# Regression Estimation – Least Squares and Maximum Likelihood

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## Least Squares Max(min)imization

• Function to minimize w.r.t.  $\beta_0$ ,  $\beta_1$ 

$$Q = \sum_{i=1}^{n} (Y_i - (\beta_0 + \beta_1 X_i))^2$$

- Minimize this by maximizing –Q
- Find partials and set both equal to zero

$$\frac{dQ}{d\beta_0} = 0$$

$$\frac{dQ}{d\beta_1} = 0$$

go to board

## Normal Equations

• The result of this maximization step are called the normal equations.  $b_0$  and  $b_1$  are called point estimators of  $\beta_0$  and  $\beta_1$  respectively

$$\sum Y_i = nb_0 + b_1 \sum X_i$$

$$\sum X_i Y_i = b_0 \sum X_i + b_1 \sum X_i^2$$

 This is a system of two equations and two unknowns. The solution is given by...

Write these on board

## Solution to Normal Equations

After a lot of algebra one arrives at

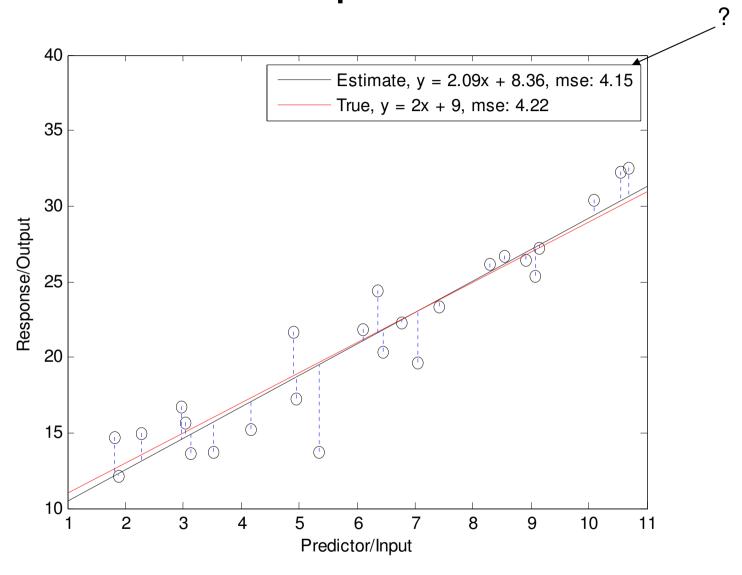
$$b_{1} = \frac{\sum (X_{i} - \bar{X})(Y_{i} - \bar{Y})}{\sum (X_{i} - \bar{X})^{2}}$$

