#### Operating Systems (CSE531) Lecture # 15



Manish Shrivastava LTRC, IIIT Hyderabad

## Memory Management

Manish Shrivastava

# Why?

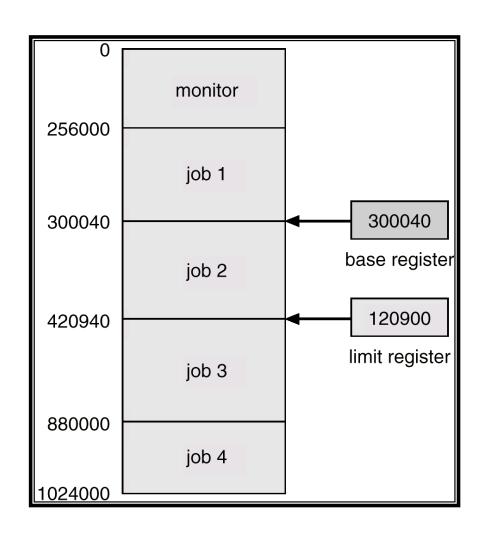
- The programs are in the Main memory
  - We need a memory management scheme to manage several processes in the main memory
- Main memory is very small
  - Secondary storage is used to support main memory
- We also need file management for on-line storage of access to both data and programs that reside on disk

#### **Memory Protection**

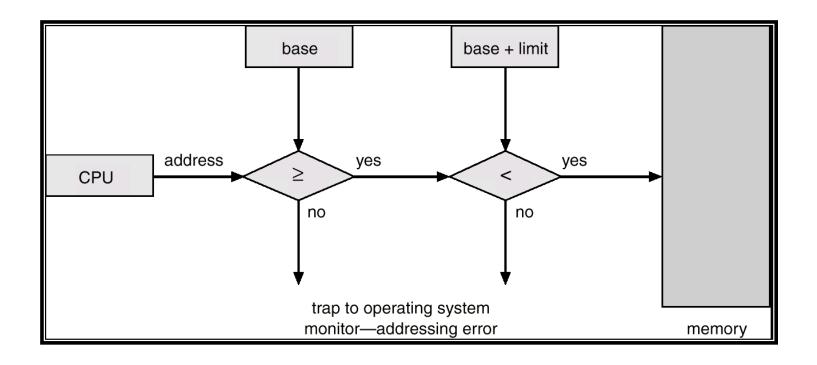
- Must provide memory protection at least for the interrupt vector and the interrupt service routines.
- In order to have memory protection, add two registers that determine the range of legal addresses a program may access:
  - Base register holds the smallest legal physical memory address.
  - Limit register contains the size of the range
- Memory outside the defined range is protected.

- Memory is a central part of modern computer systems
- Large array of bytes and words each with its own address.
- CPU fetches and executes instructions
  - After the operation, the result is stored back into memory
- Memory unit sees only stream of addresses.
- Program resides on the disk.
- Program must be brought into memory and placed within a process for it to be run.
- Input queue collection of processes on the disk that are waiting to be brought into memory to run the program.
- User programs go through several steps before being run.

#### Use of A Base and Limit Register



#### Hardware Address Protection



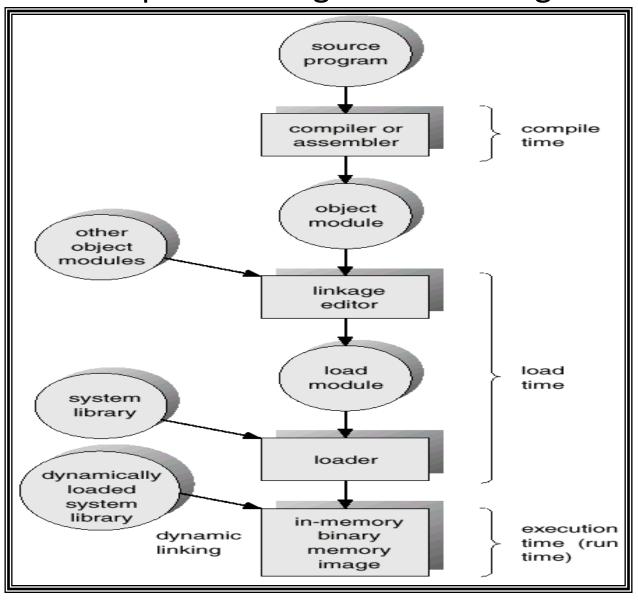
#### **Memory Protection**

- When executing in monitor mode, the operating system has unrestricted access to both monitor and user's memory.
- The load instructions for the base and limit registers are privileged instructions.

#### Address binding

- Most systems allow user process to reside in any part of the physical memory.
- Address space starts at 00000; However, the first address of user process may not start at 00000.
- So user program will go through several steps.
- Addresses in the source program are symbolic.
  - Example: Count
- A compiler will bind these addresses to re-locatable addresses.
  - Example: 14 bytes from the beginning of the module.
- A linkage editor or a loader will bind these re-locatable addresses to absolute addresses.
- A binding is a mapping from one address space to another.

#### Multi-step Processing of a User Program



### **Dynamic Loading**

- Dynamic loading is used to obtain better memoryspace utilization
- Routine is not loaded until it is called
- All routines are kept on disk in a re-locatable load format
  - Better memory-space utilization; unused routine is never loaded.
  - Useful when large amounts of code are needed to handle infrequently occurring cases.
  - No special support from the operating system is required.
  - Implemented through program design.

# Dynamic Linking

- Some OSs support static linking.
  - System language libraries are treated like any other object module and loader combines them into binary program image.
- In dynamic linking, the linking is postponed until execution time.
- Small piece of code, *stub*, used to locate the appropriate memory-resident library routine.
- Stub replaces itself with the address of the routine, and executes the routine.
- Operating system needed to check if routine is in processes' memory address.
- Dynamic linking is particularly useful for libraries.
  - Library updates; different versions
- Needs support from OS.

