





## GNSS + IMU Dead Reckoning Module **RF Circuit** - Generally, use software reset over the UART. RESET\_N triggers the RAM to clear and the firmware reloaded from Layout notes: - RF\_IN: 50 ohm characteristic impedance on transmission - RF\_IN must have 50 ohm characteristic impedance - use GND via wall around microstrip - Battery backup is needed for hot start - no stubs ANN-MB5 has SMA (plug) connector Interface: - D\_SEL to VCC or open: UART or I2C. D\_SEL -> GND: SPI - UART 9600 baudrate - 8 bit no parit, 1 stop RF\_IN J3 SMA-J-P-X-RA-TH1 LQG15HN27NJ02D VCC\_RF 22 1/2 W 1206 C14 D5 ESD9R3.3ST5G 100nF 16V X7R Limits short circuit current to 150 mA RF\_GND RF\_GND RF\_GND +3V3 +BATT\_BCKP C13 Supercap backup supply **=** 0.1uF C12 \_ 1uF GND U3 GND JP2 NEO-M9V-20B Jumper\_2\_Bridged Backup operating voltage: 1.65 - 3.6 V Backup current: 45 uA typical Target backup operating time: 30 min (1800 s) VCC V\_USB GND V\_BCKP ~0.2V drop @ 5mA +BATT\_BCKP VCC\_RF GNSS\_RESETD 8 RESET VCC\_RF +3.3V D4 R6 BAT54A × 1 SAFEBOOT TIMEPULSE — □ GNSS\_TIMEPULSE 470 WOM — □ GNSS\_WAKE\_ON\_MOTION 11 LNA\_EN RF IN LNA\_EN -> external LNA disabled CHP5R5L104R-TW +3V3← D\_SEL USB\_DM Charge path: USB\_DP 100 mF 5.5V diode prevents backfeed current limiting resistor for inrush WHEELTICK C = Q1 / V\_low C = Q2 / V\_high RXD/SPI\_MOSI ─☐UART\_MCU\_TX × 15 TXD/SPI\_MISO 20 DUART\_MCU\_RX GND C = Q2 / V1 Q = Q2 - Q1 t = (Q2 - Q1) / I t = C \* (V\_high - V\_low) / I C = t \* I / (V\_high\_V\_low) SCL/SPI\_SLK 19 × × 16 RESERVED 18 🗙 SDA/SPI\_CS GND 1.5 safety factor (1800 \* 1.5) \* 45E-6 / (3.3 - 0.2 - 1.65) = 84 mF minimum GND\_1 GND\_2 GND\_3 GND RF GND Keep digital return currents away from RF ground. Sheet: /GPS Module/ File: qps\_ublox\_max-f10s.kicad\_sch Title:

Size: A4

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