$$b_{0} = \bar{Y} - b_{1}\bar{X}$$

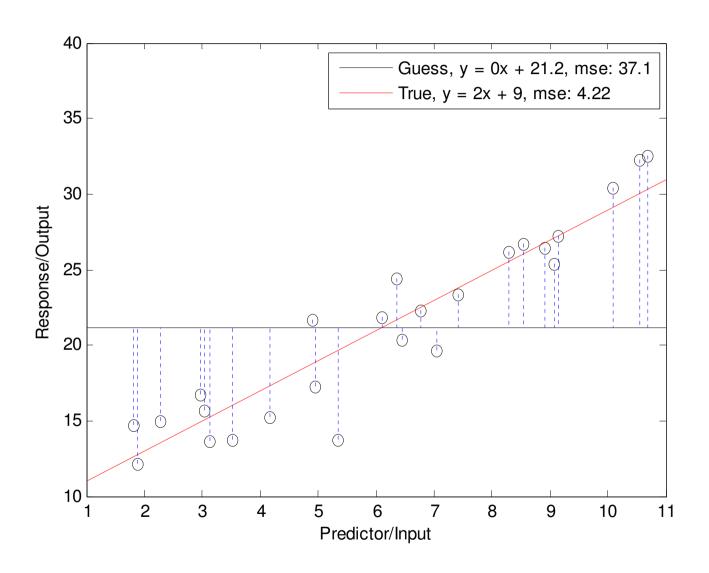
$$\bar{X} = \frac{\sum X_{i}}{n}$$

$$\bar{Y} = \frac{\sum Y_{i}}{n}$$

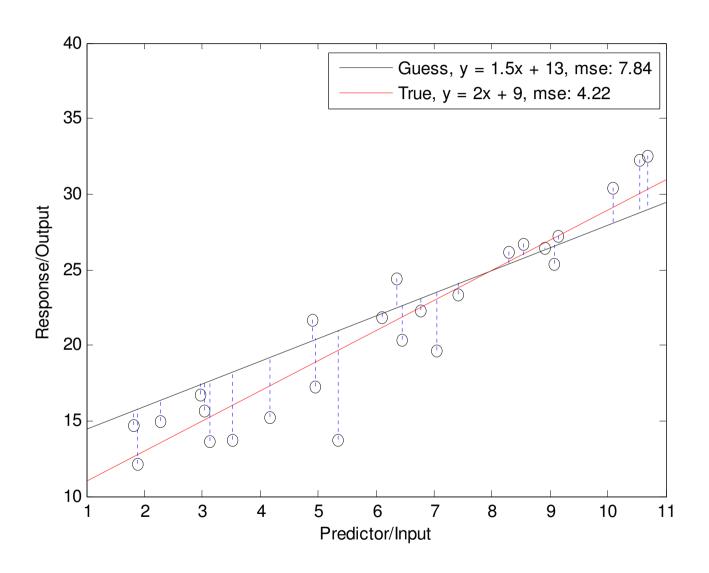
## Least Squares Fit



#### Guess #1



#### Guess #2



## Looking Ahead: Matrix Least Squares

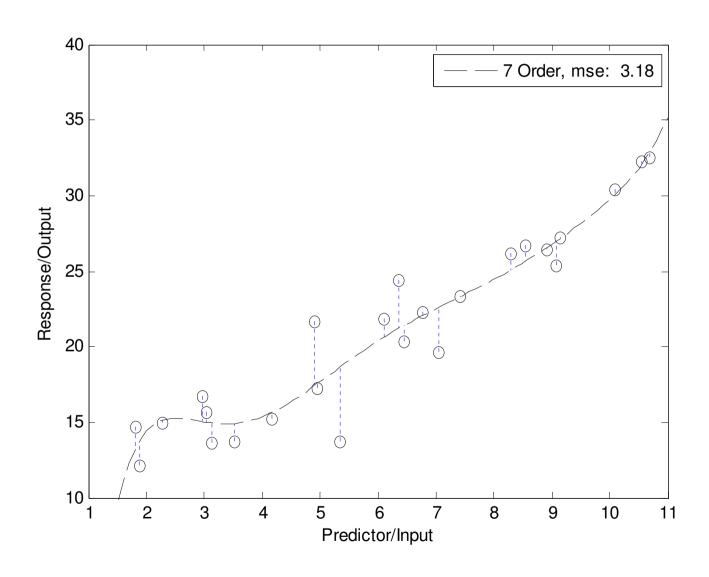
$$\left[ egin{array}{c} Y_1 \ Y_2 \ dots \ Y_n \end{array} 
ight] = \left[ egin{array}{c} X_1 & 1 \ X_2 & 1 \ dots \ X_n & 1 \end{array} 
ight] \left[ egin{array}{c} eta_1 \ eta_0 \end{array} 
ight]$$

 Solution to this equation is solution to least squares linear regression (and maximum likelihood under normal error distribution assumption)

#### Questions to Ask

- Is the relationship really linear?
- What is the distribution of the of "errors"?
- Is the fit good?
- How much of the variability of the response is accounted for by including the predictor variable?
- Is the chosen predictor variable the best one?

#### Is This Better?



#### Goals for First Half of Course

- How to do linear regression
  - Self familiarization with software tools
- How to interpret standard linear regression results
- How to derive tests
- How to assess and address deficiencies in regression models

The i<sup>th</sup> residual is defined to be

$$e_i = Y_i - \hat{Y}_i$$

The sum of the residuals is zero:

$$egin{array}{lll} \sum_i e_i &=& \sum (Y_i - b_0 - b_1 X_i) \ &=& \sum Y_i - n b_0 - b_1 \sum X_i \ &=& 0 \end{array}$$
 By first normal equation.