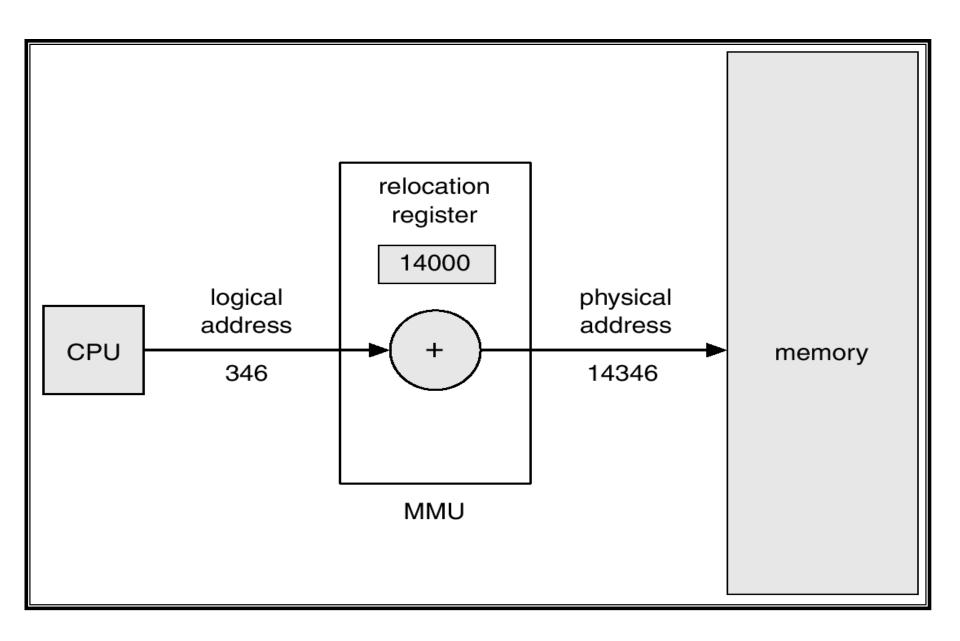
#### Logical vs. Physical Address Space

- The concept of a logical address space that is bound to a separate physical address space is central to proper memory management.
  - Logical address generated by the CPU; also referred to as virtual address.
    - Set of logical addresses generated by a program is called logical address space.
  - Physical address address seen by the memory unit.
    - Set of physical addresses corresponds to logical space is called physical address space.
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme.

# Memory-Management Unit (мми)

- Hardware device that maps virtual to physical address.
- In MMU scheme, the value in the relocation register is added to every address generated by a user process at the time it is sent to memory.
- The user program deals with logical addresses; it never sees the real physical addresses.

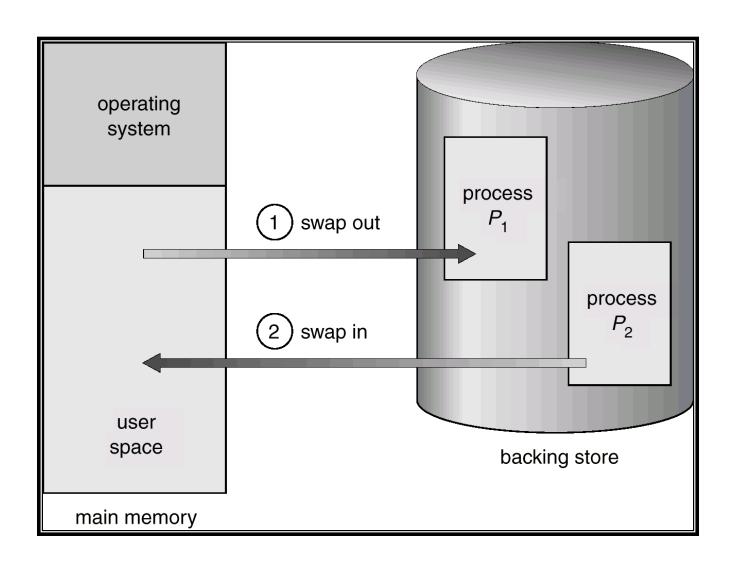
#### Dynamic relocation using a relocation register



### Swapping

- Whenever the CPU scheduler decides to execute a process, it calls the dispatcher.
- The dispatcher checks whether the process is in main memory.
- If the process is not, and there is no free memory, the dispatcher swaps out a process currently in main memory and swaps in the desired process.
- Backing store fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images.
- Roll out, roll in swapping variant used for priority-based scheduling algorithms;
   lower-priority process is swapped out so higher-priority process can be loaded and executed.
- Major part of swap time is transfer time; total transfer time is directly proportional to the *amount* of memory swapped.
- When a process which is swapped-out swaps-in
  - Binding during assembly and loading
    - Process can not be moved to different locations.
  - Binding during execution
    - Process can be moved to different locations
- Modified versions of swapping are found on many systems, i.e., UNIX, Linux, and Windows.

# Schematic View of Swapping



## Swapping...

- A process should be idle to swap.
  - It should not have any pending I/Os.

#### Solutions

- Never swap a process with pending I/Os
  - Difficult if the process is accessing asynchronously.
- Execute I/O operations into OS buffers.
  - Transfers between OS buffers to process occur only when the process is swapped in.

#### UNIX

- Swapping is normally disabled.
- However, swapping starts if many processes are running and using threshold amount of memory.
- Swapping is halted when the load is reduced.

#### WINDOWS

- OS does not provide full swapping.
- The scheduler decides when the process should be swapped out.
- When the user selects the process, the process is swapped-in.

