A Generalized Focused Information Criterion for GMM Model and Moment Selection

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Generalized Focused Information Criterion (GFIC)

Purpose

Simultaneous Model and Moment Selection for GMM Estimation

Main Idea

Choose model and moment conditions to yield minimum MSE estimator of user-specified target parameter even if mis-specified.

Some Related Work

- ► GMM Model and Moment Selection (Andrews & Lu, 2001)
- Focused Moment Selection Criterion (DiTraglia, 2013)
- ► Focused Information Criterion (Claeskens & Hjort, 2003)

Key Features of GFIC

Select "Wrong" Specification on Purpose

- ▶ Minimize MSE rather than search for "true" specification.
- ▶ Tolerate some bias to reduce variance.

Focused Selection

- ▶ MSE of user-specified target parameter μ
- ▶ Different Research Goal ⇒ Different Criterion

Local Mis-specification

- Asymptotic MSE to approximate finite sample MSE
- lackbox Local asymptotics \Rightarrow bias-variance tradeoff in the limit

GFIC Model & Moment Selection Framework

Parameters

- ▶ Always estimate "protected" parameters θ
- lacktriangle Consider setting "nuisance" parameters γ equal to constant γ_0

Moment Conditions

- ${\it g}$ correctly specified provided we estimate γ
- \blacktriangleright h possibly mis-specified even if we estimate γ

Scalar Target Parameter

▶ Want minimum MSE estimator of $\mu = \phi(\theta, \gamma)$

GFIC Asymptotics: Local Mis-specification

Triangular Array DGP (Only a Device!)

$$E\begin{bmatrix}g(Z_{ni}, \gamma_0 + \delta/\sqrt{n}, \theta_0)\\h(Z_{ni}, \gamma_0 + \delta/\sqrt{n}, \theta_0)\end{bmatrix} = \begin{bmatrix}0\\\tau/\sqrt{n}\end{bmatrix}$$

δ Controls Model Mis-specification

- Restriction $\gamma = \gamma_0$ false for finite *n* unless $\delta = 0$
- Model mis-specification disappears in the limit

au Controls Moment Mis-specification

- ▶ MCs in h are invalid for finite n unless $\tau = 0$
- Moment mis-specification disappears in the limit

Notation for Model and Moment Selection

Model Selection – Which Elements of γ to estimate?

- ▶ Parameters $\beta = (\theta, \gamma)$
- ▶ Model Selection Vector *b*

Moment Selection – Which MCs to use in Estimation?

- ▶ Full set of moment conditions f = (g, h)
- Moment Selection Vector c

Putting Them Together

- Candidate Specification (b, c)
- \triangleright Set of all candidates \mathcal{BC}

Overview of GFIC Derivation

Step 1 – Asymptotic Normality of GMM Estimator $\widehat{\beta}(b,c)$

- \blacktriangleright Biased unless γ estimated, no MCs from h used
- ▶ Smaller variance if γ set to γ_0 , MCs from h used

Step 2 – Asymptotic Normality of Target Parameter $\widehat{\mu}(b,c)$

- ▶ Inherits bias-variance tradeoff from $\widehat{eta}(b,c)$
- lacksquare AMSE $(\widehat{\mu}(b,c))$ depends on $B=\left[egin{array}{cc} au au' & au\delta' \ \delta au' & \delta\delta' \end{array}
 ight]$

Step 3 – GFIC =
$$\widehat{\mathsf{AMSE}}(\widehat{\mu}(b,c))$$

▶ Substitute asymptotically unbiased estimator \widehat{B} of B, consistent estimators of everything else.

Estimating δ, τ – Overview

Why is this difficult?

- ▶ Local mis-specification \Rightarrow no consistent estimators of δ, τ
- Can construct asymptotically unbiased estimators
- ▶ Actually need to estimate $B = \begin{bmatrix} \tau \tau' & \tau \delta' \\ \delta \tau' & \delta \delta' \end{bmatrix}$

How and when can we proceed?

- $ightharpoonup \widehat{eta}_{\mathbf{v}} = (\widehat{\theta}_{\mathbf{v}}, \widehat{\gamma}_{\mathbf{v}})$ estimates all parameters using g only
- ▶ Plug $\widehat{\beta}_v$ into sample analogue of h to estimate τ/\sqrt{n}
- Use $(\widehat{\gamma}_{v} \gamma_{0})$ to estimate δ/\sqrt{n}
- ▶ Bias correction to get asymptotically unbiased estimator of B

Estimating δ, τ – Details

Limit Distribution of Bias Parameter Estimators

$$\left[\begin{array}{c} \widehat{\delta} \\ \widehat{\tau} \end{array}\right] = \sqrt{n} \left[\begin{array}{c} (\widehat{\gamma}_{V} - \gamma_{0}) \\ h_{n}(\widehat{\beta}_{V}) \end{array}\right] \rightarrow_{d} \left[\begin{array}{c} \delta \\ \tau \end{array}\right] + \Psi \ \textit{N}(0, \Omega)$$

▶ Both Ψ and Ω can be estimated consistently!

