

# **DOCUMENTATION REPORT**

**Programming Project 1  
Solving the 8-puzzle using A\* algorithm**

**ITCS 6150/8150 - Intelligent Systems**

**Submitted by**

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## **PROBLEM STATEMENT:**

To implement A\* search algorithm and apply it to 8-puzzle problem using programming language

8-puzzle problem

A 3x3 grid contains 8 tiles numbered 1 to 8 and tile adjacent to the empty space can be slide to the empty space finally reaching the goal state

## **A\* ALGORITHM:**

A\* method uses admissible heuristic to determine the next state. The heuristic used to evaluate distances in A\* is:

$$f(n) = g(n) + h(n)$$

where  $g(n)$  represents the cost (distance) of the path from the starting state to current state, and  $h(n)$  represents the estimated cost to the goal.

## **$h(n)$ Manhattan Distance**

The distance between two points measured along axes at right angles. In a plane with  $p_1$  at  $(x_1, y_1)$  and  $p_2$  at  $(x_2, y_2)$ , it is  $|x_1 - x_2| + |y_1 - y_2|$ .

## **h(n) Misplaced Tiles**

The number of misplaced tiles comparing current state and goal state

Initial state

1	2	3
4	0	6
7	5	8

Goal state

6	2	3
4	5	1
7	8	0

`heuristic_manhattan_dist=3+0+0+0+3+0+1+1 = 8`  
tiles 1,6,5,8 take 3,3,1,1 steps respectively to reach their goal state.

`heuristic_misplaced_dist=1+0+0+0+1+0+1+1= 4`  
tiles 1,6,5,8 are misplaced.

### **CODE:**

Programming language:Python3

python interpreter version:3.6

additional libraries needed:numpy

Data structure used:

each node is a structured array and stored in fringe (open) or closed list

node Data format `[[list],g(n),h(n),f(n),nodeID,parentID]`

example: `[[1,2,3,4,5,6,7,8,0],1,4,5,2,1]`

```

# ;=====
# ; Title: A* Algorithm using manhattan distance and misplaced tiles
# ; Author: Bhanu Prakash Reddy ,Satabdhi Reddy
# ; Date: 10 Feb 2019

# ;=====

import numpy as np
from copy import deepcopy
import collections

print("enter input by giving spaces example:1 2 3 4 5 6 7 8 0 ")
initial_node = list(map(int,input("Enter Input node:").split()))          #input initial node
initial_node = np.array(initial_node)
final_node = list(map(int,input("Enter Output node:").split()))          #input final node
final_node = np.array(final_node)
Astarmethod=0    #flag for manhattan or misplaced tiles Astarmethod=0 manhattan 1 for misplaced
tiles

# definition to calculate hn using manhattan distance
def manhattan_distance(mlist):
    copy = mlist
    mhtndist = 0
    for i, list_item in enumerate(copy):
        if list_item != 0:
            for j,list_item_final in enumerate(final_node):
                if list_item_final == list_item:
                    lr = j
                    break
            row1,col1 = int(i/ 3) , i% 3
            row2,col2 = int((lr) / 3), (lr) % 3
            mhtndist += abs(row1-row2) + abs(col1 - col2)
    return mhtndist

#definition to calculate hn using misplaced tiles
def misplaced_tiles(mlist):
    copy = mlist
    mis_dist=0
    for i, list_item in enumerate(copy):
        if list_item != 0 and final_node[i] != list_item:
            mis_dist = mis_dist+1
    return mis_dist

#definition to calculate successor nodes of the node to be expanded
def successorNodes(board):
    global open_struct_array
    global closed_struct_array

```

```

global nodeid
moves = np.array(
    [
        ([0, 1, 2], -3),
        ([6, 7, 8], 3),
        ([0, 3, 6], -1),
        ([2, 5, 8], 1)
    ],
    dtype=[
        ('pos', list),
        ('ind', int)
    ]
)

gn=board[1]+1
state = board[0]
loc = int(np.where(state == 0)[0])
parentid=board[4]
for m in moves:
    if loc not in m['pos']:
        nodepresent = 0
        succ = deepcopy(state)
        delta_loc = loc + m['ind']
        succ[loc], succ[delta_loc] = succ[delta_loc], succ[loc]

        for i in closed_struct_array:          #checking if successor nodes are duplicates
            if(i[0]==succ).all():
                nodepresent = 1

        for i in open_struct_array:           #checking if successor nodes are duplicates
            if (i[0] == succ).all():
                nodepresent = 1

    if nodepresent == 0:
        #print("inloop")

        if (Astarmethod == 0):
            hn = manhattan_distance(succ)
        else:
            hn = misplaced_tiles(succ)
        fn=gn + hn
        nodeid=nodeid+1                      #increment value of nodeid for each node generated
        #appending successor nodes to open_struct_array
        open_struct_array=np.append(open_struct_array, np.array([(succ, gn, hn, fn, nodeid,
parentid)], STATE), 0)

#definition to check if the node is final node
def solution(board):
    global STATE

