#### CS3.304.M22

# Advanced Operating Systems Lecture # 01



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#### **Course Content**

- History of Operating Systems
- Processes and OS Abstractions
- OS APIs, Interrupts and system calls
- Introduction to the Linux Kernel
- Compiling the kernel
- Module programming
- Writing your own system calls
- Overview of kernel startup and initialization
- Kernel Debugging Techniques
- Interrupts PICs, APICs, exceptions (traps) and hard interrupts, IDTs
- Address Spaces and Loading, Virtual Memory, Memory allocators,

- Overview of memory spaces: logical segmentation, linear virtual, actual physical
- Detecting BIOS-provided physical RAM map, paging, buddy system, setting up page directories (global, upper, middle), tables and PTEs
- (N)UMA, nodes, zone, memory types, Setting up buddy system
- Allocating contiguous pages from buddy system
- Setting up slabs for small memory objects
- CPU Scheduling, Threads, Process structures, organization, initialization
- Concurrent Programming, Locking, Deadlocks
- Structures: thread union, thread info, stack, task, and thread struct
- Creating kernel threads, using kthread, Kernel process scheduling
- Scheduling processes with red-black tree, process switching, Context switches, Switching to suspended process
- Linux File Systems and Disk Scheduling.

#### Reference Material

#### PREFERRED TEXT BOOKS:

- Thomas Anderson and Michael Dahlin
- Operating Systems: Principles and Practice, 2nd Edition
- Recursive books (August 21, 2014),
- ISBN: 0985673524
- Daniel P. Bovet & Marco Cesati
- Understanding the Linux Kernel (3rd edition)
- O'Reilly & Associates, November 2005.
- ISBN: 0596005652

#### REFERENCE BOOKS:

- Remzi Arpaci-Dusseau and Andrea Arpaci-Dusseau
- Operating Systems: Three Easy Pieces
- Arpaci-Dusseau Books
- August, 2018 (Version 1.00)
- Jonathan Corbet; Alessandro Rubini; Greg Kroah-Hartman
- Linux Device Drivers (3rd edition)
- O'Reilly & Associates, February 2005.
- ISBN-13: 978-0-596-00590-0
- Robert Love
- Linux Kernel Development (3nd Edition)
- Addison-Wesley Professional, 2010.
- ISBN: 0672329468
- Ellen Siever, Stephen Figgins, Robert Love, and Arnold Robbins
- Linux in a Nutshell, 6th Edition
- O'Reilly & Associates, September 2009.
- ISBN: 978-0-596-15448-6

#### **Expected Outcome**

- Do not revisit but re-establish your basics
  - Go deeper
  - Better understand
  - Be more up-to-date
- We will ensure that both *theoretical* as well as *practical* aspects are learnt simultaneously.
- The project deliverables are expected to working code/prototype.

### **Grading Scheme**

- Relative Grading.
- Detailed Grading Breakup (~ 36% Exams/Quiz + 64% Practical Learning):
  - ➤ 34% Course Project
  - ➤ 30% Assignments (6×5)
  - ➤ 10% Mid-semester Exams
  - > 20% Final Exam
  - > 06% Quiz/Others
- Zero marks in assignment if a copying is detected
- Cooperation with TA's is expected
- Zero tolerance from institute's attendance policy

#### Lecture 01: Plan

- System
- Characteristics
- System Concepts
- System Components
- Recap of historical OS efforts

# What is an Operating System?

#### Abstracts the computer hardware

- Hides the messy details of the underlying hardware
- Present users with an easy to use resource abstraction
- Extends or virtualizes the underlying machine

