

# Google Summer of Code 2017 Additions

Vandit Jain

August 2017

## Expected Hitting Time using CTMC

The package provides `ExpectedTime` function to calculate average hitting time from one state to another. Let the final state be  $j$ , then for every state  $i \in I$ , where  $I$  is the set of all possible states and holding time  $q_i > 0$  for every  $i \neq j$ . Assuming the conditions to be true, expected hitting time is equal to minimal non-negative solution vector  $p$  to the system of linear equations (Norris 1998):

$$\begin{aligned} p_k &= 0 & k &= j \\ -\sum_{l \in I} q_{kl} p_k &= 1 & k &\neq j \end{aligned} \quad (1)$$

For example, consider the continuous time markovchain which is as follows:

```
library(markovchain)
states <- c("a","b","c","d")
byRow <- TRUE
gen <- matrix(data = c(-1, 1/2, 1/2, 0, 1/4, -1/2, 0, 1/4, 1/6, 0, -1/3, 1/6, 0, 0, 0, 0),
nrow = 4, byrow = byRow, dimnames = list(states, states))
ctmc <- new("ctmc", states = states, byrow = byRow, generator = gen, name = "testctmc")
```

The generator matrix of the ctmc is:

$$M = \begin{pmatrix} -1 & 1/2 & 1/2 & 0 \\ 1/4 & -1/2 & 1/4 & 1/6 \\ 1/6 & 0 & -1/3 & 1/6 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Now if we have to calculate expected hitting time the process will take to hit state  $d$  if we start from  $a$ , we apply the `ExpectedTime` function. `ExpectedTime` function takes four inputs namely a `ctmc` class object, initial state  $i$ , the final state  $j$  that we have to calculate expected hitting time and a logical parameter whether to use RCpp implementation. By default, the function uses RCpp as it is faster and takes lesser time.

```
ExpectedTime(ctmc,1,4)
```

```
## [1] 7
```

We find that the expected hitting time for process to be hit state  $d$  is 7 units in this case.

## Calculating Probability at time T using ctmc

The package provides a function `probabilityatT` to calculate probability of every state according to given `ctmc` object. The Kolmogorov's backward equation gives us a relation between transition matrix at any time  $t$  with the generator matrix (Dobrow 2016):

$$P'(t) = QP(t) \quad (2)$$

Here we use the solution of this differential equation  $P(t) = P(0)e^{tQ}$  for  $t \geq 0$  and  $P(0) = I$ . In this equation,  $P(t)$  is the transition function at time  $t$ . The value  $P(t)[i][j]$  at time  $P(t)$  describes the conditional probability

of the state at time  $t$  to be equal to  $j$  if it was equal to  $i$  at time  $t = 0$ . It takes care of the case when `ctmc` object has a generator represented by columns. If initial state is not provided, the function returns the whole transition matrix  $P(t)$ .

Also to mention is that the function is also implemented using Rcpp and can be used to lessen the time of computation. It is used by default. Next, We consider both examples where initial state is given and case where initial state is not given.

In the first case, the function takes two inputs, first of them is an object of the S4 class 'ctmc' and second is the final time  $t$ .

```
probabilityatT(ctmc,1)
```

```
##           a           b           c           d
## a 0.41546882 0.24714119 0.2703605 0.06702946
## b 0.12357060 0.63939068 0.0348290 0.20220972
## c 0.09012017 0.02321933 0.7411205 0.14553997
## d 0.00000000 0.00000000 0.0000000 1.00000000
```

Here we get an output in the form of a transition matrix.

If we take the second case i.e. considering some initial input:

```
probabilityatT(ctmc,1,1)
```

```
## [1] 0.41546882 0.24714119 0.27036052 0.06702946
```

In this case we get the probabilities corresponding to every state. this also includes probability that the process hits the same state  $a$  after time  $t = 1$ .

