#### **Master Thesis**

# Online in-hand slip detection with an event-based camera

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30.09.2021

### Affidavit

I hereby declare that the following thesis "Online in-hand slip detection with an event-based camera" has been written only by the undersigned and without any assistance from third parties.

Furthermore, I confirm that no sources have been used in the preparation of this thesis other than those indicated in the thesis itself.

Berlin, 30.09.2021

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Berlin, 30.09.2021

### ABSTRACT

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Problemstellung

Wissenschaftlicher Beitrag

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## INTRODUCTION

### 1.1 Background and Motivation

As a student of a double MsC in Industrial Engineering and Automatic Control and Robotics with experience in research in robotics field, my aim was to work on a thesis in a cutting edge topic about robotics which is applicable to the industry. After contacting my supervisor, I got the opportunity to work on part of a project called "Online in-hand object tracking and grasp failure detection with an event-based camera", which is a Amazon Research Awards Proposal.

The two main expected outcomes of this project are the creation of a dataset using event-based cameras for manipulation and the design of an algorithm capable to detect grasp failure and object slipping and recover from it in real-time. This project is really relevant for Amazon, as the automation of the package preparation requires to effectively perform pick and place motions by robotic arms. Actually, every year Amazon organizes the Amazon Robotics Challenge, where several teams try to solve a proposed problem. Concretely, they have asked the teams to develop an algorithm to grasp, recognize and place objects in clutter.

The problem of object tracking during manipulation to detect grasp failure and object slipping requires of in-hand object perception, which typically is approached with tactile sensing. However, tactile sensors may have disadvantages in industrial settings due to wear and a lack of long-term robustness. Additionally, they are expensive and provide only limited local information to infer the motion of objects that extend far beyond the contact region. This is why in this project event-based cameras, that provide an external view of the grasping operation, are explored as a novel alternative technology for high-speed in-hand object tracking, as for real-time grasping failure mitigation a fast detection is required.

## 1.2 Objectives

The project "Online in-hand object tracking and grasp failure detection with an event-based camera" is planned to be completed in at least 1 year, and it has started at the

same time as this thesis, i.e. in April 2021. Therefore, this thesis is meant to describe the initial results of this project, being the concrete objectives:

- Setup the experimental environment: robot, gripper, event-based camera and objects to be manipulated.
- Setup the software to execute pick and place motions and collect data.
- Generate an initial dataset containing slip and non-slip cases in pick and place motions.
- Explore of different methods to detect slip cases and compare them.
- Build an initial algorithm capable of detecting slip cases in pick and place motions.

### 1.3 Assumptions and Scope

As the thesis is an initial part of the aforementioned Amazon project, for the purpose of this thesis it has been assumed that the pick and place motions happen in a non-cluttered environment, having only one pickable object in the scene. Moreover, the complete trajectory is given, including not only the shape of it, but also the initial and and final positions. Therefore, it is assumed that some external object recognition algorithm will recognize the object to be picked and provide its position. Finally, the there are no obstacles present in the environment, so that the trajectory is collision-free at all moments.

In terms of the scope, this study is focused on exploring different kinds of slips and grasping failures during manipulations, but only providing a solution for a particular kind of slip, namely rotational slip, which mainly occurs due to off-centered grasping of the object. In addition, the goal is only to detect such kind of slippage without trying to modify the trajectory with any kind of closed-loop control, which would use the information provided by the detection algorithm.

#### 1.4 Outline

((todo: Cite like this: Chapter 1))

## STATE OF THE ART

### 2.1 Introduction

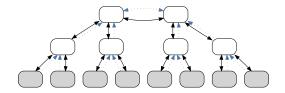


Figure 2.1: Related area 1 within the structure of research

### 2.1.1 Specific Example 1

### 2.2 Conclusion

((todo: Summary)) ((todo: Takeaways)) ((todo: Next chapter))

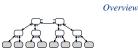
Summary

## REQUIREMENT ANALYSIS

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#### 3.1 Introduction

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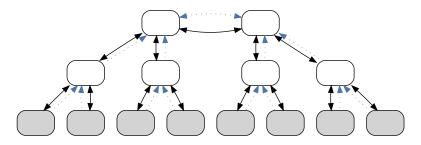


Figure 3.1: More detailed overview of the requirements

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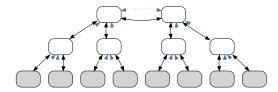


Figure 3.2: Placement of the requirement section in the structure of research

### 3.2 Stakeholder 1

*Table 3.1* ((todo: write about Table 3.1)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