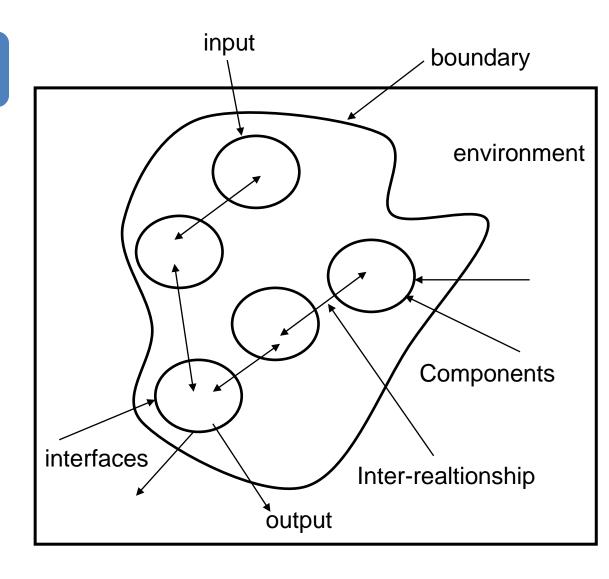
#### Manages the resources

- Processors, memory, timers, disks, mice, network interfaces, printers, displays, ...
- Allows multiple users and programs to share the resources and coordinates the sharing

### System

#### Characteristics of a system:

- Components
- Inter-related components
- A boundary
- A purpose
- An environment
- Interfaces
- Input
- Output
- Constraints



- Components:
  - A system is made up of components.
  - A component is either an irreducible part or aggregation of parts that make-up a system. A component is also called a sub-system.
- Interrelated Components:
  - The components of interrelated
  - Dependence of one subsystem on one or more subsystems.

- Boundary (Scope):
  - A system has a boundary, within which all of its components are contained and which establishes the limits of a separating the system from other systems.
- Purpose
  - The overall goal of function of a system. The system's reason for existing.

- Environment
  - Everything external to the system that interacts with the system.
- Interface
  - Point of contact where a system meets its environment or subsystems meet each other.
- Constraint:
  - A limit what a system can accomplish: Capacity, speed or capabilities.

#### Input

 Whatever a system takes from its environment in order to fulfill its purpose.

#### • Output:

 Whatever a system returns to its environment in order to fulfill its purpose.

### Important System Concepts

- Decomposition
- Modularity
- Coupling
- Cohesion

# Decomposition

- Divide and Conquer Strategy
- It deals with being able to break down a system into its components.
- Decomposition results in smaller and less complex pieces that are easier to understand than larger, complex pieces.
- Decomposing a system also allows to focus on one particular part of a system, making easier to think of how to modify that part independently of the entire system.

# Modularity

- Modularity refers to dividing a system up into chunks or modules of a relatively uniform size.
- You can replace or add any other module (or a component) without effecting the rest of the system.
- It is a design strategy in which system is composed of relatively small and autonomous routines fit together.

# Coupling

- Coupling is the extent to which subsystems are dependent on each other.
- Subsystems should be as independent as possible.
- If a subsystem fails and other subsystems are highly dependent on it, the others will either fail themselves or have problems in functioning.

#### Cohesion

• The extent to which a system or a subsystem performs a single function.

# Operating System (OS)

- The operating part of a tool is called as operating system of that tool.
- The purpose of operating system is to facilitate the operation of the underlying machine or tool.
- For a machine, the OS abstracts the machine part in terms of simple services by hiding the details of the machine.
- The OS can provide services to users or other subsystems.
- Examples of typical operating systems:
  - Car operating system, Telephone operating system, TV operating system and so on.