• The sum of the observed values  $Y_i$  equals the sum of the fitted values  $\hat{Y}_i$ 

$$\sum_{i} Y_{i} = \sum_{i} \hat{Y}_{i}$$

$$= \sum_{i} (b_{1}X_{i} + b_{0})$$

$$= \sum_{i} (b_{1}X_{i} + \bar{Y} - b_{1}\bar{X})$$

$$= b_{1} \sum_{i} X_{i} + n\bar{Y} - b_{1}n\bar{X}$$

$$= b_{1}n\bar{X} + \sum_{i} Y_{i} - b_{1}n\bar{X}$$

 The sum of the weighted residuals is zero when the residual in the i<sup>th</sup> trial is weighted by the level of the predictor variable in the i<sup>th</sup> trial

$$\sum_{i} X_{i} e_{i} = \sum_{i} (X_{i}(Y_{i} - b_{0} - b_{1}X_{i}))$$

$$= \sum_{i} X_{i}Y_{i} - b_{0} \sum_{i} X_{i} - b_{1} \sum_{i} (X_{i}^{2})$$

$$= 0$$

By second normal equation.

 The sum of the weighted residuals is zero when the residual in the i<sup>th</sup> trial is weighted by the fitted value of the response variable for the i<sup>th</sup> trial

$$egin{array}{lll} \sum_i \hat{Y}_i e_i &=& \sum_i (b_0 + b_1 X_i) e_i \ &=& b_0 \sum_i e_i + b_1 \sum_i e_i X_i \ &=& 0 \end{array}$$

• The regression line always goes through the point  $\bar{X}, \bar{Y}$ 

,

## Estimating Error Term Variance $\sigma^2$

- Review estimation in non-regression setting.
- Show estimation results for regression setting.

#### **Estimation Review**

 An estimator is a rule that tells how to calculate the value of an estimate based on the measurements contained in a sample

i.e. the sample mean

$$\bar{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_i$$

#### Point Estimators and Bias

Point estimator

$$\hat{\theta} = f(\{Y_1, \dots, Y_n\})$$

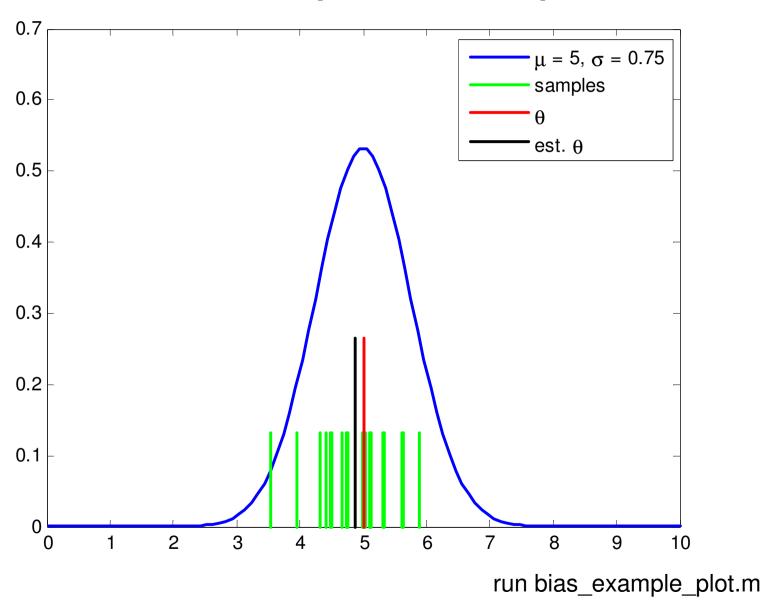
Unknown quantity / parameter

heta

Definition: Bias of estimator

$$B(\hat{\theta}) = E(\hat{\theta}) - \theta$$

## One Sample Example



#### Distribution of Estimator

- If the estimator is a function of the samples and the distribution of the samples is known then the distribution of the estimator can (often) be determined
  - Methods
    - Distribution (CDF) functions
    - Transformations
    - Moment generating functions
    - Jacobians (change of variable)

## Example

• Samples from a Normal( $\mu$ , $\sigma$ <sup>2</sup>) distribution

$$Y_i \sim \text{Normal}(\mu, \sigma^2)$$

Estimate the population mean

$$\theta = \mu, \quad \hat{\theta} = \bar{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_i$$

