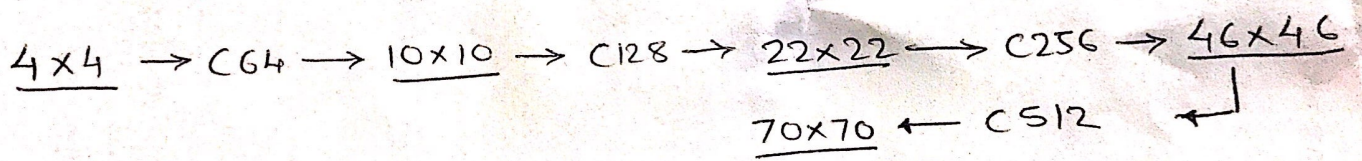


7.2



7.3]

Why only minimizing the $L1$ Loss results in a blurry image?

- $L1$ loss for a CNN is the difference between predicted & ground truth pixels.
- $L1$ loss is minimized by averaging all plausible outputs, which causes blurring.
- Since $L1$ loss is a pixel to pixel loss, it minimizes it by averaging all the possible & plausible location of that pixel in the predicted image.
- Hence $L1$ loss is useful for low-frequency correction & not suitable for high-frequency correction.



- In conditional GAN, patch GAN penalizes structure at the $N \times N$ patches. i.e. it tries to classify if each $N \times N$ patch is real or fake. Hence, patch GAN looks after penalizing the structure while L1 loss penalizes ~~low frequency~~ low-frequencies.