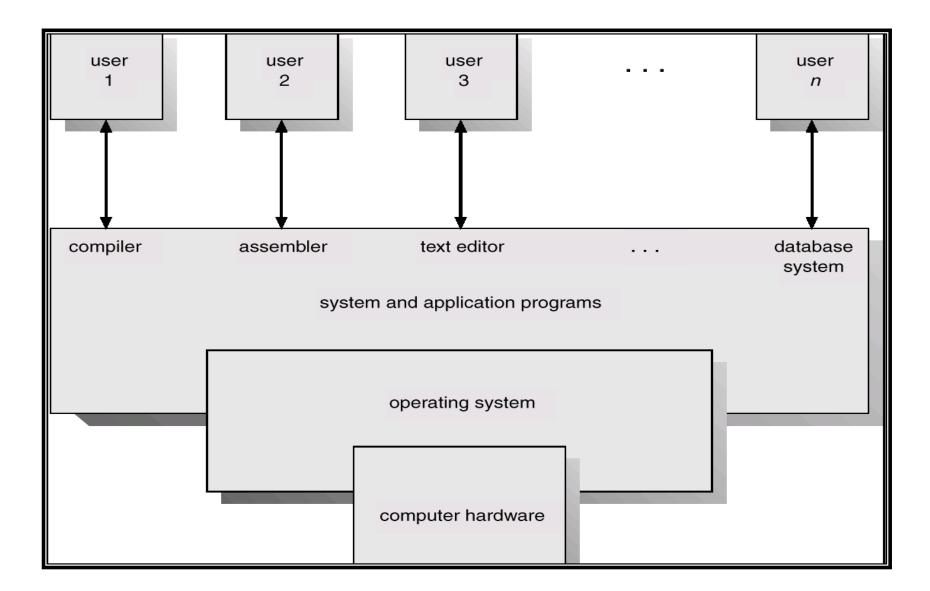
#### **Computer Operating System**

- A computer is also a tool that contains machine part and operating part.
- The operating part of a computer is called Computer Operating System.
- For a computer, the operating system abstracts the underlying hardware in terms of simple services by hiding the details of the hardware. The OS can provide services to users or other subsystems.
- Examples of Computer operating systems:
  - WINDOWS, Macintosh, UNIX, SOLARIS, LINUX and so on.
- In the rest of this course, operating system means computer operating system.

#### Computer OS components

- Hardware provides basic computing resources (CPU, memory, I/O devices).
- Operating system controls and coordinates the use of the hardware among the various application programs for the various users.
- **Applications programs** define the ways in which the system resources are used to solve the computing problems of the users (compilers, database systems, video games, business programs).
- Users (people, machines, other computers).

### Computer OS components



#### Other OS Definitions

- Resource allocator manages and allocates resources.
  - Resources: CPU time, Memory Space, file storage space, I/O devices and son on.
- Control program controls the execution of user programs and operations of I/O devices.
- Kernel the one program running at all times (all else being application programs).
- The two goals, efficiency and convenience are sometimes contradictory.
- Much of OS theory concentrates on optimal use of resources.

### Objectives

- The main objective is to understand the operational part of any computer.
- Understanding the general principles of OS design.
  - Focus on general-purpose, multi-user, uni-processor systems.
  - Emphasis on widely applicable concepts rather than any specific features of any specific OS.
- Understanding problems, solutions and design choices.
- Understanding the structure of specific OSs: UNIX, LINUX, WINDOWS

# Early Systems (Serial Processing)

#### 1940-50:

- The programmer interacted directly with the computer hardware.
- Display light, switches, printer, card reader.
- No OS. Error is displayed through lights.

#### Problems:

- Scheduling → Users spend lots of time at the computer.
  - Signup sheet was used.
- Job Setup time
  - Loading and compiling
    - Mounting and Un-mounting of tapes
    - Setting up of card desks
- Libraries of functions, linkers, loaders, debuggers, and I/O driver routines were available for all the users.

### Early Systems

- Early computers were (physically) large machines run from a console.
- The programmer would operate the program directly from the console.
  - The program is loaded to the memory from panel of switches, paper tape, and from punched cards.
- As time went on, additional software and hardware were developed.
  - Card readers, line printers, and magnetic tape became common place.
  - Libraries, loaders, and common functions were created.
    - Software reusability.



**IBM029** 



### Early Systems

- The setup time was a real problem
- CPU is idle while tapes are being mounted or the programmer was operating the console.
- In the early days, few computers were available and they were expensive (millions of dollars).
  - operational costs: power, cooling, programmers.
- Main question:

How to increase the utilization of CPU?