## Plotting generator matrix of continuous-time markovchains

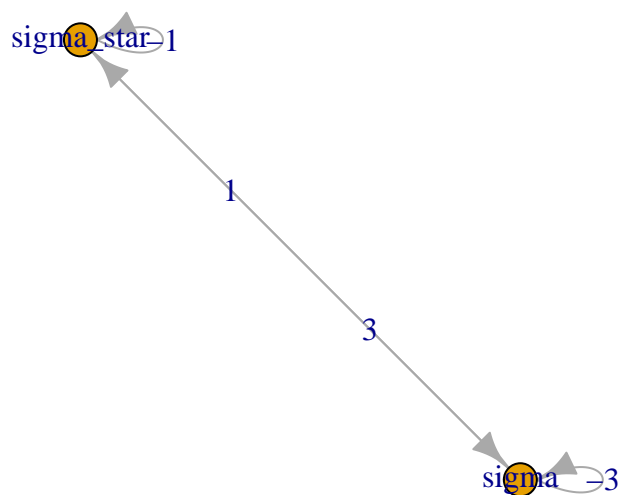
The package provides a `plot` function for plotting a generator matrix  $Q$  in the form of a directed graph where every possible state is assigned a node. Edges connecting these nodes are weighted. Weight of the edge going from a state  $i$  to state  $j$  is equal to the value  $Q_{ij}$ . This gives a picture of the generator matrix.

For example, we build a `ctmc`-class object to plot it.

```
energyStates <- c("sigma", "sigma_star")
byRow <- TRUE
gen <- matrix(data = c(-3, 3,
                      1, -1), nrow = 2,
              byrow = byRow, dimnames = list(energyStates, energyStates))
molecularCTMC <- new("ctmc", states = energyStates,
                    byrow = byRow, generator = gen,
                    name = "Molecular Transition Model")
```

Now if we plot this function we get the following graph:

```
plot(molecularCTMC)
```



The figure shown is built using the *igraph* package. The package also provides options of plotting graph using *diagram* and *DiagramsR* package. Plot using these packages can be built using these commands:

```
plot(molecularCTMC, package = "diagram")
```



Similarly, one can easily replace *diagram* package with *DiagrammeR*

## Imprecise Conitnuous-Time Markovchains

Continuous-time Markov chains are mathematical models that are used to describe the state-evolution of dynamical systems under stochastic uncertainty. However, building models usign continuous time markovchains tkae in consideration a number of assumptions which may not be realistic for the domain of application; in particular; the ability to provide exact numerical parameter assessments, and the applicability of time-homogeneity and the eponymous Markov property. Hence we take ICTMC into consideration.

More technically, an ICTMC is a set of “precise” continuous-time finite-state stochastic processes, and rather than computing expected values of functions, we seek to compute lower expectations, which are tight lower bounds on the expectations that correspond to such a set of “precise” models.

### Types of ICTMCs

For any non-empty bounded set of rate matrices  $L$ , and any non-empty set  $M$  of probability mass functions on  $X$ , we define the following three sets of stochastic processes that are jointly consistent with  $L$  and  $M$ :

- $P_{L,M}^W$  is the consistent set of all well-behaved stochastic processes;
- $P_{L,M}^{WM}$  is the consistent set of all well-behaved Markov chains;
- $P_{L,M}^{WHM}$  is the consistent set of all well-behaved homogeneous Markov chains(Thomas Krak 2017).

From a practical point of view, after having specified a (precise) stochastic process, one is typically interested in the expected value of some function of interest, or the probability of some event. Similarly, in this work,

our main objects of consideration will be the lower probabilities that correspond to the ICTMCs.

## Lower Transition Rate Operators for ICTMCs

A map  $Q_l$  from  $L(X)$  to  $L(X)$  is called a lower transition rate operator if, for all  $f, g \in L(X)$ , all  $\lambda \in R_{\geq 0}$ , all  $\mu \in L(X)$ , and all  $x \in X$  (Thomas Krak 2017):

1.  $[Q_l m](x) = 0$
2.  $[Q_l I](x) \geq 0 \forall y \in X$  such that  $x \neq y$
3.  $[Q_l(f + g)](x) \geq [Q_l f](x) + [Q_l g](x)$
4.  $[Q_l(\lambda f)](x) = \lambda Q_l f(x)$

## Lower Transition Operators

A map  $T_l$  from  $L(X)$  to  $L(X)$  is called a lower transition operator if, for all  $f, g \in L(X)$ , all  $\lambda \in R_{\geq 0}$ , all  $\mu \in L(X)$ , and all  $x \in X$  (Thomas Krak 2017):