```

```

STATE = [
    ('board', list),
    ('gn', int),
    ('hn', int),
    ('fn', int),
    ('nodeid',int),
    ('parentid',int)
]
global open_struct_array
global closed_struct_array
global nodeid
nodeid = 0
if(Astarmethod==0):
    hn=manhattan_distance(board)
else:
    hn=misplaced_tiles(board)
open_struct_array = np.array([(board, 0, hn, 0 + hn, 0, -1)], STATE)

varran=np.array([0,0,0,0,0,0,0,0,0]) #closed struct array 1 time initialization
closed_struct_array=np.array([(varran, 0, 0, 0, 0, 0)], STATE)
closed_struct_array=np.delete(closed_struct_array, 0, 0)

while True:
    length_queueues = len(open_struct_array) + len(closed_struct_array) #checking if total nodes are
crossing the threshold value
    if length_queueues >3000:
        break
    a=open_struct_array[0]
    s=a[0]
    if (s == final_node).all(): #comparing with final node
        return len(closed_struct_array), nodeid
    open_struct_array = np.delete(open_struct_array, 0, 0)
    closed_struct_array=np.append(closed_struct_array, np.array([(a[0], a[1], a[2], a[3], a[4], a[5])],
STATE), 0) #appending expanded node to closed node
    successorNodes(a)
    open_struct_array = np.sort(open_struct_array, kind='mergesort', order=['fn', 'nodeid']) #sort
based on value of fn
    return 0,0

#definition to find the path of the final node
def solutionpath(open_structured_array, closedNode):
    storelastelement = open_structured_array[0][0]
    parentidd=open_structured_array[0][5]
    con = np.concatenate((open_structured_array, closedNode), axis=0)
    de = collections.deque([])
    de.append(storelastelement)
    while(parentidd != -1):
        for i in con:
            if i[4] == parentidd:

```

```

        de.appendleft(i[0])
        parentidd = i[5]
        break
print('cost to reach final_node:',len(de)-1)

for i in de:
    print(np.reshape(i,(3,3)),'\n')

#definition to print output using both manhattan distance and misplaced tiles as hn
def main():
    global open_struct_array
    global closed_struct_array
    global Astarmethod

    comparearrays = (np.sort(initial_node) == np.sort(final_node)).all()    #checking if input is correct
    if not comparearrays:
        print('incorrect input')
        return
    else:
        nodes_expanded,nodes_generated=solution(initial_node)                #if correct input find path
        if(nodes_expanded==0 and nodes_generated ==0):
            print('no solution')
            return
        print("-----A* Manhattan DIsTance-----")
        # print(open_struct_array)
        # print(closed_struct_array)
        print('nodes_generated:',nodes_generated)
        print('nodes_expanded',nodes_expanded)

        solutionpath(open_struct_array, closed_struct_array)                #finding solution path hn= manhattan
distance
        print("-----A* Misplaced Tiles-----")
        Astarmethod=1                                                         #set Astarmethod=1
        open_struct_array=[]                                                  #empty both open and closed
        closed_struct_array=[]
        nodes_expanded, nodes_generated = solution(initial_node)
        if (nodes_expanded == 0 and nodes_generated == 0):                    #return 0,0 if no solution
            print('no solution')
            return
        # print(open_struct_array)
        # print(closedNode)
        print('nodes_generated:',nodes_generated)
        print('nodes_expanded',nodes_expanded)
        solutionpath(open_struct_array, closed_struct_array)                #finding solution path hn=misplaced tiles

if __name__ == "__main__":
    main()

```



Global variables used:

1. Nodeid ,each node has a unique id
2. open\_struct\_array ,storing expanded nodes
3. closed\_struct\_Array ,storing closed nodes

**Functions used:**

1. main()
2. solution()
3. solutionpath()
4. successorNodes()
5. manhattan\_distance()
6. misplaced\_tiles()

**main function**

- check for correct inputs from user
- sending initial\_node to solution function
- toggle flag for finding path using misplaced tiles
- printing generated nodes,nodes expanded

**solution function**

- Runs a infinite while loop which breaks on finding final path or if length of fringe + closed exceeds a threshold.
- Delete node expanded from open and add it in closed
- sending the node to be expanded to successor node function
- sorting the fringe(open) based on  $f(n)$

**successornodes function**

- generating successor nodes and adding it to open
- checking if successor nodes are duplicates

**manhattan\_distance function**

- calculating manhattan distance for a node

### **misplaced\_tiles function**

- calculating number of misplaced tiles

### **solutionpath function**

- backtracking the solution path using the parent node of found solution node

### **SAMPLE INPUT OUTPUT:**

#### **Example1:**

enter input by giving spaces example:1 2 3 4 5 6 7 8 0

Enter Input node:1 0 8 2 5 7 4 6 3

Enter Output node:0 8 7 1 2 3 4 5 6

-----A\* Manhattan DIstance-----

nodes\_generated: 14

nodes\_expanded 7

cost to reach final\_node: 7

[[1 0 8]

[2 5 7]

[4 6 3]]

[[1 8 0]

[2 5 7]

[4 6 3]]

[[1 8 7]

[2 5 0]

[4 6 3]]

[[1 8 7]

[2 5 3]

[4 6 0]]

[[1 8 7]

[2 5 3]

[4 0 6]]

[[1 8 7]

[2 0 3]

[4 5 6]]

[[1 8 7]  
[0 2 3]  
[4 5 6]]

[[0 8 7]  
[1 2 3]  
[4 5 6]]

-----A\* Misplaced Tiles-----

nodes\_generated: 14

nodes\_expanded 7

cost to reach final\_node: 7

[[1 0 8]  
[2 5 7]  
[4 6 3]]

[[1 8 0]  
[2 5 7]  
[4 6 3]]

[[1 8 7]  
[2 5 0]  
[4 6 3]]

[[1 8 7]  
[2 5 3]  
[4 6 0]]

[[1 8 7]  
[2 5 3]  
[4 0 6]]

[[1 8 7]  
[2 0 3]  
[4 5 6]]

[[1 8 7]  
[0 2 3]  
[4 5 6]]

[[0 8 7]  
[1 2 3]  
[4 5 6]]

Process finished with exit code 0

## Example 2 :

enter input by giving spaces example:1 2 3 4 5 6 7 8 0

Enter Input node:1 2 7 6 0 8 4 3 5

Enter Output node:1 2 0 4 8 7 3 6 5

-----A\* Manhattan DIstance-----

nodes\_generated: 17

nodes\_expanded 8

cost to reach final\_node: 6

[[1 2 7]