## **Contiguous Allocation**

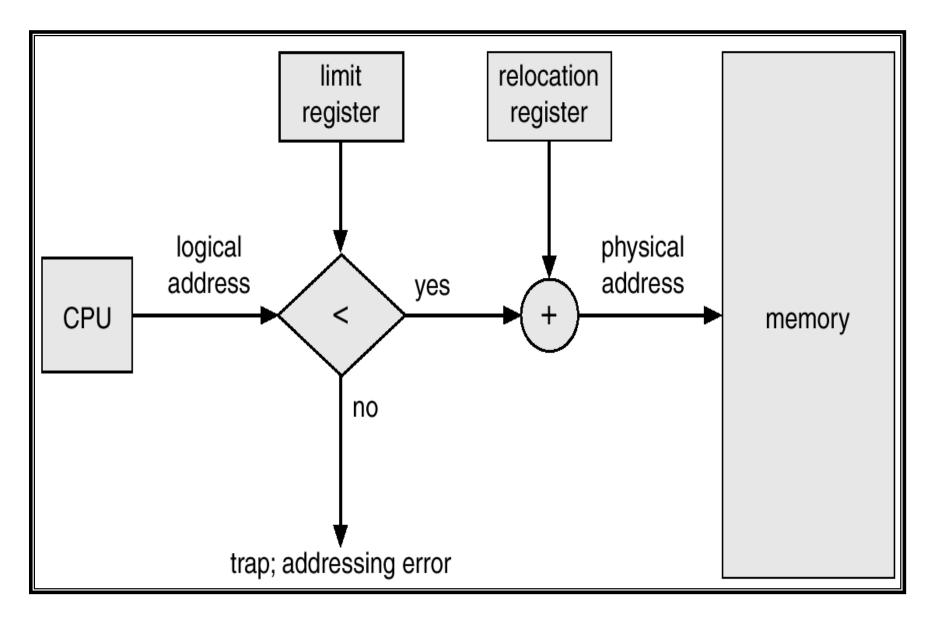
- Main memory usually into two partitions:
  - Resident operating system, usually held in low memory with interrupt vector.
  - User processes then held in high memory.
- Single-partition allocation
  - Relocation-register scheme used to protect user processes from each other, and from changing operating-system code and data.
  - Relocation register contains value of smallest physical address; limit register contains range of logical addresses – each logical address must be less than the limit register.
- When a CPU scheduler selects a process from execution, the dispatcher loads the relocation and limit registers with correct values as a part of context switch.

Operating system user

512K

0

#### Hardware Support for Relocation and Limit Registers

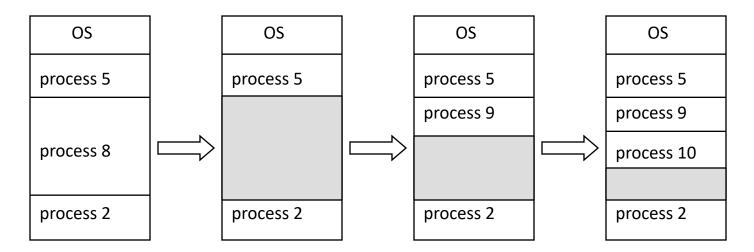


# Contiguous Allocation (Cont.)

- Multiple-partition allocation
- How to allocate available main-memory to the various processes
   ?
- Simple solution (fixed partition solution): partition the memory
  - Number of programs= Number of processes.
  - Not efficient
- Improved solution:
  - Generalization of fixed partition solution.
- OS keeps a table indicating which parts of memory are available and which are occupied.
- Initially all memory available for a user process.
- Free partition or Hole block of available memory; holes of various size are scattered throughout memory.
  - When a process arrives, it is allocated memory from free partitions large enough to accommodate it.
  - Operating system maintains information about:
     a) allocated partitions
     b) free partitions (hole)

# Contiguous Allocation (Cont.)

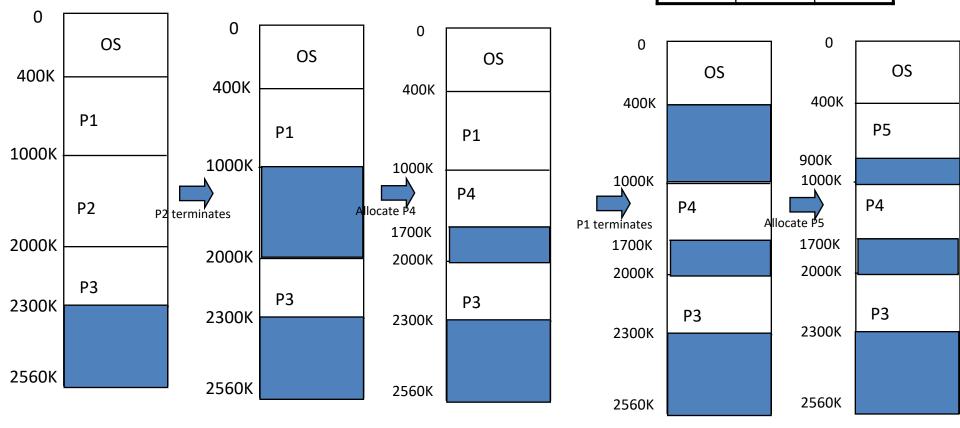
- At any time a set of holes of various sizes scattered throughout the memory
- A free partition large enough for the requesting process is searched.
- If the free partition is too large it is split into two: one is allocated to the arriving process and the other is returned to the set of partitions.
- When a process terminates, it releases its block of memory, which is then placed back in the set of free partitions.
- If the new hole is adjacent to other partitions, we merge these partitions to form a larger hole.
- Example:



# Contiguous Allocation (Cont.)

- Example: 2560K of memory available and a resident OS of 400K. Allocate memory to processes P1...P4 following FCFS.
- Shaded regions are holes
- Initially P1, P2, P3 create first memory map.