## Early Systems

- The solution was two fold.
- First, a professional computer operator was hired.
  - Once the program was finished, the operator could start next job.
  - The operator sets up the job, produces the dump, and starts the next job.
  - The set up time was reduced due to operator's experience.
- Second, jobs with similar needs were batched together and run through the computer as a group.
  - For example, if there is a FORTRAN job, COBOL job, and FORTRAN job, two FORTRAN jobs were batched together.
- However, during transition time CPU sat idle.
- Automatic job sequencing to avoid CPU idle time.
  - A first rudimentary OS was created
  - A small program called a resident monitor was developed.
  - The resident monitor always resided in memory.

### Simple Batch Systems

- In serial systems
  - Machines were very expensive
  - Wasting time was not acceptable.
- To improve usage, the concept of batch OS was developed.
- The main idea is the use of software known as monitor.
  - The user no longer has access to machine.
- The user submits the job (tape) to the operator.
- The operator batches the jobs together sequentially, places entire batch as an input device for use by the computer.

## Features of Batch System

- The batch OS is simply a program.
- It relies on the ability of the processor to fetch instructions from various portions of main memory to seize and relinquish control.
- Hardware features:
  - Memory protection: While the user program is running, it must not alter the memory area containing the monitor.
  - If such is the case the processor hardware should detect the error and transfer control to monitor.
  - Timer: A timer is used to prevent the single job from monopolizing the system

### Features of Batch System

- Hardware Features
  - Privileged instructions
    - Contains instructions that are only executed by monitor.
    - I/O instructions
    - If a program encounters them the control shifts through monitor.
  - Interrupts: It gives OS more flexibility.
    - Relinquishing control and regain control
- With batch OS the machine time alters between execution of user programs and execution of monitor.
- Two overheads
  - Machine time is consumed by the monitor.
  - Memory is consumed by the monitor.
- Still, they improved the performance over serial systems.

# Problem with Batch System

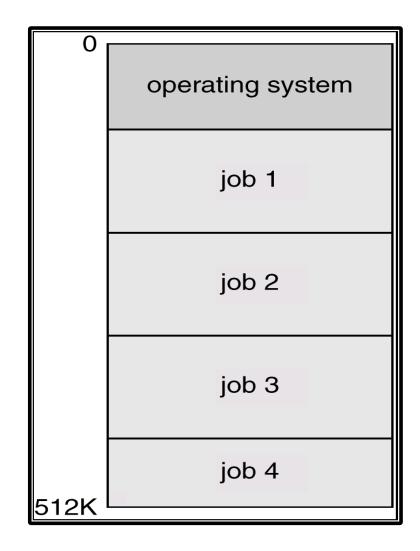
- CPU is idle
- Speed of mechanical devices is very slower than those of electronic devices.
- CPU works in a microsecond range
  - Thousands of instructions/second
- A card reader may read 1200 cards per minute (20 cards per second)
- CPU speed has increased at a faster rate.
- Tape technology improved the performance little-bit.
- Main perceived problem
  - Turn-around time: upto two days
  - CPU often underutilized
    - Most of the time was spent reading and writing from tape.

# Multi-programmed Batched Systems (1960s) (or Multi tasking)

- If CPU is executing a job and requires a tape to be mounted
  - In a non multi-programmed system
    - CPU sits idle.
  - In a Multi-programmed system
    - CPU takes up another job.
- Multiprogramming is the first instance when the OS started taking decisions.
- Job scheduling is done by OS.
- Having several programs in the memory requires memory management.