Table 3.1: Requirements from stakeholder 1 perspective

#	Description
U1: Foo	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.
U2: Bar	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

#### 3.3 Stakeholder 2

Table 3.2 ((todo: write about Table 3.2)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

Table 3.2: Requirements from stakeholder 2 perspective

#	Description
S1: Foo	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.
S2: Bar	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

#### Stakeholder 3 3.4

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Table 3.3: Requirements from stakeholder 3 perspective

#	Description
T1: Foo	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.
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#### 3.5 **Conclusion**

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Next chapter

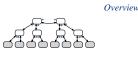
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## CONTRIBUTION 1

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	4.2.2 Related Work 2
	4.2.3 Related Work 3
4.3	Own Approach
	4.3.1 Overview
	4.3.2 First Part
	4.3.3 Second Part
	4.3.4 Third Part
4.4	Conclusion

### 4.1 Introduction

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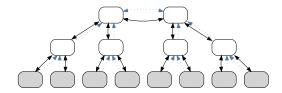


Figure 4.1: Placement of contribution 1 in the structure of research

#### 4.2 State of the Art

*Overview* ((todo: write about Figure 4.2)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

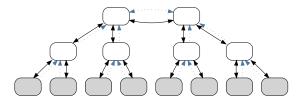


Figure 4.2: Relationship of contribution 1 to related work

#### 4.2.1 Related Work 1

Overview

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Listing 4.1: Listing related to related work 1 for contribution 1

```
class HelloWorld {

private final static String MESSAGE="Hello_World!";

public static void main(String[] args) {

System.out.println(MESSAGE);

}
```

6 | }

#### 4.2.2 **Related Work 2**

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```
Listing 4.2: Listing related to related work 2 for contribution 1
```

```
1
   class HelloWorld {
      private final static String MESSAGE="Hello_World!";
2
3
          public static void main(String[] args) {
4
          System.out.println(MESSAGE);
5
6
```

#### 4.2.3 **Related Work 3**

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Listing 4.3: Listing related to related work 3 for contribution 1

```
class HelloWorld {
2
      private final static String MESSAGE="Hello_World!";
```

### 4.3 Own Approach

#### 4.3.1 Overview

Intro ((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

Goal ((todo: write about Figure 4.3)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

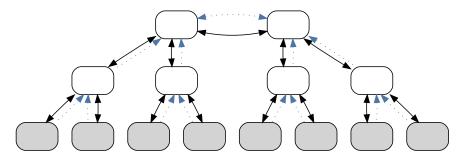


Figure 4.3: Contribution 1 goal

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#### 4.3.2 First Part

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Approach

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#### 4.3.3 **Second Part**

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#### 4.3.4 **Third Part**

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#### Conclusion 4.4

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Takeaway 3

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Next chapter

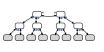
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## CONTRIBUTION 2

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5.2	State of the Art
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	5.2.2 Related Work 2
	5.2.3 Related Work 3
5.3	Own Approach
	5.3.1 Overview
	5.3.2 First Part
	5.3.3 Second Part
	5.3.4 Third Part
5.4	Conclusion

#### 5.1 Introduction

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Overview

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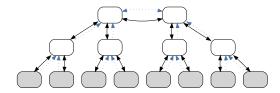


Figure 5.1: Placement of Contribution 2 in the structure of research

#### 5.2 State of the Art

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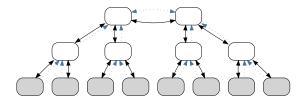


Figure 5.2: Relationship of Contribution 2 to related work

#### 5.2.1 **Related Work 1**

Overview

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Some Aspects

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Issues

((todo: write about Listing 5.1)) Lorem ipsum dolor sit amet, consectetur adipisicing

Listing 5.1: Listing related to related work 1 for Contribution 2

```
class HelloWorld {
1
2
      private final static String MESSAGE="Hello_World!";
3
          public static void main(String[] args) {
4
          System.out.println(MESSAGE);
5
          }
```

6 | }

#### 5.2.2 **Related Work 2**

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((todo: write about Listing 5.2)) Lorem ipsum dolor sit amet, consectetur adipisicing Issues

Listing 5.2: Listing related to related work 2 for Contribution 2

```
1
   class HelloWorld {
      private final static String MESSAGE="Hello_World!";
2
3
          public static void main(String[] args) {
4
          System.out.println(MESSAGE);
5
6
```

#### 5.2.3 **Related Work 3**

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Listing 5.3: Listing related to related work 3 for Contribution 2

