Estimating the number of COVID-19 victims by using a Monte Carlo algorithm on a generalized logistic equation

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- Idea: if it works, repeat now to predict June/July...
- Chosen Countries: Germany, France, Italy.

The model in theory: ODE description

X(t): number of deaths in time. Modeled via a simple 1-d ODE with initial conditions X_0 . Generalized logistic map (S-shaped, exp initially, then flat):

$$X'(t) = \frac{q}{v}X(t)\left(1 - \left(\frac{X(t)}{Q}\right)^{v}\right) \tag{1}$$

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- It has a close form solution (here not written);
- Depends on the parameter $P = \{q, Q, v\}$ (more next slide).
- In others words: assume $\exists P \in \mathbb{R}^3$, s.t. $X^P(t)$ correctly describe the (past and future) number of victims. Want to find P.

Do not need to remember the form of $X^P(t)$. It's worth understanding the role of the parameter P.

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- Keep in mind: Q large, > 10.000, v, q small, $\in [0, 1]$.

The model in practice: observed vector

The available dataset are "numbers of total deaths until day t_i ": discrete, limited, ODE trajectory of $X_{X_0}^P(t)$. Use them to infer P.

Fix T+1 times $\{t_i\}_{i=0,...,T}$, e.g. 21 days. The observed vector $\mathbf{y} \in \mathbb{R}^{T+1}$ is the random variable defined componentwise as:

$$y_i(\omega) = X_{X_0}^P(t_i) + \eta_i(\omega)$$
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where $\eta_i \sim \mathcal{N}(0, \sigma_i^2)$, $i \in \{0, \ldots, T\}$.

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• In other words, **y** is what we measure: "noised truth".

To assume an error of the form

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is a strong assumption (I know). Need to decide the standard variations σ_i for each day. Abritrately.

Quantile formula: $\eta_i \sim N(0, \sigma_i^2) \implies \mathbb{P}[-2\sigma_i \leq \eta_i \leq 2\sigma_i] \geq 95\%$

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- Warning: the inference algorithm [not yet described] is destroyed for higher errors, but not with our cases - checked with toy model data.

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- Step 3: conclude by using the Bayes formula:

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- Infer P =sample from the posterior

The pCN Monte Carlo method

Let $\mathbb{P}[P|\mathbf{y}]$ be the posterior on \mathbb{R}^3 . Let $0 < \beta < 1$ the speed parameter, and the acceptance probability, for $v, u \in \mathbb{R}^3$:

$$a(u, v) \doteq \min\{1, \frac{\mathbb{P}(\mathbf{y}|v)}{\mathbb{P}(\mathbf{y}|u)}\}$$
 (5)

To produce a **single sample**, construct a chain $\{x_i\}_{i\in\mathbb{N}}$ as follows:

- 1. set $x_0 \in \mathbb{R}^n$ arbitrarily. Then, for each k > 0:
- 2. sample a point $R \in \mathbb{R}^3$ from the **gaussian** prior $\mathbb{P}(P \in dx)$;
- 3. propose a candidate as $\hat{x}_k = \sqrt{(1-\beta^2)}x_{k-1} + \beta R$;
- 4. accept it (i.e. set $x_k = \hat{x}_k$) with probability $a(x_{k-1}, \hat{x}_k)$;
- 5. (accepted or not) repeat from 2;

Run 120.000 multiple chains in parallel, different starting point, each stopped after 250.000 iterations. Beta around 0.05, s.t. acceptance rate \sim 25%. Last missing info: which prior?

Prior measure on P: part 1

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• Therefore: we only need to choose the σ , and then we can move on the simulations!

Goal of this slide: explain how the values for σ_q , σ_Q and σ_v have been chosen.

• The idea is: the prior represents the "guess", the "default" choice. But if "nothing is done", the phenomenon propagates exponentially. Therefore we run an exponential interpolation, and register the number of victims in 1 Month: K. Then choose σ_Q in order to have the Gaussian 95% quantile just below this quantity;

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- Dealing with σ_q and σ_v , they have been chosen in order to have that quantile between 0 and 1.
- These idea formalize the intuition that we expect parameters in these range, without forcing any constraint.