1.  $[T_l f](x) \geq \min(f(y) : y \in L)$
2.  $[T_l(f + g)](x) \geq [T_l f](x) + [T_l g](x)$
3.  $[T_l(\lambda f)](x) = \lambda [T_l f](x)$

## Imprecise probability at T function

Now I would like to come onto the practical purpose of using ICTMC classes. ICTMC classes in these package are defined to represent a generator that is defined in such a way that every row of the generator corresponding to every state in the process is governed by a separate variable. As defined earlier, an imprecise continuous time markov chain is a set of many precise CTMCs. Hence this representation of set of precise CTMCs can be used to calculate transition probability at some time in future. This can be seen as an analogy with **probability at T** function. It is used to calculate the transition function at some later time  $t$  using generator matrix.

For every generator matrix, we have a corresponding transition function. Similarly, for every Lower Transition rate operator of an ICTMC, we have a corresponding lower transition operator denoted by  $L_t^s$ . Here  $t$  is the initial time and  $s$  is the final time.

Now we mention a proposition (Thomas Krak 2017) which states that: Let  $Q_l$  be a lower transition rate operator, choose any time  $t$  and  $s$  both greater than 0 such that  $t \leq s$ , and let  $L_t^s$  be the lower transition operator corresponding to  $Q_l$ . Then for any  $f \in L(X)$  and  $\epsilon \in R_{>0}$ , if we choose any  $n \in N$  such that:

$$n \geq \max((s - t) * \|Q\|, \frac{1}{2\epsilon}(s - t)^2 \|Q\|^2 \|f\|_v)$$

with  $\|f\|_v := \max f - \min f$ , we are guaranteed that (Thomas Krak 2017)

$$\|L_t^s - \prod_{i=1}^n (I + \Delta Q_l)\| \leq \epsilon$$

with  $\Delta := \frac{s-t}{n}$

Simple put this equation tells us that, using  $Q_l g$  for all  $g \in L(X)$  then we can also approximate the quantity  $L_t^s$  to arbitrary precision, for any given  $f \in L(X)$ .

To explain this approximate calculation, I would take a detailed example of a process containing two states healthy and sick, hence  $X = (\text{healthy}, \text{sick})$ . If we represent in form of an ICTMC, we get:

$$Q = \begin{pmatrix} -a & a \\ b & -b \end{pmatrix}$$

for some  $a, b \in R_{\geq 0}$ . The parameter  $a$  here is the rate at which a healthy person becomes sick. Technically, this means that if a person is healthy at time  $t$ , the probability that he or she will be sick at time  $t + \Delta$ , for small  $\Delta$ , is very close to  $\Delta a$ . More intuitively, if we take the time unit to be one week, it means that he or she will, on average, become sick after  $\frac{1}{a}$  weeks. The parameter  $b$  is the rate at which a sick person becomes healthy again, and has a similar interpretation.

Now to completely represent the ICTMC we take an example and write the generator as:

$$Q = \begin{pmatrix} -a & a \\ b & -b \end{pmatrix} : a \in [\frac{1}{52}, \frac{3}{52}], b \in [\frac{1}{2}, 2]$$

Now suppose we know the initial state of the patient to be sick, hence this is represented in the form of a function by:

$$I_s = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

We observe that the  $\|I_s\| = 1$ . Now to use the proposition mentioned above, we use the definition to calculate the lower transition operator  $Q_t$ . Next we calculate the norm of the lower transition rate operator and use it in the proposition. Also we take value of  $\epsilon$  to be 0.001.

Using the proposition we can come upto an algorithm for calculating the probability at any time  $s$  given state at initial time  $t$  and a ICTMC generator (Thomas Krak 2017).

The algorithm is as follows:

**Input:** A lower transition rate operator  $Q$ , two time points  $t, s$  such that  $t \leq s$ , a function  $f \in L(X)$  and a maximum numerical error  $\epsilon \in R_{>0}$ .