Asymptotically Unbiased Estimator of B

$$B = \begin{bmatrix} \tau \tau' & \tau \delta' \\ \delta \tau' & \delta \delta' \end{bmatrix}$$

$$\widehat{B} = \begin{bmatrix} \widehat{\tau} \widehat{\tau}' & \widehat{\tau} \widehat{\delta}' \\ \widehat{\delta} \widehat{\tau}' & \widehat{\delta} \widehat{\delta}' \end{bmatrix} - \widehat{\Psi} \widehat{\Omega} \widehat{\Psi}'$$

Using the GFIC for Selection

- ▶ Calculate $\widehat{\mathsf{AMSE}}(\widehat{\mu}(b,c))$ for each $(b,c) \in \mathcal{BC}$
- Choose the specification with the lowest AMSE estimate.
- Expression for AMSE is complicated but easy to compute.

Simple Dynamic Panel Example – Large N, Small T

True Data Generating Process

$$y_{it} = \gamma y_{it-1} + \theta x_{it} + \eta_i + v_{it}$$

- ▶ Dynamics unless $\gamma = 0$
- ▶ Correlated effects $\eta_i \Rightarrow$ first differences
- \triangleright x_{it} predetermined but *not* strictly exogenous

Goal – Estimate θ with minimum MSE

- ▶ Model Selection Decision: set $\gamma = 0$?
- ▶ Moment Selection Decision: treat x_{it} as strictly exogenous?

Anderson & Hsiao-esque 2SLS Estimators (1982)

LW Moment Conditions:

$$\mathbb{E}\left[\left(\begin{array}{c} y_{i,t-2} \\ x_{i,t-1} \end{array}\right) \left(\Delta y_{it} - \gamma \Delta y_{i,t-1} - \theta \Delta x_{it}\right)\right] = 0, \text{ for } t = 3, \dots, T$$

LS Adds the Moment Conditions:

$$\mathbb{E}\left[x_{it}\left(\Delta y_{it} - \gamma \Delta y_{i,t-1} - \theta \Delta x_{it}\right)\right] = 0, \text{ for } t = 3, \dots, T$$

Only the LW conditions are correct

Anderson & Hsiao-esque 2SLS Estimators (1982)

W Moment Conditions:

$$\mathbb{E}\left[x_{i,t-1}\left(\Delta y_{it} - \theta \Delta x_{it}\right)\right] = 0$$
, for $t = 2, \dots, T$

S Adds the Moment Conditions:

$$\mathbb{E}\left[x_{it}\left(\Delta y_{it} - \theta \Delta x_{it}\right)\right] = 0$$
, for $t = 2, \dots, T$

None of these moment conditions are correct

Why Use an Incorrect Specification?

$$\Delta y_{it} = \gamma \Delta y_{it-1} + \theta \Delta x_{it} + \Delta v_{it}$$

Wrong Model

- $ightharpoonup \gamma$ small \implies ignore dynamics
- Adds small bias
- ► Much lower variance: extra time period, fewer parameters

Invalid MCs

- ▶ $E[x_{it}v_{it-1}]$ small \implies add x_{it} as instrument for period t
- Adds small bias
- ▶ Much lower variance: x_{it} is a strong instrument for Δx_{it}

Simulation Setup

Similar to Andrews & Lu (2001)

- $y_{i0} = 0$
- $y_{it} = \frac{\gamma}{\gamma} y_{it-1} + 0.5 x_{it} + \eta_i + v_{it}$ (t = 1, ..., T)

$$\begin{bmatrix} x_i \\ \eta_i \\ v_i \end{bmatrix} \sim \text{iid } N \begin{pmatrix} \begin{bmatrix} 0_T \\ 0 \\ 0_T \end{bmatrix}, \begin{bmatrix} I_T & 0.2\iota_T & \sigma_{XV} \Gamma \\ 0.2\iota_T' & 1 & 0_T' \\ \sigma_{XV} \Gamma' & 0_T & I_T \end{bmatrix} \end{pmatrix}$$