## Sampling Distribution of the Estimator

First moment

$$E(\hat{\theta}) = E(\frac{1}{n} \sum_{i=1}^{n} Y_i)$$

$$= \frac{1}{n} \sum_{i=1}^{n} E(Y_i) = \frac{n\mu}{n} = \theta$$

This is an example of an unbiased estimator

$$B(\hat{\theta}) = E(\hat{\theta}) - \theta = 0$$

#### Variance of Estimator

Definition: Variance of estimator

$$V(\hat{\theta}) = E([\hat{\theta} - E(\hat{\theta})]^2)$$

Remember:

$$V(cY) = c^{2}V(Y)$$

$$V(\sum_{i=1}^{n} Y_{i}) = \sum_{i=1}^{n} V(Y_{i})$$

Only if the Y<sub>i</sub> are *independent* with *finite variance* 

## Example Estimator Variance

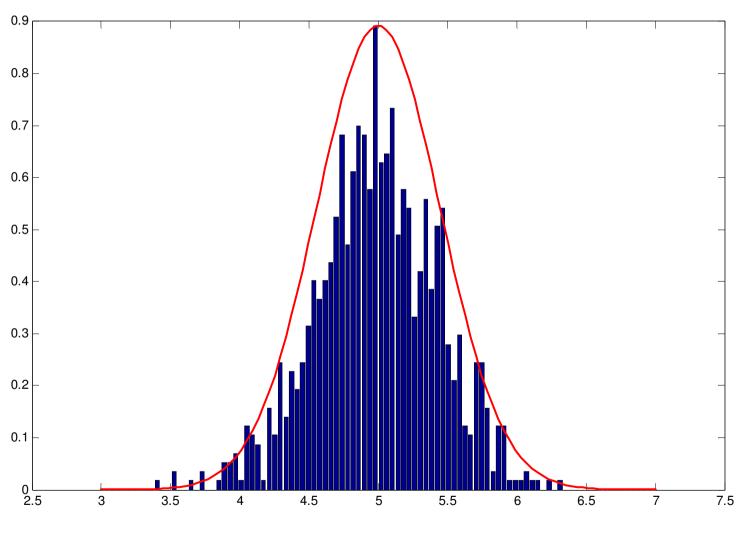
For N(0,1) mean estimator

$$V(\hat{\theta}) = V(\frac{1}{n} \sum_{i=1}^{n} Y_i)$$

$$= \frac{1}{n^2} \sum_{i=1}^{n} V(Y_i) = \frac{n\sigma^2}{n^2} = \frac{\sigma^2}{n}$$

Note assumptions

## Distribution of sample mean estimator



1000 samples

#### Bias Variance Trade-off

The mean squared error of an estimator

$$MSE(\hat{\theta}) = E([\hat{\theta} - \theta]^2)$$

Can be re-expressed

$$MSE(\hat{\theta}) = V(\hat{\theta}) + (B(\hat{\theta})^2)$$

#### $MSE = VAR + BIAS^2$

#### Proof

$$MSE(\hat{\theta}) = E((\hat{\theta} - \theta)^{2})$$

$$= E(([\hat{\theta} - E(\hat{\theta})] + [E(\hat{\theta}) - \theta])^{2})$$

$$= E([\hat{\theta} - E(\hat{\theta})]^{2}) + 2E([E(\hat{\theta}) - \theta][\hat{\theta} - E(\hat{\theta})]) + E([E(\hat{\theta}) - \theta]^{2})$$

$$= V(\hat{\theta}) + 2E([E(\hat{\theta})[\hat{\theta} - E(\hat{\theta})] - \theta[\hat{\theta} - E(\hat{\theta})])) + (B(\hat{\theta}))^{2}$$

$$= V(\hat{\theta}) + 2(0 + 0) + (B(\hat{\theta}))^{2}$$

$$= V(\hat{\theta}) + (B(\hat{\theta}))^{2}$$

#### Trade-off

- Think of variance as confidence and bias as correctness.
  - Intuitions (largely) apply
- Sometimes a biased estimator can produce lower MSE if it lowers the variance.

## Estimating Error Term Variance $\sigma^2$

- Regression model
- Variance of each observation  $Y_i$  is  $\sigma^2$  (the same as for the error term  $\epsilon_i$ )
- Each Y<sub>i</sub> comes from a different probability distribution with different means that depend on the level X<sub>i</sub>
- The deviation of an observation Y<sub>i</sub> must be calculated around its own estimated mean.