[6 0 8]

[4 3 5]]

[[1 2 7]

[0 6 8]

[4 3 5]]

[[1 2 7]

[4 6 8]

[0 3 5]]

[[1 2 7]

[4 6 8]

[3 0 5]]

[[1 2 7]

[4 0 8]

[3 6 5]]

[[1 2 7]

[4 8 0]

[3 6 5]]

[[1 2 0]

[4 8 7]

[3 6 5]]

-----A\* Misplaced Tiles-----

nodes\_generated: 19

nodes\_expanded 9

cost to reach final\_node: 6

[[1 2 7]

[6 0 8]

[4 3 5]]

```
[[1 2 7]
[0 6 8]
[4 3 5]]
```

```
[[1 2 7]
[4 6 8]
[0 3 5]]
```

```
[[1 2 7]
[4 6 8]
[3 0 5]]
```

```
[[1 2 7]
[4 0 8]
[3 6 5]]
```

```
[[1 2 7]
[4 8 0]
[3 6 5]]
```

```
[[1 2 0]
[4 8 7]
[3 6 5]]
```

Process finished with exit code 0

### Example 3:

enter input by giving spaces example:1 2 3 4 5 6 7 8 0

Enter Input node:6 3 5 8 7 0 2 1 4

Enter Output node:6 5 7 8 3 4 2 1 0

-----A\* Manhattan DIstance-----

nodes\_generated: 12

nodes\_expanded 6

cost to reach final\_node: 5

```
[[6 3 5]
[8 7 0]
[2 1 4]]
```

```
[[6 3 5]
[8 0 7]
[2 1 4]]
```

```
[[6 0 5]
[8 3 7]
[2 1 4]]
```

```
[[6 5 0]
 [8 3 7]
 [2 1 4]]
```

```
[[6 5 7]
 [8 3 0]
 [2 1 4]]
```

```
[[6 5 7]
 [8 3 4]
 [2 1 0]]
```

-----A\* Misplaced Tiles-----

nodes\_generated: 13

nodes\_expanded 7

cost to reach final\_node: 5

```
[[6 3 5]
 [8 7 0]
 [2 1 4]]
```

```
[[6 3 5]
 [8 0 7]
 [2 1 4]]
```

```
[[6 0 5]
 [8 3 7]
 [2 1 4]]
```

```
[[6 5 0]
 [8 3 7]
 [2 1 4]]
```

```
[[6 5 7]
 [8 3 0]
 [2 1 4]]
```

```
[[6 5 7]
 [8 3 4]
 [2 1 0]]
```

Process finished with exit code 0

### Example 4:

enter input by giving spaces example:1 2 3 4 5 6 7 8 0

Enter Input node:2 1 8 3 0 4 6 7 5

Enter Output node:2 7 1 3 0 8 6 5 4

-----A\* Manhattan DIstance-----

nodes\_generated: 12

nodes\_expanded 6

cost to reach final\_node: 6

[[2 1 8]

[3 0 4]

[6 7 5]]

[[2 1 8]

[3 7 4]

[6 0 5]]

[[2 1 8]

[3 7 4]

[6 5 0]]

[[2 1 8]

[3 7 0]

[6 5 4]]

[[2 1 0]

[3 7 8]

[6 5 4]]

[[2 0 1]

[3 7 8]

[6 5 4]]

[[2 7 1]

[3 0 8]

[6 5 4]]

-----A\* Misplaced Tiles-----

nodes\_generated: 19

nodes\_expanded 10

cost to reach final\_node: 6

[[2 1 8]

[3 0 4]

[6 7 5]]

[[2 1 8]

[3 7 4]

[6 0 5]]

[[2 1 8]

[3 7 4]

[6 5 0]]

[[2 1 8]  
[3 7 0]  
[6 5 4]]

[[2 1 0]  
[3 7 8]  
[6 5 4]]

[[2 0 1]  
[3 7 8]  
[6 5 4]]

[[2 7 1]  
[3 0 8]  
[6 5 4]]