Process	Memory	time
P1	600K	10
P2	1000K	5
P3	300K	20
P4	700K	8
P5	500K	15



### Dynamic Storage-Allocation Problem

Algorithms to search for a free partition of size n.

- **First-fit**: Allocate the *first* free partition that is big enough.
- **Best-fit**: Allocate the *smallest* partition that is big enough; must search entire list, unless ordered by size. Produces the smallest leftover hole.
- Worst-fit: Allocate the *largest* partition; must also search entire list. Produces the largest leftover hole.

First-fit and best-fit better than worst-fit in terms of speed and storage utilization.

#### Fragmentation

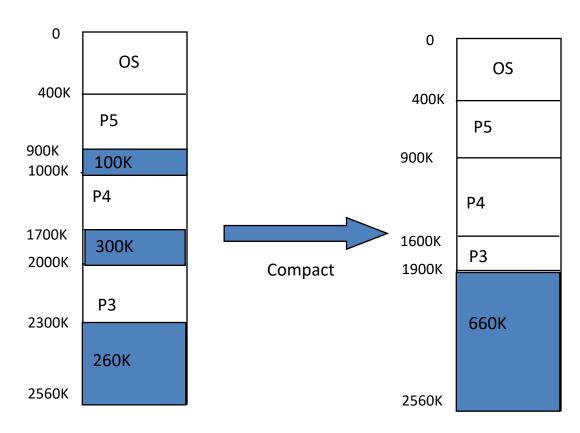
- External Fragmentation total memory space exists to satisfy a request, but it is not contiguous.
  - 50 % rule: Given N allocated blocks 0.5 blocks will be lost due to fragmentation.
- Internal Fragmentation allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used.
  - Consider the hole of 18,464 bytes and process requires 18462 bytes.
  - If we allocate exactly the required block, we are left with a hole of 2 bytes.
  - The overhead to keep track of this free partition will be substantially larger than the hole itself.
  - Solution: allocate very small free partition as a part of the larger request.

# Solution to fragmentation

- Compaction
- Paging
- Segmentation

#### Compaction

- Reduce external fragmentation by compaction
  - Shuffle memory contents to place all free memory together in one large block.
  - Compaction is possible only if relocation is dynamic, and is done at execution time.
  - I/O problem
    - Latch job in memory while it is involved in I/O.
    - Do I/O only into OS buffers.
  - Compaction depends on cost.



# **Paging**

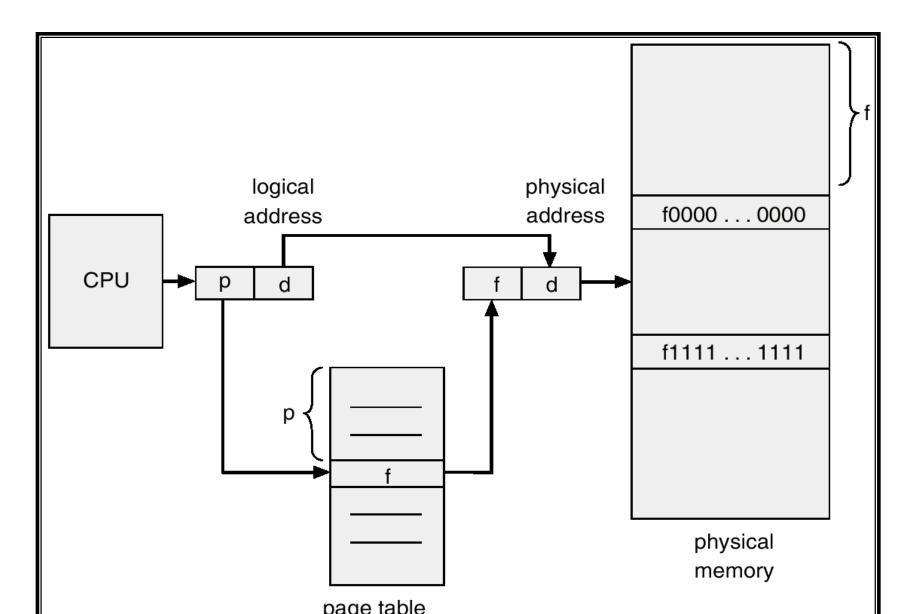
- Solution to external fragmentation
  - Permit the logical address space of the process to be non contiguous, allowing a process to be allocated physical memory whenever the later is available.
  - Paging is a solution.
- Logical address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available.
  - Divide physical memory into fixed-sized blocks called frames (size is power of 2, between 512 bytes and 8192 bytes).
  - Divide logical memory into blocks of same size called pages.
  - Keep track of all free frames.
- To run a program of size n pages, need to find n free frames and load program.
- Set up a page table to translate logical to physical addresses.
- Internal fragmentation.

