - h y_i' + \frac{1}{2} h^2 y_i'' + O(h^3)$$

$$y_{i-2} = y_i - 2h y_i' + 2h^2 y_i'' + O(h^3)$$

Now we have a system of equations to solve:

$$y_i' = a_0 y_i + a_1 y_{i+1} + a_2 y_{i+2} + O(h^2)$$

Substituting:

$$\begin{aligned} y_i' &= a_0 y_i + a_1 \left(y_i - h y_i' + \frac{1}{2} h^2 y_i'' + O(h^3) \right) + \\ &\quad a_2 \left(y_i - 2h y_i' + 2h^2 y_i'' + O(h^3) \right) + O(h^2) = \\ &= (a_0 + a_1 + a_2) y_i - h(a_1 + 2a_2) y_i' + \frac{h^2}{2} (a_1 + 4a_2) y_i'' \end{aligned}$$

Finally, $y_i' = (a_0 + a_1 + a_2) y_i - h(a_1 + 2a_2) y_i' + \frac{h^2}{2} (a_1 + 4a_2) y_i''$ requires:

$$a_0 + a_1 + a_2 = 0$$

$$h(a_1 + 2a_2) = -1$$

$$\frac{h^2}{2} (a_1 + 4a_2) = 0$$

yielding $a_0 = \frac{3}{2h}$, $a_1 = -\frac{2}{h}$ and $a_2 = \frac{1}{2h}$:

The Second Order Finite Backward Difference Formula for the First Derivative is:

$$y'_i = \frac{3y_i - 4y_{i-1} + y_{i-2}}{2h} + O(h^2)$$

Notice that this is just the formula for the forward difference but substituting h by $-h$ and substituting i by $i - 2$.

Finite Centered Difference Formulas

Centered difference formulas are those that enable us to compute the value y'_i of the derivative of a function y at a certain point x_i based on the value y_i of the function at that same point x_i and a certain number of points of which half are smaller than x_i (y_{i-1}, y_{i-2}, \dots) and the other half are larger than x_i (y_{i+1}, y_{i+2}, \dots).

Again, these formulas derive from the Taylor expansion of y around x_i up to order N that we simplified before to:

$$y_{i+n} = \sum_{k=0}^N \frac{(nh)^k}{k!} y_i^{(k)} + O(h^{N+1})$$

If we want to find the expression of the derivative $y_i^{(r)}$, then we need to find the previous expansion up to even $N \geq r$ and evaluate it at $n = -N/2, \dots, -1, 0, 1, \dots, N/2$. This will allow us to build a system of equations with enough equations to find the coefficients a_n of:

$$y_i^{(r)} = a_{-N/2} y_{i-N/2} + \dots + a_{-1} y_{i-1} + a_0 y_i + a_1 y_{i+1} + \dots + a_{N/2} y_{i+N/2} + O(h^{N+1})$$

The order of centered finite difference formulas is usually equal to the number of points of the function y on which the formula depends.

Example: Second Order Finite Centered Difference Formula for the First Derivative

We want to find the second order finite difference formula, so $N = 2$. We know this is possible because, as we want the first derivative ($r = 1$), we can verify that $N = 2 > 1 = r$.

As $N = 2$, we need to expand y_{i+n} up to the second order and evaluate for $n = 0, 1, 2$:

$$y_{i+n} = \sum_{k=0}^2 \frac{(nh)^k}{k!} y_i^{(k)} + O(h^3) = y_i + nh y'_i + \frac{1}{2} (nh)^2 y''_i + O(h^3)$$

Then:

$$y_i = y_i$$

$$y_{i+1} = y_i + h y'_i + \frac{1}{2} h^2 y''_i + O(h^3)$$

$$y_{i-1} = y_i - h y'_i + \frac{1}{2} h^2 y''_i + O(h^3)$$

Now we have a system of equations to solve:

$$y'_i = a_{-1} y_{i-1} + a_0 y_i + a_1 y_{i+1} + O(h^3)$$

Substituting:

$$y'_i = a_{-1} \left(y_i - hy'_i + \frac{1}{2}h^2y''_i + O(h^3) \right) + a_0y_i + \\ + a_1 \left(y_i + hy'_i + \frac{1}{2}h^2y''_i + O(h^3) \right) + O(h^3) =$$

$$= (a_{-1} + a_0 + a_1)y_i + h(-a_{-1} + a_0 + a_1)y'_i + \frac{h^2}{2}(a_{-1} + a_1)y''_i + O(h^3)$$

Finally, $y'_i = (a_{-1} + a_0 + a_1)y_i + h(-a_{-1} + a_0 + a_1)y'_i + \frac{h^2}{2}(a_{-1} + a_1)y''_i$ requires:

$$a_{-1} + a_0 + a_1 = 0$$

$$h(-a_{-1} + a_0 + a_1) = 1$$

$$\frac{h^2}{2}(a_{-1} + a_1) = 0$$

yielding $a_{-1} = -\frac{1}{2h}$, $a_0 = 0$ and $a_1 = \frac{1}{2h}$:

The *Second Order Finite Centered Difference Formula for the First Derivative* is:

$$y'_i = \frac{y_{i+1} - y_{i-1}}{2h} + O(h^3)$$

Online finite differences calculator [here](#).