

# Time Series Econometrics

## Brief Overview

Day 1 or 2

# Econometrics and Time Series

- Two main uses of econometrics
  1. Predict an unknown
    - Forecasting, nowcasting, prediction in-sample vs out-of-sample.
    - Leverage multivariate/conditional correlations, joint distributions of variables, dependence on past values.
  2. Estimate a “true” parameter
    - Causal inference, construct counterfactuals
    - Causal effect of a policy or decision, demand and supply elasticities, shape parameters of production functions, cost functions, utility functions, etc.

# Power plant emissions control example

# Time Series

- What is special about time series?
  - Data observations have a particular **order** - time.
  - May be **dependence** of each observation on the last one, or the last 10.
    - How many past values? Which ones? How strong is the dependence? How can we use it or control for it?
  - Classical statistics: observations are independent.
    - Sample 100 people about their purchases at different price levels. Then sample 100 more.
    - Randomized control trial of a drug with 100 people. Conduct many trials.

# Linear model examples

- Capital Asset Pricing Model
- Forecasting the future from past & present values
- Estimate supply and demand functions
- Estimate the causal impact of a policy change on an industry

# General problem

Want to know

1. “true” relationship between time series variables  $y_t$  and  $x_t$ , or
2. the best prediction of  $y_t$  if all we know is  $x_t$ .

$$y_t = \alpha + \beta x_t + e_t$$

- $\alpha$  is intercept,  $\beta$  is slope in the  $x$  dimension.
- $x_t$  might be a vector of multiple explanatory variables.
- $e_t$  is everything else about  $y_t$  not captured in  $x_t$ .

## General problem

$$y_t = \alpha + \beta x_t + e_t$$

- What is in  $e_t$ ? Make a list of things that determine  $y_t$ , whether observable or not.
- How can **lag dependence within**  $y_t$ ,  $x_t$ ,  $e_t$  help or hurt the model?
- How can **joint dependence between**  $y_t$ ,  $x_t$ ,  $e_t$  help or hurt the model?
- *pay attention to subscripts.*

## Examples: CAPM

- Market Model:  $y_t$  is a stock return,  $x_t$  market return, e.g., S&P500, S&P Value-Weighted, sector index, etc.

$$r_{it} = \alpha + \beta r_{mt} + e_t$$

- $\alpha$  is stock  $i$ 's average return when markets are zero.
- $\beta$  is stock  $i$ 's volatility relative to market (i.e.,  $\beta > 1$  vs.  $\beta < 1$ ).



## Examples: CAPM

- Capital Asset Pricing Model:  $y_t$  and  $x_t$  are *excess returns* over a risk free rate  $r_{ft}$ , e.g., interest on 3-month T-bill:

$$(r_{it} - r_{ft}) = \alpha + \beta(r_{mt} - r_{ft}) + e_t$$

- Fama-French 3-factor model<sup>1</sup>

$$(r_{it} - r_{ft}) = \alpha + \beta(r_{mt} - r_{ft}) + \gamma_1 SMB_t + \gamma_2 HML_t + e_t$$

- $SMB_t$  (small - big): small cap portfolio return minus large cap.
- $HML_t$  (high - low): value minus growth portfolio return.

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<sup>1</sup>Kenneth French updates factor data at

## Examples: Autoregressive (AR) model

$$y_t = \alpha + \beta x_t + e_t$$

- AR( $p$ ):  $x_t$  is a vector containing  $p$  **lags** (past values) of  $y_t$  and other variables  $z_t$ .

$$y_t = \alpha + \beta_1 y_{t-1} + \dots + \beta_p y_{t-p} + \theta_1 z_{1,t-1} + \theta_2 z_{2,t-1} + e_t$$

- What if  $e_t$  also depends on its own past values?

