

# Multimodal Generative Models: Unification, Planning Agents, Evaluation

Mohit Bansal



THE UNIVERSITY  
*of* NORTH CAROLINA  
*at* CHAPEL HILL

# Talk Outline

A journey of multimodal generative models for enhancing their unification, interpretable planning/programming, evaluation:

- **Unified/Universal Multimodal Learning** (for Generalizability, Shared Knowledge, Efficiency)
  - VLT5: Unifying Vision-and-Language Tasks via Text Generation [\[ICML 2021\]](#)
  - TVLT: Textless Vision-Language Transformer [\[NeurIPS 2022\]](#)
  - UDOP: Unifying Vision, Text, and Layout for Universal Document Processing [\[CVPR 2023\]](#)
  - CoDi: Any-to-Any Generation via Composable Diffusion [\[NeurIPS 2023\]](#) & CoDi-2: In-Context, Interleaved, and Interactive Any-to-Any Generation [\[CVPR 2024\]](#)
- **Interpretable Multimodal Generation via LLM Planning/Programming Agents** (for Understanding, Control, Faithfulness, OOD)
  - VPGen: Step-by-Step Text-to-Image Generation with Interpretable Visual Programming [\[NeurIPS 2023\]](#)
  - VideoDirectorGPT: Consistent Multi-Scene Video Generation via LLM-Guided Planning [\[COLM 2024\]](#)
  - DiagrammerGPT: Generating Diagrams via LLM Planning [\[COLM 2024\]](#); EnvGen: Adapting Environments via LLMs for Training Embodied Agents [\[COLM 2024\]](#)
- **Evaluation of Multimodal Generation Models** (of Fine-grained Skills, Faithfulness, Social Biases)
  - DALL-Eval: Probing the Reasoning Skills and Social Biases of Text-to-Image Generation Models [\[ICCV 2023\]](#)
  - VPEval: Step-by-Step Text-to-Image Evaluation with Interpretable Visual Programming [\[NeurIPS 2023\]](#)
  - Davidsonian Scene Graph: Improving Reliability in Fine-grained Evaluation for Text-to-Image Generation [\[ICLR 2024\]](#)
- **Next Big Challenges:** trade-offs, structure, non-verbal, interaction, reasoning, causality, long-distance fine-grained evaluation, efficiencies

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# Language: Pre-training → Fine-tuning

Motivation: the amount of data is limited in downstream tasks and pre-training enables much more data.

Language  
Pre-training:



Text in Wikipedia  
~2500M Tokens (i.e., Words)

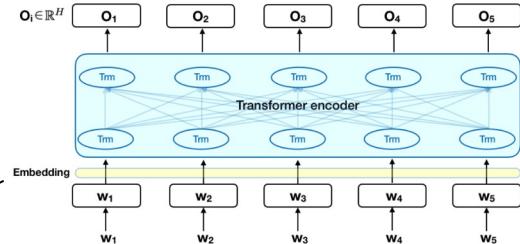
Language  
Fine-tuning



Movie Review [Maas et al., ACL 2011]  
~2.5M Tokens (i.e., Words)

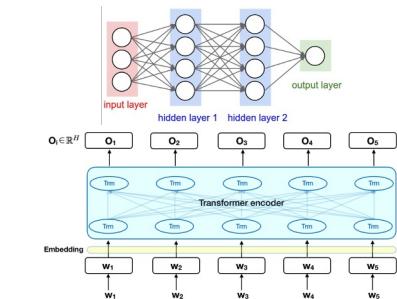
Language  
Model

[Peters et al., NAACL 2018],  
[Devlin et al., NAACL 2019]



Transformer  
[Vaswani, NeurIPS 2017]

Sentiment  
Analysis



Transformer +  
Linear Layers

# Vision: Pre-training → Fine-tuning

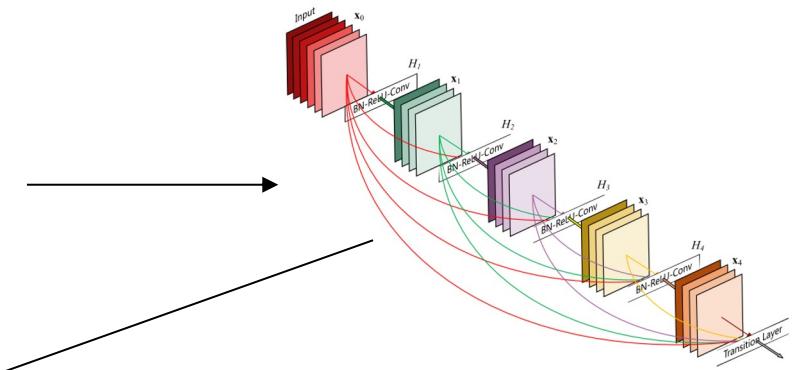
Motivation: the amount of data is limited in downstream tasks and pre-training enables much more data.

Visual  
Pre-training:



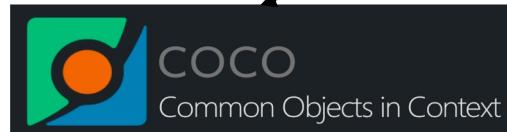
ImageNet  
[Deng, CVPR 2009]  
1.3M Images, 1000 Labels

Image  
Classification



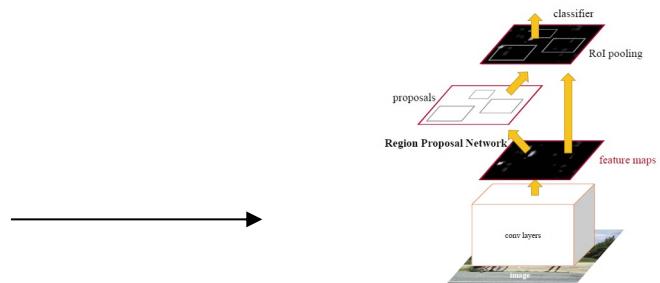
DenseNet  
[Huang, CVPR 2017]

Visual  
Fine-tuning:



MS COCO  
[Lin, ECCV 2009]  
120K Images, 80 Labels

Object  
Detection



Faster RCNN  
[Ren, NeurIPS 2015]

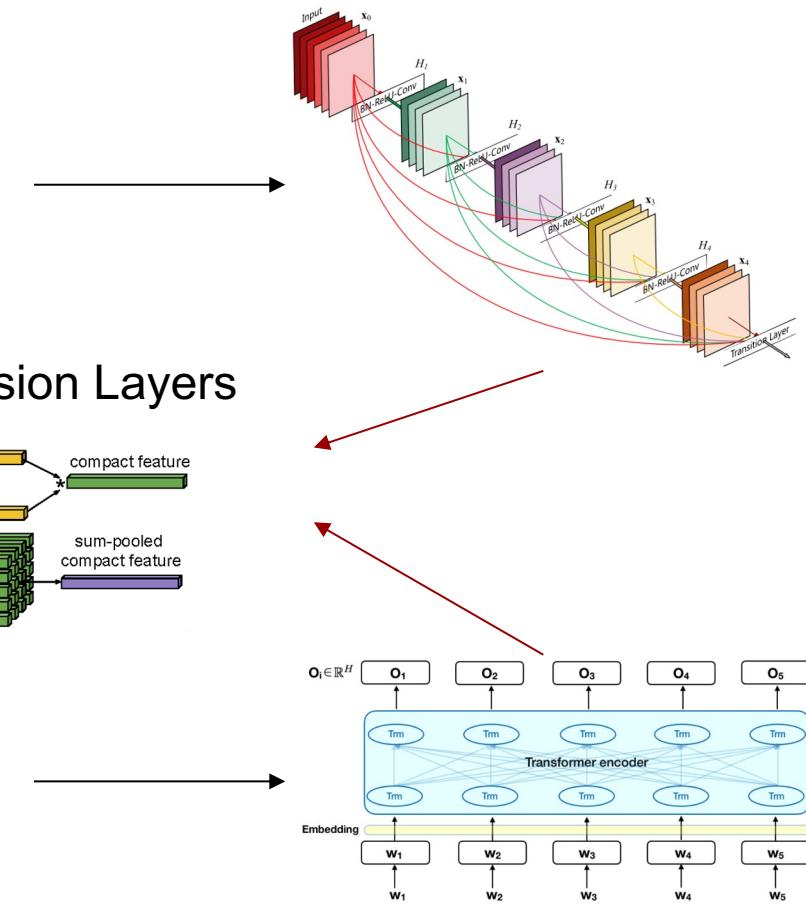
# Pre-training of Single Modality Tasks

Limitation: Single-modality pre-trained models are not aware of the interactions between vision and language

Visual  
Pre-training:



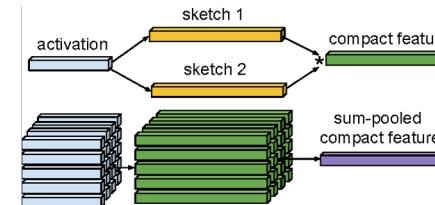
Image  
Classification



Language  
Pre-training:



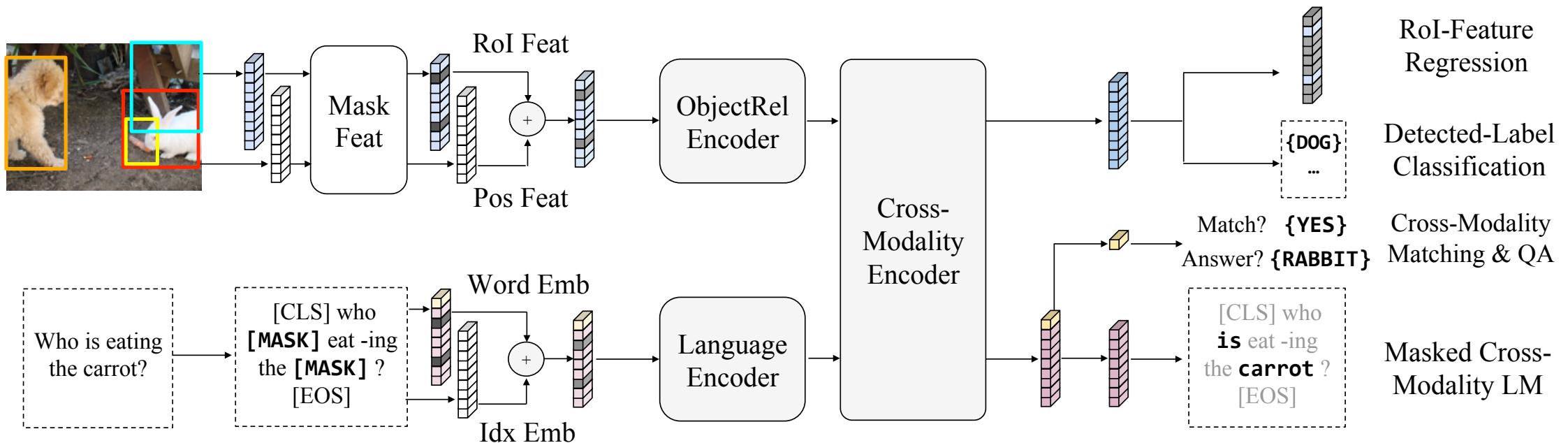
Multimodal Fusion Layers



Language  
Model

# Large-Scale Cross-Modal Pre-training: LXMERT

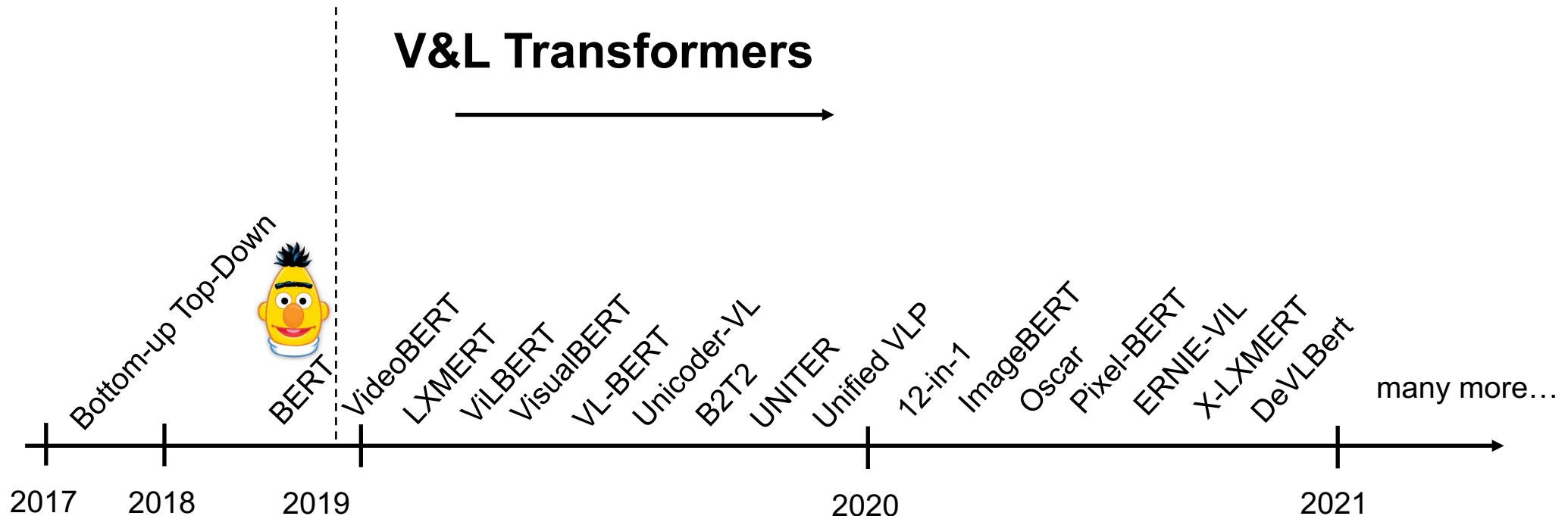
- LXMERT combines knowledge from text, vision and cross-modal matching: vision-language transformers with 3 encoders (object relations, language, cross-modal) & 5 pretraining tasks: masked-LM, masked-Object-Prediction (feature regression+label classification), cross-modality matching, image-QA.



- Achieved big gains + sota on several VL tasks such as VQA, GQA, NLVR2, VizWiz, etc.

# Tons of Specialized Vision-and-Language Pretraining Models

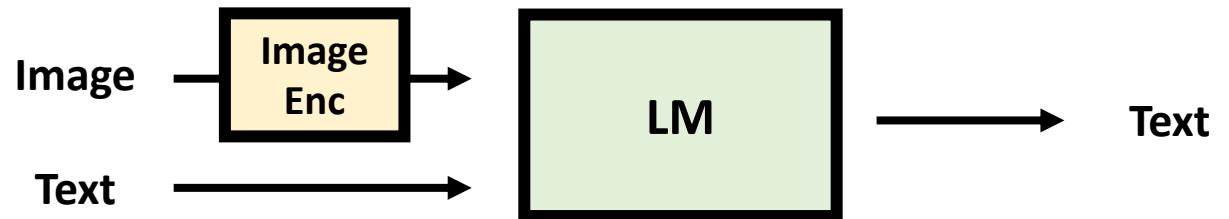
- Many different architectures (single vs. multi-stream), attention methods, objective functions, encoder/decoders, output heads, specialized modules (OCR/ASR/Tokenizers), etc., etc.!



# Part 1: Unified/Universal Multimodal Learning

## VL-T5 (ICML 2021)

all multimodal tasks via text generation



## TVLT (NeurIPS 2022)

video modeling without text (audio as images)



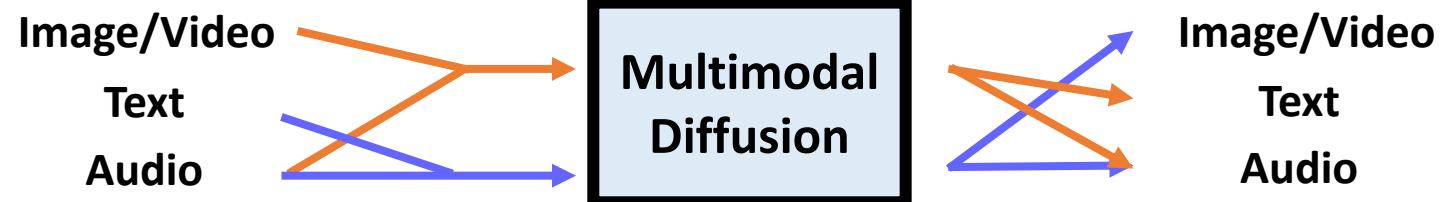
## UDOP (CVPR 2023)

document image/text/layout with single architecture



## CoDi (NeurIPS 2023)

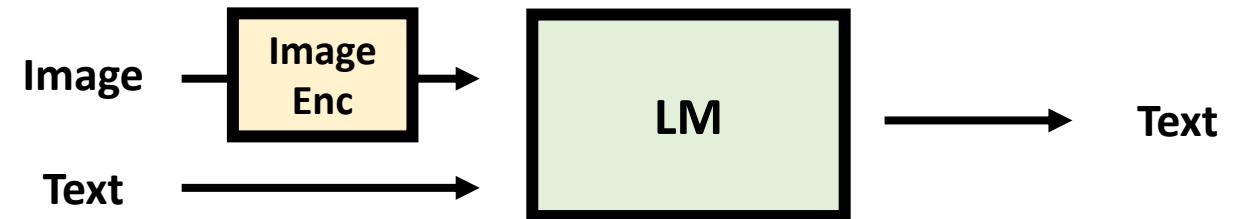
generating any-to-any input-output modality combination



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# Diverse Vision-and-Language Tasks (and Specialized Models)



What is the  
mustache made of?

Model

e.g., MCAN

Banana

Visual Question Answering



Model

e.g., BUTD/AoANet

A woman with  
banana mustache

Image Captioning



banana mustache

Model

e.g., MAttNet



Visual Grounding



A woman with  
banana mustache

Model

e.g., ImageiT

바나나 콧수염을  
한 여자

Multimodal Machine Translation (En-Kr)

Anderson et al., 2018, Bottom-Up and Top-Down Attention for Image Captioning and Visual Question Answering

Yu et al., 2019, Deep Modular Co-Attention Networks for Visual Question Answering

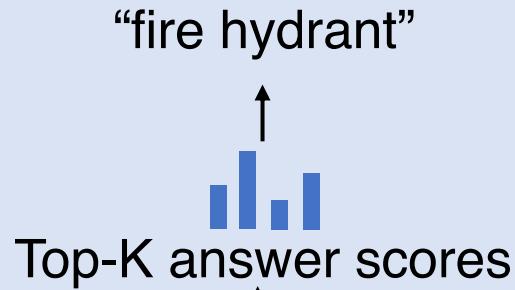
Huang et al., 2019, Attention on Attention for Image Captioning

Yu et al., 2018, MAttNet: Modular Attention Network for Referring Expression Comprehension

Long et al., 2021, Generative Imagination Elevates Machine Translation

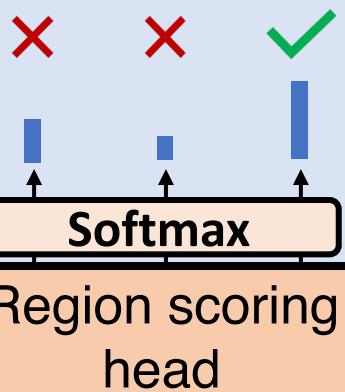
# Task-specific Architectures / Objectives / Modules

## Visual Question Answering



Multi-label  
Classification

## Visual Grounding



Classification

V&L Transformer 1



[CLS] What is the man jumping over?