### **OBSERVATIONS:**

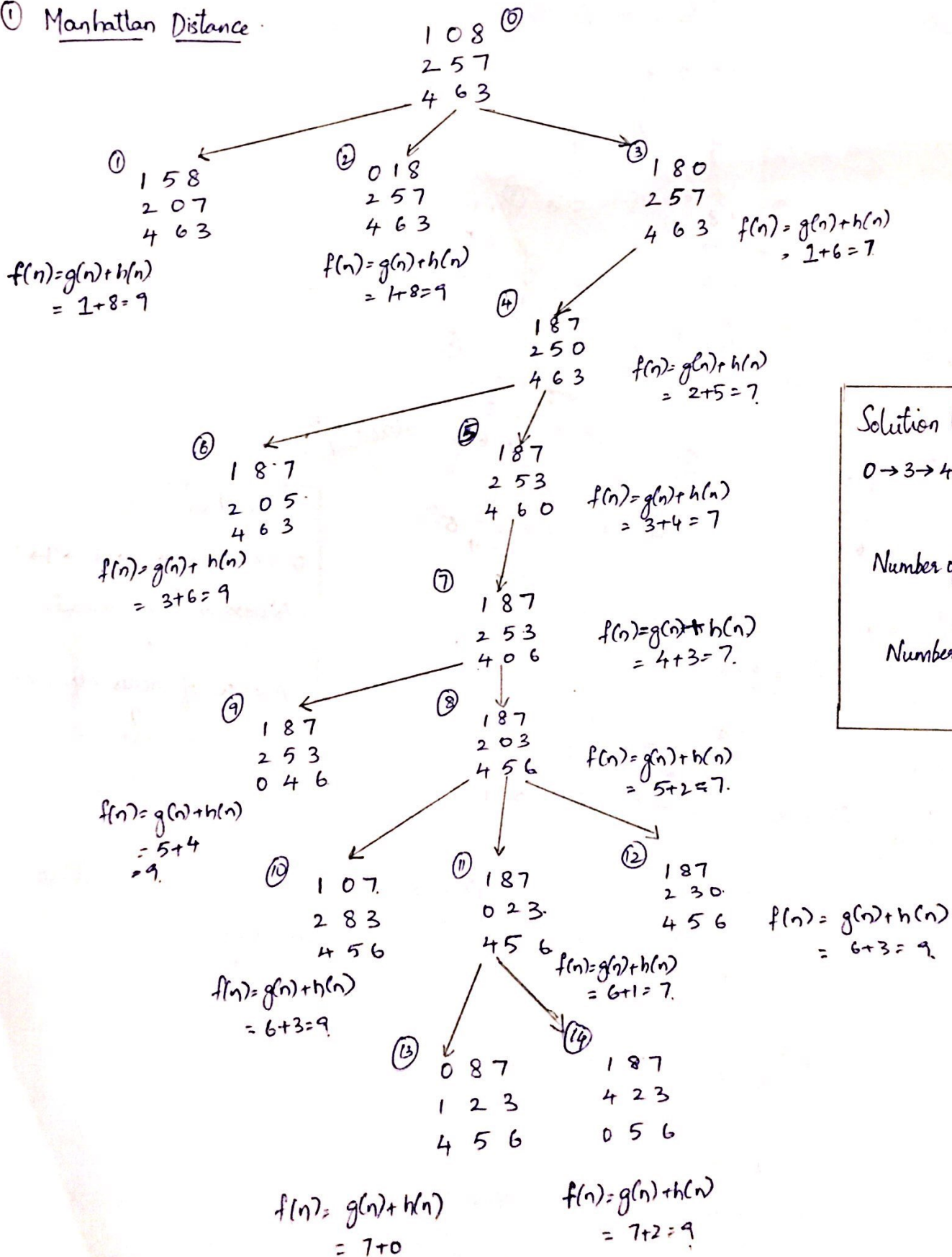
Heuristic misplaced tiles only considers whether a tile is misplaced or not unlike manhattan distance which takes into consideration the distance of the misplaced tile. We see through experimental results that number of nodes generated are more when misplaced tiles heuristic is used



### Example - 1

Initial Node	Final Node
1 0 8	0 8 7
2 5 7	1 2 3
4 6 3	4 5 6

① Manhattan Distance



Solution Path:

$0 \rightarrow 3 \rightarrow 4 \rightarrow 5 \rightarrow 7 \rightarrow 8$   
 $13 \leftarrow 11 \leftarrow$