# Multi-programmed Batched Systems (1960s) (or Multi tasking)

- A single user can not keep either CPU or I/O busy.
- Multiprogramming increases CPU utilization by organizing jobs such that the CPU always has one to execute.
- The OS keeps several jobs in memory at a time and CPU is multiplexed among them



# OS Requirements (60s)

- OS Research in 60s
  - MULTICS at MIT
  - Atlas (spooling, demand paging) at Manchester Univ.
  - Multiprogramming
    - Memory allocation and protection
    - I/O operations were responsibility of OS.
  - Interactive systems
    - Scheduling issues
    - Swapping and virtual memory.
  - Users wanted permanent files
    - Hierarchical directory systems.
  - Increased in size and complexity were not well understood
    - IBM: OS/360

# UNIX (early 1970s)

- Originally developed at Bell labs for the PDP-7
  - Ken Thomson
  - Dennis Ritchie
- Smaller & Simpler
  - Process spawn and control
    - Each command creates a new process
  - Simple inter-process communication
  - Command interpreter not built in: runs as a user process
  - Files were streams of bytes.
  - Hierarchical file system
- Advantages
  - Written in a high-level language
  - Distributed in source form
  - Powerful OS primitives on an inexpensive platform

## Personal Computers (1980s)

- Originally
  - Single user
  - Simplified OSs
    - No memory protection
    - MS-DOS
- Now run sophisticated OSs
  - Windows NT, Linux

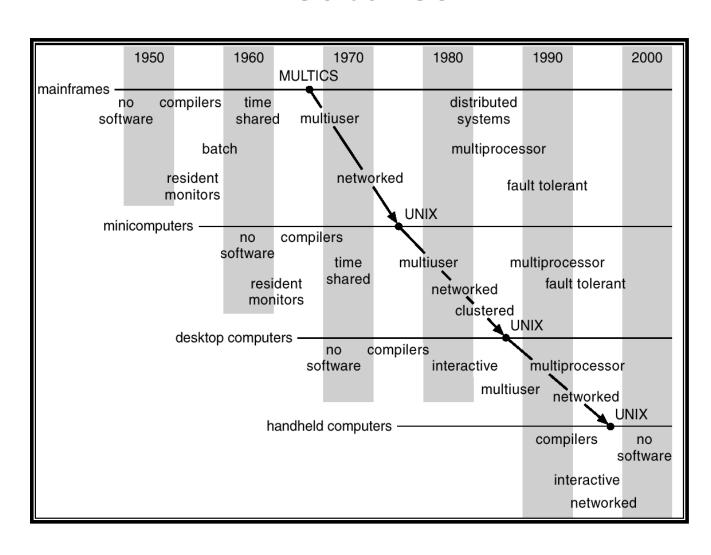
## Networks of workstations (1990s)

- High-speed network connections
- Local & world-wide
- Client-server systems
  - File systems
  - Remote windowing systems
- Support a variety of node OSs
  - Unix, Windows XP, OS/2

#### **Future**

- Distributed systems
  - Network is invisible
- Micro-kernel and extensible OSs
  - Supports multiple OS flavors
    - E.g., Mach, Amoeba, WINDOWS XP
- Embedded services and network computers
  - Computer runs a very thin OS (Java Virtual machine).

# Migration of Operating-System Concepts and Features

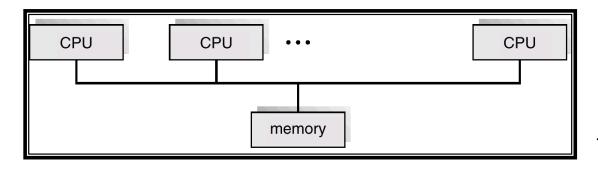


## Multiprocessor Systems

- Multiprocessor systems with more than one CPU in close communication.
- *Tightly coupled system* processors share memory and a clock; communication usually takes place through the shared memory.
- Advantages of multiprocessor system:
  - Increased throughput: more processors more work
  - Economical: more computing in same box
  - Increased reliability
    - Graceful degradation & Fault tolerance: failure of one processor will not halt the system. Service is proportional to the level of surviving hardware.