#### $s^2$ estimator for $\sigma^2$

$$s^2 = MSE = \frac{SSE}{n-2} = \frac{\sum (Y_i - \hat{Y}_i)^2}{n-2} = \frac{\sum e_i^2}{n-2}$$

• MSE is an unbiased estimator of  $\sigma^2$ 

$$E(MSE) = \sigma^2$$

 The sum of squares SSE has n-2 degrees of freedom associated with it.

## Normal Error Regression Model

- No matter how the error terms  $\epsilon_i$  are distributed, the least squares method provides unbiased point estimators of  $\beta_{\rm o}$  and  $\beta_{\rm l}$ 
  - that also have minimum variance among all unbiased linear estimators
- To set up interval estimates and make tests we need to specify the distribution of the  $\epsilon_i$
- We will assume that the  $\epsilon_i$  are normally distributed.

## Normal Error Regression Model

$$Y_i = \beta_0 + \beta_1 X_i + \epsilon_i$$

- Y<sub>i</sub> value of the response variable in the i<sup>th</sup> trial
- $\beta_0$  and  $\beta_1$  are parameters
- X<sub>i</sub> is a known constant, the value of the predictor variable in the i<sup>th</sup> trial
- $\epsilon_i \sim_{\mathsf{iid}} \mathsf{N}(\mathsf{0},\sigma^2)$
- i = 1,...,n

#### **Notational Convention**

• When you see  $\epsilon_i \sim_{\text{iid}} N(0, \sigma^2)$ 

• It is read as  $\epsilon_i$  is distributed identically and independently according to a normal distribution with mean 0 and variance  $\sigma^2$ 

- Examples
  - $-\theta \sim Poisson(\lambda)$
  - $-z \sim G(\theta)$

## Maximum Likelihood Principle

 The method of maximum likelihood chooses as estimates those values of the parameters that are most consistent with the sample data.