Number of nodes generated:  
14

Number of nodes expanded:  
7

## Example - 1

Initial State

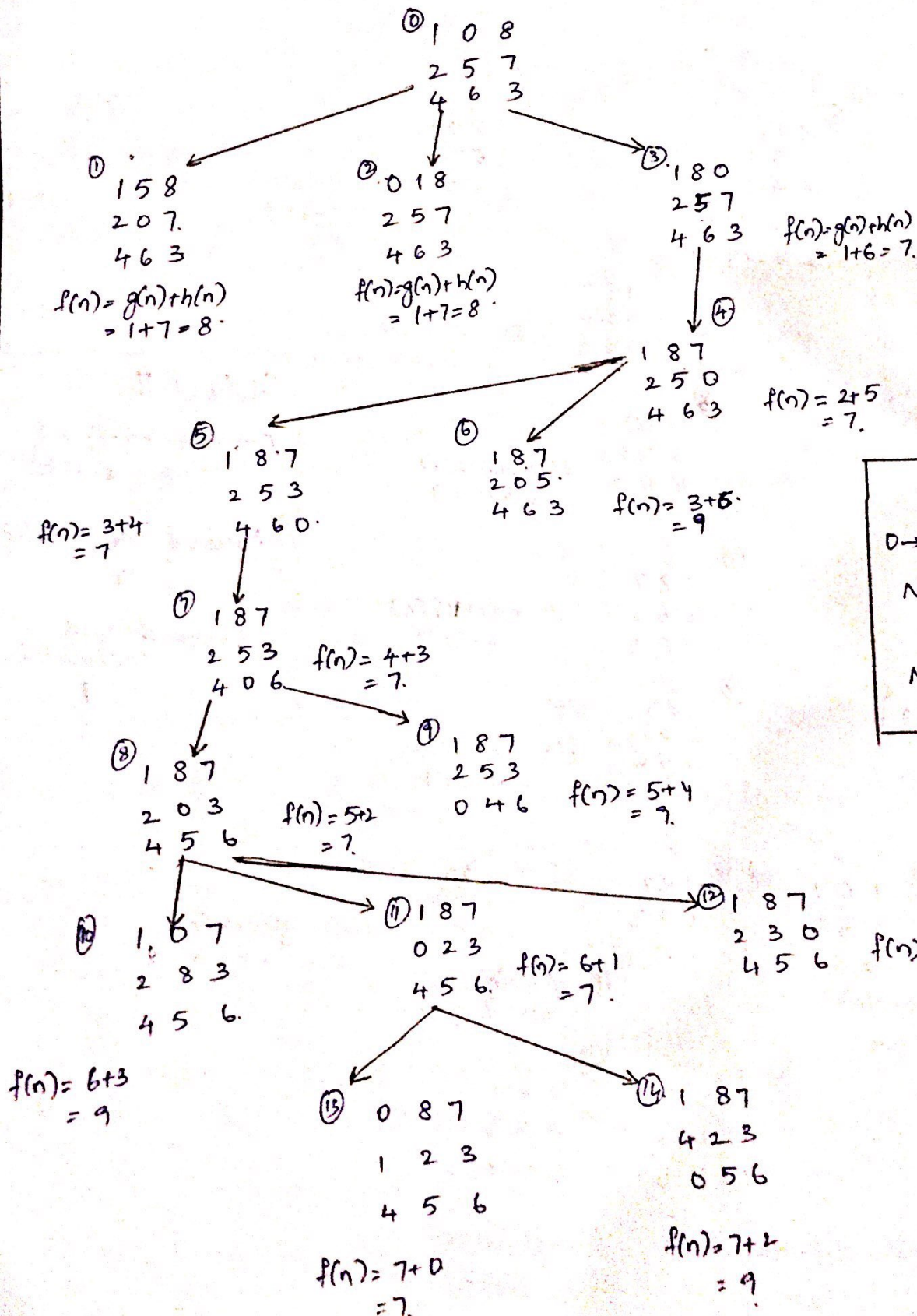
1 0 8  
2 5 7  
4 6 3

Final State:

0 8 7  
1 2 3  
4 5 6

### State Space Representation

2. Misplaced Tiles:



Solution Path:

0 → 3 → 4 → 5 → 7 → 8 → 11 → 13

Number of nodes generated:  
14

Number of nodes expanded:  
7



## Example - 2

Initial State

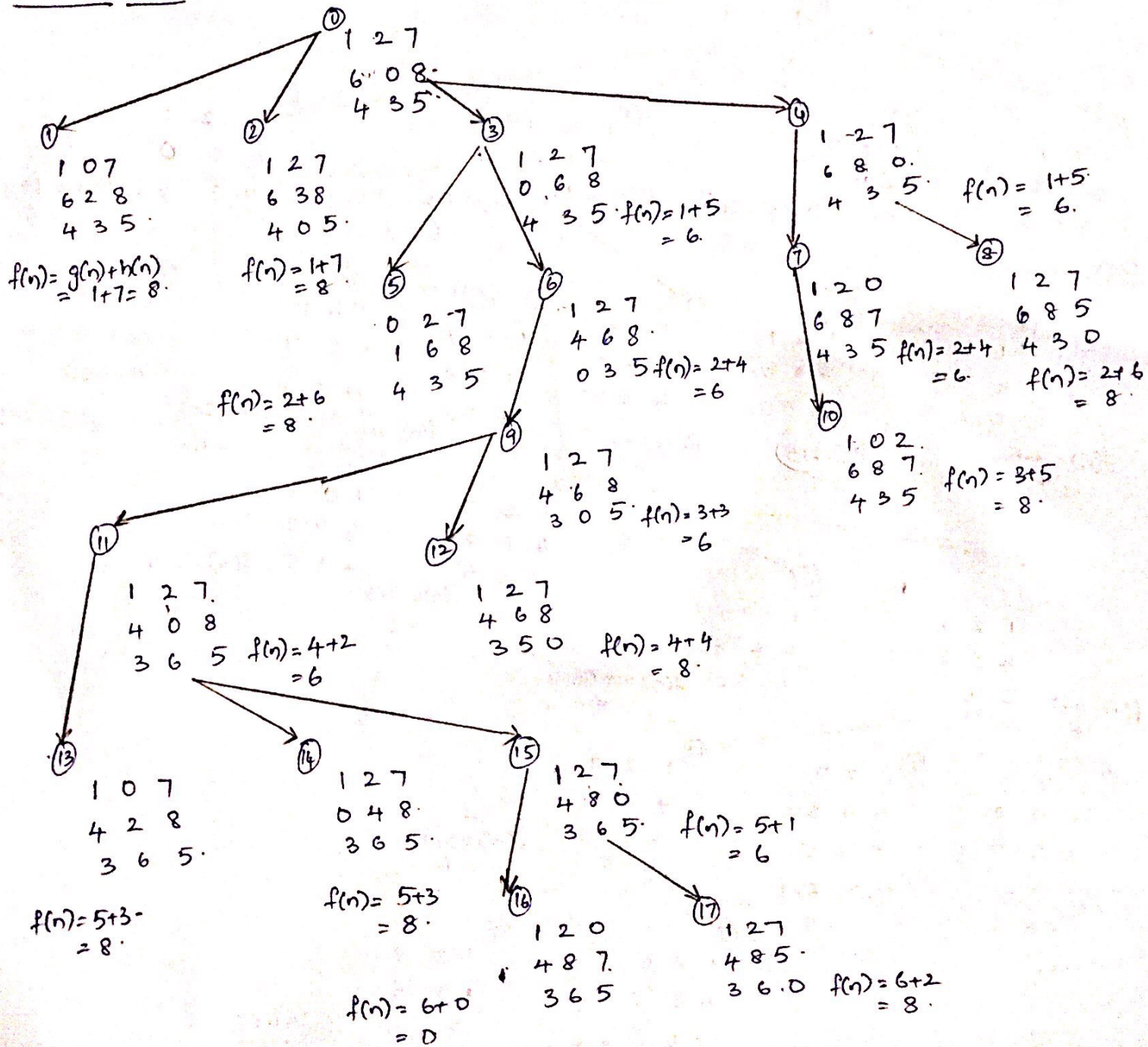
1 2 7  
6 0 8  
4 3 5

Final State

1 2 0  
4 8 7  
3 6 5

### State Space Representation

1 Manhattan Distance:



Solution Path:  $0 \rightarrow 3 \rightarrow 6 \rightarrow 9 \rightarrow 11 \rightarrow 15 \rightarrow 16$

Number of nodes generated: 17.