 $ightharpoonup E[x_{it}v_{it-1}] = \sigma_{xv}$ but $E[x_{it}v_{is}] = 0, s \neq t-1$

Vary γ and σ_{xv} over a grid

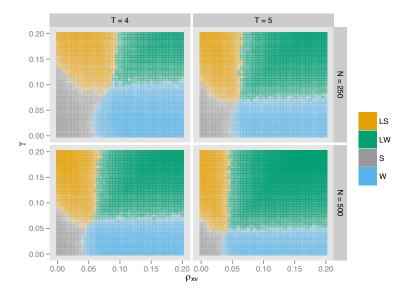


Figure: Minimum RMSE Specification at each combination of parameter values. Shading gives RMSE relative to second best specification.

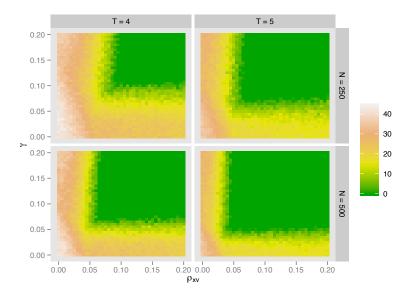


Figure: % RMSE Advantage of Best Specification (vs. LW)

Competing Procedure: Downward J-test

- 1. Use S unless J-test rejects.
- 2. If S rejected, use W unless J-test rejects.
- 3. If W rejected, use LS unless J-test rejects.
- 4. Only use LW if all others rejected.

Competing Procedures: Andrews & Lu (2001)

J-test Statistic Minus Penalty Term

BIC-Type
$$J-(|c|-|b|)\log n$$

AIC-Type $J-2(|c|-|b|)$
HQ-Type $J-2.01(|c|-|b|)\log\log n$

- ightharpoonup |b| = # (parameters estimated)
- |c| = #(MCs used)
- Select specification with *lowest* value of criterion

-	N = 250		N = 500	
	T = 4	T = 5	T = 4	T = 5
LW	19	10	13	7
LS	30	44	54	79
W	24	34	46	64
S	31	50	64	94
GFIC	17	13	15	10
J-test 10%	32	45	55	74
J-test 5%	31	47	57	79
GMM-BIC	32	48	62	87
GMM-HQ	32	46	57	77
GMM-AIC	31	39	47	57

Table: Average RMSE minus Pointwise Optimal (% points)

	N = 250		N = 500	
	T = 4	T = 5	T = 4	T = 5
LW	0	0	0	0
LS	42	81	94	154
W	49	88	105	158
S	48	92	107	171
GFIC	3	8	6	11
J-test 10%	43	78	91	140
J-test 5%	45	83	98	153
GMM-BIC	48	89	106	168
GMM-HQ	46	85	102	154
GMM-AIC	39	68	81	118

Table: Worst-case RMSE minus Minimax Optimal (% points)

Valid Post-Selection Inference

Post Selection Estimator

Randomly Weighted Average of candidate estimators (0-1 weights).

Standard Cls are Invalid

Nonstandard limit distribution since weights are data dependent

What about consistent selection?

No *pointwise* effect on the limiting distribution, but the same is *not* true uniformly (Pötscher, 1991).

Post-Selection Inference via Model Average Estimators

Consider an estimator of the form

$$\widehat{\mu} = \sum_{(b,c) \in \mathcal{BC}} \widehat{\omega}(b,c) \widehat{\mu}(b,c)$$

where $\widehat{\omega}(b,c)$ is a set of data-dependent weights.

Some Notation

$$F = \begin{bmatrix} \nabla_{\gamma'} g(Z, \gamma_0, \theta_0) & \nabla_{\theta'} g(Z, \gamma_0, \theta_0) \\ \nabla_{\gamma'} h(Z, \gamma_0, \theta_0) & \nabla_{\theta'} h(Z, \gamma_0, \theta_0) \end{bmatrix}$$

$$F = \begin{bmatrix} F_{\gamma} & F_{\theta} \end{bmatrix} = \begin{bmatrix} G_{\gamma} & G_{\theta} \\ H_{\gamma} & H_{\theta} \end{bmatrix} = \begin{bmatrix} G \\ H \end{bmatrix}$$

$$\Omega = Var \begin{bmatrix} g(Z, \gamma_0, \theta_0) \\ h(Z, \gamma_0, \theta_0) \end{bmatrix} = \begin{bmatrix} \Omega_{gg} & \Omega_{gh} \\ \Omega_{hg} & \Omega_{hh} \end{bmatrix}$$

These expressions are evaluated in the limit where all MCs have expectation zero at (γ_0, θ_0) .