#### Likelihood Function

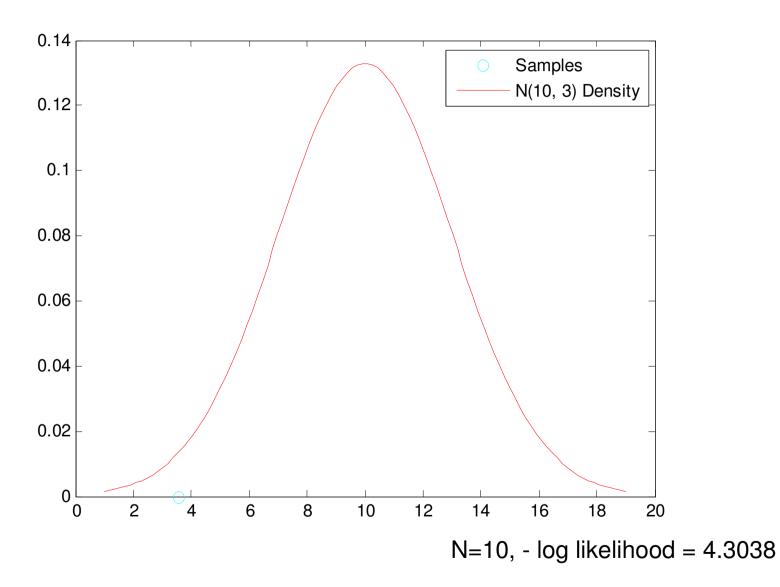
• If

$$X_i \sim F(\Theta), i = 1 \dots n$$

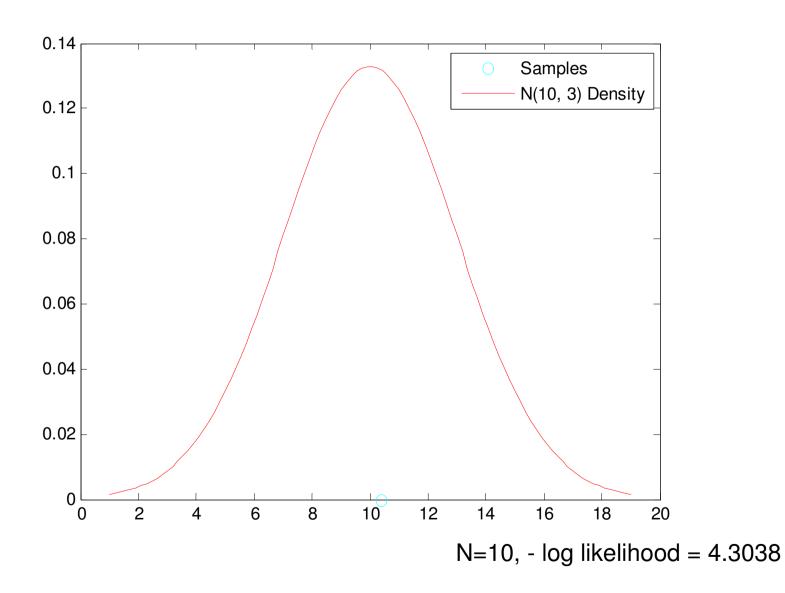
then the likelihood function is

$$\mathcal{L}(\{X_i\}_{i=1}^n, \Theta) = \prod_{i=1}^n F(X_i; \Theta)$$

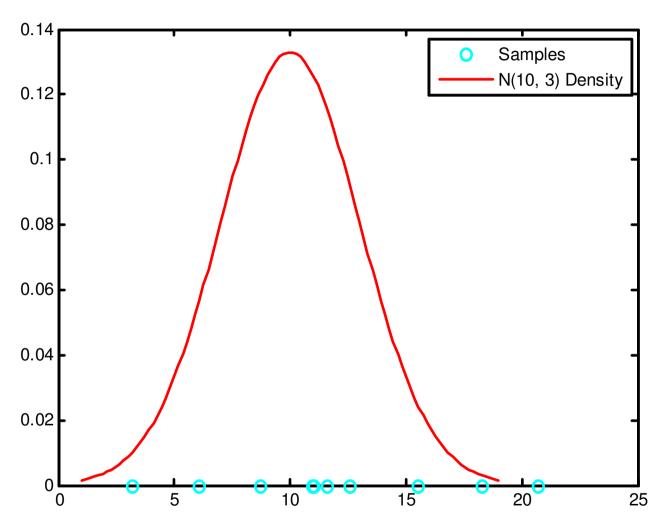
## Example, N(10,3) Density, Single Obs.



#### Example, N(10,3) Density, Single Obs. Again



#### Example, N(10,3) Density, Multiple Obs.



N=10, - log likelihood = 36.2204

#### Maximum Likelihood Estimation

 The likelihood function can be maximized w.r.t. the parameter(s) Θ, doing this one can arrive at estimators for parameters as well.

$$\mathcal{L}(\{X_i\}_{i=1}^n, \Theta) = \prod_{i=1}^n F(X_i; \Theta)$$

 To do this, find solutions to (analytically or by following gradient)

$$\frac{d\mathcal{L}(\{X_i\}_{i=1}^n,\Theta)}{d\Theta} = 0$$

## Important Trick

 Never (almost) maximize the likelihood function, maximize the log likelihood function instead.

$$log(\mathcal{L}(\{X_i\}_{i=1}^n, \Theta)) = log(\prod_{i=1}^n F(X_i; \Theta))$$

$$= \sum_{i=1}^n log(F(X_i; \Theta))$$

Quite often the log of the density is easier to work with mathematically.

## ML Normal Regression

Likelihood function

$$\mathcal{L}(\beta_0, \beta_1, \sigma^2) = \prod_{i=1}^{n} \frac{1}{(2\pi\sigma^2)^{1/2}} e^{-\frac{1}{2\sigma^2}(Y_i - \beta_0 - \beta_1 X_i)^2}$$

$$= \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^{n} (Y_i - \beta_0 - \beta_1 X_i)^2}$$

which if you maximize (how?) w.r.t. to the parameters you get...

## Maximum Likelihood Estimator(s)

- $\beta_0$ 
  - b<sub>0</sub> same as in least squares case
- $\beta_1$ 
  - − b<sub>1</sub> same as in least squares case
- $\bullet$   $\sigma_2$

$$\hat{\sigma}^2 = \frac{\sum_i (Y_i - \hat{Y}_i)^2}{n}$$

 Note that ML estimator is biased as s<sup>2</sup> is unbiased and

$$s^2 = MSE = \frac{n}{n-2}\hat{\sigma}^2$$

#### Comments

- Least squares minimizes the squared error between the prediction and the true output
- The normal distribution is fully characterized by its first two central moments (mean and variance)

- Food for thought:
  - What does the bias in the ML estimator of the error variance mean? And where does it come from?