## Parallel Systems

- Symmetric multiprocessing (SMP)
  - Each processor runs and identical copy of the operating system.
  - Many processes can run at once without performance deterioration.
  - Most modern operating systems support SMP
- Asymmetric multiprocessing
  - Each processor is assigned a specific task; master processor schedules and allocated work to slave processors.
  - More common in extremely large systems



**SMP** Architecture

## Distributed Systems

- Distribute the computation among several physical processors.
- Loosely coupled system
  - each processor has its own local memory;
  - processors communicate with one another through various communications lines such as highspeed buses or telephone lines.
- Advantages of distributed systems
  - Resources Sharing
  - Computation speed up/load sharing
  - Reliability
  - Communications

## Real-Time Systems

- Often used as a control device in a dedicated application such as controlling scientific experiments, medical imaging systems, industrial control systems, and some display systems.
- Well-defined fixed-time constraints.
  - A process must complete within the defined constraints or system will fail.
- Real-Time systems may be either hard or soft real-time.

## Real-Time Systems

#### Hard real-time:

- Guarantees that critical tasks complete within time.
- All the delays in the system are bounded.
- Secondary storage limited or absent, data stored in short term memory, or read-only memory (ROM)
- Conflicts with time-sharing systems, not supported by general-purpose operating systems.

#### Soft real-time

- Critical time tasks gets priority over other tasks, and retails that priority until it completes.
- Limited utility in industrial control of robotics
- Useful in applications (multimedia, virtual reality) requiring advanced operatingsystem features.

## Concept of Virtual Computer

- Multilevel implementation
  - also called layered
- Resources
  - Hardware: provided to the OS
  - Logical (virtual): created by the OS
- Resource management
  - transformation
  - multiplexing
    - time and space

## Levels in a computer system

User programs Operating system interface Operating system Hardware interface Hardware

## Design: Two-level Implementation

- Two-level implementation
  - Lower level is a problem-specific language
  - Upper level solves the problem at hand
  - Lower level is reusable

- In operating systems
  - mechanism: lower level of basic functions, does not change
  - policy: upper level policy decisions, easy to change and experiment

## **Operating System Functions**

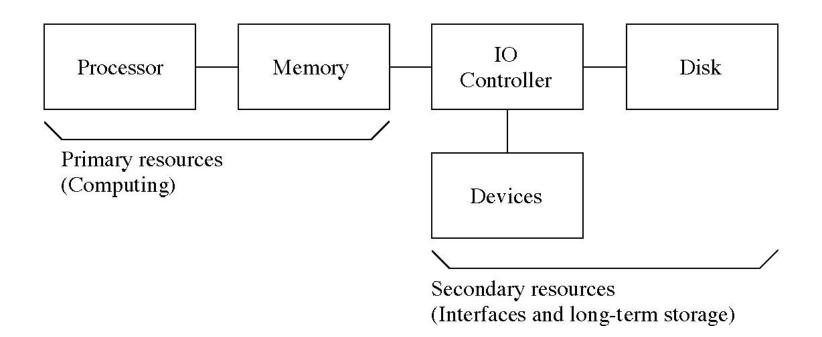
- Resource manager
  - manage hardware and software resources

- Virtual machine manager
  - implement a virtual machine for processes to run in
  - a nicer environment than the bare hardware

### Hardware Resources

- *Processor*: execute instructions
- Memory: store programs and data
- Input/output (I/O)controllers: transfer to and from devices
- Disk devices: long-term storage
- Other devices: conversion between internal and external data representations

### Hardware Resources



## Resource Management Functions

- Transforming physical resources to logical resources
  - Making the resources easier to use

- Multiplexing one physical resource to several logical resources
  - Creating multiple, logical copies of resources

- Scheduling physical and logical resources
  - Deciding who gets to use the resources

