

An Introduction to the Dirichlet Process and Nonparametric Bayesian Models

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Motivation for Nonparametric Bayes

Gaussian Mixture Model

- EM for GMM
- Bayesian GMM
- The Infinite Limit

Dirichlet Process

- Definition
- Stick Breaking Construction
- Pólya Urn Scheme and Chinese Restaurant Process
- Extensions: Pitman-Yor Process and Hierarchical DP

Many successful applications of Bayesian models:

- Machine Learning
- Cognitive Science
- Theoretical Neuroscience?

But complex models have to be specified in advance. Not yet *fully* unsupervised learning.

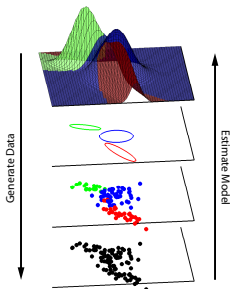
For models with a fixed number of parameters (e.g. clustering, HMM) many ways to pick the optimal number of parameters:

$$AIC = -2\ln P(D|\hat{\Theta}_k) + 2k$$

$$BIC = -2\ln P(D|\hat{\Theta}_k) + k\ln|D|$$

$$P(D|\mathcal{M}_k) = \int P(D|\Theta_k)P(\Theta_k|\mathcal{M}_k)d\Theta_k$$

Different methods have different shortcomings.



GMM

$$\theta_k = \{\vec{\mu}_k, \Sigma_k\}$$

$$c_i | \vec{\pi} \sim \text{Discrete}(\pi_1, \dots, \pi_K)$$

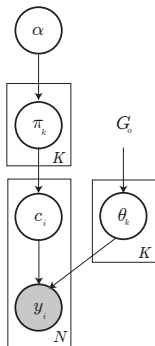
$$\vec{y}_i | c_i = k, \Theta \sim \text{Gaussian}(\theta_k)$$

Expectation-Maximization

$$\text{E-step} \quad T_{i,k}^{(t)} = P(c_i = k | \vec{y}_i, \theta_k^{(t)})$$

$$Q(\Theta, \vec{\pi} | \Theta^{(t)}, \vec{\pi}^{(t)}) = \mathbb{E}[\log L(\Theta, \vec{\pi} | \vec{y}, T^{(t)})]$$

$$\text{M-step} \quad (\Theta^{(t+1)}, \vec{\pi}^{(t+1)}) = \arg \max_{\Theta, \vec{\pi}} Q(\Theta, \vec{\pi} | \Theta^{(t)}, \vec{\pi}^{(t)})$$



Bayesian GMM

$$\Sigma_k \sim \text{IW}_{\nu_0}(\Lambda_0^{-1})$$

$$\vec{\mu}_k \sim \text{Gaussian}(\vec{\mu}_0, \Sigma_k / \kappa_0)$$

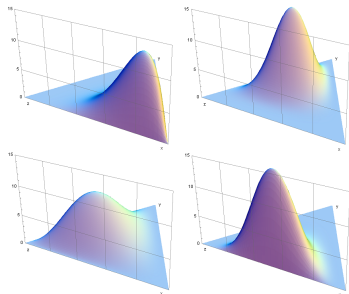
$$\vec{\pi} | \alpha \sim \text{Dir}\left(\frac{\alpha}{K}, \dots, \frac{\alpha}{K}\right)$$

$$\theta_k = \{\vec{\mu}_k, \Sigma_k\}$$

$$c_i | \vec{\pi} \sim \text{Discrete}(\pi_1, \dots, \pi_K)$$

$$\vec{y}_i | c_i = k, \Theta \sim \text{Gaussian}(\theta_k)$$

- Inference: sample posterior of c_i via MCMC
- Applied to spike sorting by Lewicki [1994].



[Source: Wikimedia Commons]

Dirichlet Distribution

$$\vec{\pi} \sim \text{Dir}(\vec{\alpha})$$

$$\vec{\alpha} = \alpha \vec{H}, \sum_{i=1}^K H_i = 1$$

$$\mathbb{E}[\vec{\pi}] = \vec{H}$$

$$\alpha \rightarrow \infty \Rightarrow \vec{\pi} \rightarrow \vec{H}$$

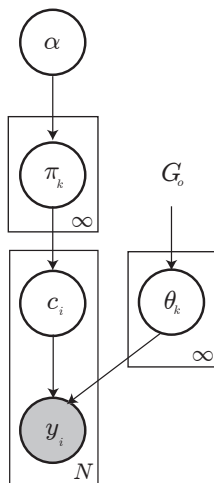
$$\alpha \rightarrow 0 \Rightarrow \vec{\pi} \text{ becomes sparse}$$

$$\begin{aligned}
 \vec{\pi} &\sim \text{Dir}\left(\frac{\alpha}{K}, \dots, \frac{\alpha}{K}\right) \\
 P(c_{i+1} = k | c_1, \dots, c_i, \alpha) &= \int P(c_i + 1 = k | \vec{\pi}) p(\vec{\pi} | c_1, \dots, c_i, \alpha) d\vec{\pi} \\
 &= \frac{\Gamma(\alpha + i)}{\prod_{j=1}^K \Gamma(\frac{\alpha}{K} + n_j)} \int \pi_1^{\frac{\alpha}{K} + n_1 - 1} \dots \pi_k^{\frac{\alpha}{K} + n_k} \dots \pi_K^{\frac{\alpha}{K} + n_K - 1} d\vec{\pi} \\
 &= \frac{n_k + \frac{\alpha}{K}}{\alpha + i}
 \end{aligned}$$

Where n_k is the number of c_j , $j = 1, \dots, i$ such that $c_j = k$. Order the clusters so $n_k > 0$ if $k \leq K_+$ and $n_k = 0$ if $k > K_+$. Then as $K \rightarrow \infty$

$$P(c_{i+1} = k | c_1, \dots, c_i, \alpha) = \begin{cases} \frac{n_k}{\alpha + i} & k \leq K_+ \\ \frac{\alpha}{\alpha + i} & k > K_+ \end{cases} .$$

This is the *Chinese Restaurant Process*, $CRP(\alpha)$.