#### **Address Translation Scheme**

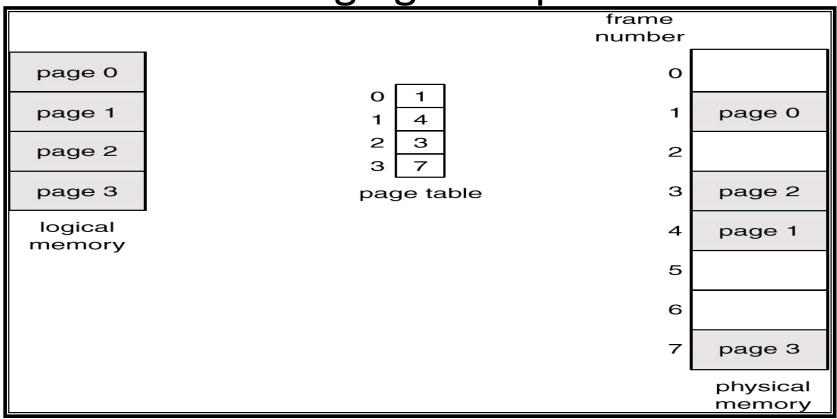
- Address generated by CPU is divided into:
  - Page number (p) used as an index into a page table which contains base address of each page in physical memory.
  - Page offset (d) combined with base address to define the physical memory address that is sent to the memory unit.
- Page number is an index to the page table.
- The page table contains base address of each page in physical memory.
- The base address is combined with the page offset to define the physical address that is sent to the memory unit.
- The size of a page is typically a power of 2.
  - 512 –8192 bytes per page.
- The size of logical address space is 2<sup>m</sup> and page size is 2<sup>n</sup> address units.
- Higher m-n bits designate the page number
- n lower order bits indicate the page offset.



#### **Address Translation Architecture**



# Paging Example



- Page size= 4 bytes; Physical memory=32 bytes (8 pages)
- Logical address 0 maps 1\*4+0=4
- Logical address 3 maps to= 1\*4+3=7
- Logical address 4 maps to =4\*4+0=16
- Logical address 13 maps to= 7\*4+1=29.

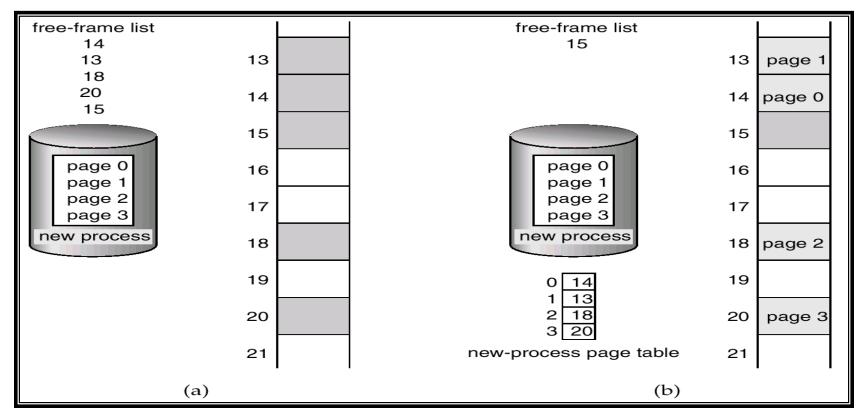
Paging Example

	T dania Examera		
0 a 1 b	О		
1 b 2 c 3 d 4 e	4	i	-
5 f	o 5	j	
7 h	1 6	k I	
8 i 9 j	2 1 8	m n	
10 k 11 l	3 2 page table	o p	
12 m	12	P	1
13 n 14 o			
15 p			-
logical memo	Sry		
	20	a b	
		c d	
	24	е	1
		f g h	
			-
	20		
	physica	al memo	ory

- Page size= 4 bytes; Physical memory=32 bytes (8 pages)
- Logical address 0 maps 5\*4+0=20
- Logical address 3 maps to= 5\*4+3=23
- Logical address 4 maps to =6\*4+0=24
- Logical address 13 maps to= 2\*4+1=9.

#### Free Frames

- When a process arrives the size in pages is examined
- Each page of process needs one frame.
- If n frames are available these are allocated, and page table is updated with frame number.



Before allocation

After allocation

### More about Paging

- Paging separates user's view of memory and the actual physical memory.
- User program views memory as single contiguous space.
- In fact, user program is scattered throughout physical memory.
- OS maintains copy of the page table for each process. This copy is used to translate logical addresses to physical addresses.

- With paging we have no external fragmentation.
- We may have some internal fragmentation.
- In general, page sizes of 2K or 4K bytes.

#### Two issues

- Speed
- Space

## Implementation of Page Table

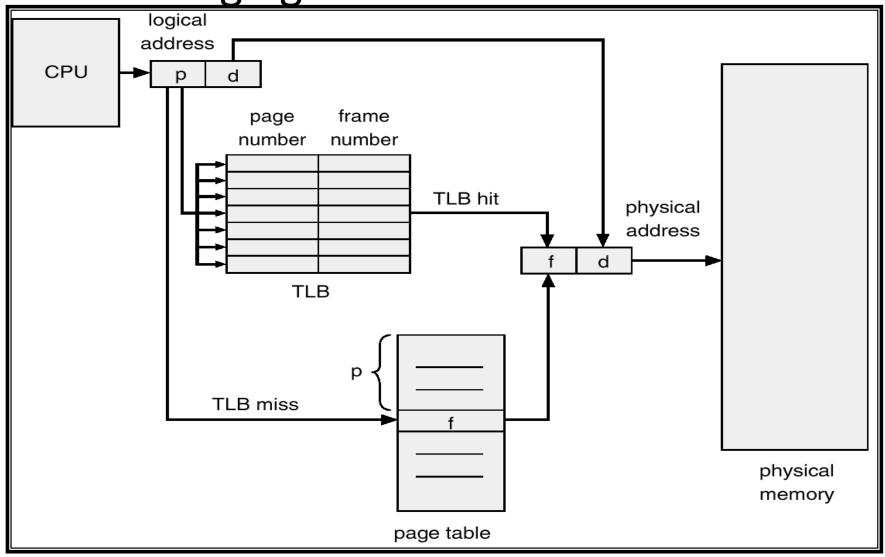
- Two options: Page table can be kept in registers or main memory
- Page table is kept in main memory due to bigger size.
  - Ex: address space =  $2^{32}$  to  $2^{64}$
  - Page size= 2<sup>12</sup>
  - Page table=  $2^{32} / 2^{12} = 2^{20}$
  - If each entry consists of 4 bytes, the page table size = 4MB.
- Page-table base register (PTBR) points to the page table.
- Page-table length register (PRLR) indicates size of the page table.
- PTBR, and PRLR are maintained in the registers.
- Context switch means changing the contents of PTBR and PRLR.
- In this scheme every data/instruction access requires two memory accesses. One for the page table and one for the data/instruction.
  - Memory access is slowed by a factor of 2.
  - Swapping might be better!
- The two memory access problem can be solved by the use of a special fast-lookup hardware cache called associative memory or translation look-aside buffers (TLBs)