```
class HelloWorld {
2
      private final static String MESSAGE="Hello_World!";
```

```
public static void main(String[] args) {
    System.out.println(MESSAGE);
}
```

## 5.3 Own Approach

### 5.3.1 Overview

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Goal ((todo: write about Figure 5.3)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

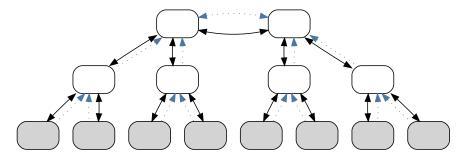


Figure 5.3: Contribution 2 goal

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### 5.3.2 First Part

Overview

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Approach

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#### Conclusion 5.4

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Takeaway 2

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Next chapter

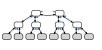
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# CONTRIBUTION 3

6.1	Introduction
6.2	
0.2	22
	6.2.1 Related Work 1
	6.2.2 Related Work 2
	6.2.3 Related Work 3
6.3	Own Approach
	6.3.1 Overview
	6.3.2 First Part
	6.3.3 Second Part
	6.3.4 Third Part
6.4	Conclusion

#### Introduction 6.1

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Overview

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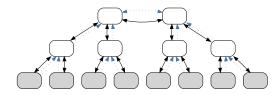


Figure 6.1: Placement of Contribution 3 in the structure of research

## 6.2 State of the Art

*Overview* ((todo: write about Figure 6.2)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

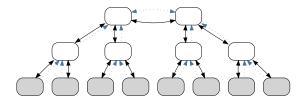


Figure 6.2: Relationship of Contribution 3 to related work

### 6.2.1 Related Work 1

Overview

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Some Aspects

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Issues

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Listing 6.1: Listing related to related work 1 for Contribution 3

```
class HelloWorld {
    private final static String MESSAGE="Hello_World!";
    public static void main(String[] args) {
        System.out.println(MESSAGE);
    }
```

6 | }

#### 6.2.2 **Related Work 2**

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((todo: write about Listing 6.2)) Lorem ipsum dolor sit amet, consectetur adipisicing Issues

Listing 6.2: Listing related to related work 2 for Contribution 3

```
1
   class HelloWorld {
      private final static String MESSAGE="Hello_World!";
2
3
          public static void main(String[] args) {
4
          System.out.println(MESSAGE);
5
6
```

#### 6.2.3 **Related Work 3**

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((todo: write about Listing 6.3)) Lorem ipsum dolor sit amet, consectetur adipisicing Issues

Listing 6.3: Listing related to related work 3 for Contribution 3

```
class HelloWorld {
2
      private final static String MESSAGE="Hello_World!";
```

## 6.3 Own Approach

### 6.3.1 Overview

Intro ((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

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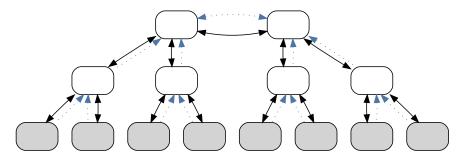


Figure 6.3: Contribution 3 goal

Approach ((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis

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### 6.3.2 First Part

Overview

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Approach

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Goal

6.4. CONCLUSION 25

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#### 6.3.3 **Second Part**

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#### 6.3.4 **Third Part**

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#### Conclusion 6.4

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Next chapter

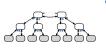
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# EVALUATION

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7.2	Experimental Validation
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	7.2.2 Setup 2
7.3	Performance Evaluation
	7.3.1 Evaluation 1
	7.3.2 Evaluation 2
7.4	Observational Validation
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7.5	Deployments
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7.6	Code Verification
7.7	Comparative Analysis
	7.7.1 Requirement Evaluation
	7.7.2 Comparison with Other Approaches
7.8	Conclusion

## 7.1 Introduction

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Overview

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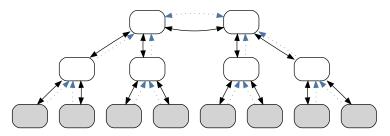


Figure 7.1: Choice of verification and validation techniques [a0]

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Structure of Research

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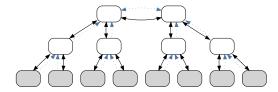


Figure 7.2: Placement of the evaluation in the structure of research

## 7.2 Experimental Validation

Overview

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## 7.2.1 Setup 1

Overview

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Integration

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Chapter 7

Table 7.1: Sideways table

Experiment 1	Experiment 2	Experiment 3	Experiment 4	Experiment 5	Experiment 6	Experiment 7
CATCH	ME	IF	YOU	CAN	NOM	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
САТСН	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER
CATCH	ME	IF	YOU	CAN	NOW	OR NEVER

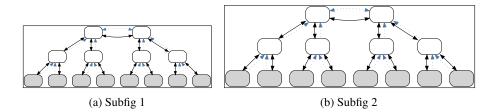


Figure 7.3: Sub Figures

$$t_{fw}^{p_d}(d) = \max_{d} (t_{child_i})$$

$$t_{db}^{p_d}(d) = \sum_{i=1}^{d} t_{db_i}$$

$$t_{pc}^{p_d}(n,d) = \begin{cases} t_{pc}(d) + c(n) & \text{if } d = 1, \\ t_{pc}(d) + c(n) + \max(t_{avail}(d)) & \text{if } d > 1. \end{cases}$$
(7.1)

Example ((todo: write about Listing 7.1)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

### Listing 7.1: Experiment 1

