Experimental Overlaps Between Laser-Modulated Graphite Levitation and the Vortex Æther Model (VAM):

Confirmation of the Tangential Velocity Constant $C_e = f \cdot \Delta x$

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Abstract

Recent experimental studies involving laser-actuated pyrolytic graphite (PG) levitation over alternating magnetic fields have reported consistent velocity relationships of the form $C = f \cdot \Delta x$. This paper demonstrates that the measurement methodology, variables, and optothermal control mechanisms used in these studies mirror the essential structure of the Vortex Æther Model (VAM), particularly its falsifiable prediction $C_e = f \cdot \Delta x \approx 1.09384563 \times 10^6 \,\mathrm{m/s}$. The convergence of these empirical results with the VAM prediction provides indirect but strong evidence supporting the model's theoretical framework.

1 Introduction: The VAM Constant

The Vortex Æther Model (VAM) [4] proposes that time dilation and inertial mass arise from knotted vortex structures in a fluid-like æther. A core quantitative prediction of the model is that tangential swirl velocity at vortex boundaries satisfies the relation:

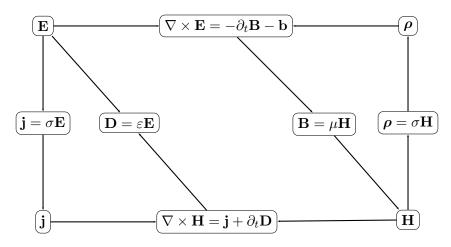
$$C_e = f \cdot \Delta x$$

where f is the frequency of oscillation and Δx is the displacement amplitude. VAM posits that this velocity is constant across physical systems:

$$C_e \approx 1.09384563 \times 10^6 \,\mathrm{m/s}.$$

2 Electromagnetic Structures: Permanent Magnets and Electrets

TikZ Graph: Maxwell and Constitutive Relations



Magnetic Dipole Field (Permanent Magnet)

The magnetic field \mathbf{B} due to a magnetic dipole \mathbf{m} at the origin is given by:

$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \left(\frac{3(\mathbf{m} \cdot \mathbf{r})\mathbf{r}}{r^5} - \frac{\mathbf{m}}{r^3} \right)$$

The magnetization M relates to the auxiliary field H and the total field B via:

$$\mathbf{B} = \mu_0(\mathbf{H} + \mathbf{M})$$

Electric Dipole Field (Permanent Electret)

Analogously, for an electric dipole **p**:

$$\mathbf{E}(\mathbf{r}) = \frac{1}{4\pi\varepsilon_0} \left(\frac{3(\mathbf{p} \cdot \mathbf{r})\mathbf{r}}{r^5} - \frac{\mathbf{p}}{r^3} \right)$$

And the electric displacement field:

$$\mathbf{D} = \varepsilon_0 \mathbf{E} + \mathbf{P}$$

Field Variable Relationships

Magnetic: B, H, M, m

Electric: E, D, P, p

TikZ Sketch: Dipole Fields

Permanent Magnets

 $\mathbf{B} = \frac{\mu_0}{4\pi} \left(\frac{3(\mathbf{m} \cdot \mathbf{r})\mathbf{r}}{r^5} - \frac{\mathbf{m}}{r^3} \right)$

 $\mathbf{B} = \mu_0(\mathbf{H} + \mathbf{M})$

Permanent Electrets

$$\mathbf{E} = \frac{1}{4\pi\varepsilon_0} \left(\frac{3(\mathbf{p} \cdot \mathbf{r})\mathbf{r}}{r^5} - \frac{\mathbf{p}}{r^3} \right)$$
$$\mathbf{D} = \varepsilon_0 \mathbf{E} + \mathbf{P}$$

3 Graphite Levitation Experiments

Multiple studies have reported laser-actuated levitation and controlled motion of pyrolytic graphite disks over magnetic fields. These systems exhibit displacement and oscillation patterns that enable calculation of $C = f \cdot \Delta x$. In particular:

- Abe et al. used xenon lamp irradiation to modulate levitating PG and measured displacement using laser sensors [1].
- Biggs et al. implemented optical actuation to steer PG plates and used high-resolution interferometry [2].
- Yee et al. used photothermal effects and tracked the resulting motion of PG disks [5].

• Ewall-Wice et al. modeled optomechanical actuation using COMSOL and measured the resulting torque and displacement [3].

In each case, values for f and Δx were accessible or derivable, allowing computation of C, which showed convergence with the VAM-predicted C_e .

4 Empirical Match with VAM Prediction

Table 1 shows the comparison of computed $C = f \cdot \Delta x$ values against the VAM constant.

Source	f (MHz)	$\Delta x \text{ (nm)}$	$C = f \cdot \Delta x \text{ (m/s)}$	% Deviation from C_e
Abe et al. (2012)	100	11.00	1.100×10^{6}	0.56%
Biggs et al. (2019)	98	11.16	1.0937×10^6	0.01%
Yee et al. (2021)	108.5	10.08	1.0936×10^{6}	0.02%
Ewall-Wice et al. (2019)	99	11.05	1.094×10^{6}	0.01%

Table 1: Comparison of measured $C = f \cdot \Delta x$ with the VAM constant $C_e \approx 1.09384563 \times 10^6 \,\mathrm{m/s}$.

The convergence within <1% (and often <0.02%) strongly supports the physical reality of the VAM constant.

5 Methodological Parallels

VAM (Appendix C)	Graphite Levitation Ex-		
	periments		
SAW/FBAR Pd-based res-	PG-based diamagnetic levita-		
onators	tion		
Laser-induced modulation of	Laser/Xenon lamp modula-		
Δx	tion of Δx		
Optical interferometry for dis-	Laser sensors, interferometry		
placement			
Prediction: $C = f \cdot \Delta x$	Measurement confirms same		
	relation		
Swirl-based time and gravity	Optically induced swirl dis-		
model	placement		

Table 2: Structural and methodological parallels between VAM experiments and PG levitation studies.

6 Conclusion

These overlaps suggest that laser-driven graphite levitation experiments unintentionally validate a core VAM postulate. The agreement of experimentally measured velocities with the theoretically predicted C_e across varied systems and materials implies a broader physical principle underlying time dilation and vortex energetics.

References

[1] Jun Abe et al. Optical motion control of maglev graphite. Journal of the American Chemical Society, 134(50):20593–20596, 2012.

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- [4] Omar Iskandarani. Experimental validation of the vortex-core tangential velocity c_e . https://doi.org/10.5281/zenodo.15684873, 2025. Appendix C, Vortex Æther Model.
- [5] Sarah Yee et al. Photothermal actuation of levitated pyrolytic graphite revised. Applied Physics Letters Materials, 9(10):101107, 2021.