V&L Transformer 2



[CLS] fire hydrant

# Task-specific Architectures / Objectives

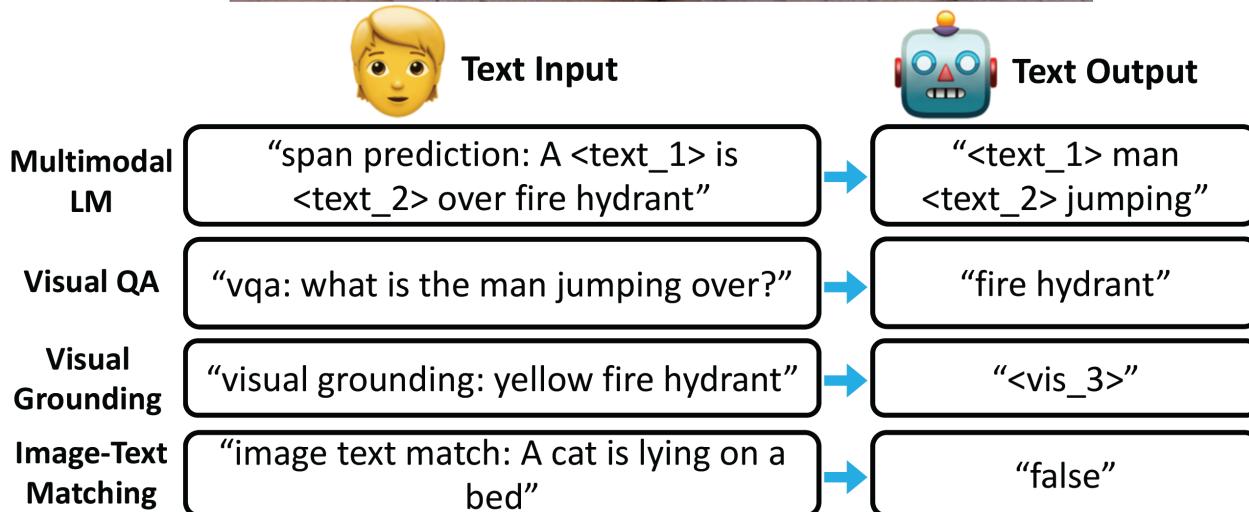
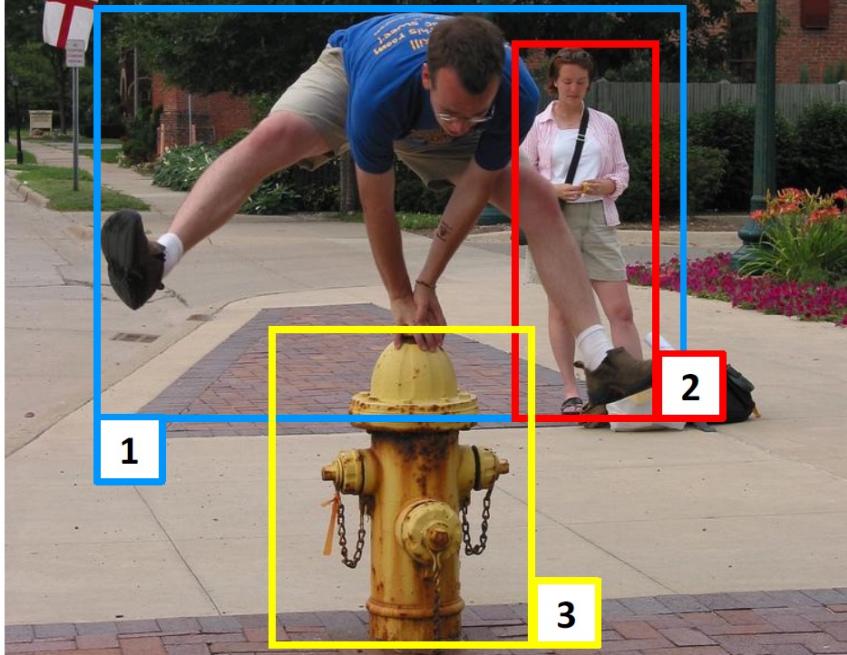
Visual Question Answering

Visual Grounding

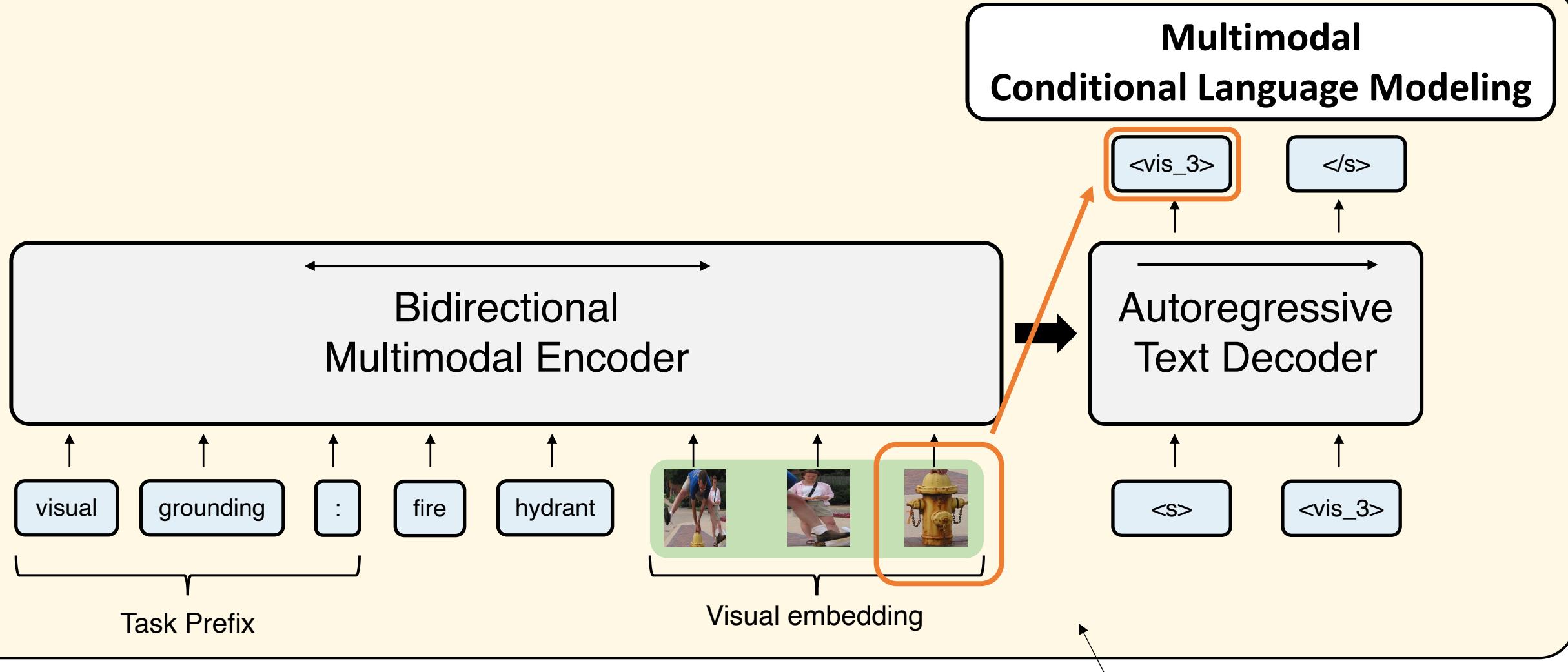
Can we tackle all V&L tasks  
with a single objective?



# VL-T5: Many Multimodal Tasks as Text Generation



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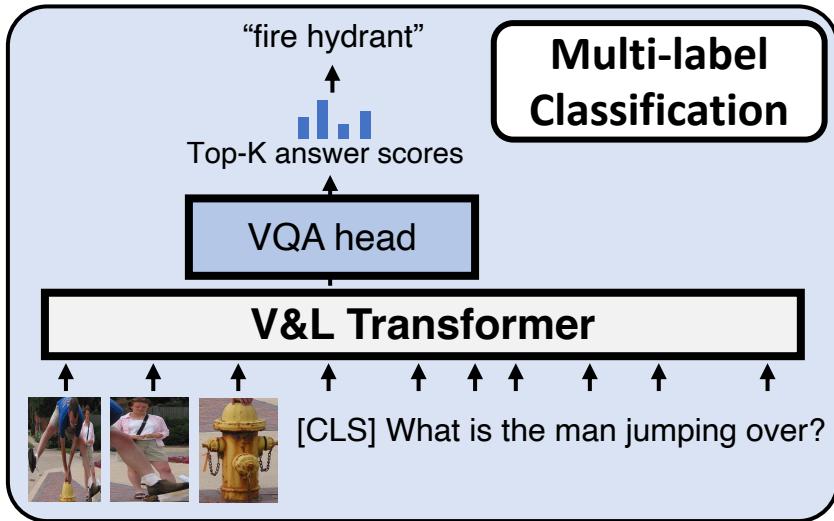


Weights are initialized from off-the-shelf Seq2Seq LMs (e.g., T5)

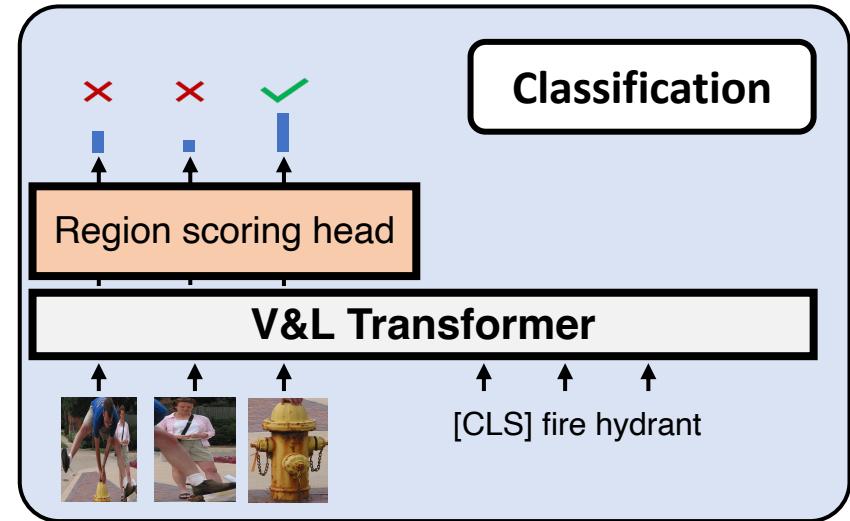
# VL-T5: Many Multimodal Tasks as Text Generation

Previous  
models

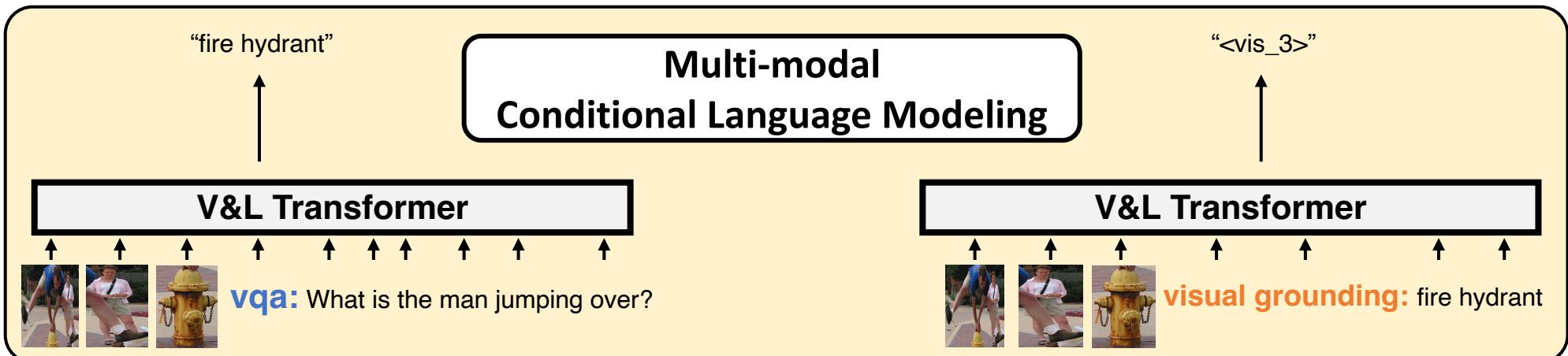
Visual Question Answering



Visual Grounding

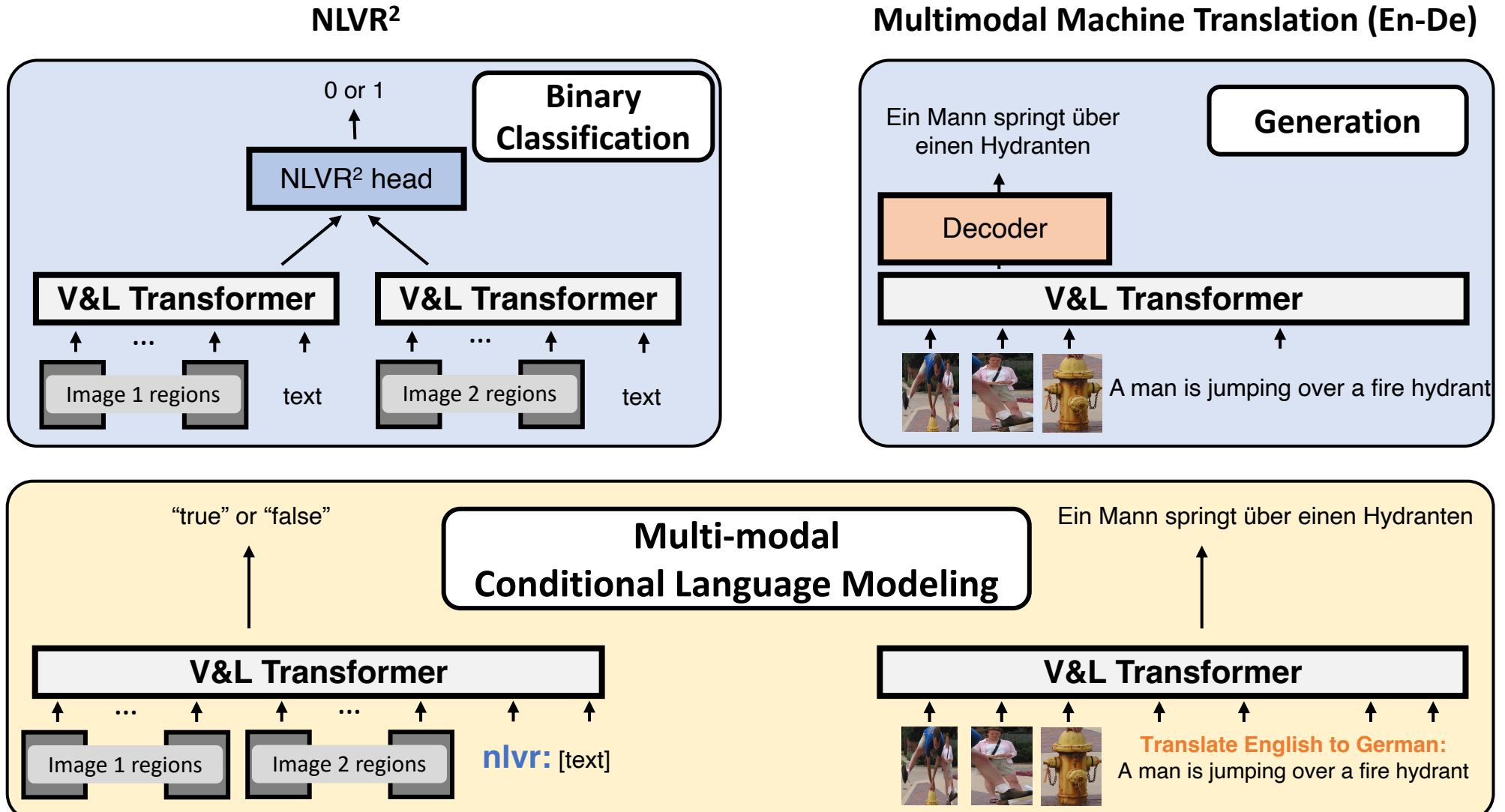


Ours



# VL-T5: Many Multimodal Tasks as Text Generation

Previous  
models



# Unified Architecture Comparable to Specialized Models

Method	# Pretrain Images	Discriminative tasks					Generative tasks		
		VQA test-std Acc	GQA test-std Acc	NLVR <sup>2</sup> test-P Acc	RefCOCOg test <sup>d</sup> Acc	VCR Q→ AR test Acc	COCO Cap Karpathy test CIDEr	Multi30K En-De test 2018 BLEU	
		180K	72.5	60.3	74.5	-	-	-	-
LXMERT	180K	72.5	60.3	74.5	-	-	-	-	-
ViLBERT	3M	70.9	-	-	-	54.8	-	-	-
UNITER <sub>Base</sub>	4M	72.9	-	77.9	74.5	58.2	-	-	-
Unified VLP	3M	70.7	-	-	-	-	117.7	-	-
Oscar <sub>Base</sub>	4M	73.4	61.6	78.4	-	-	123.7	-	-
XGPT	3M	-	-	-	-	-	120.1	-	-
MeMAD	-	-	-	-	-	-	-	38.5	-
VL-T5	180K	70.3	60.8	73.6	71.3	58.9	116.5	38.6	
VL-BART	180K	71.3	60.5	70.3	22.4*	48.9	116.6	28.1	

# Multi-task Learning with Single Shared Set of Parameters

Method	Finetuning tasks	# Params	Discriminative tasks					Generative tasks		
			VQA Karpathy test	GQA test-dev	NLVR <sup>2</sup> test-P	RefCOCOg test <sup>d</sup>	VCR val	COCO Caption Karpathy test	Multi30K En-De	
			Acc	Acc	Acc	Acc	Acc	CIDEr	test2018 BLEU	
VL-T5	single task	7P	67.9	60.0	73.6	71.3	57.5	116.1	38.6	
VL-T5	all tasks	P	67.2	58.9	71.6	69.4	55.3	110.8	37.6	

Similar performance with  $1/7^{\text{th}} = 14\%$  parameters!

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- Also performs better on rare/unseen categories!
- Many follow-up useful works on unification:  
e.g., SimVLM, Flamingo, OFA, UnifiedIO, BLIP-2, CoCa, PaLI, etc.

Wang et al., 2021, SimVLM: Simple Visual Language Model Pretraining with Weak Supervision

Alayrac et al., 2022, Flamingo: a Visual Language Model for Few-Shot Learning

Wang et al., 2022, OFA: Unifying Architectures, Tasks, and Modalities Through a Simple Sequence-to-Sequence Learning Framework

Lu et al., 2022, Unified-IO: A Unified Model for Vision, Language, and Multi-Modal Tasks

Li et al., 2023, BLIP-2: Bootstrapping Language-Image Pre-training with Frozen Image Encoders and Large Language Models

Yu et al., 2022, CoCa: Contrastive Captioners are Image-Text Foundation Models

Chen et al., 2023, PaLI: A Jointly-Scaled Multilingual Language-Image Model

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video modeling without text (audio as images)