```
class HelloWorld {
   private final static String MESSAGE="Hello_World!";
   public static void main(String[] args) {
      System.out.println(MESSAGE);
   }
}
```

## 7.2.2 Setup 2

Overview

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Integration

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Example

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#### 7.3 **Performance Evaluation**

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#### 7.3.1 **Evaluation 1**

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#### **Evaluation 2** 7.3.2

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- In: 159 ms  $\pm$  21 ms (95% CI)
- *Out*: 33 ms  $\pm$  5 ms (95% CI)
- Between: 238 ms  $\pm$  9 ms (95% CI)
- After: 45 ms  $\pm$  1 ms (95% CI)
- *Under*: 215 ms  $\pm$  2 ms (95% CI)
- *Over*: 148 ms  $\pm$  3 ms (95% CI)

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## 7.4 Observational Validation

Overview

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## 7.4.1 **Project 1**

Overviev

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System Specification

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Extraction

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Example

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## **7.4.2** Project 2

Overview

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System Specification

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Extraction

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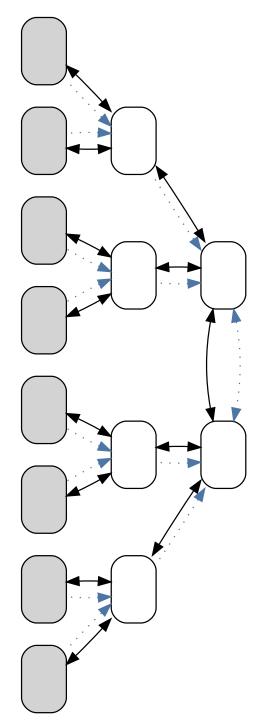


Figure 7.4: Sideways figure

Example

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## 7.5 Deployments

Overview

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### 7.5.1 Installation 1

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Integration

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### 7.5.2 Installation 2

Overview

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Integration

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## 7.6 Code Verification

Overview

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Static Tests

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#### 7.7 **Comparative Analysis**

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#### 7.7.1 **Requirement Evaluation**

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Table 7.2: Mapping requirements against own approach

Requirements	Approach
U1 (Foo)	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.
U2 (Bar)	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.
S1 (Foo)	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

Requirements	Approach			
S2 (Bar)	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.			
T1 (Foo)	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.			
T2 (Bar)	((todo: write)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.			

## 7.7.2 Comparison with Other Approaches

Overview

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Table 7.3

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Table 7.3: Comparison of related work with own approach

Requirements	Related 1	Related 2	Related 3	Related 4	Related 5	Own Ap- proach
U1 U2	(+)	(++)	<b>(o)</b>	(-)	<b>(o)</b>	(+++)

7.8. CONCLUSION 37

Requirements	Related 1	Related 2	Related 3	Related 4	Related 5	Own Ap- proach
(Attributed Based Access Control (ABAC) [a0, p0])	ABAC v3, ABAC ABAC	ABAC v2, ABAC, native ABAC	ABAC	native ABAC	ABAC ABAC v2	ABAC v3, ABAC ABAC, ABAC, native ABAC, native
T1 (Details)	(o) via foo	(++) by bar / role-foo	_	_	(++) bar / foo	(+) foo-bar
S1 S2 T2 (Barli)	(+) via barli	(+) via fooli	_	(+) via bar-foo	(+) via foo-bar	(+) via bar-bar

#### 7.8 Conclusion

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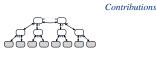
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## SUMMARY AND FURTHER WORK

8.1	Overview	39
8.2	Conclusions and Impact	39
8.3	Outlook	40

## 8.1 Overview

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## 8.2 Conclusions and Impact

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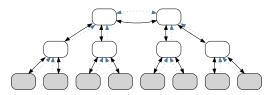


Figure 8.1: Placement of the outlook in the structure of research

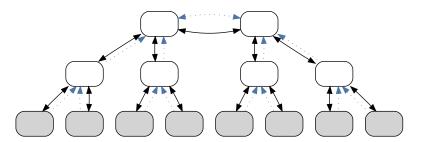


Figure 8.2: Area 1 [a0]

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Contribution 1

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## 8.3 Outlook

Intro

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Application Area 1

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Application Area 2

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Application Area 3

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8.3. OUTLOOK 41

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### APPENDIX A

## SPECIFICATIONS

## A.1 Specification 1

((todo: write about Listing A.1)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

Listing A.1: Specification 1