**Algorithm:**

1.  $n = \max((s - t)\|Q\|, \frac{1}{2\epsilon}(s - t)^2\|Q\|^2\|f\|_v)$
2.  $\Delta = \frac{s - t}{n}$
3.  $g_0 = I_s$
4. for  $i \in (1, \dots, n)$  do  $g_i = g_{i-1} + \Delta Q_t g_{i-1}$
5. end for
6. return  $g_n$

**Output:**

The conditional probability vector after time  $t$  with error  $\epsilon$ . Hence, after applying the algorithm on above example we get the following result:

$g_{\{n\}} = 0.0083$  if final state is *healthy* and  $g_n = 0.141$  if the final state is *sick*. The probability calculated is with an error equal to  $\epsilon$  i.e. 0.001.

Now we run the algorithm on the example through R code.

```
states <- c("n", "y")
Q <- matrix(c(-1, 1, 1, -1), nrow = 2, byrow = TRUE, dimnames = list(states, states))
range <- matrix(c(1/52, 3/52, 1/2, 2), nrow = 2, byrow = 2)
name <- "testictmc"
ictmc <- new("ictmc", states = states, Q = Q, range = range, name = name)
impreciseProbabilityT(ictmc, 2, 0, 1, 10^-3, TRUE)
```

```
## [1] 0.008259774 0.140983476
```

The probabilities we get are with an error of  $10^{-3}$

## Continuous time markovchain generator using frequency Matrix

The package provides `freq2Generator` function. It takes in a matrix representing relative frequency values along with time taken to provide a continuous time markovchain generator matrix. Here, frequency matrix is a 2-D matrix of dimensions equal to relative number of possible states describing the number of transitions from a state  $i$  to  $j$  in time  $t$ , which is another parameter to be provided to the function. The function also allows to chose among three methods for calculation of the generator matrix.(Alexander Kreinin 2001)

Three methods are as follows:

1. Quasi Optimisation - “QO”
2. Diagonal Adjustment - “DA”
3. Weighted Adjustment - “WA”

See reference for details about the methods.

Here is an example matrix on which `freq2Generator` function is run:

```
sample <- matrix(c(150,2,1,1,1,200,2,1,2,1,175,1,1,1,1,150),nrow = 4,byrow = TRUE)
sample_rel = rbind((sample/rowSums(sample))[1:dim(sample)[1]-1,],c(rep(0,dim(sample)[1]-1),1))
freq2Generator(sample_rel,1)
```

```
##           [,1]      [,2]      [,3] [,4]
## [1,] -0.024212164  0.01544797  0.008764198    0
## [2,]  0.006594821 -0.01822834  0.011633520    0
## [3,]  0.013302567  0.00749703 -0.020799597    0
## [4,]  0.000000000  0.00000000  0.000000000    0
```

## Committor of a markovchain

Consider set of states A,B comprising of states from a markovchain with transition matrix P. The committor vector of a markovchain with respect to sets A and B gives the probability that the process will hit a state from set A before any state from set B.

Committor vector  $u$  can be calculated by solving the following system of linear equations(StackOverflow 2015):

$$\begin{aligned}Lu(x) &= 0, x \notin A \cup B \\ u(x) &= 1, x \in A \\ u(x) &= 0, x \in B\end{aligned}$$

where  $L = P - I$ .

Now we apply the method to an example:

```
transMatr <- matrix(c(0,0,0,1,0.5,0.5,0,0,0,0,0.5,0,0,0,0,0.2,0.4,0,0,0,0.8,0.6,0,0.5),nrow = 5)
object <- new("markovchain", states=c("a","b","c","d","e"),transitionMatrix=transMatr, name="simpleMc")
committorAB(object,c(5),c(3))
```

```
##           a           b           c           d           e
## 0.4444444 0.8888889 0.0000000 0.4444444 1.0000000
```

Here we get probability that the process will hit state “e” before state “c” given different initial states.

## First Passage probability for set of States

Currently computation of the first passage time for individual states has been implemented in the package. `firstPassageMultiple` function provides a method to get first passage probability for given provided set of states.