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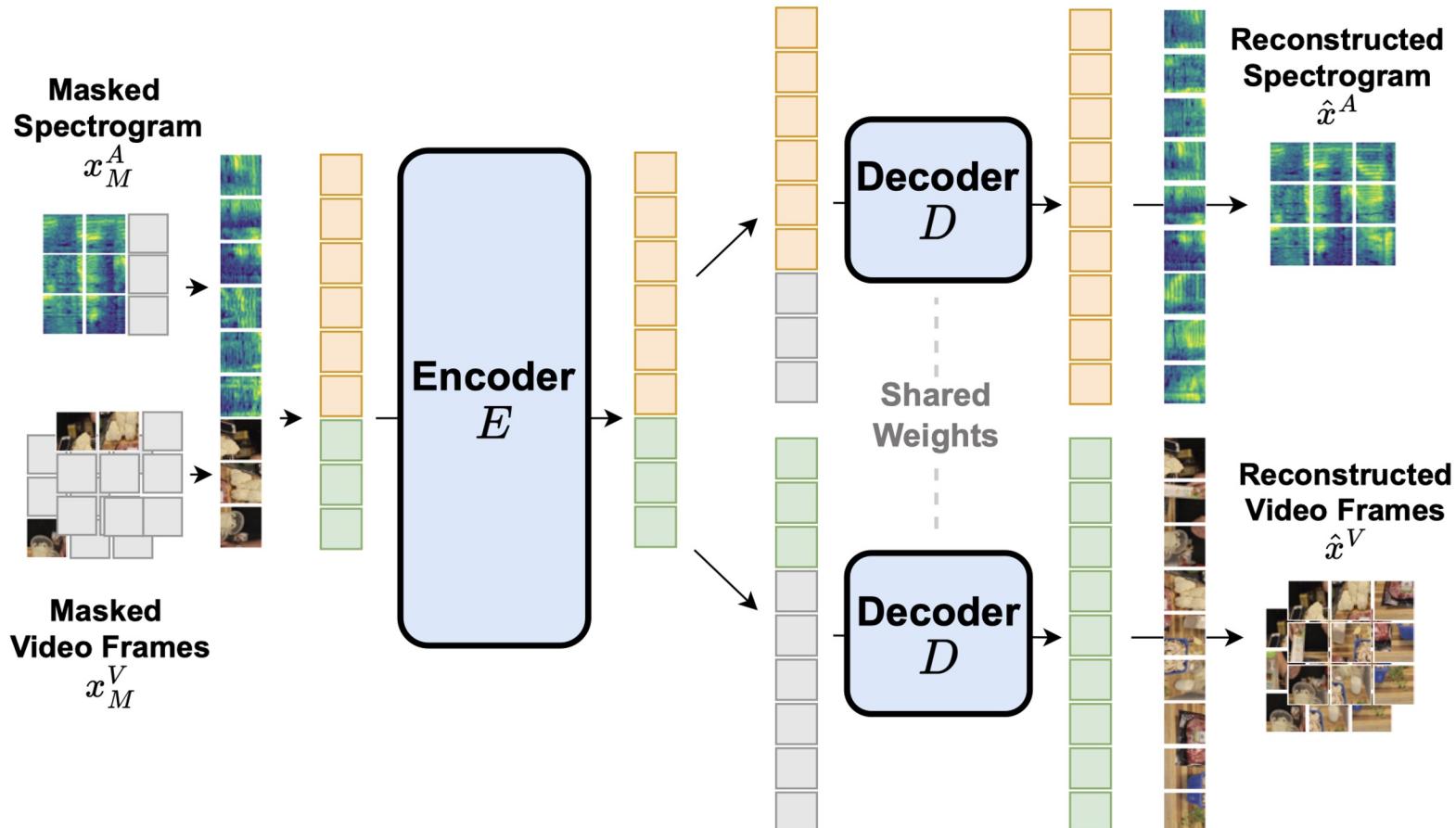
**CoDi (NeurIPS 2023)**

generating any-to-any input-output modality combination



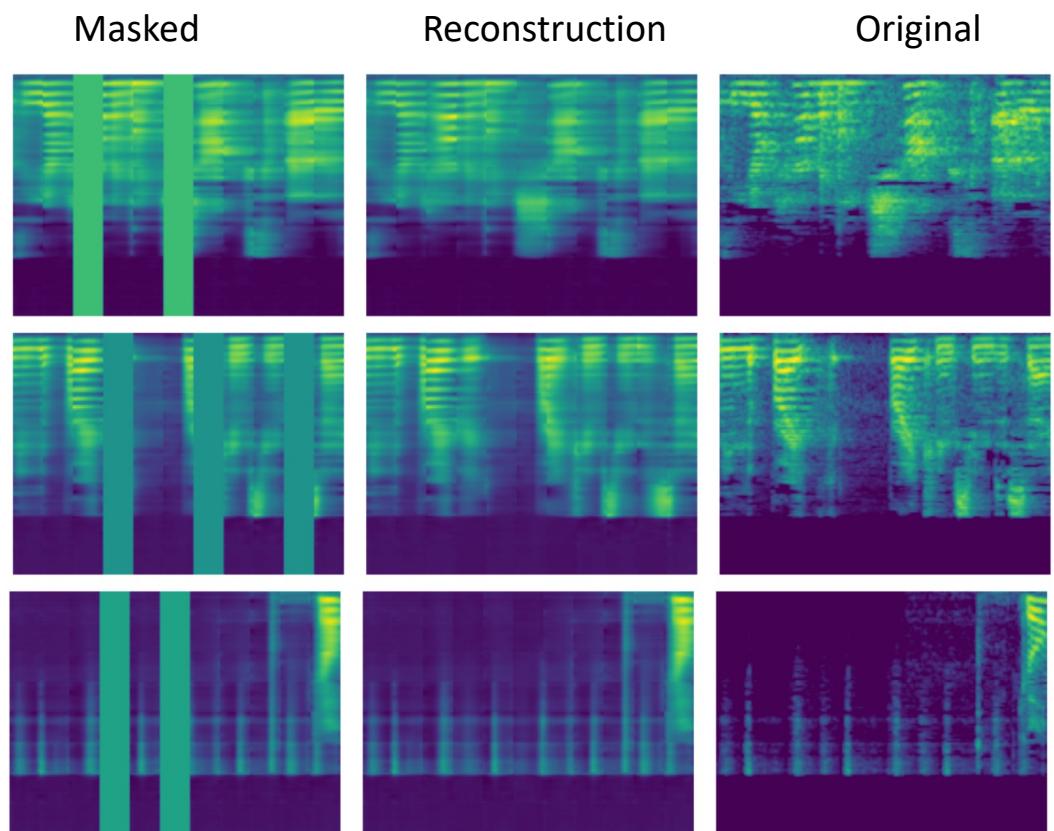
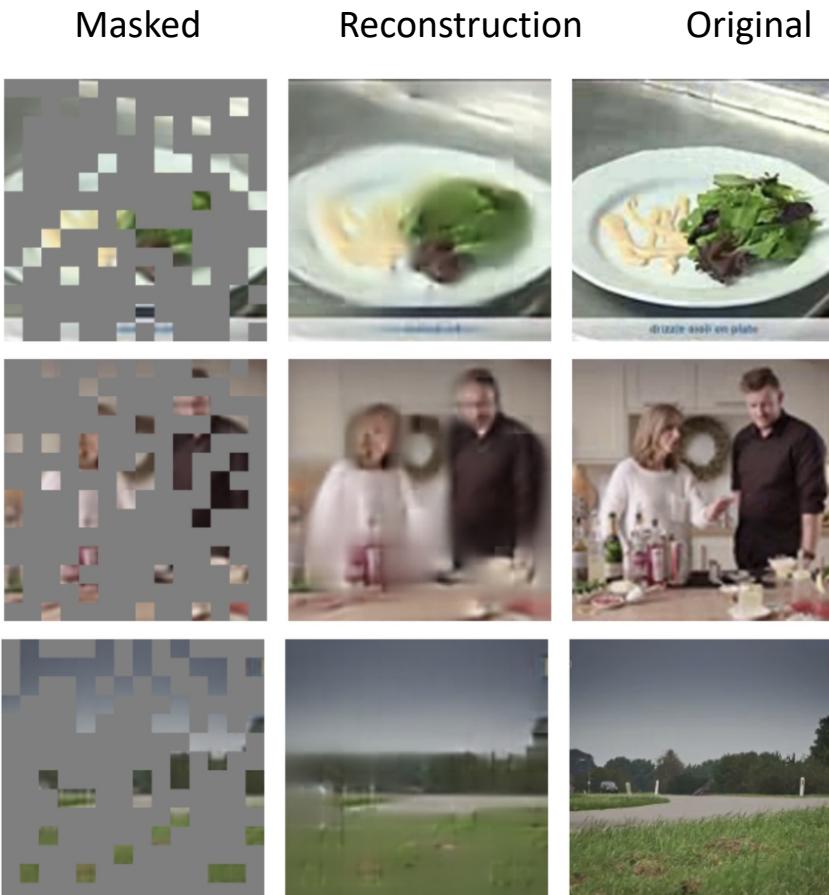
# TVLT: Textless Vision-Language Transformer

- Unified ViT-style patch embeddings for both video and audio inputs
- MAE-style enc-dec: multimodal joint encoder; decoder weights are shared for video & audio decoding
- Two objectives: (1) masked autoencoding, (2) contrastive learning



# TVLT: Textless Vision-Language Transformer

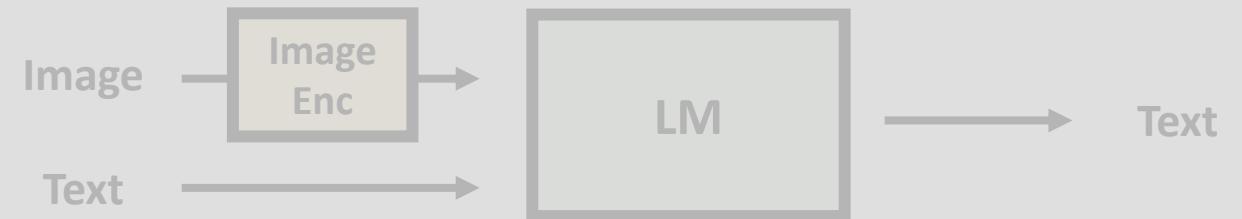
- Results: Audio-based TVLT (**w/o any ASR/tokenization/text modules!**) performs competitively with text-based model on diverse tasks: image-retrieval, video-retrieval, visual-QA, multimodal sentiment analysis, emotion analysis (while also being much more efficient = 28x faster inference, 1/3 #parameters)!



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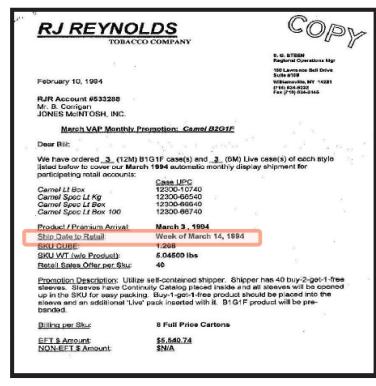
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# UDOP: Unifying Vision, Text, Layout for Universal Document Processing

(even different multi-image / image+text layouts hard to handle!!)

- Unifies text, image, layout modalities (w/o specialized modules incl. OCR or layout-specific architectures) with varied task formats, doing document understanding + generation/editing via masked image reconstruction.



OCR  
Text  
Ship Date to  
...  
Bounding Boxes  
(x0, y0, x1, y2)

Text reconstruction with layout. <text\_layout\_0>  
Retail: Week of March 14, 1994

Visual text recognition. <text\_0>  
<100><350><118><372>  
</text\_0> Week of March 14, 1994

Question answering.  
What is the date?

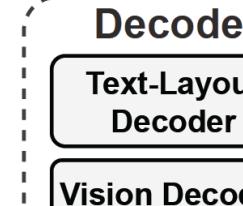
Layout modeling. <layout\_0> Ship Date </layout\_0> to Retail: Week of March 14, 1994

Layout analysis. Title

Masked image reconstruction.  
Ship Date to Retail: Week of March 14, 1994

## Vision-Text-Layout Transformer

### Unified Encoder



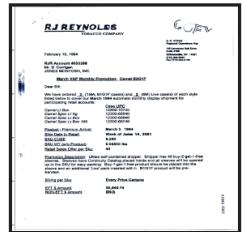
<text\_layout\_0> Ship Date <0><10><2><20>

<text\_0> Ship Date

Week of March 14, 1994

<layout\_0> <100><350><118><372>

Title <20><50><40><80>



### Vision Outputs

Ship Date ...

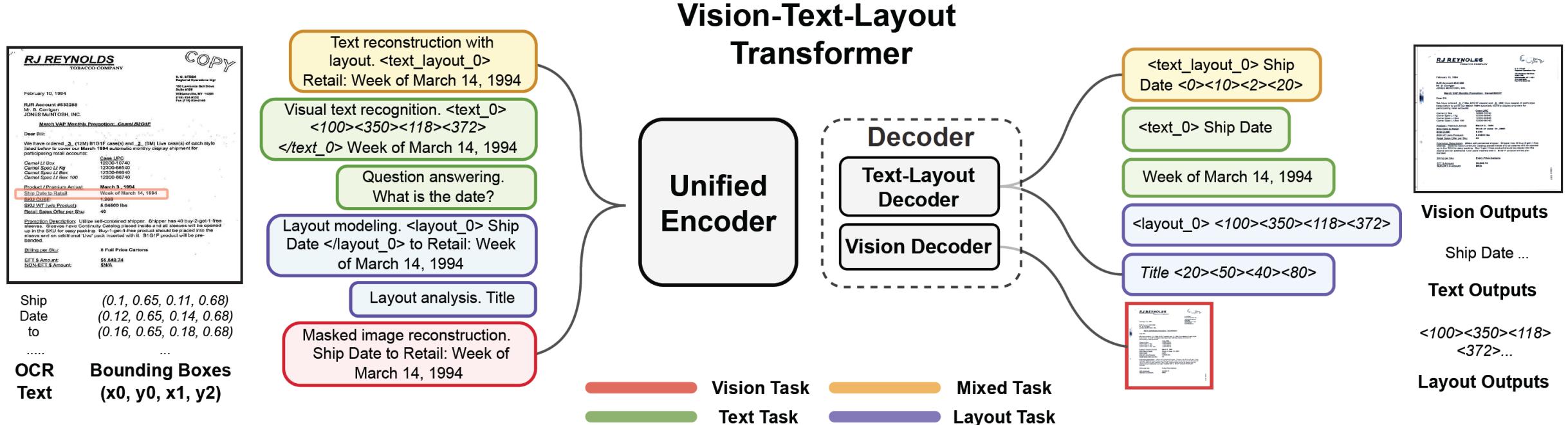
### Text Outputs

<100><350><118><372>...

### Layout Outputs

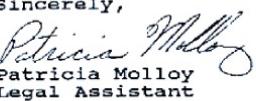
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- Unifies text, image, layout modalities (w/o specialized modules incl. OCR or layout-specific architectures) with varied task formats, doing document understanding + generation/editing via masked image reconstruction.



- State-of-the-art & rank-1 on 8 DocAI tasks / DUE-benchmark, e.g., document-VQA, table-NLI, table-QA, doc-IE, etc. across diverse data domains like finance reports, academic papers, and websites.

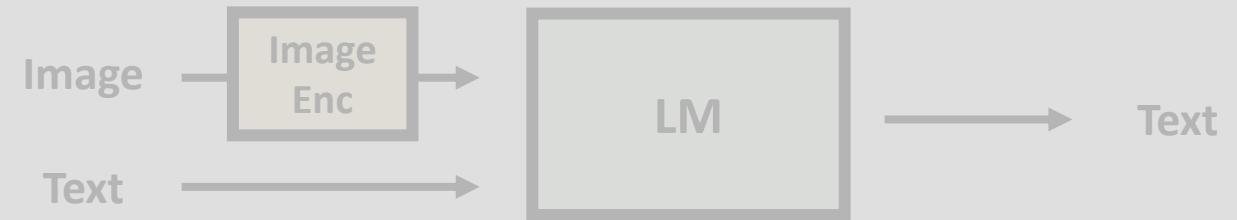
# UDOP: Unifying Vision, Text, Layout for Universal Document Processing

<p> <b>PHILIP MORRIS</b> COMPANIES INC. 120 PARK AVENUE, NEW YORK, N.Y. 10017 • TELEPHONE (212) 880-5000</p> <p>April 19, 1990</p> <p>[Redacted]</p> <p>Mr. Abner T. Herbert, III 9470 Martin Rd. Roswell, GA 30076</p> <p>Dear Mr. Herbert:</p> <p>In accordance with your request, the following are the proponents of Proposals 3 and 4 included in our 1990 Proxy Statement:</p> <table><tr><td><u>Proposal #3</u></td><td>Claim to <u>Beneficially Own</u></td></tr><tr><td>Evangelical Lutheran Church in America 8765 West Higgins Road Chicago, IL</td><td>120,000 shares</td></tr><tr><td>Ed Crane, Director Corporate Social Responsibility</td><td></td></tr><tr><td><u>Proposal #4 (co-sponsored)</u> Adrian Dominican Sisters 1257 East Siena Heights Drive Adrian, MI</td><td>1,098 shares</td></tr><tr><td>Sister Annette M. Sinagra, O.P. Corporate Responsibility Coordinator</td><td></td></tr><tr><td colspan="2">and</td></tr><tr><td>Corporate Responsibility Office Province of Saint Joseph of the Capachin Order 1534 Arch Street Berkeley, CA</td><td>40 shares</td></tr><tr><td>(Rev.) Michael H. Crosby, OFMCap Corporate Responsibility Agent</td><td></td></tr></table> <p>Sincerely,  Patricia Molloy Legal Assistant</p> <p style="text-align: right;">2048130205</p>	<u>Proposal #3</u>	Claim to <u>Beneficially Own</u>	Evangelical Lutheran Church in America 8765 West Higgins Road Chicago, IL	120,000 shares	Ed Crane, Director Corporate Social Responsibility		<u>Proposal #4 (co-sponsored)</u> Adrian Dominican Sisters 1257 East Siena Heights Drive Adrian, MI	1,098 shares	Sister Annette M. Sinagra, O.P. Corporate Responsibility Coordinator		and		Corporate Responsibility Office Province of Saint Joseph of the Capachin Order 1534 Arch Street Berkeley, CA	40 shares	(Rev.) Michael H. Crosby, OFMCap Corporate Responsibility Agent		<p> <b>PHILIP INC</b> COMPANIES INC. 120 PARK AVENUE, NEW YORK, N.Y. 10017 • TELEPHONE (212) 880-5000</p> <p>April 19, 1990</p> <p>The company address below is: <b>Replace Title</b></p> <p>Mr. Abner T. Herbert, III 9470 Martin Rd. Roswell, GA 30076</p> <p>Dear Mr. Herbert:</p> <p>In accordance with your request, the following are the proponents of Proposals 3 and 4 included in our 1990 Proxy Statement:</p> <table><tr><td><u>Proposal #3</u></td><td>Claim to <u>Beneficially Own</u></td></tr><tr><td>Evangelical Lutheran Church in America 8765 West Higgins Road Chicago, IL</td><td>120,000 shares</td></tr><tr><td>Ed Crane, Director Corporate Social Responsibility</td><td></td></tr><tr><td><u>Proposal #4 (by UDOP)</u> Some random name. Some random street. Some random city, state.</td><td>1,098 shares</td></tr><tr><td>Sister Annette M. Sinagra, O.P. Corporate Responsibility Coordinator</td><td></td></tr><tr><td colspan="2">and</td></tr><tr><td>Corporate Responsibility Office Province of Saint Joseph of the Capachin Order 1534 Arch Street Berkeley, CA</td><td>40 shares</td></tr><tr><td>(Rev.) Michael H. Crosby, OFMCap Corporate Responsibility Agent</td><td></td></tr></table> <p>Sincerely,  Patricia Molloy Legal Assistant</p> <p style="text-align: right;">2048936486</p>	<u>Proposal #3</u>	Claim to <u>Beneficially Own</u>	Evangelical Lutheran Church in America 8765 West Higgins Road Chicago, IL	120,000 shares	Ed Crane, Director Corporate Social Responsibility		<u>Proposal #4 (by UDOP)</u> Some random name. Some random street. Some random city, state.	1,098 shares	Sister Annette M. Sinagra, O.P. Corporate Responsibility Coordinator		and		Corporate Responsibility Office Province of Saint Joseph of the Capachin Order 1534 Arch Street Berkeley, CA	40 shares	(Rev.) Michael H. Crosby, OFMCap Corporate Responsibility Agent	
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# Part 1: Unified/Universal Multimodal Learning

**VL-T5 (ICML 2021)**

all multimodal tasks via text generation



**TVLT (NeurIPS 2022)**

video modeling without text (audio as images)