```
class HelloWorld {
  private final static String MESSAGE="HellouWorld!";
  public static void main(String[] args) {
    System.out.println(MESSAGE);
  }
}
```

## A.2 Specification 2

((todo: write about Listing A.2)) Lorem ipsum dolor sit amet, consectetur adipisicing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur.

Listing A.2: Specification 2

```
1 class HelloWorld {
```

```
private final static String MESSAGE="Hello_World!";

public static void main(String[] args) {
    System.out.println(MESSAGE);
}
```

## APPENDIX B

# TEST RESULTS

B.1	Conformance Results III
B.2	Performance Results
	B.2.1 Histograms IV
	B.2.2 Lineplots IV

## **B.1** Conformance Results

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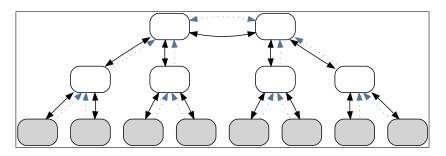


Figure B.1: Test results (page 1)

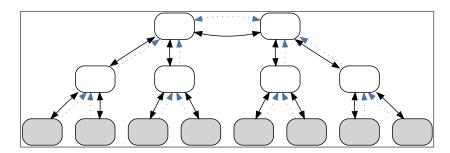


Figure B.2: Test results (page 2)

## **B.2** Performance Results

## **B.2.1** Histograms

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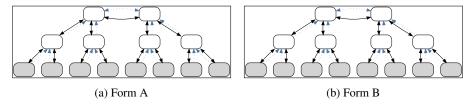


Figure B.3: Histogram of Forms

## **B.2.2** Lineplots

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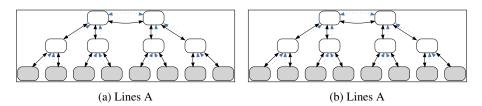


Figure B.4: Lineplot of the lines

# ACRONYMS

Glossary IX

## BIBLIOGRAPHY

## **List of Author's Publications Covered in this Thesis**

[a0] Ninghui Li, J. Mitchell, and W. Winsborough. "Design of a role-based trust-management framework". In: *Symposium on Security and Privacy*. IEEE Comput. Soc, 2002, pp. 114–130. ISBN: 0-7695-1543-6. DOI: 10.1109/SECPRI.2002.1004366 (cit. on pp. 28, 37, 40).

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[p0] E. Yuan and J. Tong. "Attributed based access control (ABAC) for Web services". English. In: *International Conference on Web Services (ICWS)*. IEEE, 2005, p. 569. ISBN: 0-7695-2409-5. DOI: 10.1109/ICWS.2005.25 (cit. on p. 37).

### **Technical References**

### Miscellaneous References

## Not referenced (will be empty)

((todo: this section should be empty at the end))

- [x0] S. Auer, C. Bizer, G. Kobilarov, J. Lehmann, R. Cyganiak, and Z. Ives. "DB-pedia: A Nucleus for a Web of Open Data". In: *The Semantic Web (ISWC)*. Springer, 2007, pp. 722–735. DOI: 10.1007/978-3-540-76298-0\_52.
- [x0] J. Heflin. *OWL Web Ontology Language Use Cases and Requirements*. W3C Recommendation. World Wide Web Consortium (W3C), 2004. URL: http://www.w3.org/TR/2004/REC-webont-req-20040210/.
- [x0] H. Karimi and M. Hashemi. "Accessible Wayfinding Testbed: Infrastructure and Components". In: 10th EAI International Conference on Testbeds and Research Infrastructures for the Development of Networks & Communities. Vol. 15. 2. Canada: ACM, June 2015, pp. 1–8. ISBN: 978-1-63190-070-9. DOI: 10.4108/ icst.tridentcom.2015.259709.