Consider this example markovchain object:

```
statesNames <- c("a", "b", "c")
testmarkov <- new("markovchain", states = statesNames, transitionMatrix =
matrix(c(0.2, 0.5, 0.3,
0.5, 0.1, 0.4,
0.1, 0.8, 0.1), nrow = 3, byrow = TRUE,
dimnames = list(statesNames, statesNames)
))
```

Now we apply `firstPassageMultiple` function to calculate first passage probabilities for set of states "b", "c" when initial state is "a".

```
firstPassageMultiple(testmarkov,"a",c("b","c"),4)
```

```
##      set
## 1 0.8000
## 2 0.6000
## 3 0.2540
## 4 0.1394
```

This shows us the probability that the process will hit any of the state from the set after n number of steps for instance, as shown, the probability of the process to hit any of the states among "b", "c" after 2 steps is 0.6000.

## Joint PDF of number of visits to the various states of a markovchain

The package provides a function `noofVisitsDist` that returns the PDF of the number of visits to the various states of the discrete time markovchain during the first N steps, given initial state of the process.

We will take an example to see how to use the function on a `markovchain-class` object:

```
transMatr<-matrix(c(0.4,0.6,.3,.7),nrow=2,byrow=TRUE)
simpleMc<-new("markovchain", states=c("a","b"),
            transitionMatrix=transMatr,
            name="simpleMc")
noofVisitsDist(simpleMc,5,"a")
```

```
##      a      b
## 0.348148 0.651852
```

The output clearly shows the probabilities related to various states of the process.

## Expected Rewards for a markovchain

The package provides a function `expectedRewards` that returns a vector of expected rewards for different initial states. The user provides reward values, a vector  $r$  of size equal to number of states having a value corresponding to every state. Given a transition matrix  $[P]$ , we get the vector of expected rewards  $v$  after  $n$  transitions according to the equation as follows(Gallager 2013):



$$v[n] = r + [P] * v[n - 1]$$

Applying this equation on a markovchain-class object

```
transMatr<-matrix(c(0.99,0.01,0.01,0.99),nrow=2,byrow=TRUE)
simpleMc<-new("markovchain", states=c("a","b"),
             transitionMatrix=transMatr)
expectedRewards(simpleMc,1,c(0,1))
```

```
## [1] 0.01 1.99
```

## Expected Rewards for a set of states in a markovchain process

The package provides a function `expectedRewardsBeforeHittingA` that returns the value of expected first passage rewards  $E$  given rewards corresponding to every state, an initial state. This means the function returns expected reward for given initial state  $s_0$ , number of transitions  $n$  and for a set of states  $A$  with a constraint such that the process does not hit any of the states that belong to state  $A$ .  $S$  is the set of all possible states.

The function uses an equation which is as follows:

$$E = \sum_{i=1}^n 1_{s_0} P_{S-A}^i R_{S-A}$$

here  $1_{s_0} = [0, 0, \dots, 0, 1, 0, \dots, 0, 0, 0]$ , 1 being on  $s_0$  position and  $R_{S-A}$  being the rewards vector for  $S - A$  state.

## Checking Irreducibility of a CTMC

The package provides a function `is.CTMCirreducible` that returns a boolean value stating whether the ctmc object is irreducible. We know that a continuous time markovchain is irreducible if and only if its embedded chain is irreducible (Sigman 2009).

We demonstrate an example running the function:

```
energyStates <- c("sigma", "sigma_star")
byRow <- TRUE
gen <- matrix(data = c(-3, 3,
                      1, -1), nrow = 2,
              byrow = byRow, dimnames = list(energyStates, energyStates))
molecularCTMC <- new("ctmc", states = energyStates,
                    byrow = byRow, generator = gen,
                    name = "Molecular Transition Model")
is.CTMCirreducible(molecularCTMC)
```

```
## [1] TRUE
```