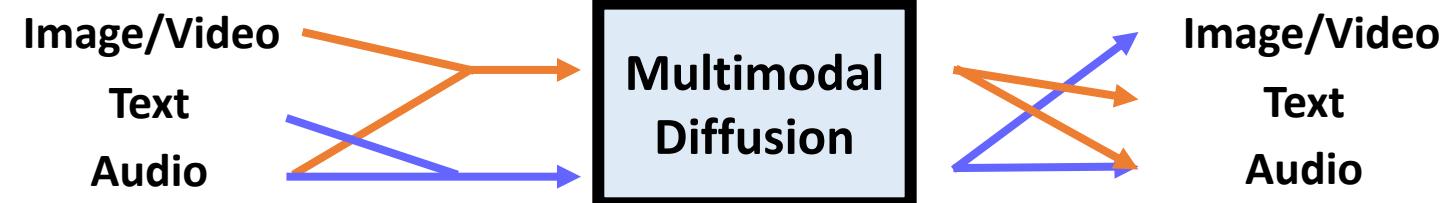
**UDOP (CVPR 2023)**

document image/text/layout with single architecture

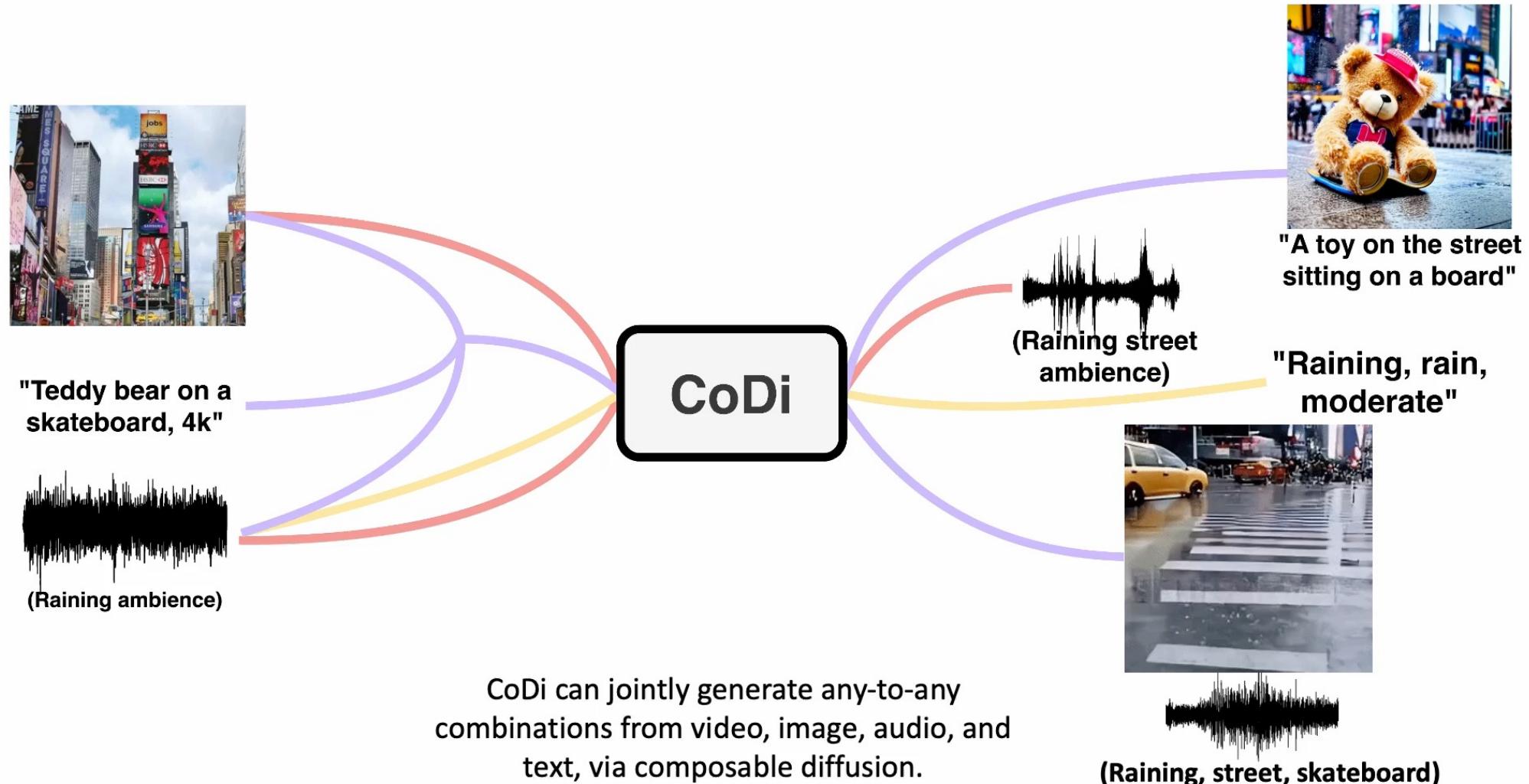


**CoDi (NeurIPS 2023)**

generating any-to-any input-output modality combination



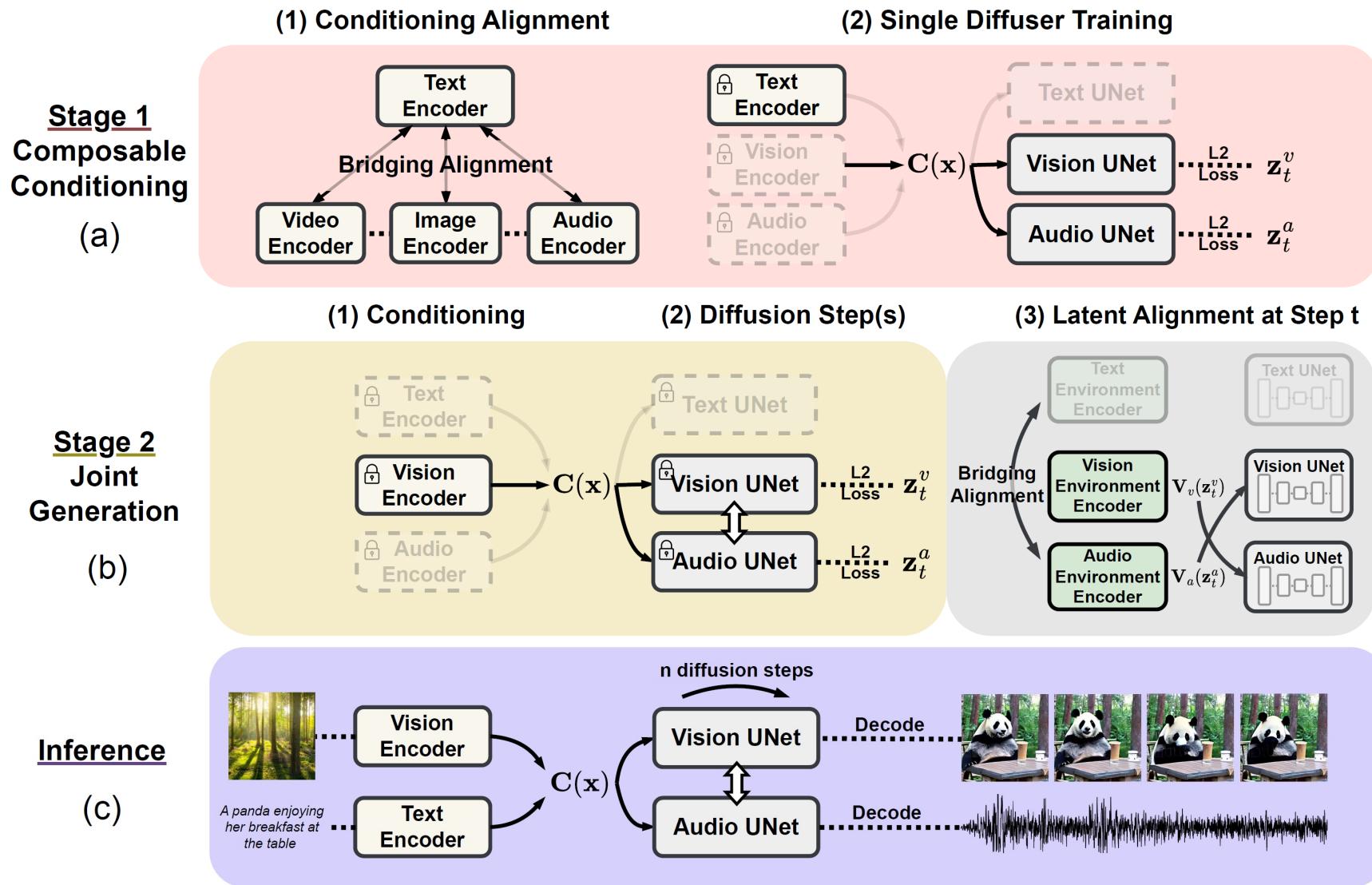
# CoDi: Any-to-Any Multimodal Generation



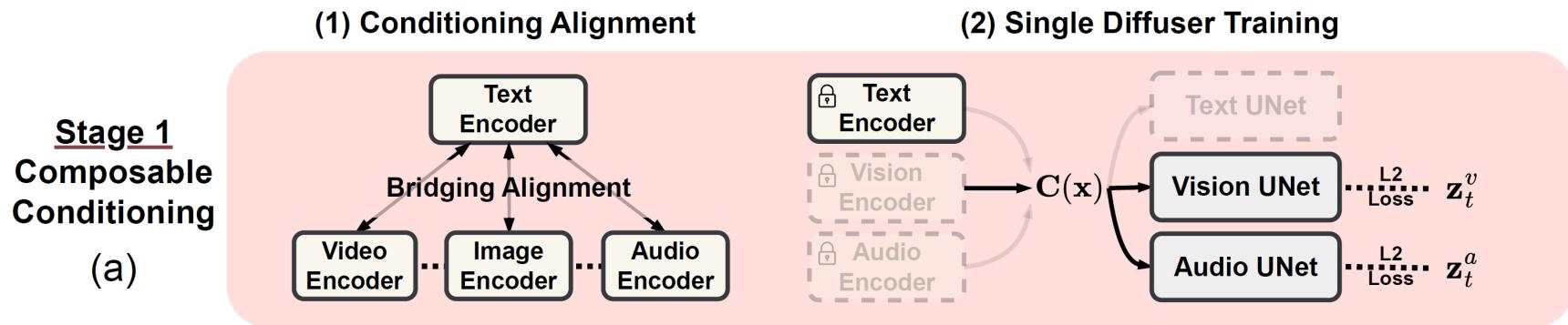
# CoDi: Any-to-Any Multimodal Generation

- New generative-AI foundation model that allows **any combination of input modalities & generates any combination of output modalities** (text, audio, image, video) – can help create diverse ‘**many-modal**’ stories using different types of inputs on the storyboard!
- **BUT** training such a model presents **significant costs**, as the # combinations for input and output modalities scales **exponentially** & training datasets **missing** for many combinations of modalities.
- We propose “**Bridging Alignment**” strategy to **efficiently model the exponential number** of input-output combinations with a **linear number** of training objectives.
- Allows CoDi to freely condition on any input combination+generate any group of modalities, even if **not present in the training data**.

# CoDi: Any-to-Any Multimodal Generation

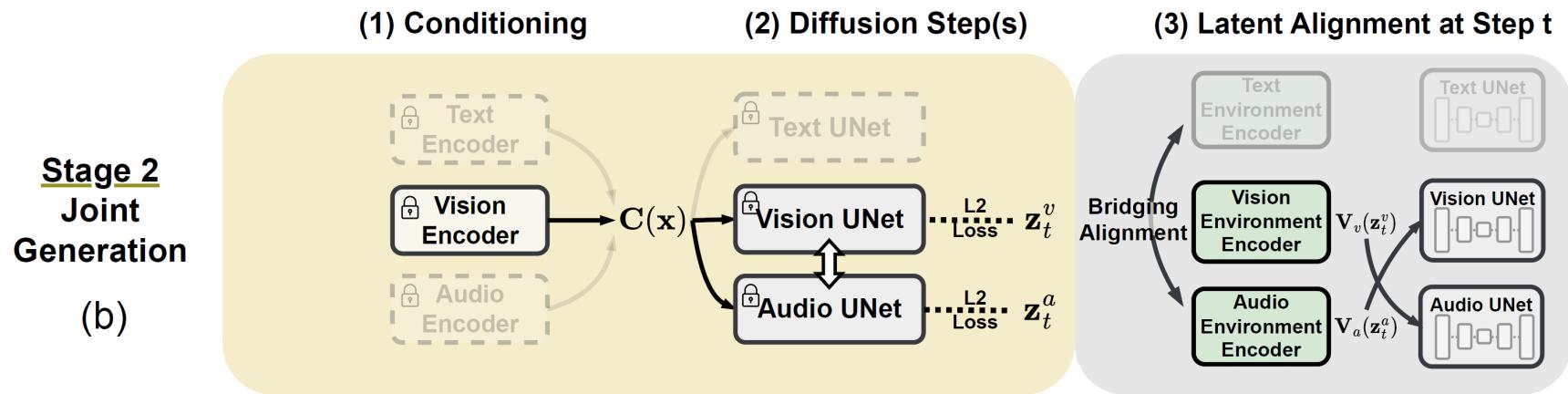


# CoDi: Any-to-Any Multimodal Generation



- **Stage 1:** We train a **latent diffusion model (LDM)** for each modality. They can be trained **independently**, ensuring high-quality generation for each modality. For conditional generation, e.g., *audio+language*→*image*, the input modalities are projected into a **shared feature space**, and the **output LDM attends to this combination of input features**.
- This multimodal conditioning mechanism prepares the diffusion model to **condition on any combination of modalities without directly training** for such settings.

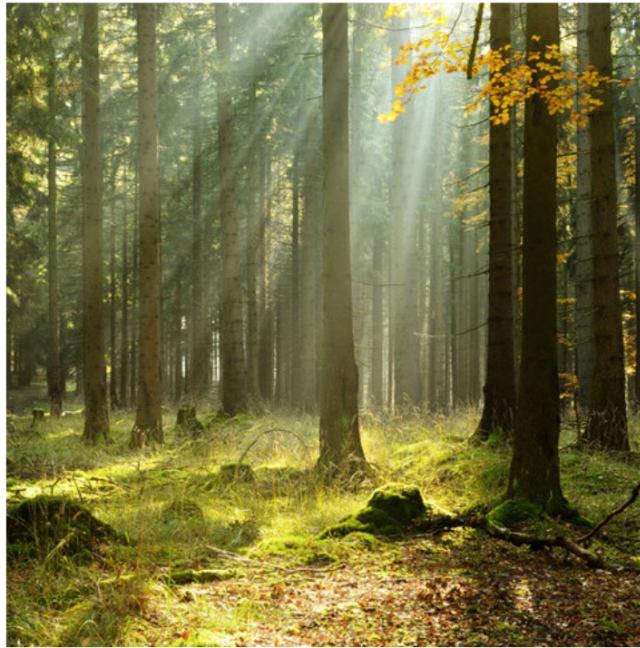
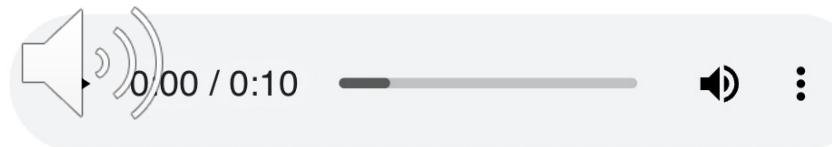
# CoDi: Any-to-Any Multimodal Generation



- **Stage 2:** We add a **cross-attention module** to each LDM and an **environment encoder** to project the **LDM latent variables into a shared/mixed space**.
- This enables CoDi to seamlessly **mix/generate any group of output modalities, w/o training** on all generation combinations (with linear # training objectives).

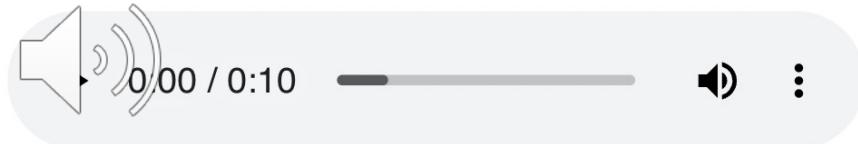
# CoDi: Any-to-Any Multimodal Generation

Audio + Image → Text + Image



# CoDi: Any-to-Any Multimodal Generation

Audio + Image → Text + Image



"Playing piano in a forest."



# CoDi: Any-to-Any Multimodal Generation

Text + Image → Video

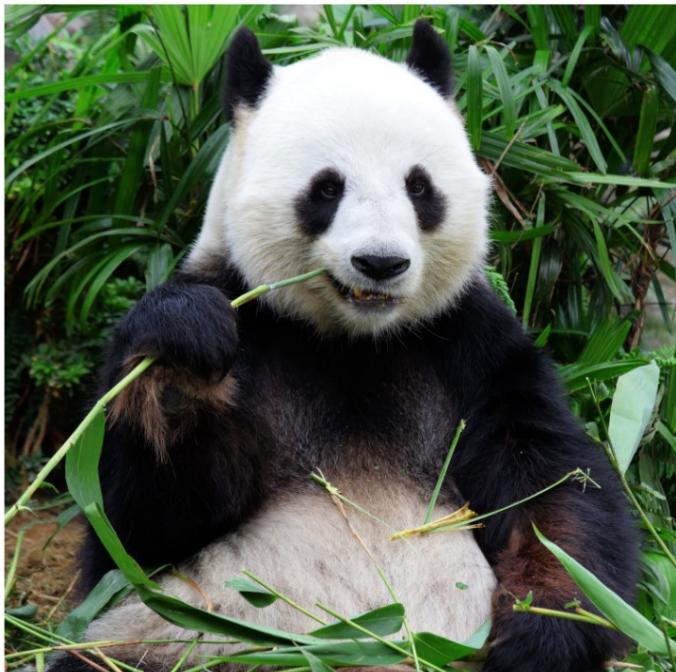
"Eating on a coffee table."



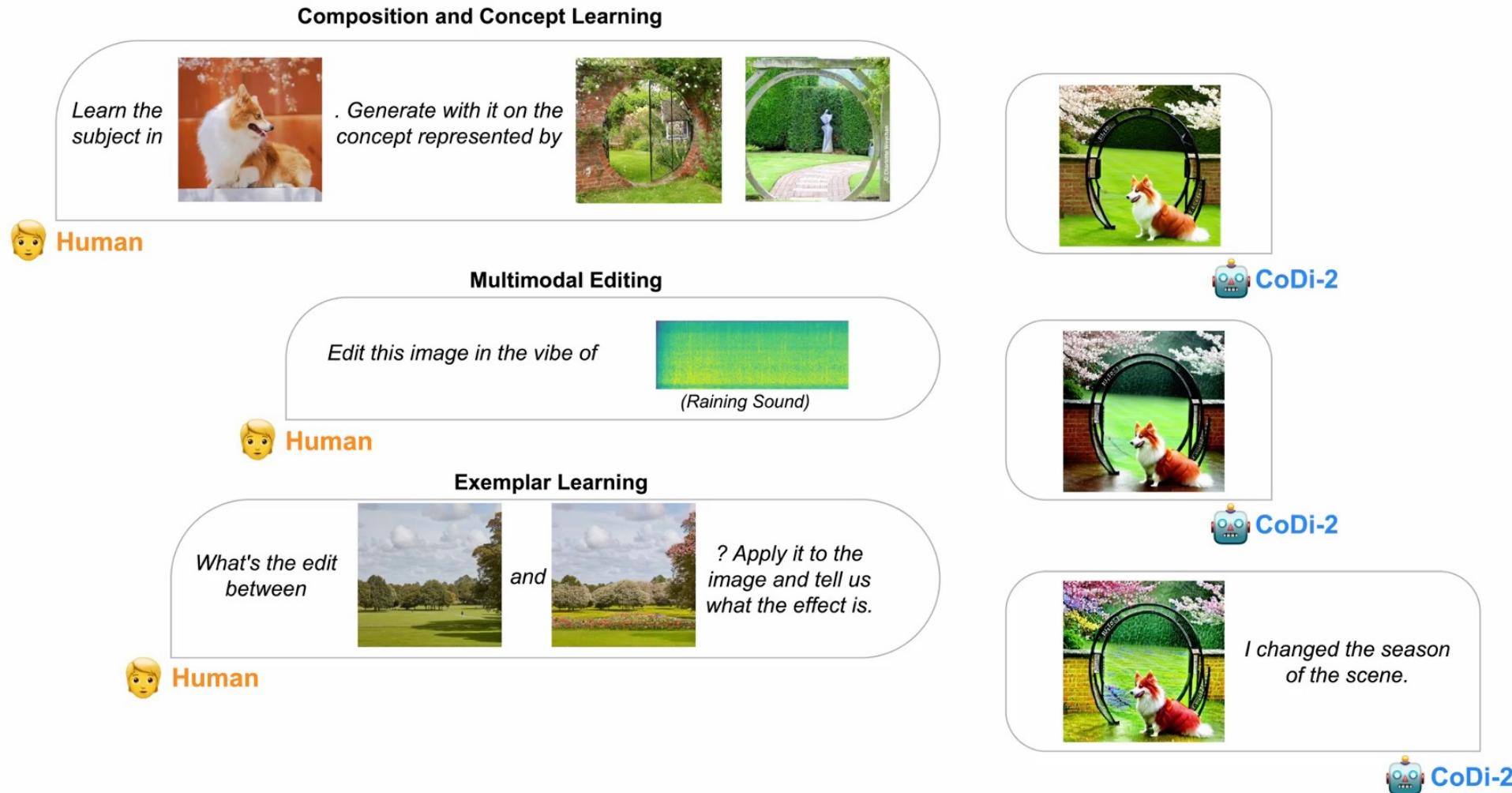
# CoDi: Any-to-Any Multimodal Generation

Text + Image → Video

"Eating on a coffee table."