 Now all the parameters, assumptions, hypothesis should be clear. In particular, we are using a possibly-not-so-good Monte Carlo algorithm with strong assumptions on the noise and the prior;

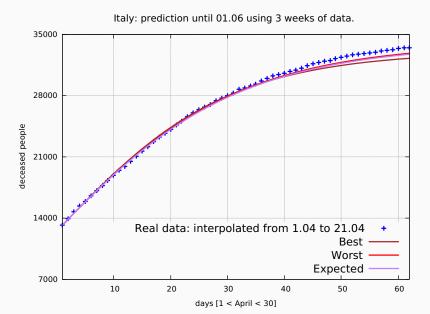
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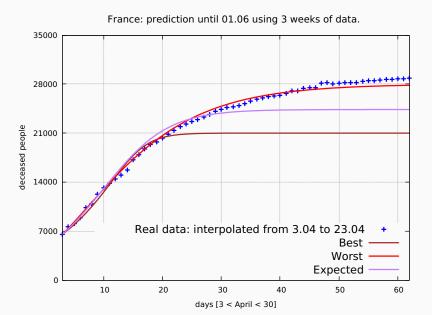
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- We have plots for the "10%" error scenario, as well as for the "100%" (meaning explained before)

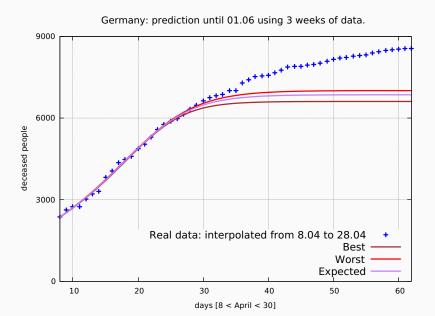
Results: Italy, assuming 10% of "error"



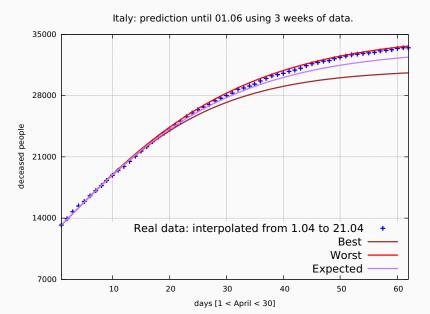
Results: France, assuming 10% of "error"



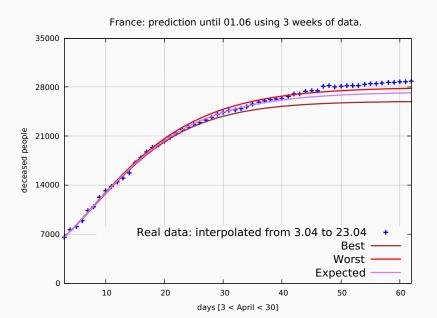
Results: Germany, assuming 10% of "error"



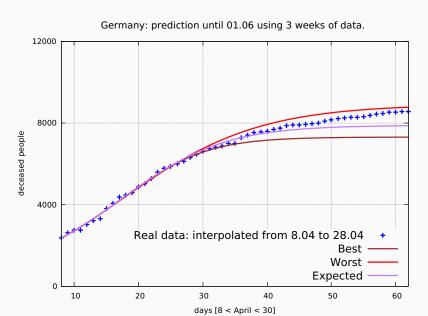
Results: Italy, assuming 100% of "error"



Results: France, assuming 100% of "error"



Results: Germany, assuming 100% of "error"



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- Or instead of the Bayesian approach, try maximizing the Likelihood (i.e. probabilistic least square);
- Or simply to consider this example as a nice application of Monte Carlo Bayesian techniques, before moving back to the main PhD topic.

Thanks for the attention!