## Types of Multiplexing

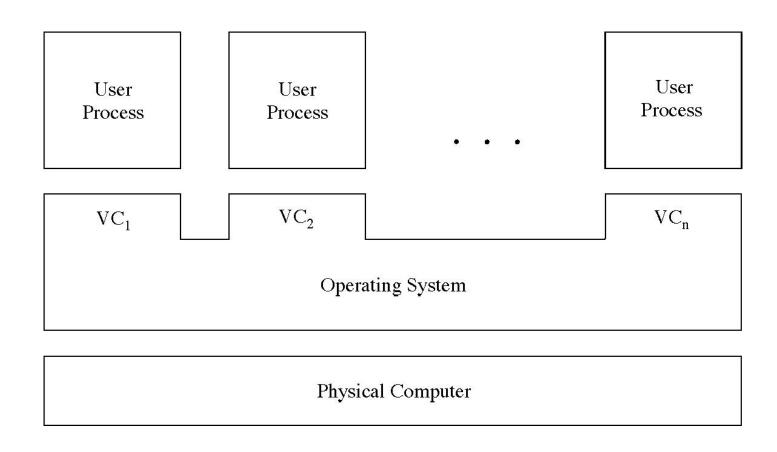
- Time multiplexing
  - time-sharing
  - scheduling a serially-reusable resource among several users

- Space multiplexing
  - space-sharing
  - dividing a multiple-use resource up among several users

## Virtual Computers

- Processor virtualized to processes
  - mainly time-multiplexing
- Memory virtualized to address spaces
  - space and time multiplexing
- Disks virtualized to files
  - space-multiplexing
  - transforming

## Multiple Virtual Computers



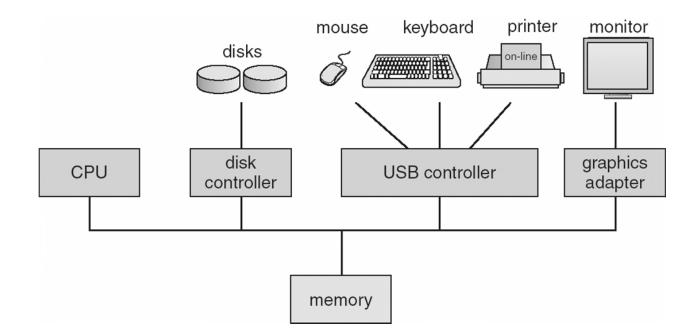
#### Do we need an OS?

- Not always
  - Some programs run "stand-alone"
- But they are very useful
  - Reusable functions
  - Easier to use than the bare hardware

## System Structures I

## Computer System Organization

- Computer-system operation
  - One or more CPUs, device controllers connect through common bus providing access to shared memory
  - Concurrent execution of CPUs and devices competing for memory cycles



## Computer-Components

- Computer consists of processor, memory, and I/O components, with one or more modules of each type. These modules are connected through interconnection network.
- I/O devices and the CPU can execute concurrently.
- Each device controller is in-charge of a particular device type.
- Each device controller has a local buffer.
- CPU moves data from/to main memory to/from local buffers
- I/O is from the device to local buffer of controller.
- Device controller informs CPU that it has finished its operation by causing an interrupt.

## I/O Hardware

- I/O devices can be categorized as storage, communications, user-interface, and others
- Devices connect with the computer via ports, e.g. a serial or parallel port.
- A common set of wires connecting multiple devices is termed a bus.
  - Buses include rigid protocols for the types of messages that can be sent across the bus and the procedures for resolving contention issues.
  - Bus types commonly found in a modern PC:
    - The PCI bus connects high-speed high-bandwidth devices to the memory subsystem (and the CPU.)
    - The expansion bus connects slower low-bandwidth devices, which typically deliver data one character at a time ( with buffering. )
    - The SCSI bus connects a number of SCSI devices to a common SCSI controller.
    - A *daisy-chain bus,* is when a string of devices is connected to each other like beads on a chain, and only one of the devices is directly connected to the host.

# THANK YOU