Infinite GMM

$$c_i | c_{1:i-1} \sim CRP(\alpha)$$

$$\Sigma_k \sim IW_{\nu_0}(\Lambda_0^{-1})$$

$$\vec{\mu}_k \sim \text{Gaussian}(\vec{\mu}_0, \Sigma_k / \kappa_0)$$

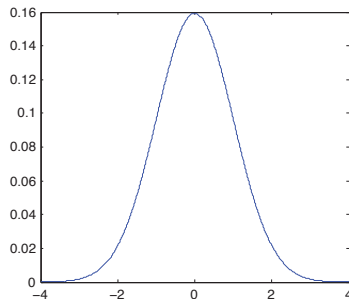
$$\theta_k = \{\vec{\mu}_k, \Sigma_k\}$$

$$\vec{y}_i | c_i = k, \Theta \sim \text{Gaussian}(\theta_k)$$

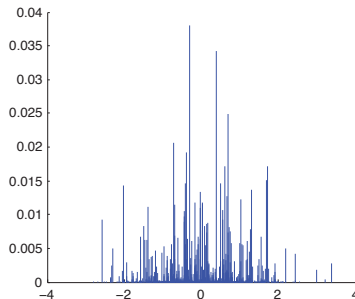
Special case of the Dirichlet Process Mixture Model, due to
Rasmussen [2000]

Dirichlet Process: $\mathcal{G} \sim DP(\alpha, H)$

- α - concentration parameter
- H - base distribution
- \mathcal{G} is *atomic*: $p(\theta|\mathcal{G}) = \sum_{k=1}^{\infty} \pi_k \delta(\theta - \theta_k)$



$H = \text{Gaussian}(0, 1)$



$\mathcal{G} \sim DP(100, H)$

$$\begin{aligned}\pi'_k &\sim \text{Beta}(1, \alpha) \\ \pi_k &= \pi'_k \prod_{i=1}^{k-1} (1 - \pi_i) \\ \theta_k &\sim H \\ \mathcal{G} &= \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}\end{aligned}$$

Draws $x_{1:i} \sim \mathcal{G}$ cluster together. Let K_+ be the number of distinct values of $x_{1:i}$, n_k be the number of draws with value θ_k .

$$\mathcal{G}|x_{1:i} \sim DP \left(\alpha + i, \sum_{k=1}^{K_+} \frac{n_k}{\alpha + i} \delta_{\theta_k} + \frac{\alpha}{\alpha + i} H \right)$$

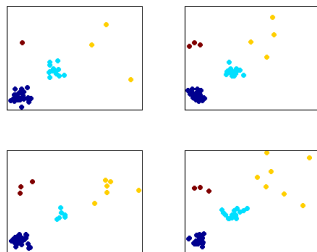
$$x_{i+1}|x_{1:i} \sim \sum_{k=1}^{K_+} \frac{n_k}{\alpha + i} \delta_{\theta_k} + \frac{\alpha}{\alpha + i} H$$

Pitman-Yor Process

$\mathcal{G} \sim PY(\alpha, d, H), PY(\alpha, 0, H) \Leftrightarrow DP(\alpha, H)$

- $d \in [0, 1]$: discount
- Stick breaking construction: $\pi'_k \sim \text{Beta}(1 - d, c + kd)$
- CRP construction:

$$P(c_{i+1} = k | c_1, \dots, c_i, \alpha, d) = \begin{cases} \frac{n_k - d}{\alpha + i} & k \leq K_+ \\ \frac{\alpha + kd}{\alpha + i} & k > K_+ \end{cases}.$$



Hierarchical Dirichlet Process

Share clusters across groups of data

$$\mathcal{G}_0 \sim DP(\alpha, H)$$

$$\mathcal{G}_j \sim DP(\alpha, \mathcal{G}_0)$$

$$\theta_{ji} \sim \mathcal{G}_j$$

Applications

- Infinite HMM - each \mathcal{G}_j is the transition probability given a state [Teh et al., 2006].
- Variable-length Markov models for language data [Teh, 2006].

- Discrete time, discrete alphabet sequence learning
- Learn probabilistic deterministic finite automata
 - Subclass of HMMs
 - Intermediate between variable-length Markov models and full HMM
 - Use HDP as prior for transition matrix, similar to infinite HMM
 - Inference via Metropolis-Hastings
 - Works on small regular grammars (~ 7 states), currently extending to richer data

Nonparametric Bayesian models sidestep the model selection problem, combining model estimation and model selection into one. We define the Dirichlet Process and use it as a prior over parameters that controls the clustering of data. We show that the DP emerges in the limit of certain parametric models as the number of parameters goes to infinity. Draws from a DP can be marginalized out, yielding a tractable model that can be estimated by standard Bayesian methods. The DP can be extended in various ways, and we are applying these tools to discrete alphabet sequence learning with as few free parameters as possible.

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References:

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