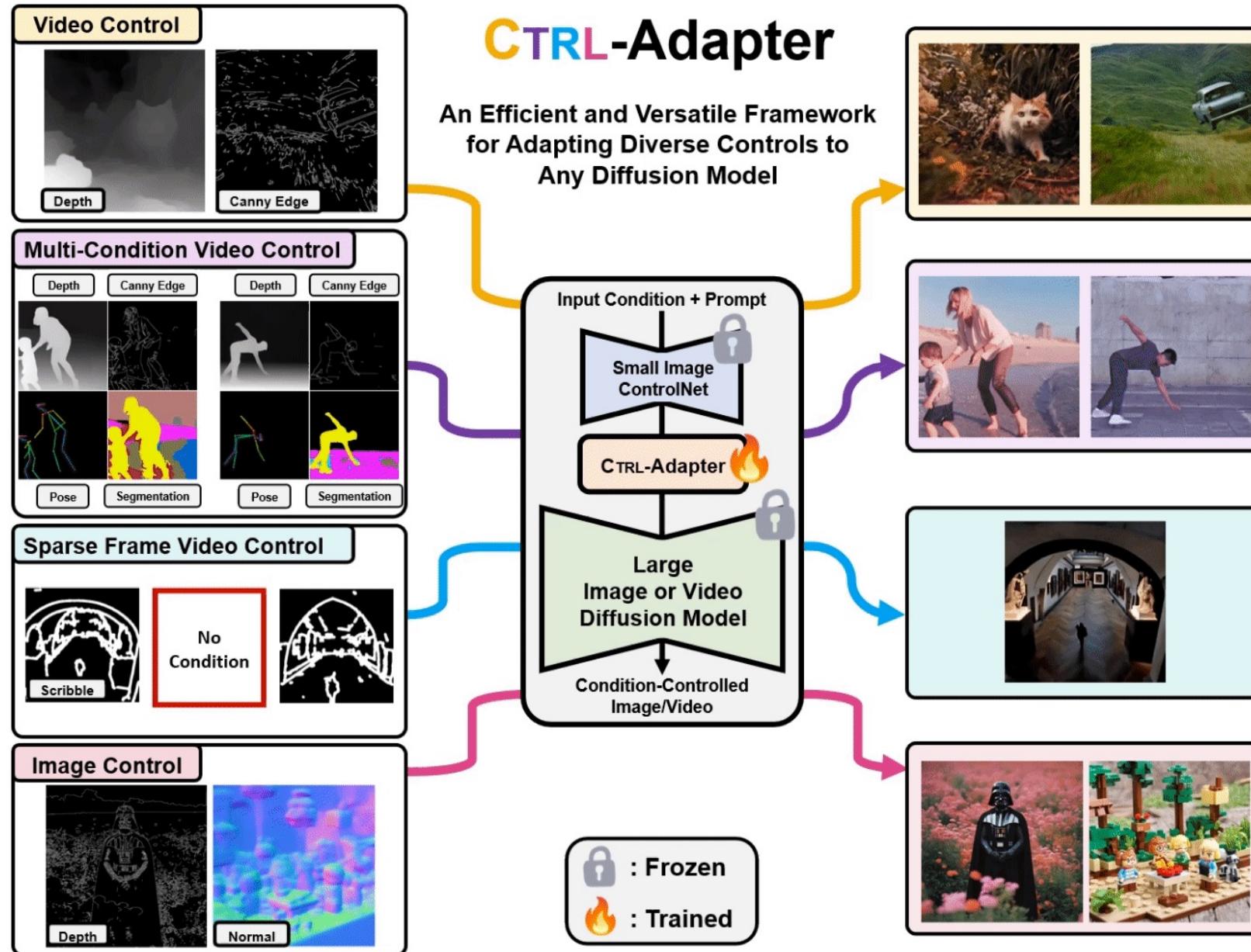


# CoDi-2: Interleaved & Interactive Any-to-Any Generation (allows Reasoning)



CoDi-2: In-Context, Interleaved, and Interactive Any-to-Any Generation

# CTRL-Adapter: Efficient+Versatile Adaptation of Any Control to Any Diffusion



# Talk Outline

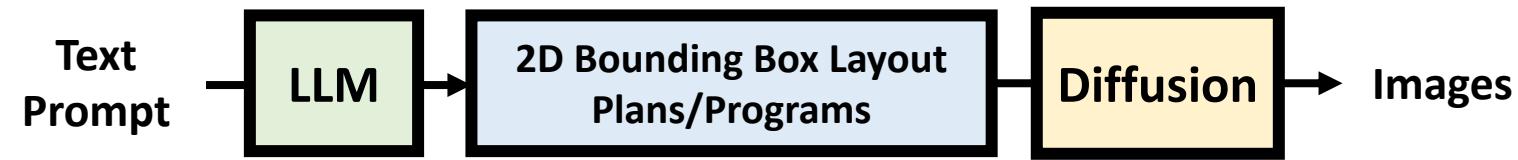
A journey of multimodal generative models for enhancing their unification, interpretable planning/programming, evaluation:

- **Unified/Universal Multimodal Learning** (for Generalizability, Shared Knowledge, Efficiency)
  - VLT5: Unifying Vision-and-Language Tasks via Text Generation [\[ICML 2021\]](#)
  - TVLT: Textless Vision-Language Transformer [\[NeurIPS 2022\]](#)
  - UDOP: Unifying Vision, Text, and Layout for Universal Document Processing [\[CVPR 2023\]](#)
  - CoDi: Any-to-Any Generation via Composable Diffusion [\[NeurIPS 2023\]](#) & CoDi-2: In-Context, Interleaved, and Interactive Any-to-Any Generation [\[CVPR 2024\]](#)
- **Interpretable Multimodal Generation via LLM Planning/Programming Agents** (for Understanding, Control, Faithfulness, OOD)
  - VPGen: Step-by-Step Text-to-Image Generation with Interpretable Visual Programming [\[NeurIPS 2023\]](#)
  - VideoDirectorGPT: Consistent Multi-Scene Video Generation via LLM-Guided Planning [\[COLM 2024\]](#)
  - DiagrammerGPT: Generating Diagrams via LLM Planning [\[COLM 2024\]](#); EnvGen: Adapting Environments via LLMs for Training Embodied Agents [\[COLM 2024\]](#)
- **Evaluation of Multimodal Generation Models** (of Fine-grained Skills, Faithfulness, Social Biases)
  - DALL-Eval: Probing the Reasoning Skills and Social Biases of Text-to-Image Generation Models [\[ICCV 2023\]](#)
  - VPEval: Step-by-Step Text-to-Image Evaluation with Interpretable Visual Programming [\[NeurIPS 2023\]](#)
  - Davidsonian Scene Graph: Improving Reliability in Fine-grained Evaluation for Text-to-Image Generation [\[ICLR 2024\]](#)
- **Next Big Challenges:** trade-offs, structure, non-verbal, interaction, reasoning, causality, long-distance fine-grained evaluation, efficiencies

## Part 2: Interpretable Multimodal Generation with LLM Planning/Reasoning

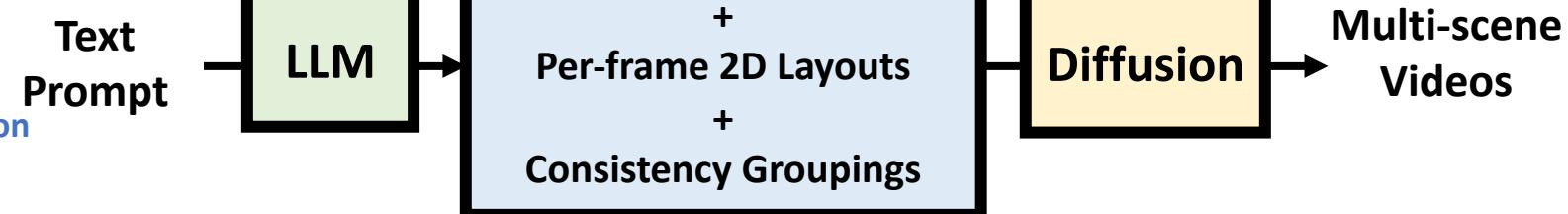
### VPGen (NeurIPS 2023)

LLM Planning for Image Generation



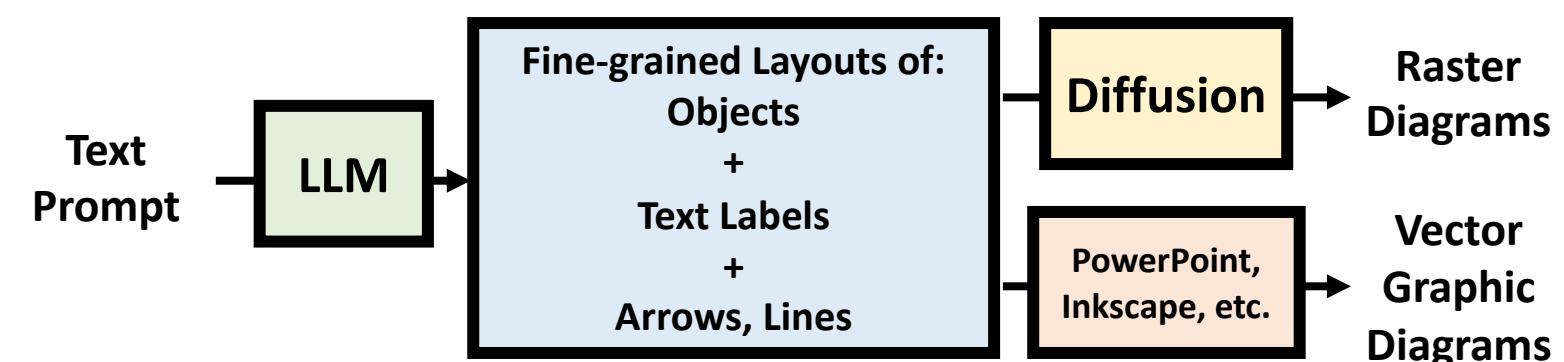
### VideoDirectorGPT (COLM 2024)

LLM Planning for Multi-Scene, Consistent Video Generation

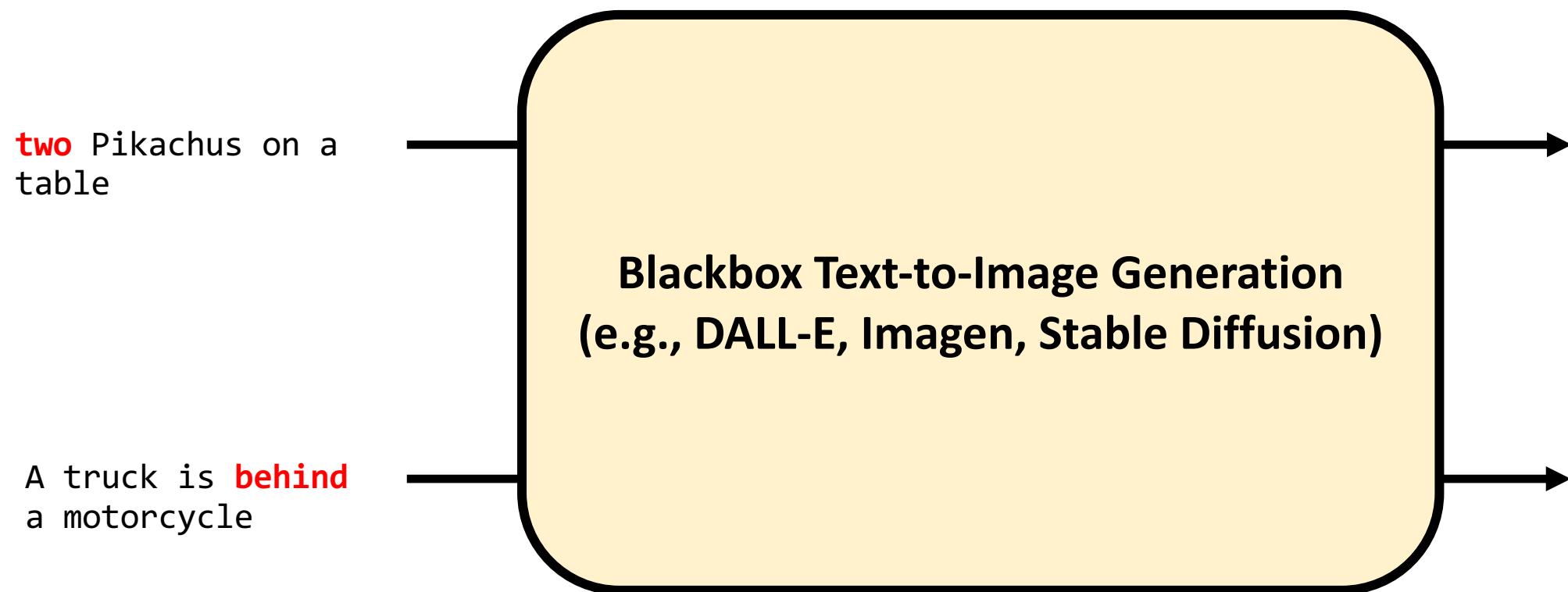


### DiagrammerGPT (COLM 2024)

LLM Planning for Open-Domain Diagram Generation



# Background: Text-to-Image Generation with Blackbox Models



# Background: Text-to-Image Generation with Blackbox Models

two Pikachus on a table

**Good visual quality! But important semantic issues...**

- lack of fine-grained layout planning/control
- lack of interpretability behind generation process
- lack of faithfulness to input (incl. hallucinations and OOD scenarios)



A truck is **behind** a motorcycle



one Pikachu ✗

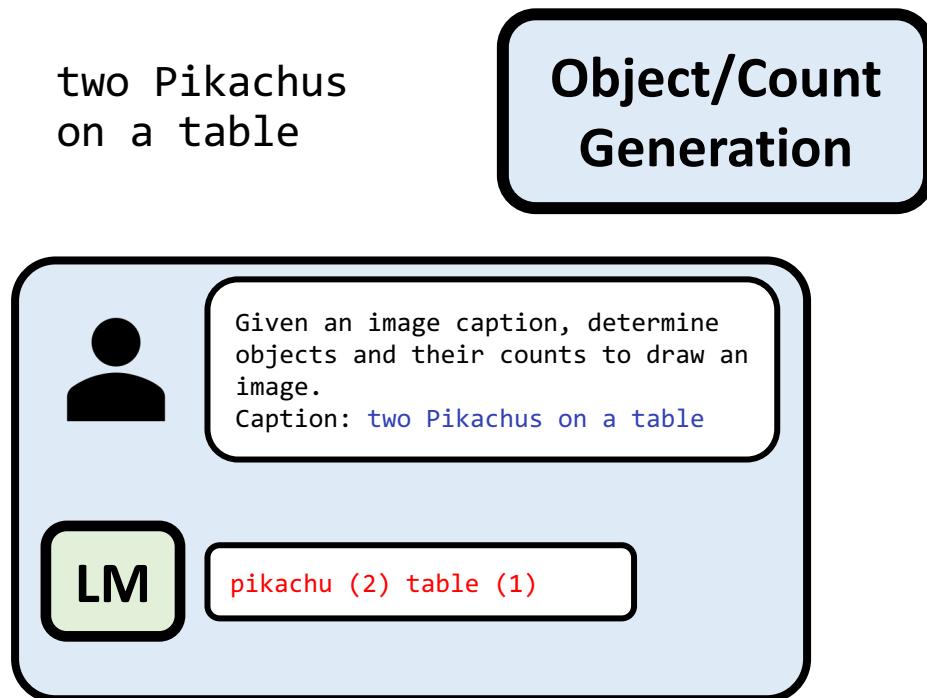


truck is **below** motorcycle ✗

# VPGen: Visual Programming for Step-by-Step T2I Generation

two Pikachu  
on a table

# VPGen: Visual Programming for Step-by-Step T2I Generation



# VPGen: Visual Programming for Step-by-Step T2I Generation

two Pikachu  
on a table

## Object/Count Generation



Given an image caption, determine  
objects and their counts to draw an  
image.  
Caption: two Pikachu on a table

LM

pikachu (2) table (1)

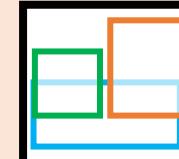
## Layout Generation



Given an image caption and objects,  
determine coordinates of the objects.  
Caption: two Pikachu on a table  
Objects: pikachu (2) table (1)

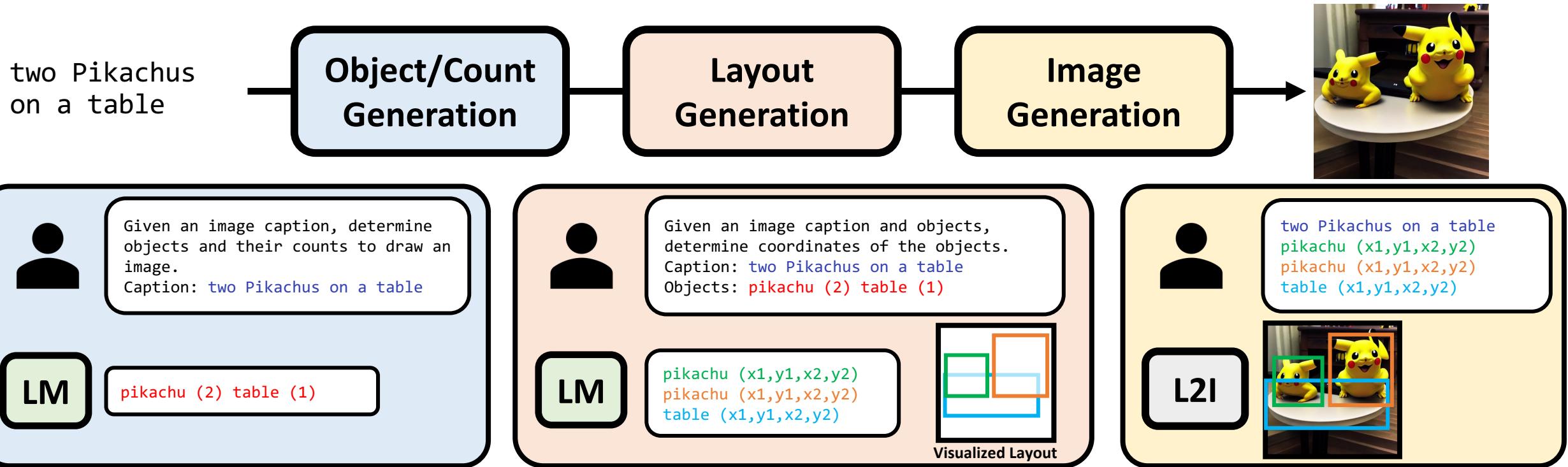
LM

pikachu (x1,y1,x2,y2)  
pikachu (x1,y1,x2,y2)  
table (x1,y1,x2,y2)



Visualized Layout

# VPGen: Visual Programming for Step-by-Step T2I Generation



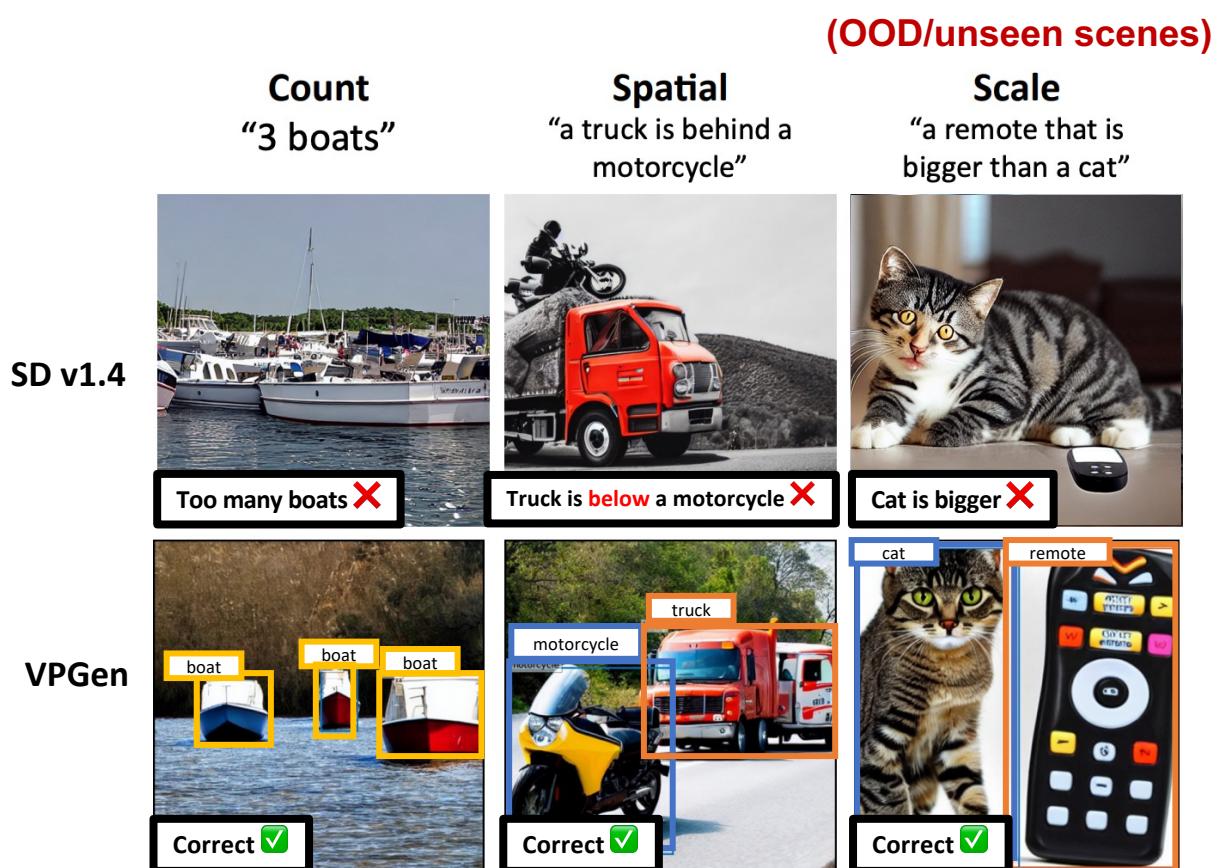
# Skill-based Results

Our VPGen shows improved spatial control

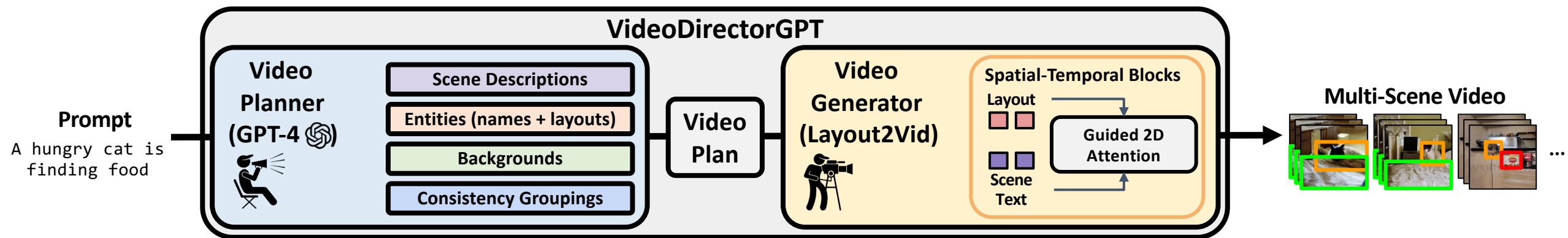
- Generation via layout programs promotes better **understanding+planning** of structure/scale/spatial relations, including **out-of-distribution/unseen** cases (also allows **explicit control** over these properties via manual, **interpretable corrections of unfaithful parts**)!