## Examples: Supply and Demand functions

$$q_{Dt} = a - bP_t + e_{Dt}$$

$$q_{St} = c + dP_t + e_{St}$$

$$q_{St} = q_{Dt}$$

- $e_{Dt}$  and  $e_{St}$  are demand and supply shifters/shocks. Some observable, some not observable.
- Algebra shows that in equilibrium,

$$q_t = \frac{-b \cdot c - a \cdot d}{-b - d} + \frac{-b \cdot e_{St} - d \cdot e_{Dt}}{-b - d}$$
$$P_t = \frac{c - a}{-b - d} + \frac{e_{St} - e_{Dt}}{-b - d}$$

- What do you get if you regress  $q_t$  on  $P_t$ ?  $P_t$  is determined by the demand and supply shocks.

# Supply/Demand example

## Examples: Causal Effect of Policy

$$y_t = \alpha + \beta D_t + \theta x_t + e_t$$

- $D_t = 1$  when some policy is in place,  $D_t = 0$  otherwise.
- $x_t$  might be a vector of multiple control variables.
- $e_t$  is everything else about  $y_t$  not captured in  $x_t$ .
- Is  $e_t$  correlated with  $D_t$ ? Who receives the policy? When does it happen?

## Other examples

### Examples:

- Energy demand:  $y_t$  is electricity or natural gas consumption, or fuel in storage,  $x_t$  is weather (e.g., heating/cooling degree days, hurricane incidence, etc.)
- Commodity market linkages (cointegration):
  - $y_t$  is copper price,  $x_t$  is gold price.
  - $y_t$  is global LNG price,  $x_t$  is Brent crude price.

# Estimation

- Classical statistics: parameters  $\alpha, \beta, \theta, a, b, c, d$ , etc. have objectively true but unknowable values.
- We can estimate them from a sample:  $\hat{\alpha}, \hat{\beta}, \hat{\theta}$ , etc.
- Every sample will produce a slightly different answer.
  - Our estimates are *noisy or uncertain* — they have *variance*.
- What is the optimal way to estimate them so that they are
  - **unbiased**: close to the truth on average across samples.
  - **efficient**: have the lowest variance possible.
- The estimates are the answer to an optimization problem.

# Estimation

- Parameter estimates are the answer to an optimization problem.
- Pick parameters that minimize a loss function, e.g., sum of squared residuals.

$$\min_{\alpha, \beta} \sum_{t=1}^T e_t^2 = \min_{\alpha, \beta} \sum_{t=1}^T (y_t - \alpha - \beta x_t)^2$$

- Ordinary Least Squares (OLS). Not the only loss function, but the most common and has some nice properties.



# Estimation

- Gauss-Markov Theorem: Under some assumptions, OLS gives the Best Linear Unbiased Estimate
  - True model is linear in parameters and residuals.
  - Right hand side variables are not constants or perfectly correlated with each other.
  - Residuals  $e_t$  have a constant variance (not more noisy for some values of  $x$  than others).
  - Residuals  $e_t$  are uncorrelated with each other.
  - All right hand side variables are uncorrelated with the residual  $e_t$ .
- How many of these are likely to be met in our examples, with time series data?

## Estimation

- Another idea: pick parameters that maximize the likelihood of having observed your data.
- Recall  $e_t = y_t - \alpha - \beta x_t = y_t - \hat{y}_t$ .
- Suppose  $f(e_1, \dots, e_t, \dots, e_T)$  is the joint probability distribution of the residuals, e.g.,  $e_t \sim N(0, \sigma^2)$ .

$$\max_{\alpha, \beta} f(e_1, \dots, e_t, \dots, e_T)$$

- If all the  $e_t$  are **independent** from each other:

$$\max_{\alpha, \beta} f(e_1) \cdot f(e_2) \cdot \dots \cdot f(e_T)$$

$$\max_{\alpha, \beta} \sum_{t=1}^T \ln f(e_t)$$

- Maximum Likelihood Estimation (MLE). Useful in more settings than OLS, shares many similar properties.