# Translation look-aside buffer (TLB)

- TLB is an associative memory parallel search
- A set of associative registers is built of especially high-speed memory.
- Each register consists of two parts: key and value
- When associative registers are presented with an item, it is compared with all keys simultaneously.
- If corresponding field is found, corresponding field is output.
- Associative registers contain only few of page table entries.
  - When a logical address is generated it is presented to a set of associative registers.
  - If yes, the page is returned.
  - Otherwise memory reference to page table mode. Then that page # is added to associative registers.
- Address translation (A', A'')
  - If A' is in associative register, get frame # out.
  - Otherwise get frame # from page table in memory
- It may take 10 % longer than normal time.
- % of time the page # is found in the associative registers is called hit ratio.

Page #	Frame #

# Paging Hardware With TLB



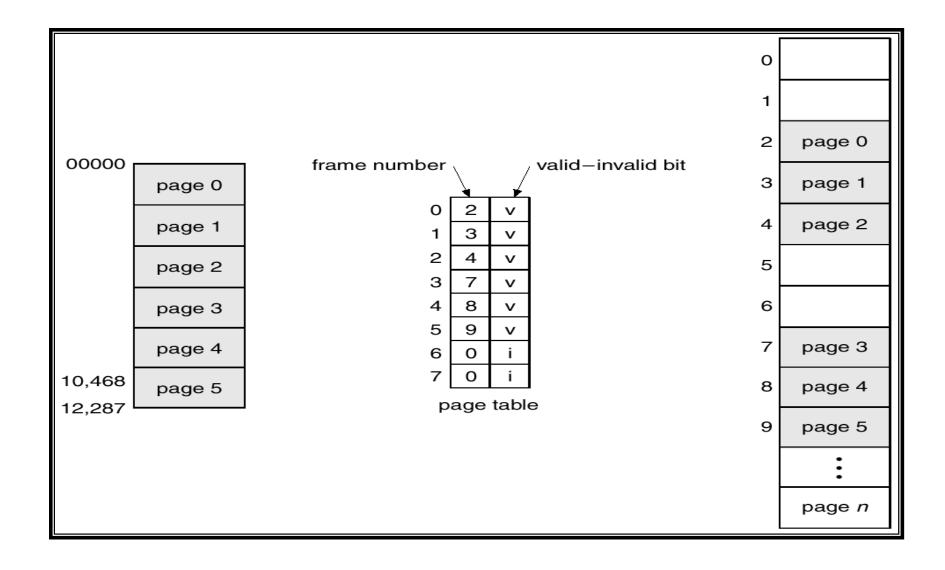
#### **Effective Access Time**

- If it takes 20 nsec to search the associative registers and 100 nsec to access memory and hit ratio is 80 %, then,
  - Effective access time=hit ratio\*Associate memory access time +miss ratio\* memory access time.
  - 0.80 \* 120+0.20\*220=140 nsec.
    - 40 % slowdown.
- For 98-percent hit ratio, we have
  - Effective access time= 98\*120+0.02\*220
    - = 122 nanoseconds
      - = 22 % slowdown.

### **Memory Protection**

- Memory protection implemented by associating protection bit with each frame.
- One bit can be assigned to indicate read and write or readonly
  - An attempt to write read-only page causes hardware trap to OS.
- More bits can be added to provide read-only, read-write or execute-only protection.
- Valid-invalid bit attached to each entry in the page table:
  - "valid" indicates that the associated page is in the process' logical address space, and is thus a legal page.
  - "invalid" indicates that the page is not in the process' logical address space.
  - Illegal addresses can be trapped with valid/invalid bit.
  - Some systems implement page table length register (PTLR) in case of internal fragmentation.
    - PTLR is used to check whether address is in valid range or not.

# Valid (v) or Invalid (i) Bit In A Page Table



# Page Table: Space Issue

#### Page table:

- Each process has a page table associated with it.
- The page table has a slot for each logical address regardless of its validity.
- Since table is sorted by virtual address, OS calculates the value directly.
- **However**, It consumes more space.
- Example regarding space issue: Modern computer systems support a very large address space: 2<sup>32</sup> to 2<sup>64</sup>.
  - Consider a system with 32-bit logical address space. If the page size is 4K, then the page table size is  $2^{12}$  entries.
  - If each entry consists of 4 bytes, then each process may need 4 mega bytes for a page table.