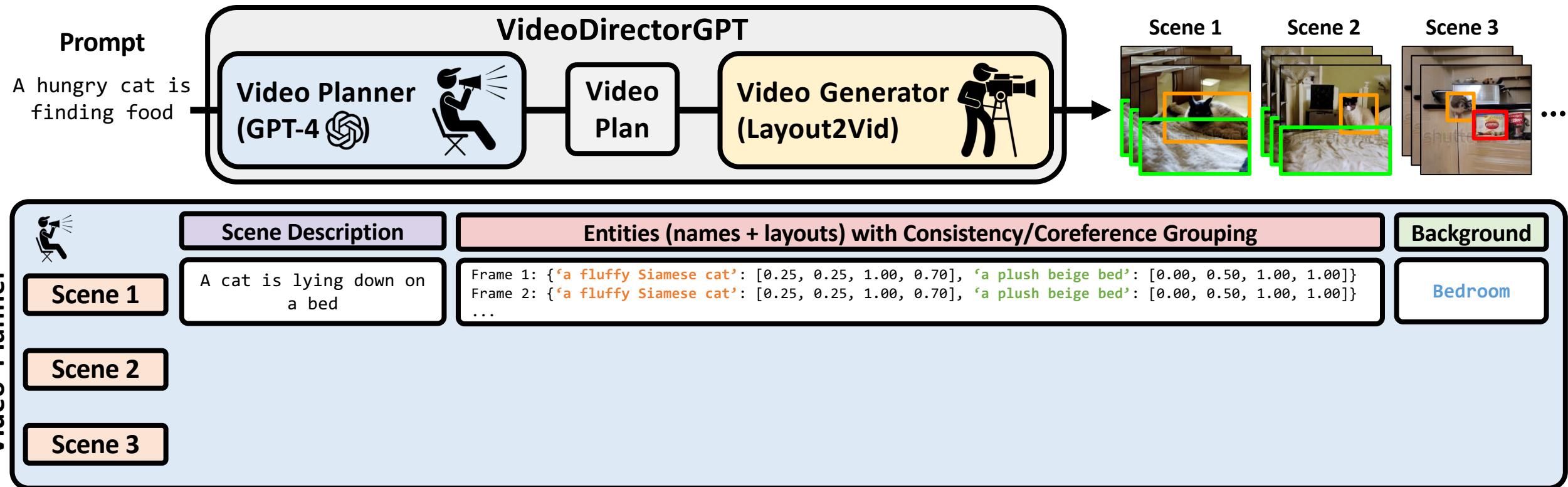
Model	VPEVAL Skill Score (%) ↑					
	Object	Count	Spatial	Scale	Text Rendering	Average
Stable Diffusion v1.4	97.3	47.4	22.9	11.9	8.9	37.7
Stable Diffusion v2.1	96.5	53.9	31.3	14.3	6.9	40.6
Karlo	95.0	59.5	24.0	16.4	8.9	40.8
minDALL-E	79.8	29.3	7.0	6.2	0.0	24.4
DALL-E Mega	94.0	45.6	17.0	8.5	0.0	33.0
VPGEN (F30)	96.8	55.0	39.0	23.3	5.2	43.9
VPGEN (F30+C+P)	96.8	72.2	56.1	26.3	3.7	51.0

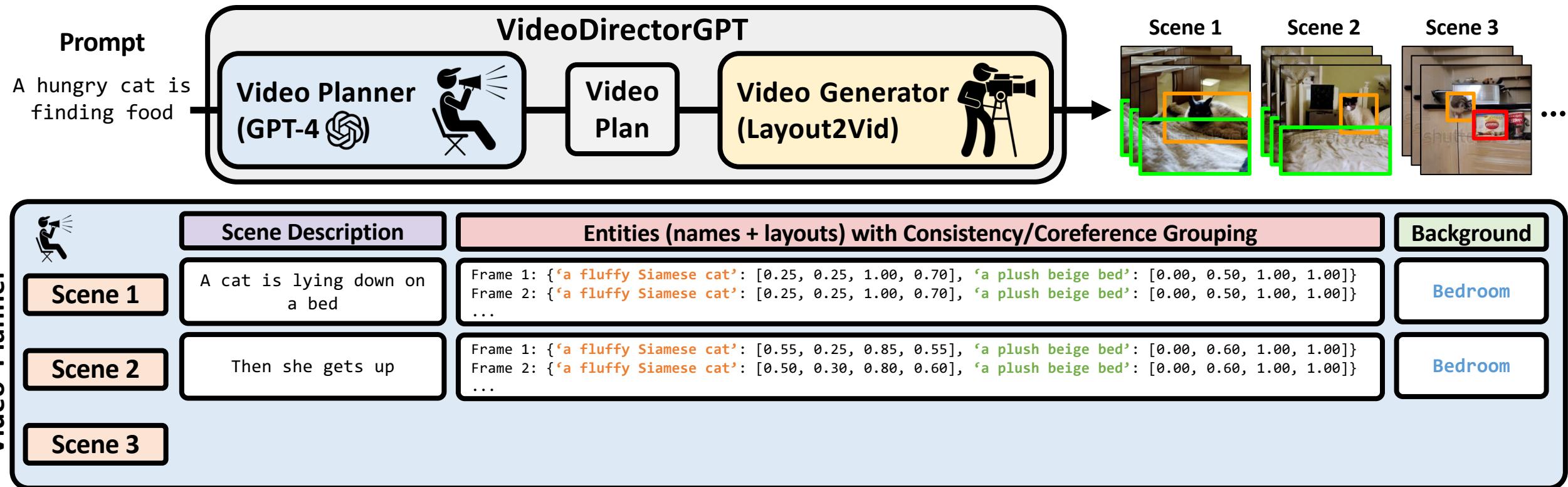
Large improvements on structural control:  
- Counting  
- Spatial relation  
- Relative size/scale comparison

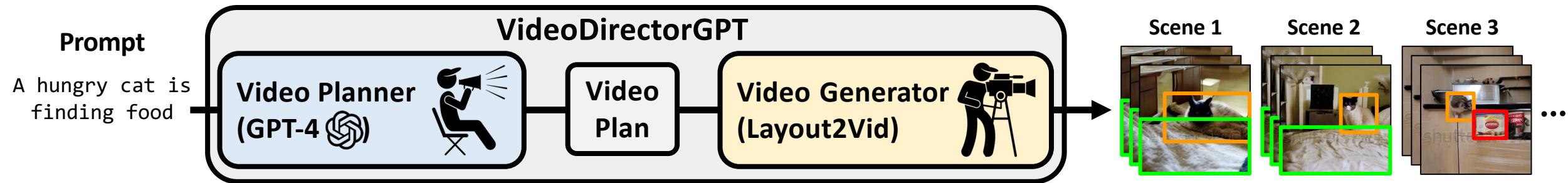


# VideoDirectorGPT: Consistent Multi-Scene Video Generation via LLM-Guided Planning/Reasoning



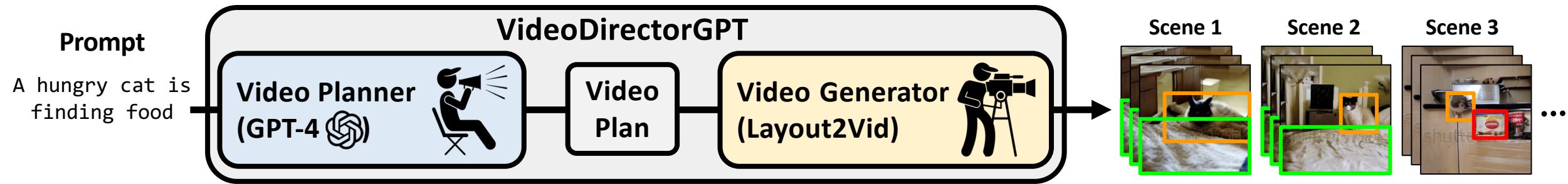






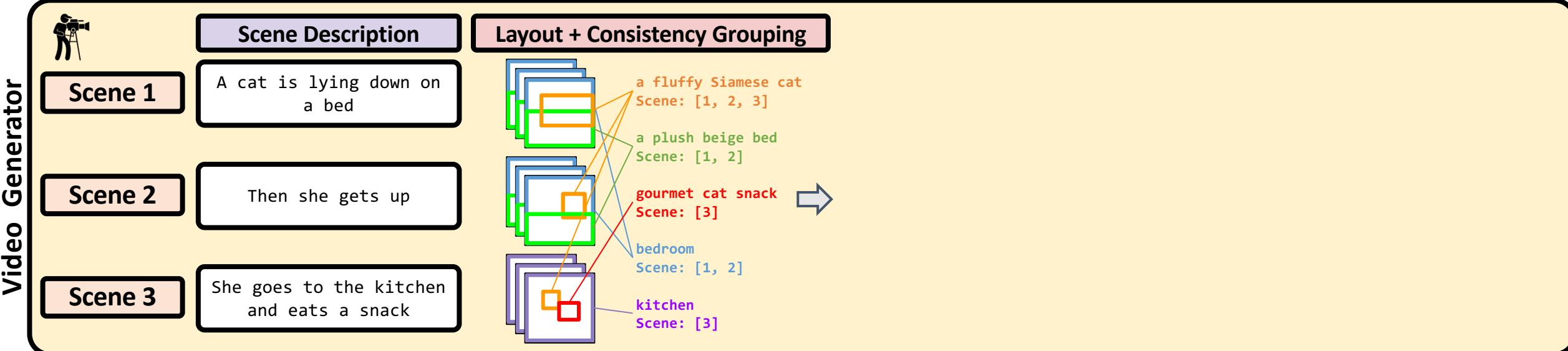
**Video Planner**

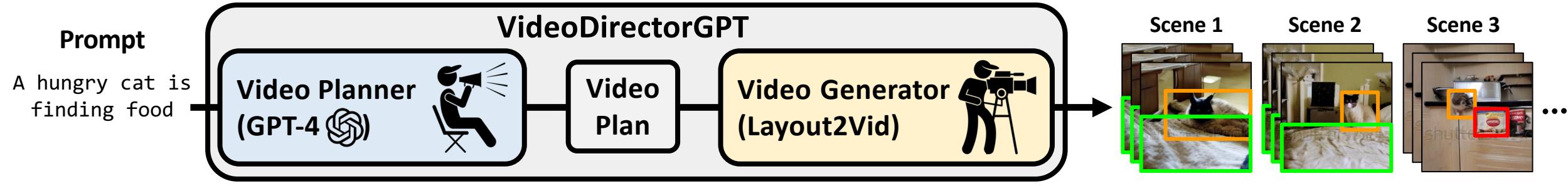
	<b>Scene Description</b>	<b>Entities (names + layouts) with Consistency/Coreference Grouping</b>	<b>Background</b>
<b>Scene 1</b>	A cat is lying down on a bed	Frame 1: {'a fluffy Siamese cat': [0.25, 0.25, 1.00, 0.70], 'a plush beige bed': [0.00, 0.50, 1.00, 1.00]} Frame 2: {'a fluffy Siamese cat': [0.25, 0.25, 1.00, 0.70], 'a plush beige bed': [0.00, 0.50, 1.00, 1.00]} ...	<b>Bedroom</b>
<b>Scene 2</b>	Then she gets up	Frame 1: {'a fluffy Siamese cat': [0.55, 0.25, 0.85, 0.55], 'a plush beige bed': [0.00, 0.60, 1.00, 1.00]} Frame 2: {'a fluffy Siamese cat': [0.50, 0.30, 0.80, 0.60], 'a plush beige bed': [0.00, 0.60, 1.00, 1.00]} ...	<b>Bedroom</b>
<b>Scene 3</b>	She goes to the kitchen and eats a snack	Frame 1: {'a fluffy Siamese cat': [0.15, 0.20, 0.40, 0.45], 'gourmet cat snack': [0.50, 0.45, 0.80, 0.65]} Frame 2: {'a fluffy Siamese cat': [0.35, 0.30, 0.60, 0.55], 'gourmet cat snack': [0.50, 0.45, 0.80, 0.65]} ...	<b>Kitchen</b>



**Video Planner**

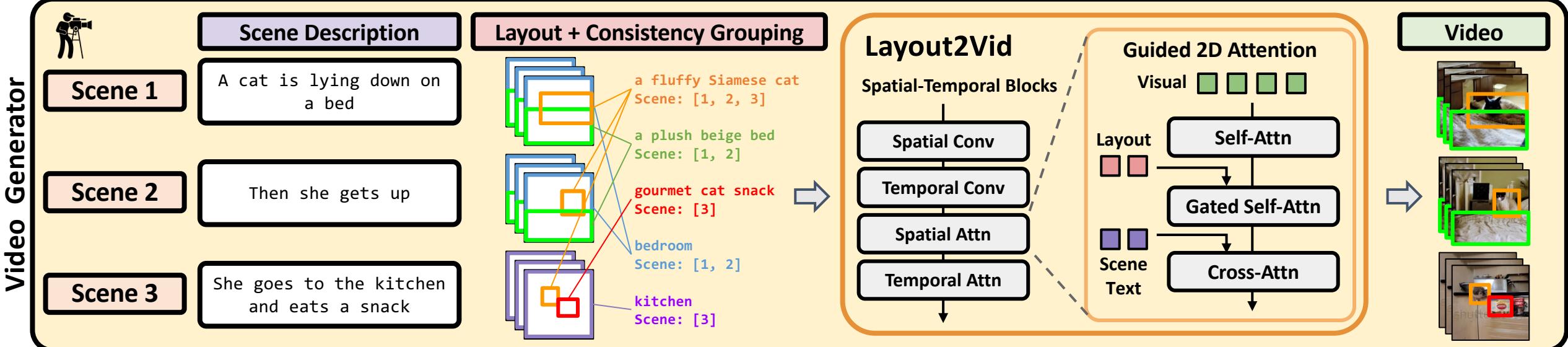
Scene Description	Entities (names + layouts) with Consistency/Coreference Grouping	Background
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<b>Scene 2</b> Then she gets up	Frame 1: { <b>a fluffy Siamese cat</b> : [0.55, 0.25, 0.85, 0.55], <b>a plush beige bed</b> : [0.00, 0.60, 1.00, 1.00]} Frame 2: { <b>a fluffy Siamese cat</b> : [0.50, 0.30, 0.80, 0.60], <b>a plush beige bed</b> : [0.00, 0.60, 1.00, 1.00]} ...	<b>Bedroom</b>
<b>Scene 3</b> She goes to the kitchen and eats a snack	Frame 1: { <b>a fluffy Siamese cat</b> : [0.15, 0.20, 0.40, 0.45], <b>gourmet cat snack</b> : [0.50, 0.45, 0.80, 0.65]} Frame 2: { <b>a fluffy Siamese cat</b> : [0.35, 0.30, 0.60, 0.55], <b>gourmet cat snack</b> : [0.50, 0.45, 0.80, 0.65]} ...	<b>Kitchen</b>





**Video Planner**

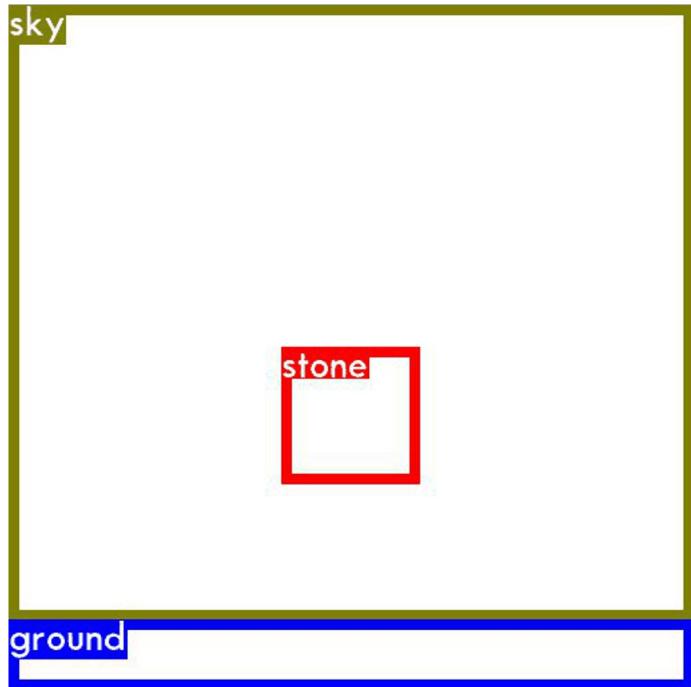
	Scene Description	Entities (names + layouts) with Consistency/Coreference Grouping	Background
<b>Scene 1</b>	A cat is lying down on a bed	Frame 1: { <b>a fluffy Siamese cat</b> : [0.25, 0.25, 1.00, 0.70], <b>a plush beige bed</b> : [0.00, 0.50, 1.00, 1.00]} Frame 2: { <b>a fluffy Siamese cat</b> : [0.25, 0.25, 1.00, 0.70], <b>a plush beige bed</b> : [0.00, 0.50, 1.00, 1.00]} ...	Bedroom
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# Understanding of Basic Physics

## Gravity

A stone thrown into the sky



## Perspective

A car is approaching from a distance

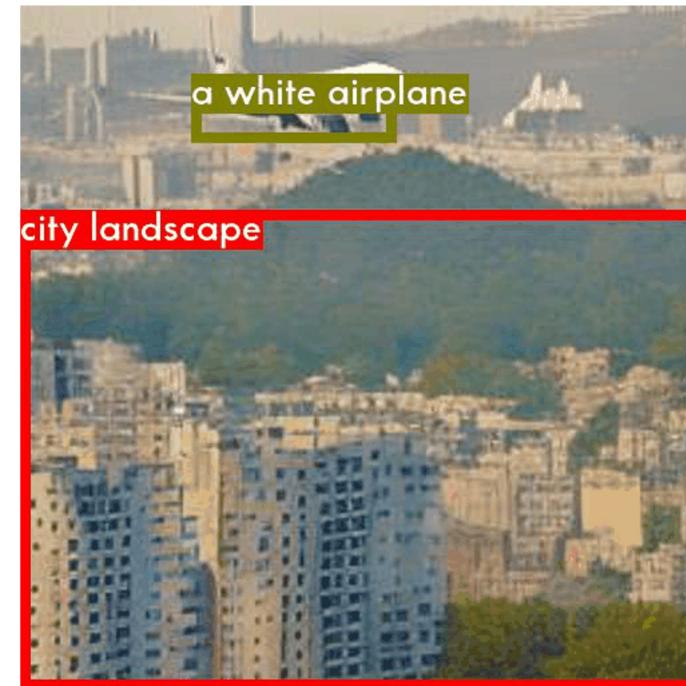


# Movement of Static Objects vs. Dynamic Objects

“A {bottle/airplane} moving from **left to right**.”