## Simulation of Higher Order Multivariate Markovchains

The package provides `predictHommc` function. This function provides a simulation system for higher order multivariate markovchains. The function assumes that the state probability distribution of the  $j$ th sequence at time  $r + 1$  depends on the state probability distribution of all the sequences at  $n$  previous moments of time i.e.  $t = r$  to  $t = r - n + 1$ . Hence the proposed model takes the form mathematically as: (Ching, Ng, and Fung 2008)

$$X_{r+1}^j = \sum_{k=1}^s \sum_{h=1}^n \lambda_{jk}^{(h)} P_h^{(jk)} X_{r-h+1}^{(k)}, \quad j = 1, 2, \dots, s, \quad r = n-1, n, \dots$$

with initials  $X_0^{(k)}, X_1^{(k)}, \dots, X_{n-1}^{(k)}$  ( $k = 1, 2, \dots, s$ ). Here,

$$\lambda_{jk}^{(h)}, \quad 1 \leq j, k \leq s, \quad 1 \leq h \leq n \quad \text{and} \quad \sum_{k=1}^s \sum_{h=1}^n \lambda_{jk}^{(h)} = 1, \quad j = 1, 2, \dots, s.$$

Now we run an example on sample hommc object for simulating next 3 steps using `predictHommc` function. The function provides a choice of entering initial states according to the hommc object. In case the user does not enter initial states, the function takes all initial states to be the first state from the set of states.

```
statesName <- c("a", "b")
P <- array(0, dim = c(2, 2, 4), dimnames = list(statesName, statesName))
P[, , 1] <- matrix(c(0, 1, 1/3, 2/3), byrow = FALSE, nrow = 2)
P[, , 2] <- matrix(c(1/4, 3/4, 0, 1), byrow = FALSE, nrow = 2)
P[, , 3] <- matrix(c(1, 0, 1/3, 2/3), byrow = FALSE, nrow = 2)
P[, , 4] <- matrix(c(3/4, 1/4, 0, 1), byrow = FALSE, nrow = 2)
Lambda <- c(0.8, 0.2, 0.3, 0.7)
ob <- new("hommc", order = 1, states = statesName, P = P,
          Lambda = Lambda, byrow = FALSE, name = "FOMMC")

predictHommc(ob, 3)

##      [,1] [,2] [,3]
## [1,] "b"  "b"  "a"
## [2,] "a"  "a"  "b"
```

## Check Time Reversibility of Continuous-time markovchains

A Continuous-time markovchain with generator  $Q$  and stationary distribution  $\pi$  is said to be time reversible if: (Dobrow 2016)

$$\pi_i q_{ij} = \pi_j q_{ji}$$

Intuitively, a continuous-time Markov chain is time reversible if the process in forward time is indistinguishable from the process in reversed time. A consequence is that for all states  $i$  and  $j$ , the long-term forward transition rate from  $i$  to  $j$  is equal to the long-term backward rate from  $j$  to  $i$ .

The package provides `is.TimeReversible` function to check if a `ctmc` object is time-reversible. We follow with an example run on a `ctmc` object.

```
energyStates <- c("sigma", "sigma_star")
byRow <- TRUE
gen <- matrix(data = c(-3, 3,
                      1, -1), nrow = 2,
              byrow = byRow, dimnames = list(energyStates, energyStates))
molecularCTMC <- new("ctmc", states = energyStates,
                    byrow = byRow, generator = gen,
                    name = "Molecular Transition Model")
is.TimeReversible(molecularCTMC)

## [1] TRUE
```

## References

Alexander Kreinin, Marina Sidelnikova. 2001. “Regularization Algorithms for Transition Matrices.” *Algo Research Quarterly* 4 (1/2). ALGO RESEARCH QUARTERLY: 23–40.

Ching, Wai-Ki, Michael K Ng, and Eric S Fung. 2008. “Higher-Order Multivariate Markov Chains and Their Applications.” *Linear Algebra and Its Applications* 428 (2). Elsevier: 492–507.

Dobrow, Robert P. 2016. *Introduction to Stochastic Processes with R*. John Wiley & Sons.

Gallager, Robert G. 2013. *Stochastic Processes: Theory for Applications*. Cambridge University Press.

Norris, J. R. 1998. *Markovchains*. Cambridge University Press.

Sigman, Karl. 2009. “Continuous Time Markovchains.” Columbia University.

StackOverflow. 2015. <https://math.stackexchange.com/questions/1450399/probability-that-a-chain-will-enter-state-5-before-it-newreg=82f90b66b949495a91661caad24db915>.

Thomas Krak, Arno Siebes, Jasper De Bock. 2017. “Imprecise Continuous Time Markov Chains.” *International Journal of Approximate Reasoning* 88. arXiv: 452–528.