Number of nodes expanded: 8

## Example-2

Initial State:

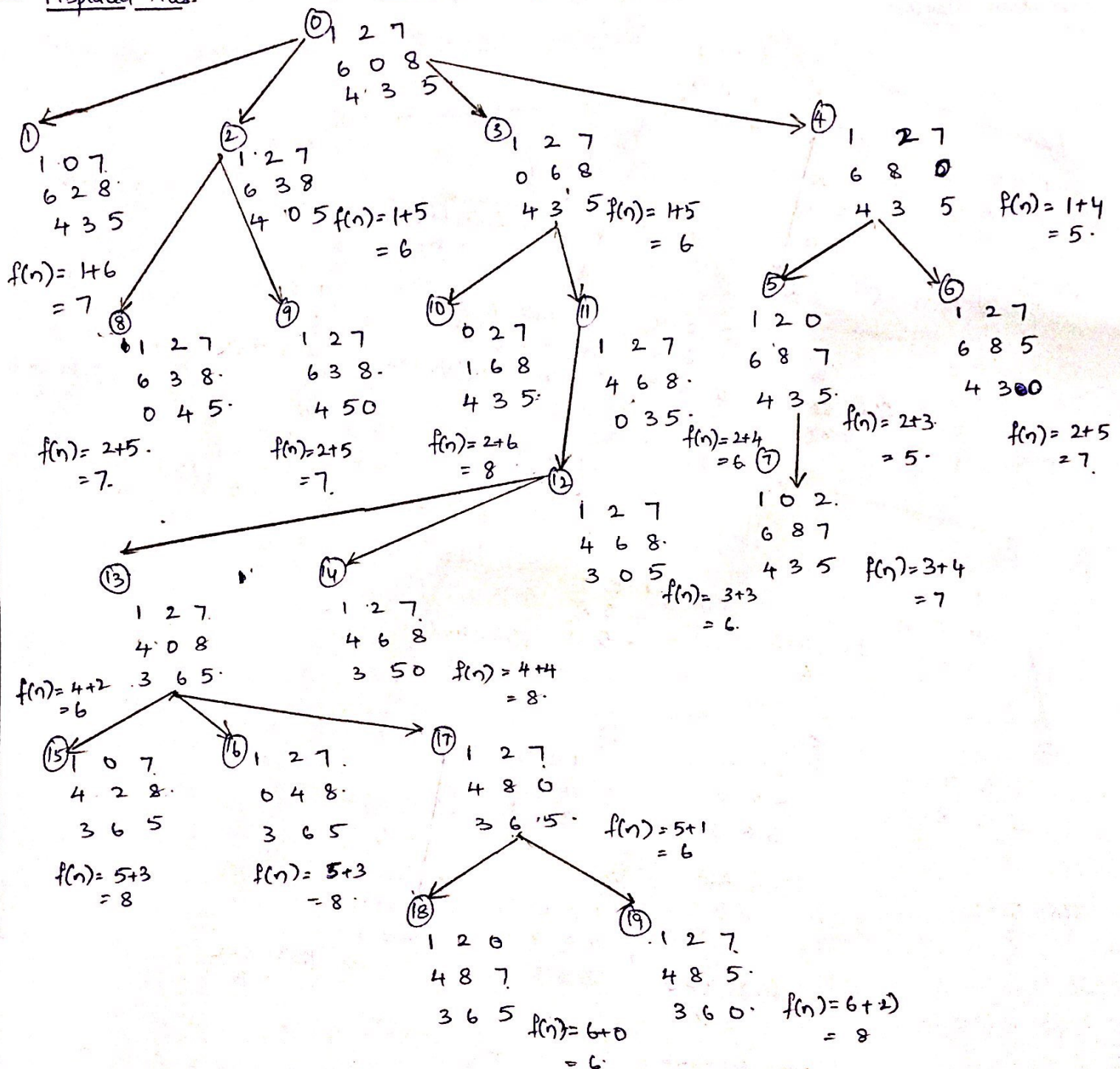
1 2 7  
6 0 8  
4 3 5

Final State:

1 2 0  
4 8 7  
3 6 5

2. Misplaced Tiles:

State Space Representation



Solution Path: 0 → 3 → 11 → 12 → 13 → 17 → 18.

Number of nodes generated: 19.

Number of nodes explored: 9.



### Example-3

Initial State:

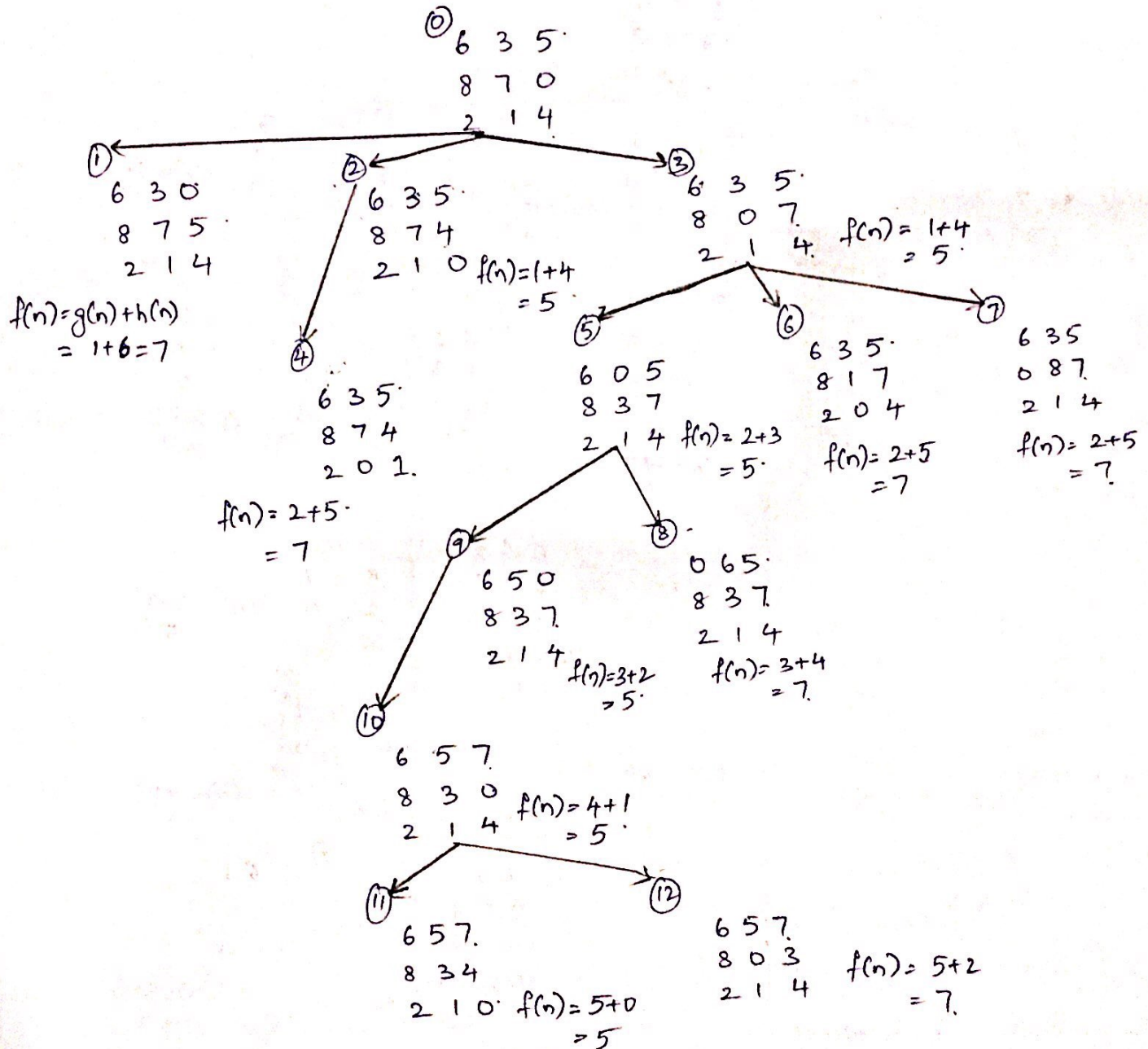
6 3 5  
8 7 0  
2 1 4

Final State:

6 5 7  
8 3 4  
2 1 0

1) Manhattan Distance:

State Space Representation:



Solution Path: 0 → 3 → 5 → ⑨ → 10 → 11

Number of nodes generated: 12

Number of nodes expanded: 6

### Example - 3

Initial State:

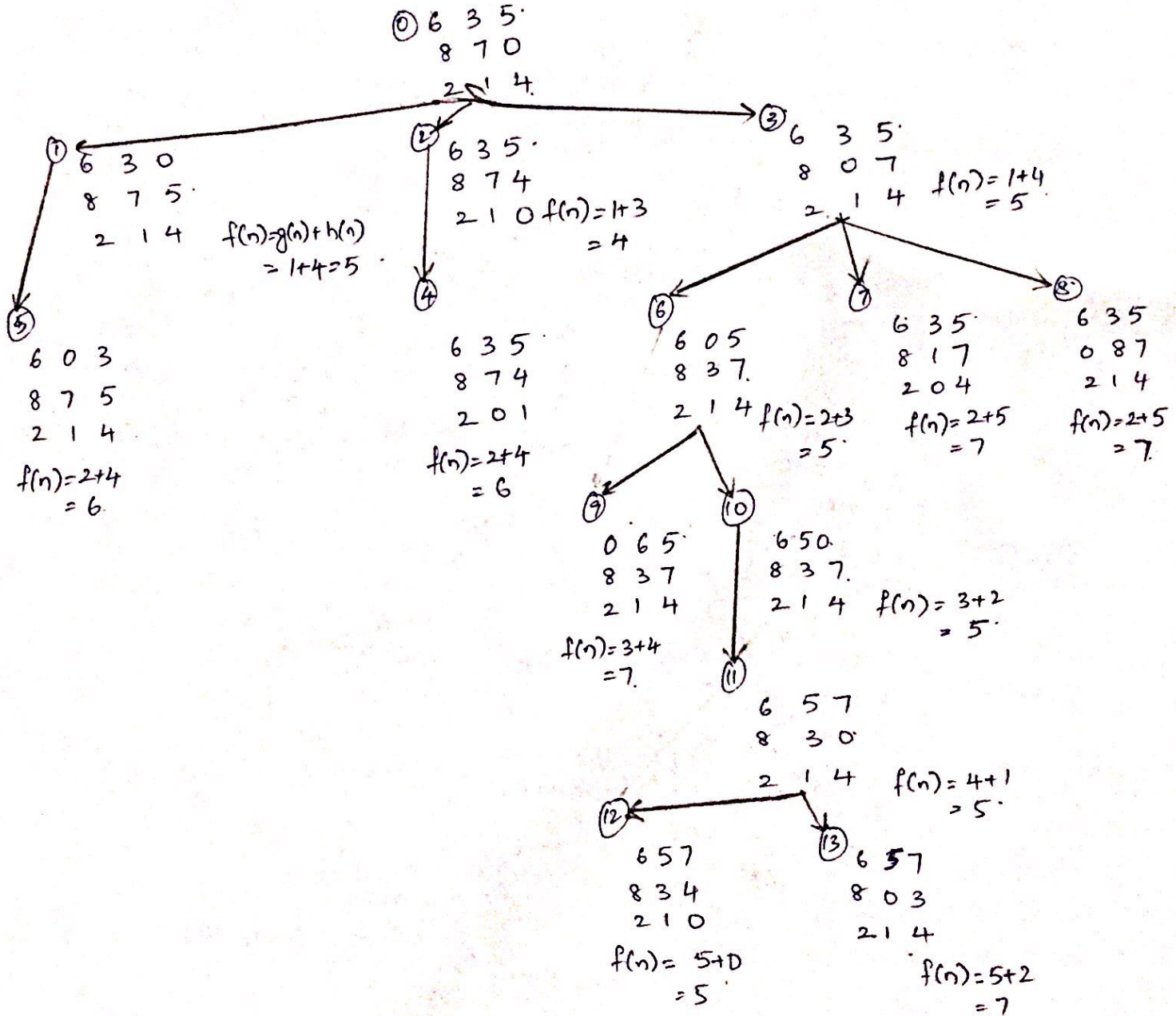
6 3 5  
8 7 0  
2 1 4

Final state:

6 5 7  
8 3 4  
2 1 0

### State Space Representation:

② Misplaced Tiles:



Path of solution:  $0 \rightarrow 3 \rightarrow 6 \rightarrow 10 \rightarrow 11 \rightarrow 12$

Number of nodes generated: 13

Number of nodes explored: 7



### Example-4

Initial State:

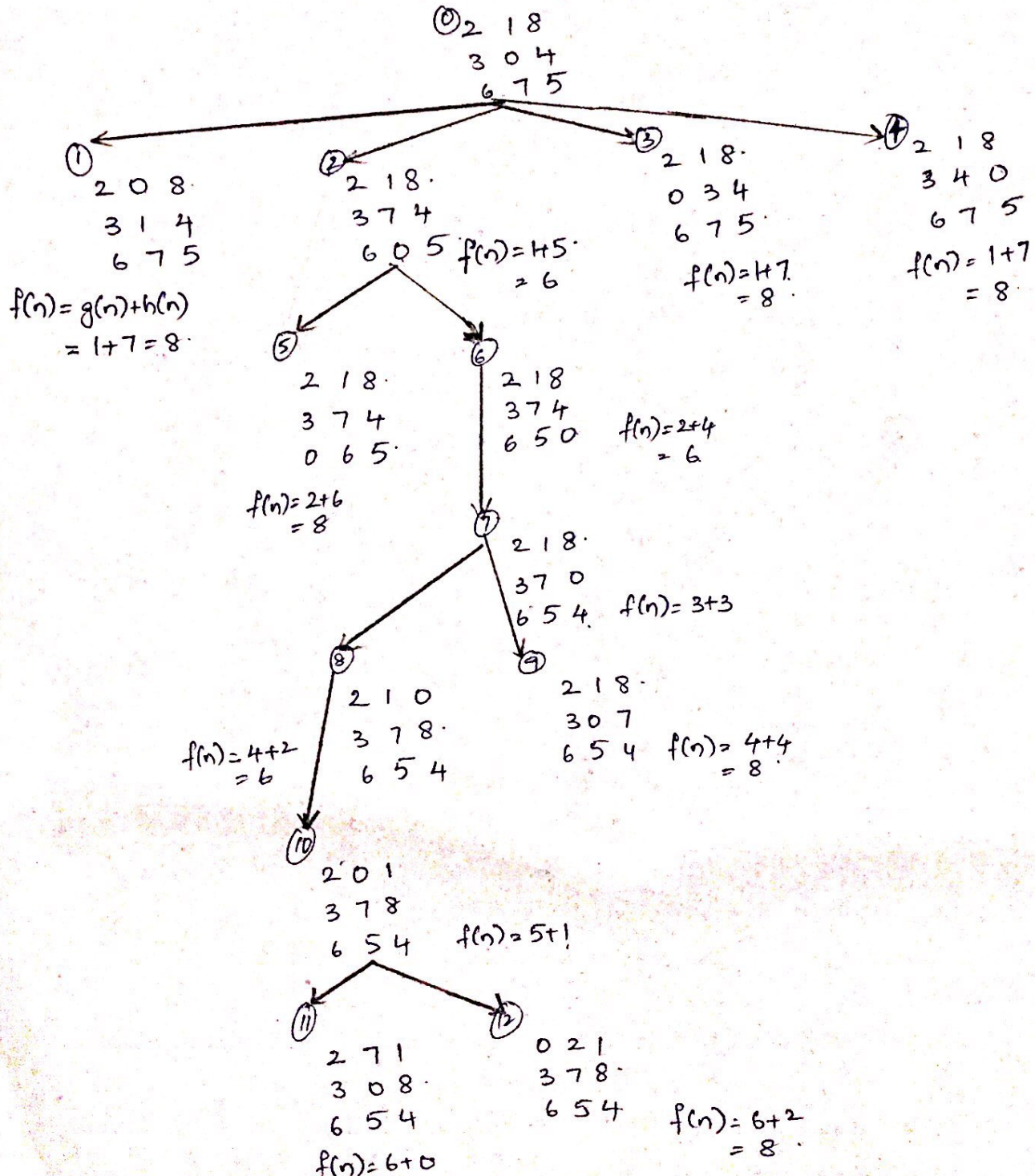
2 1 8  
3 0 4  
6 7 5

Final State

2 7 1  
3 0 8  
6 5 4

### State Space Representation

① Manhattan Distance:



Solution Path: 0 → 2 → 6 → 7 → 8 → 10 → 11.

Number of nodes generated: 12.

Number of nodes explored: 6

Initial State:

2 1 8  
3 0 4  
6 7 5

Final State:

2 7 1  
3 0 8  
6 5 4

Example-4② Misplaced Tiles:State Space Representation