Static objects  
-> Movements of Camera



Objects that can move  
-> Movements of Object (+ Camera)

# Multi-Sentence to Multi-Scene Video (Coref-SV)

**Scene 1:** **mouse** is holding a book and makes a happy face.

**Scene 2:** **he** looks happy and talks.

**Scene 3:** **he** is pulling petals off the flower.

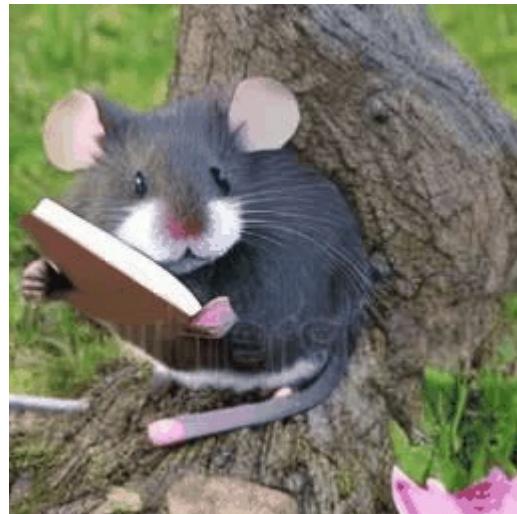
**Scene 4:** **he** is ripping a petal from the flower.

**Scene 5:** **he** is holding a flower by **his** right paw.

**Scene 6:** one paw pulls the last petal off the flower.

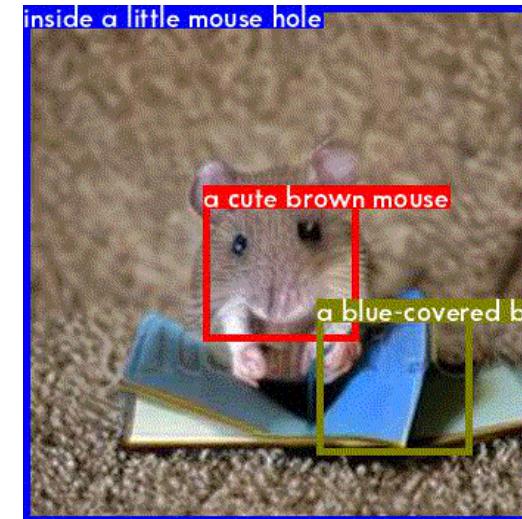
**Scene 7:** **he** is smiling and talking while holding a flower on **his** right paw.

**ModelScopeT2V**



✗ fails to keep “mouse”  
through all scenes

**VideoDirectorGPT (Ours)**



✓ the “mouse” is consistent through  
all scenes + layout control

(also helps plan+generate OOD/unseen affordances/scenes)

# Single Sentence to Multi-Scene Video (HiREST)

make a strawberry surprise

GPT-4 generated sub-scene descriptions:

- a young man in a red apron washes ripe red strawberries in a silver sink
- a young man in a red apron carefully cuts the strawberries on a wooden chopping board with a sharp knife
- a young man in a red apron places cut strawberries, banana, and Greek yogurt into an electric blender
- a young man in a red apron blends ingredients together until smooth in an electric blender
- a young man in a red apron pours the smoothie into a tall glass
- a young man in a red apron places a scoop of vanilla ice cream on top of the smoothie in a tall glass
- a young man in a red apron places a strawberry on top of the ice cream for garnishing
- a young man in a red apron serves the Strawberry Surprise on a ceramic plate

**ModelScopeT2V**



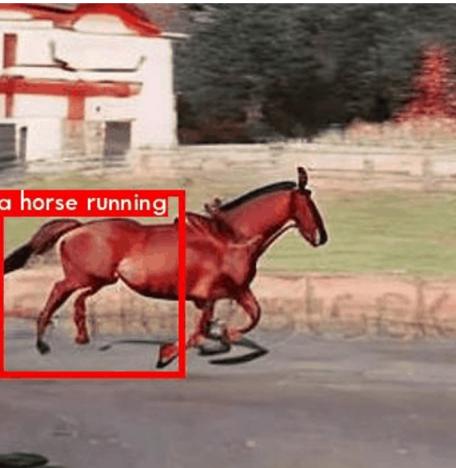
✗ no actual process shown on how to  
“make” the strawberry surprise

**VideoDirectorGPT (Ours)**



✓ step-by-step + consistent  
process on how to “make” the  
strawberry surprise

# Human-in-the-Loop Video Editing+Control



Make the horse smaller



Add “grassland” background



Add “night street” background



# User-Provided Input Image → Video

**Scene 1:** a <S> then gets up from a plush beige bed.

**Scene 2:** a <S> goes to the cream-colored kitchen and eats a can of gourmet snack.

**Scene 3:** a <S> sits next to a large floor-to-ceiling window.

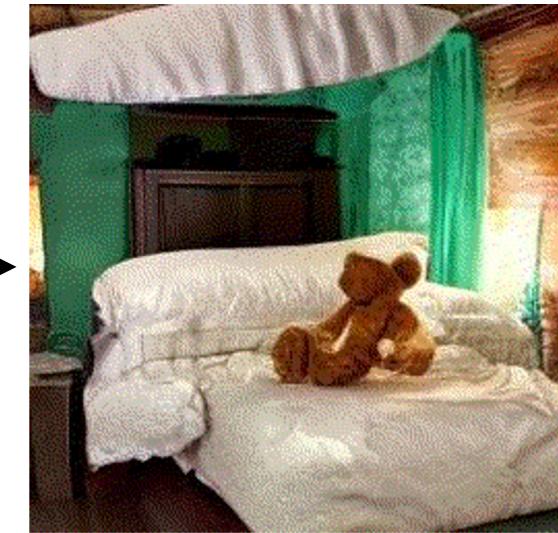
<S> = “cat”

+



<S> = “teddy bear”

+



# Quantitative Evaluation & Human Evaluation

Method	VPEval Skill-based					ActionBench-Direction	
	Object	Count	Spatial	Scale	Overall Acc. (%)	Movement	Direction Acc. (%)
ModelScopeT2V	89.8	38.8	18.0	15.8	40.8		30.5
VIDEODIRECTORGPT (Ours)	<b>97.1</b>	<b>77.4</b>	<b>61.1</b>	<b>47.0</b>	<b>70.6</b>		<b>46.5</b>

Method	ActivityNet Captions			Coref-SV		HiREST	
	FVD (↓)	FID (↓)	Consistency (↑)	Consistency (↑)	FVD (↓)	FID (↓)	
ModelScopeT2V	980	18.12	46.0	16.3	1322	23.79	
ModelScopeT2V (with GT co-reference; oracle)	-	-	-	37.9	-	-	
VIDEODIRECTORGPT (Ours)	<b>805</b>	<b>16.50</b>	<b>64.8</b>	<b>42.8</b>	<b>733</b>	<b>18.54</b>	

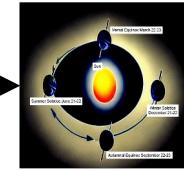
Evaluation category	Human Preference (%) ↑		
	VIDEODIRECTORGPT (Ours)	ModelScopeT2V	Tie
Quality	<b>54</b>	34	12
Text-Video Alignment	<b>54</b>	28	18
Object Consistency	<b>58</b>	30	12

# DiagrammerGPT: Generating Open-Domain, Open-Platform Diagrams via LLM Planning

A diagram showing the Earth revolve around the sun four times, one of each solstice and equinox. It also ...

## Diagram Planning

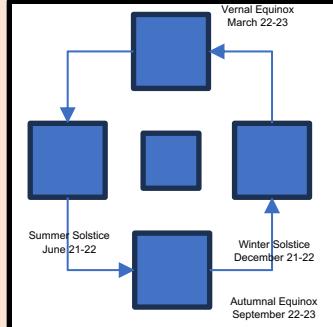
## Diagram Generation



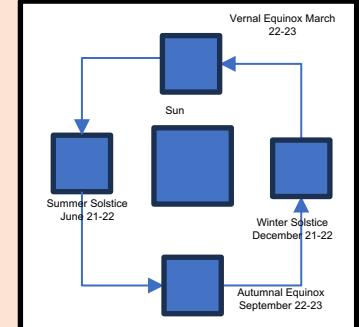
### Diagram Plan from GPT-4

**Entities:**  
images [earth (I0), earth (I1), ...]  
text labels ["Vernal..." (T0), ...]  
**Entity Locations:**  
I0: [39, 11, 17, 21], ...  
**Entity Relations:**  
I0 has an arrow to I1; ...

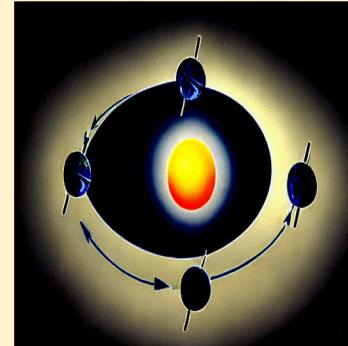
### Initial Plan Visualization



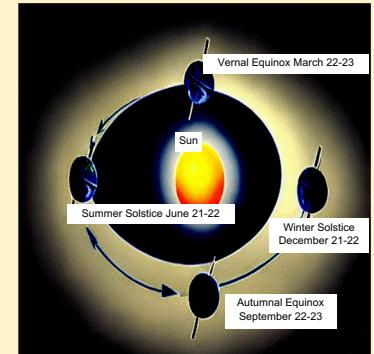
### Refined Plan After Feedback



### DiagramGLIGEN



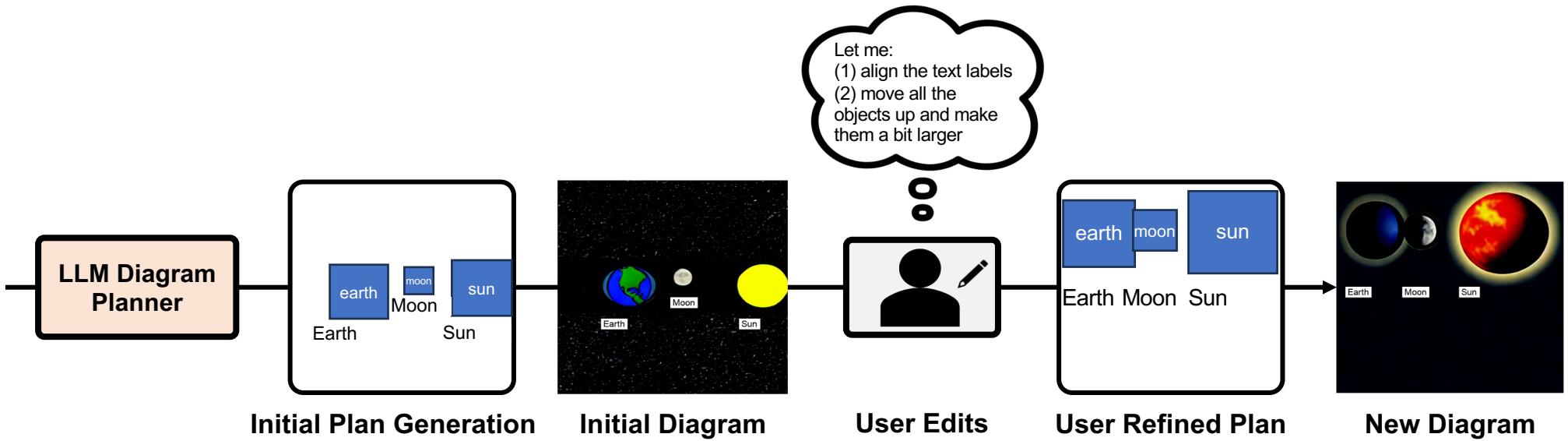
### with Text Label Rendering



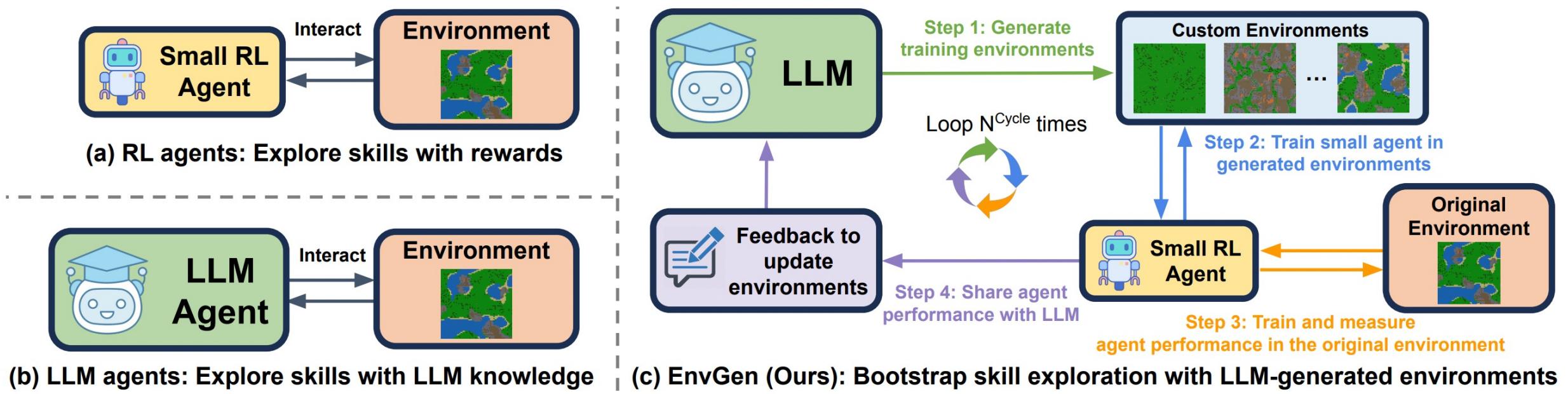
# Human-in-the-Loop Diagram Editing

A diagram showing the earth, moon, and sun with text labels.

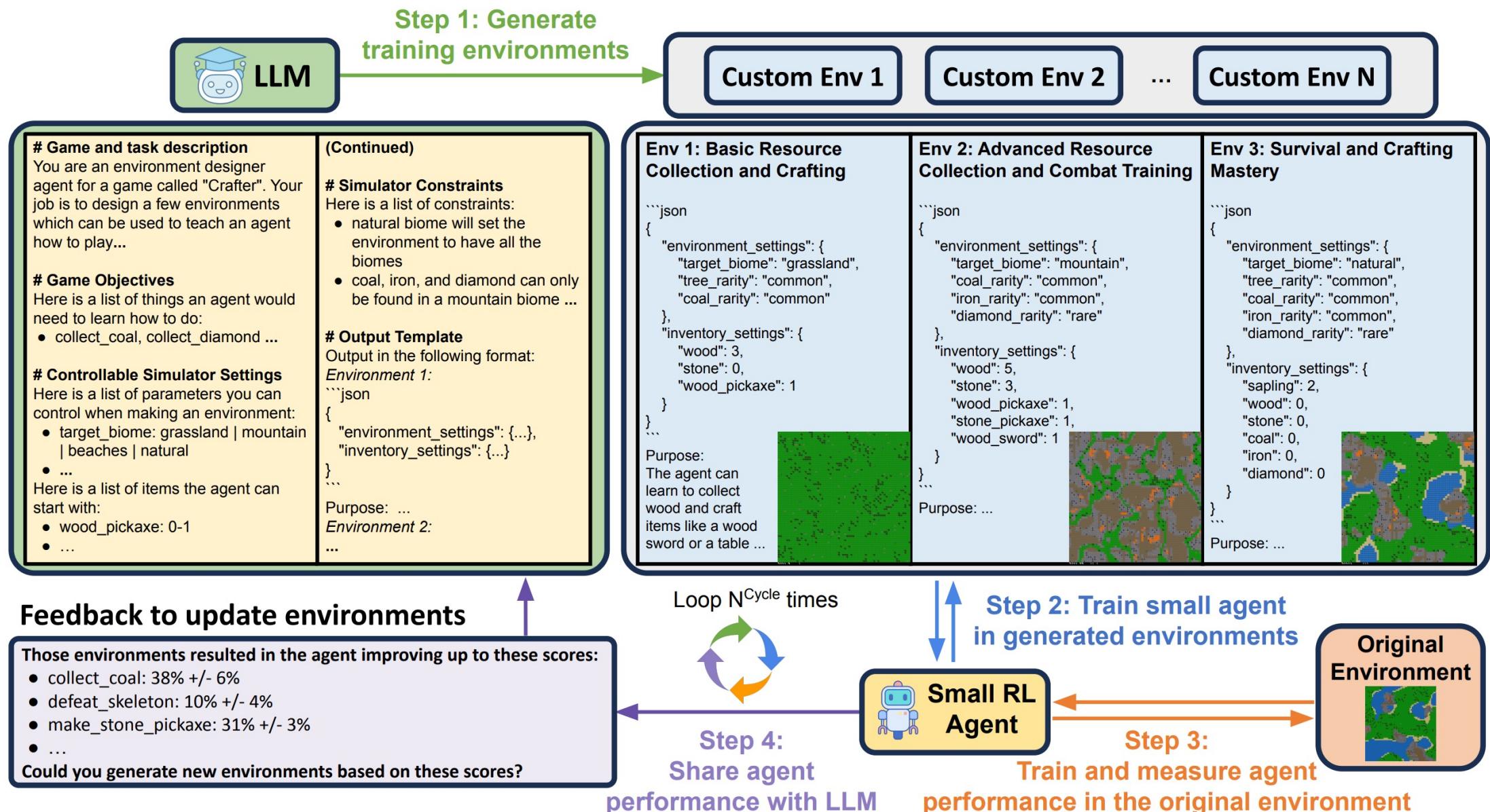
Input Prompt



# EnvGen: LLM-Planned Adaptive Environment Generation for Training Agents



# EnvGen: LLM-Planned Adaptive Environment Generation for Training Agents

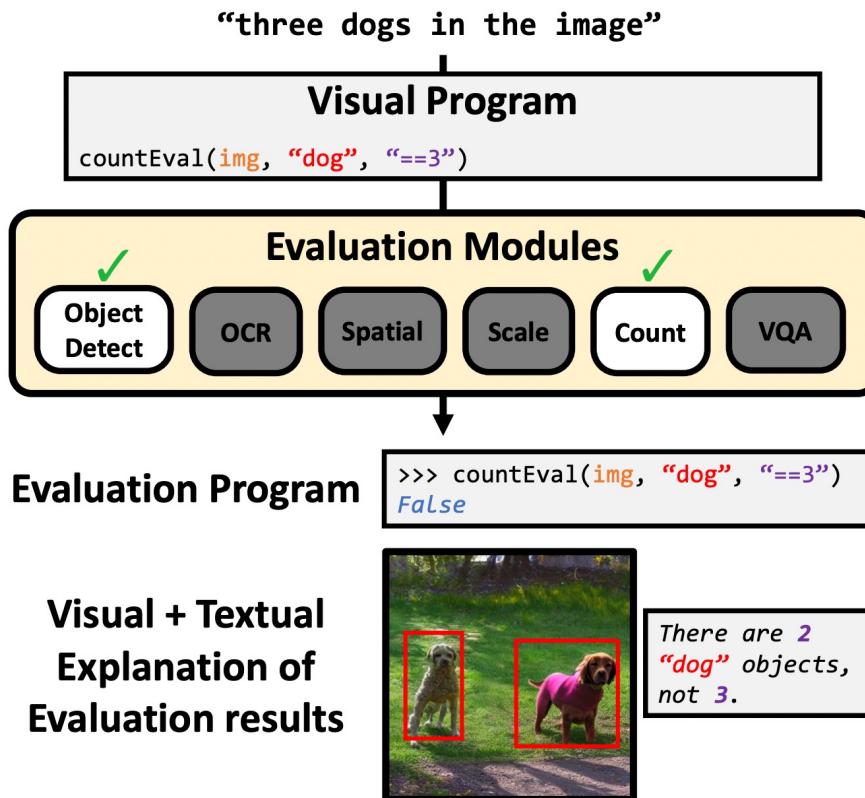


# Talk Outline

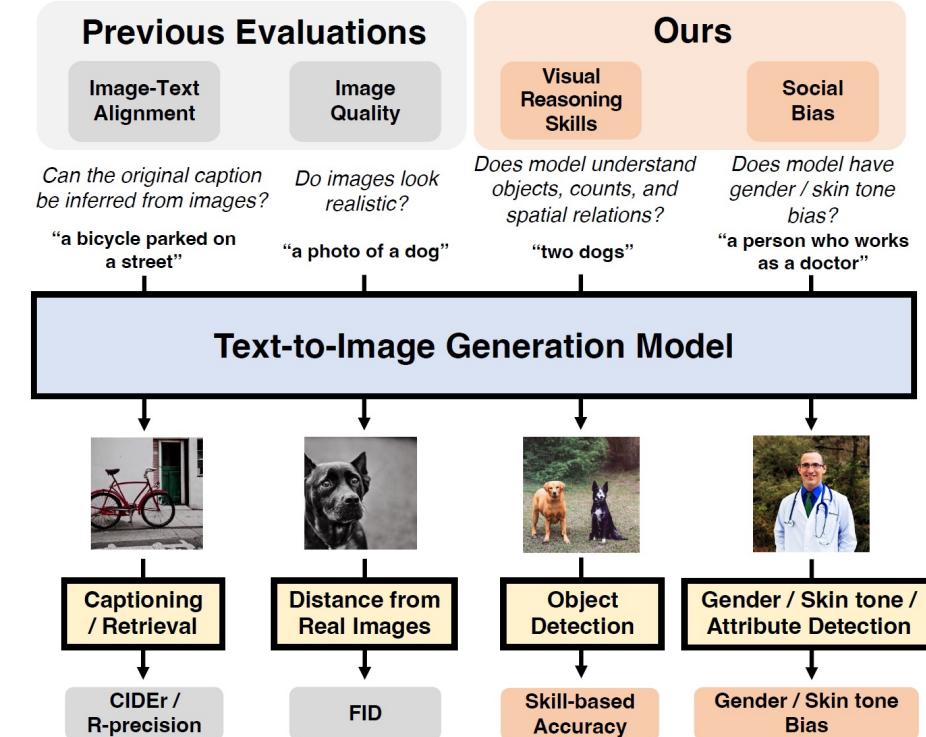
A journey of multimodal generative models for enhancing their unification, interpretable planning/programming, evaluation:

- **Unified/Universal Multimodal Learning** (for Generalizability, Shared Knowledge, Efficiency)
  - VLT5: Unifying Vision-and-Language Tasks via Text Generation [\[ICML 2021\]](#)
  - TVLT: Textless Vision-Language Transformer [\[NeurIPS 2022\]](#)
  - UDOP: Unifying Vision, Text, and Layout for Universal Document Processing [\[CVPR 2023\]](#)
  - CoDi: Any-to-Any Generation via Composable Diffusion [\[NeurIPS 2023\]](#) & CoDi-2: In-Context, Interleaved, and Interactive Any-to-Any Generation [\[CVPR 2024\]](#)
- **Interpretable Multimodal Generation via LLM Planning/Programming Agents** (for Understanding, Control, Faithfulness, OOD)
  - VPGen: Step-by-Step Text-to-Image Generation with Interpretable Visual Programming [\[NeurIPS 2023\]](#)
  - VideoDirectorGPT: Consistent Multi-Scene Video Generation via LLM-Guided Planning [\[COLM 2024\]](#)
  - DiagrammerGPT: Generating Diagrams via LLM Planning [\[COLM 2024\]](#); EnvGen: Adapting Environments via LLMs for Training Embodied Agents [\[COLM 2024\]](#)
- **Evaluation of Multimodal Generation Models** (of Fine-grained Skills, Faithfulness, Social Biases)
  - DALL-Eval: Probing the Reasoning Skills and Social Biases of Text-to-Image Generation Models [\[ICCV 2023\]](#)
  - VPEval: Step-by-Step Text-to-Image Evaluation with Interpretable Visual Programming [\[NeurIPS 2023\]](#)
  - Davidsonian Scene Graph: Improving Reliability in Fine-grained Evaluation for Text-to-Image Generation [\[ICLR 2024\]](#)
- **Next Big Challenges:** trade-offs, structure, non-verbal, interaction, reasoning, causality, long-distance fine-grained evaluation, efficiencies

# Part 3: Evaluation of Multimodal Generation



VPEval (NeurIPS 2023)

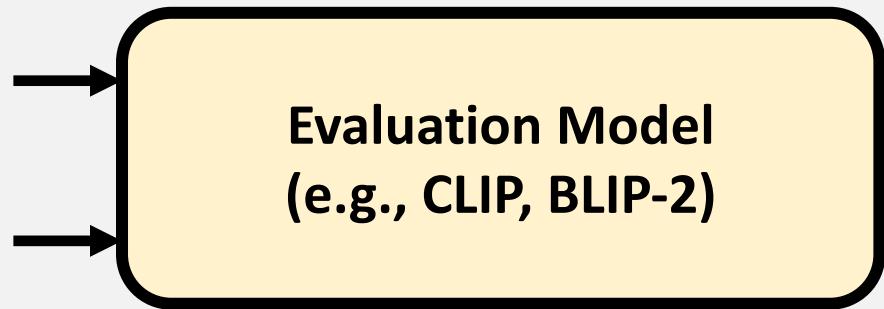


DALL-Eval (ICCV 2023)

# VPEval: Visual Programming for Explainable T2I Evaluation

## Text-to-Image Evaluation

two Pikachu on a table



- How did they compute this score?
- What does the score mean/compare?
- Which parts of the generated image are incorrect/unfaithful to the prompt?



# VPEval: Visual Programming for Explainable T2I Evaluation

## Evaluation Modules

### Object Detect

```
def objDet(img, obj_text):  
    det_objs_2d = detect(img, obj_text)  
    det_objs_3d = depth(img, det_objs_2d)  
    return det_objs_3d
```

### Object Eval

```
def objectEval(img, object_text):  
    objects = objDet(img, object_text)  
    return len(objects) > 0
```

### Count Eval

```
def countEval(img, object_text, count):  
    objects = objDet(img, object_text)  
    return len(objects) == target_count
```

### Text Eval

```
def textEval(img, target_text):  
    texts = ocr(img)  
    return target_text in texts
```

### OCR

```
def ocr(img):  
    det_texts = find_text(img)  
    return det_texts
```

### Spatial Eval

```
def spatialEval(img, obj1_text, obj2_text, relation):  
    objects = objDet(img, "obj1_text,obj2_text")  
    if target_relation == "right":  
        return any(objects[1].x > objects[0].x)  
    ...
```

### Scale Eval

```
def scaleEval(img, obj1_text, obj2_text, relation):  
    objects = objDet(img, "obj1_text,obj2_text")  
    if target_relation == "bigger":  
        return any(objects[1].area > objects[0].area)  
    ...
```

### VQA Eval

```
def vqaEval(img, question, answer_choices,  
           target_answer):  
    answer = vqa_model(img, question, answer_choices)  
    return answer == target_answer
```

# VPEval: Visual Programming for Explainable T2I Evaluation

Open-ended Evaluation

## Open-ended Interpretable Evaluation Program



```
# Task description + module description
Given an image description, generate programs that verifies if
the image description is correct.
...
# In-context examples
Description: A man posing for a selfie in a jacket and bow tie.          Example text prompt
...
objectEval(image, 'man');           vqa(image, 'who is posing for a selfie?', 'man,woman,boy,girl',
                                         'man')                         Example evaluation program
...
# New text prompt
Description: A white slope covers the background, while the
foreground features a grassy slope with several rams grazing and
one measly and underdeveloped evergreen in the foreground.
```

# VPEval: Visual Programming for Explainable T2I Evaluation

Open-ended Evaluation

## Open-ended Interpretable Evaluation Program



```
# Task description + module description  
Given an image description, generate programs that verifies if  
the image description is correct.  
...  
# In-context examples  
Description: A man posing for a selfie in a jacket and bow tie.  
...  
objectEval(image, 'man');  
vqa(image, 'who is posing for a selfie?', 'man,woman,boy,girl',  
'man')  
...  
# New text prompt  
Description: A white slope covers the background, while the  
foreground features a grassy slope with several rams grazing and  
one measly and underdeveloped evergreen in the foreground.
```

ChatGPT

```
# Generated Program  
objectEval(image, 'ram');  
objectEval(image, 'evergreen');  
countEval(image, 'ram', '>1');  
countEval(image, 'evergreen', '==1');  
vqa(image, 'what is in the foreground?', 'grassy  
slope,beach,field,forest', 'grassy slope');  
...
```

# VPEval: Visual Programming for Explainable T2I Evaluation

Open-ended Evaluation

## Open-ended Interpretable Evaluation Program



```
# Task description + module description  
Given an image description, generate programs that verifies if  
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Description: A man posing for a selfie in a jacket and bow tie.  
...  
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vqa(image, 'who is posing for a selfie?', 'man,woman,boy,girl',  
'man')  
...  
# New text prompt  
Description: A white slope covers the background, while the  
foreground features a grassy slope with several rams grazing and  
one measly and underdeveloped evergreen in the foreground.
```

```
# Generated Program  
objectEval(image, 'ram');  
objectEval(image, 'evergreen');  
countEval(image, 'ram', '>1');  
countEval(image, 'evergreen', '==1');  
vqa(image, 'what is in the foreground?', 'grassy  
slope,beach,field,forest', 'grassy slope');  
...
```

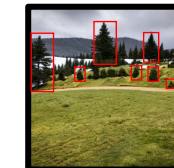
## Visual + Textual Explanations of Errors/Hallucinations

Incorrect ✗



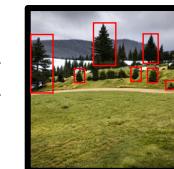
no "ram" object found.

Correct ✓



"evergreen" object found.

Incorrect ✗



there are 8 "evergreen" objects, not 1.

Correct ✓



Q: "what is in the foreground?" A: grassy slope.

ChatGPT

# Davidsonian Scene Graph: Improving Reliability in Fine-grained Evaluation for T2I



## Complex, non-atomic questions

Q: “is there a red motorcycle?”

Unclear question;

The question checks multiple aspects at once!

= “is there a motorcycle?” → Yes  
+  
“is the motorcycle red?” → No



## Invalid questions

Q1: “is there a motorcycle?” → A: No

Q2: “is the motorcycle red?” → A: Yes

Q2 is invalid;

If there is not motorcycle,  
no need to check its color!

# Davidsonian Scene Graph: Improving Reliability in Fine-grained Evaluation for T2I

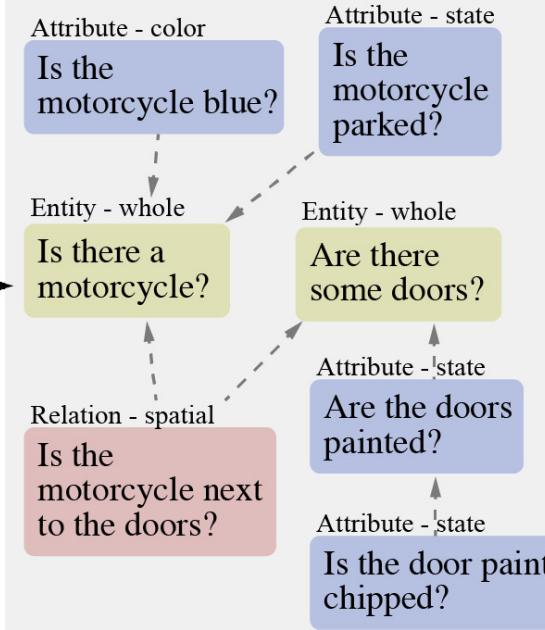
Questions w/ desired properties (following Davidsonian formal semantics):

- *Atomic*
- *Unique*
- *Full semantic coverage*
- *Valid dependencies*

## Prompt

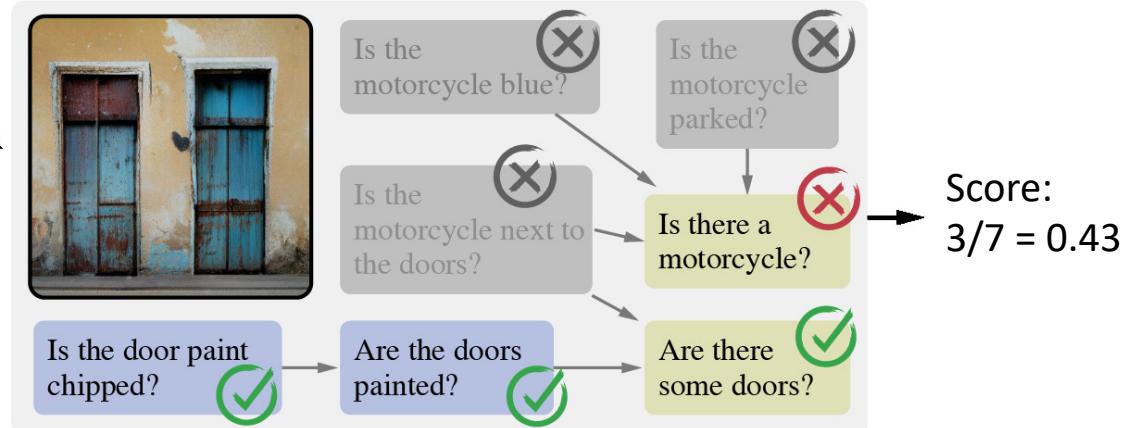
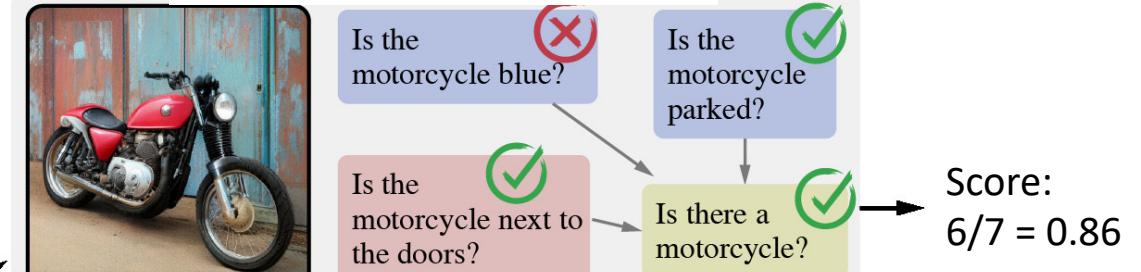
“A blue motorcycle parked by paint chipped doors.”

## Question Generation (QG)

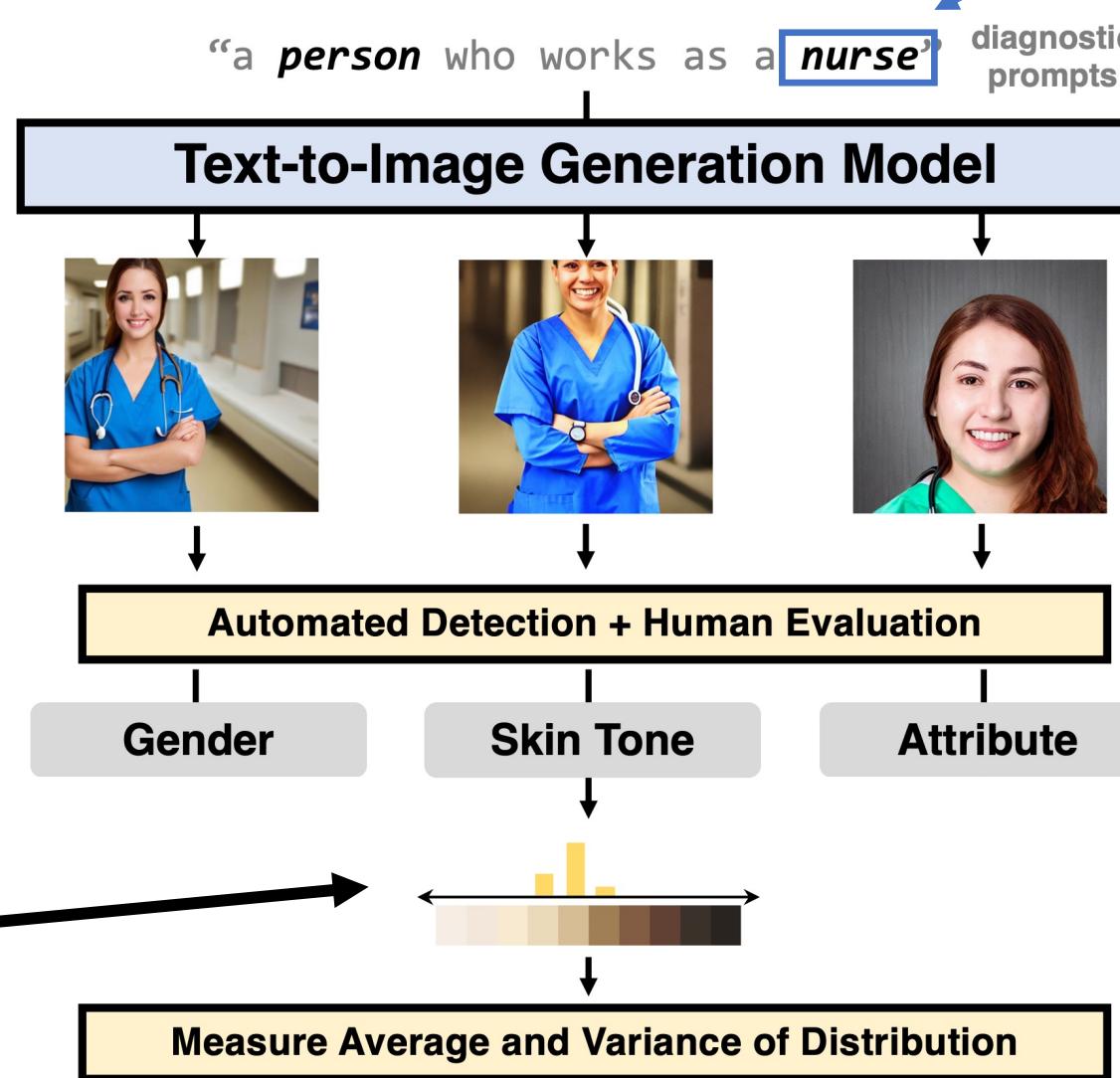


Answering Questions,  
while avoiding answering the invalid questions

## Question Answering (QA)



# DALL-Eval: Measuring Social Biases



How skewed  
are the  
distributions?

Template	[G] who works as a/an [P]
Gender [G]	a person / a man / a woman

accountant  
animator  
architect  
assistant  
athlete  
author  
baker  
biologist  
builder  
butcher  
career counselor  
caretaker  
chef  
civil servant  
clerk  
comic book writer  
company director  
computer programmer  
cook  
decorator  
dentist  
designer  
diplomat  
director  
doctor  
economist  
editor  
electrician  
engineer  
executive  
farmer  
film director  
flight attendant  
garbage collector  
geologist  
hairdresser  
jeweler  
journalist  
judge  
juggler  
lawyer  
lecturer  
lexicographer  
library assistant  
magician  
makeup artist  
manager  
miner  
musician  
nurse  
optician  
painter  
personal assistant  
photographer  
pilot  
plumber  
police officer  
politician  
porter  
prison officer  
professor  
puppeteer  
receptionist  
sailor  
salesperson  
scientist  
secretary  
shop assistant  
sign language interpreter  
singer  
soldier  
solicitor  
surgeon  
tailor  
teacher  
translator  
travel agent  
truck  
TV presenter  
veterinarian  
waiter  
web designer  
writer

# Conclusion + Big Challenges / Research Directions

- **Trade-off** of blackbox **pretraining** vs. **modular structure** (incl. faithfulness, efficiency, interpretability/understanding, human-in-loop/control, OOD, fairness/bias, privacy)?
- **Other modalities** (non-verbal gesture/gaze, action-interaction)?
- **Long-distance** text/video understanding+generation, **causal/counterfactual**?
- **Fine-grained** evaluation of **skills/consistency/bias/faithfulness+hallucination**?
- **Continual learning** when new/unseen information keeps coming?
- **Unlearning** of outdated/wrong/unsafe/private information?
- **Efficiency** w.r.t. many axes: time, storage, memory, carbon footprint, etc.?



# Thank you!

Webpage: <http://www.cs.unc.edu/~mbansal/>

Email: [mbansal@cs.unc.edu](mailto:mbansal@cs.unc.edu)

MURGe-Lab: <https://murgelab.cs.unc.edu/>

(thanks to our awesome students for all the work I presented!)

**We are hiring PhD students + Postdocs!**