Limit Distribution of GMM Estimators

$$\sqrt{n}\left(\widehat{eta}(b,c)-eta_0^{(b)}
ight)$$
 converges in distribution to

$$-K(b,c)\Xi_{c}\left(\mathcal{N}+\left[\begin{array}{c}0\\\tau\end{array}\right]-F_{\gamma}\delta\right)$$

$$K(b,c) = [F(b,c)'W_cF(b,c)]^{-1}F(b,c)'W_c$$

 $\Xi_c = \text{Moment Selection Matrix}$
 $\mathcal{N} \sim N(0,\Omega)$

Limit Distribution of Target Parameter Estimators

 $\sqrt{n}(\widehat{\mu}(b,c)-\mu_n)$ converges in distribution to

$$\begin{array}{rcl} \mu & = & \varphi(\theta,\gamma) \\ \varphi_0 & = & \varphi(\gamma_0,\theta_0) \\ \mu_n & = & \varphi(\theta_0,\gamma_0+\delta/\sqrt{n}) \\ \Xi_b & = & \mathsf{Model Selection Matrix} \\ \Xi_c & = & \mathsf{Moment Selection Matrix} \\ \mathscr{N} & \sim & \mathcal{N}(0,\Omega) \end{array}$$

Limit Distribution of $(\widehat{\delta}, \widehat{\tau})$

$$\left[\left[\begin{array}{c} \widehat{\delta} \\ \widehat{\tau} \end{array} \right] = \sqrt{n} \left[\begin{array}{c} (\widehat{\gamma}_{v} - \gamma_{0}) \\ h_{n}(\widehat{\beta}_{v}) \end{array} \right] \rightarrow_{d} \left[\begin{array}{c} \delta \\ \tau \end{array} \right] + \Psi \mathcal{N}$$

$$\Psi = \begin{bmatrix} -K_{v}^{\gamma} & \mathbf{0} \\ -HK_{v} & I \end{bmatrix}$$

$$\mathcal{N} \sim N(0, \Omega)$$

Key Point: Joint Convergence

$$\sqrt{n}\left(\widehat{\mu}\left(b,c\right)-\mu_{n}\right)$$
 converge jointly $orall\left(b,c
ight)\in\mathcal{BC}$ along with $\left(\widehat{\delta},\widehat{ au}
ight)$

- lacktriangle Only source of randomness in the limit is ${\mathscr N}$
- Everything except δ and τ is consistently estimable.
- Just need to impose some conditions on the weights...

Requirements for the Weights

Weights Sum to 1

$$\sum_{(b,c)\in\mathcal{BC}}\widehat{\omega}(b,c)=1$$

Joint Convergence

$$\widehat{\omega}(b,c)
ightarrow_d \psi(\mathscr{N},\delta, au|b,c)$$
 jointly for all $(b,c) \in \mathcal{BC}$

Limit Function ψ

Depends only on $\mathcal{N}, \delta, \tau$, and consistently estimable quantities.

Assumptions cover GFIC, J-test, Andrews & Lu (2001), etc.

Limit Distribution of Averaging Estimator

Weights Sum to 1

$$\sqrt{n}(\widehat{\mu} - \mu_n) = \sum_{(b,c) \in \mathcal{BC}} \widehat{\omega}(b,c) \sqrt{n} (\widehat{\mu}(b,c) - \mu_n)$$

Joint Convergence in Distribution

$$\sqrt{n}(\widehat{\mu}-\mu_n)\rightarrow_d \Lambda(\tau,\delta)$$

$$\Lambda(\tau, \delta) = -\nabla_{\beta} \varphi'_0 \sum_{(b,c) \in \mathcal{BC}} \psi(\mathcal{N}, \delta, \tau | b, c) \left\{ \Xi'_b K(b, c) \Xi_c \mathcal{N} + M(b, c) \begin{bmatrix} \delta \\ \tau \end{bmatrix} \right\}$$

Non-normal limit distribution that depends on (δ, τ)

"Bootstrapping the Limit Experiment"

Suppose δ and τ were known:

- (i) For each $j=1,2,\ldots,J$, generate $\mathscr{N}_j \sim \mathcal{N}(0,\widehat{\Omega})$
- (ii) For each for $j = 1, 2, \dots, J$ set

$$\Lambda_{j}(\boldsymbol{\tau},\boldsymbol{\delta}) = -\nabla_{\beta}\widehat{\varphi}'_{0} \sum_{(b,c) \in \mathcal{BC}} \widehat{\psi}(\mathcal{N}_{j},\boldsymbol{\delta},\boldsymbol{\tau}|b,c) \left\{ \Xi'_{b}\widehat{K}(b,c)\Xi_{c}\mathcal{N}_{j} + \widehat{M}(b,c) \left[\begin{array}{c} \boldsymbol{\delta} \\ \boldsymbol{\tau} \end{array}\right] \right\}$$

(iii) Using $\{\Lambda_j(\boldsymbol{\delta}, \boldsymbol{\tau})\}_{j=1}^J$, calculate $\widehat{a}(\boldsymbol{\delta}, \boldsymbol{\tau})$, $\widehat{b}(\boldsymbol{\delta}, \boldsymbol{\tau})$ such that

$$P\left\{\widehat{a}(\delta, \tau) \leq \Lambda(\delta, \tau) \leq \widehat{b}(\delta, \tau)\right\} = 1 - \alpha$$

Accounting for Estimated (δ, τ)

Let $R(\alpha_1)$ be a $(1 - \alpha_1) \times 100\%$ confidence region for (δ, τ) .

1. For each $(\delta, \tau) \in R(\alpha_1)$ construct a confidence interval

$$\mathbb{P}\left\{\widehat{a}(\underline{\delta}, \underline{\tau}) \leq \Lambda(\underline{\delta}, \underline{\tau}) \leq \widehat{b}(\underline{\delta}, \underline{\tau})\right\} = 1 - \alpha_2$$

using the simulation procedure from the previous slide.

2. Define

$$\widehat{a}_{min}(\widehat{\delta}, \widehat{\tau}) = \min_{\substack{(\delta, \tau) \in R(\alpha_1)}} \widehat{a}(\underline{\delta}, \tau)$$

$$\widehat{b}_{max}(\widehat{\delta}, \widehat{\tau}) = \max_{\substack{(\delta, \tau) \in R(\alpha_1)}} \widehat{b}(\underline{\delta}, \tau)$$

3. The following CI has asymptotic coverage of at least $1 - (\alpha_1 + \alpha_2)$

$$\mathsf{CI}_{sim} = \left[\widehat{\mu} - \frac{\widehat{b}_{max}(\widehat{\delta}, \widehat{\tau})}{\sqrt{n}}, \quad \widehat{\mu} - \frac{\widehat{a}_{min}(\widehat{\delta}, \widehat{\tau})}{\sqrt{n}} \right]$$

Extensions and Future Work

This Paper

Simulations for post-selection inference and averaging in progress.

Other Projects Underway

Risk-based model selection and averaging using local-asymptotics:

- Combining OLS and IV Estimators
- "Change in Exogeneity" (with Otilia Boldea)
- "Covariate Choice in Treatment Assignment Problems" (with Debopam Battacharya)

Generalized Focused Information Criterion

Purpose

Simultaneous Model and Moment Selection for GMM Estimation

Key Features

- Local mis-specification framework
- Estimator of AMSE of user-specified target parameter
- Focused Selection
- Select "wrong" specification on purpose
- Works well in simulations
- Provides framework for model and moment averaging
- Valid post-selection confidence intervals

Supplementary Material

Average RMSE	N = 250		N = 500	
	T = 4	T = 5	T = 4	T = 5
LW	0.073	0.057	0.051	0.040
LS	0.079	0.074	0.070	0.066
W	0.075	0.069	0.066	0.061
S	0.080	0.077	0.074	0.072
GFIC	0.071	0.058	0.052	0.041
Downward J-test (10%)	0.080	0.074	0.070	0.065
Downward J-test (5%)	0.080	0.075	0.071	0.067
GMM-BIC	0.080	0.076	0.073	0.069
GMM-HQ	0.080	0.075	0.071	0.066
GMM-AIC	0.080	0.071	0.066	0.058

Worst-Case RMSE	N = 250		N = 500	
	T = 4	T = 5	T = 4	T = 5
LW	0.084	0.064	0.059	0.045
LS	0.120	0.116	0.115	0.113
W	0.125	0.120	0.122	0.115
S	0.125	0.123	0.122	0.121
GFIC	0.087	0.069	0.063	0.049
Downward J-test (10%)	0.120	0.114	0.113	0.107
Downward J-test (5%)	0.122	0.117	0.117	0.113
GMM-BIC	0.125	0.121	0.122	0.119
GMM-HQ	0.123	0.118	0.120	0.113
GMM-AIC	0.117	0.107	0.107	0.097