# Page Table Structure

Hierarchical Paging

Hashed Page Tables

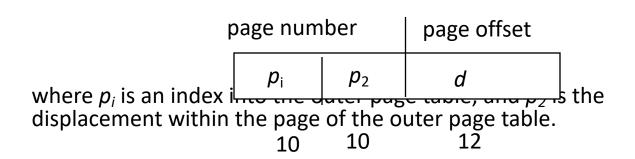
Inverted Page Tables

# Hierarchical Page Tables

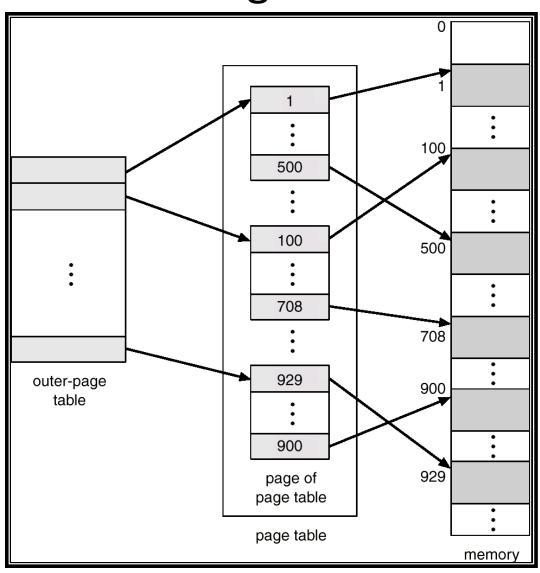
- Modern computer systems support a very large address space:  $2^{32}$  to  $2^{64}$ .
  - Consider a system with 32-bit logical address space. If the page size is 4K, then the page table size is  $2^{12}$  entries.
  - If each entry consists of 4 bytes, then each process may need 4 mega bytes.
- Solution: Break up the logical address space into multiple page tables.
- A simple technique is a two-level page table.
  - Page table itself is paged.

# Two-Level Paging Example

- A logical address (on 32-bit machine with 4K page size) is divided into:
  - a page number consisting of 20 bits.
  - a page offset consisting of 12 bits.
- Since the page table is paged, the page number is further divided into:
  - a 10-bit page number.
  - a 10-bit page offset.
- Thus, a logical address is as follows:

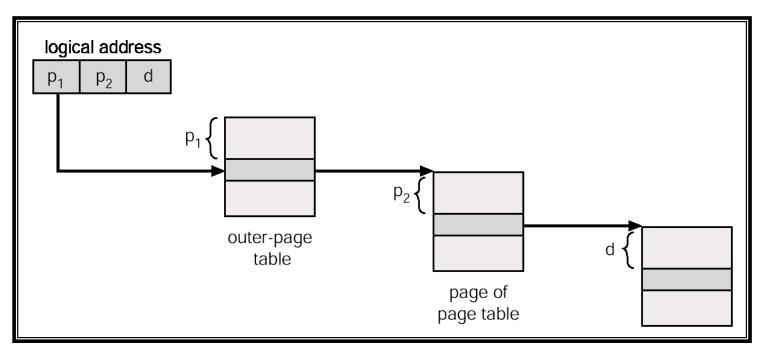


# Two-Level Page-Table Scheme



#### Address-Translation Scheme

 Address-translation scheme for a two-level 32bit paging architecture



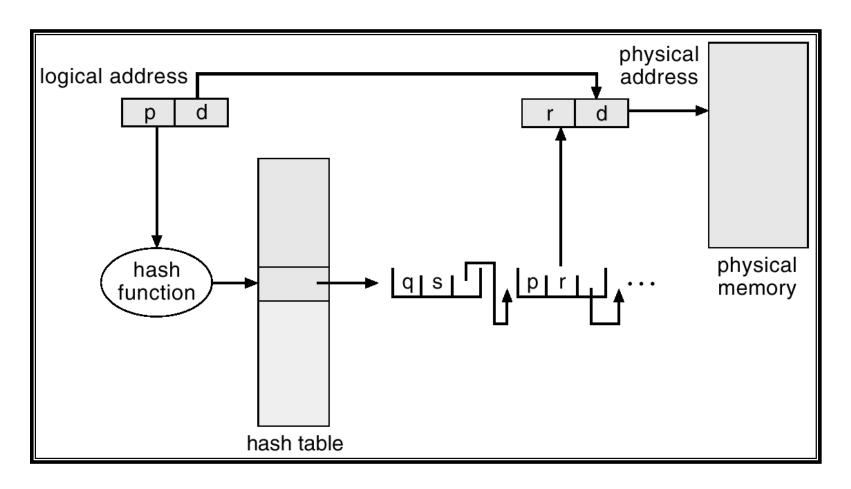
#### Address-Translation Scheme

- VAX 32-bit architecture supports a variation of two-level paging scheme
- SPARC 32 bit architecture supports 3-level paging scheme.
- 32-bit Motorola 68030 supports a 4-level paging scheme.
- Tradeoff: size versus speed
  - For 64-bit architectures hierarchical page tables are inappropriate.
  - For example, the 64-bit UltraSPARC would require seven levels of paging.

# Hashed Page Tables

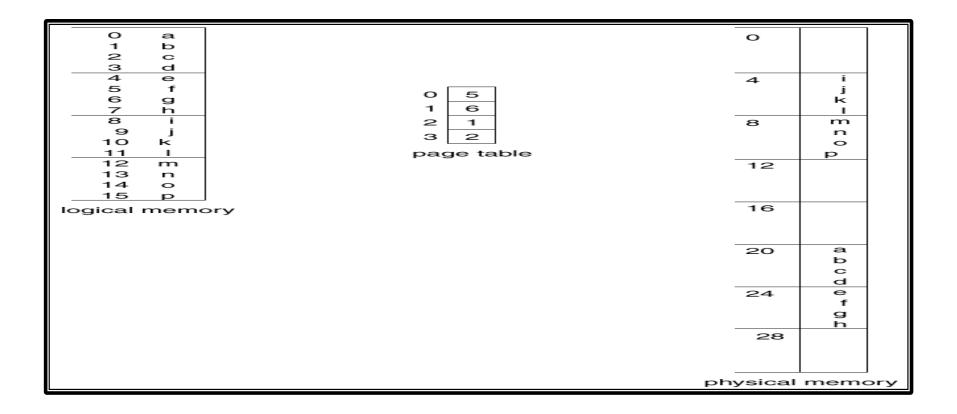
- Common in address spaces > 32 bits.
- The virtual page number is hashed into a page table. This
  page table contains a chain of elements hashing to the same
  location.
- Virtual page numbers are compared in this chain searching for a match. If a match is found, the corresponding physical frame is extracted.

# Hashed Page Table



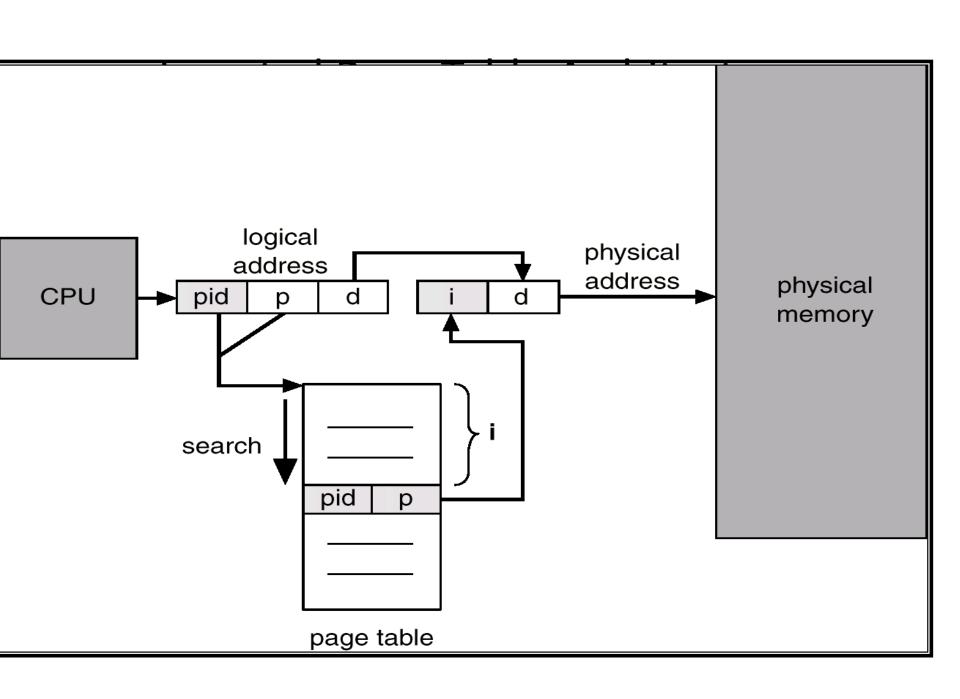
# Inverted Page Table

- Page table:
  - Each process has a page table associated with it.
  - The page table has a slot for each logical address regardless of its validity.
  - Since table is sorted by virtual address, OS calculates the value directly.
  - It consumes more space.
- Solution: Inverted page table



#### Solution: Inverted page Table

- One entry for each real page of memory.
- Entry consists of the virtual address of the page stored in that real memory location, with information about the process that owns that page.
- Decreases memory needed to store each page table, but increases time needed to search the table when a page reference occurs.
- There is only one page table in the system.
- Each virtual address space in the the system consists of a triple <Process-id, page #, offset>
- When a memory reference occurs part of process-id, page#> is presented to memory subsystem.
- The inverted page table is searched for a match.
- Use hash table to limit the search to one or at most a few page-table entries.
- It is implemented in 64-bit UltraSPARC and PowerPC.
- Decreases amount of memory but increases time needed to search the table.



# Advantage of paging Shared Pages

Paging allows sharing of common code.

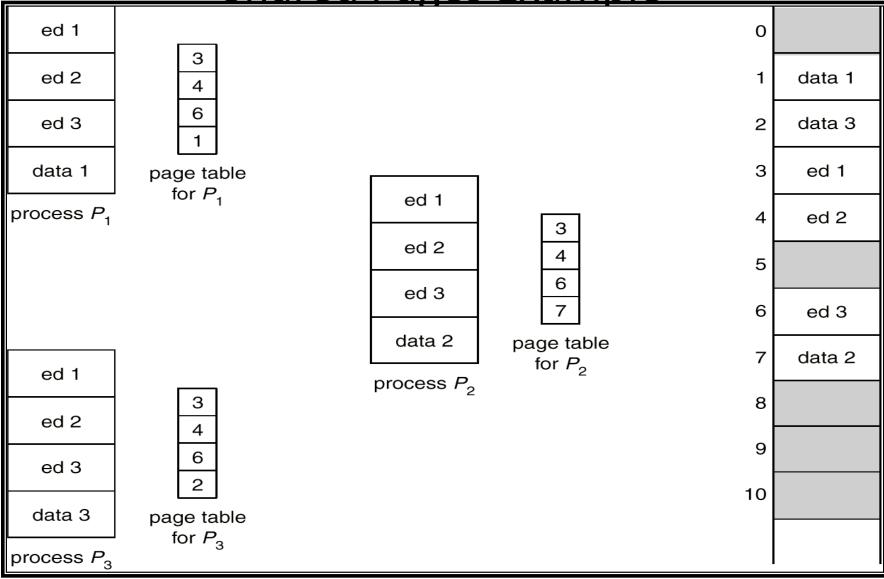
#### Shared code

- One copy of read-only (reentrant) code shared among processes (i.e., text editors, compilers, window systems).
- Shared code must appear in the same location in the logical address space of all processes.

#### Private code and data

- Each process keeps a separate copy of the code and data.
- The pages for the private code and data can appear anywhere in the logical address space.
- For example if a system supports text editor and supports 40 users. If the text editor consists of 150K and 50K of data space we need 8000K for the 40 users.
- If the code reentrant it can be shared.
  - Reentrant code is non-self modifying code
  - It never changes during execution
  - Ex: compilers, window system, DBS and so on can be shared.

Shared Pages Example

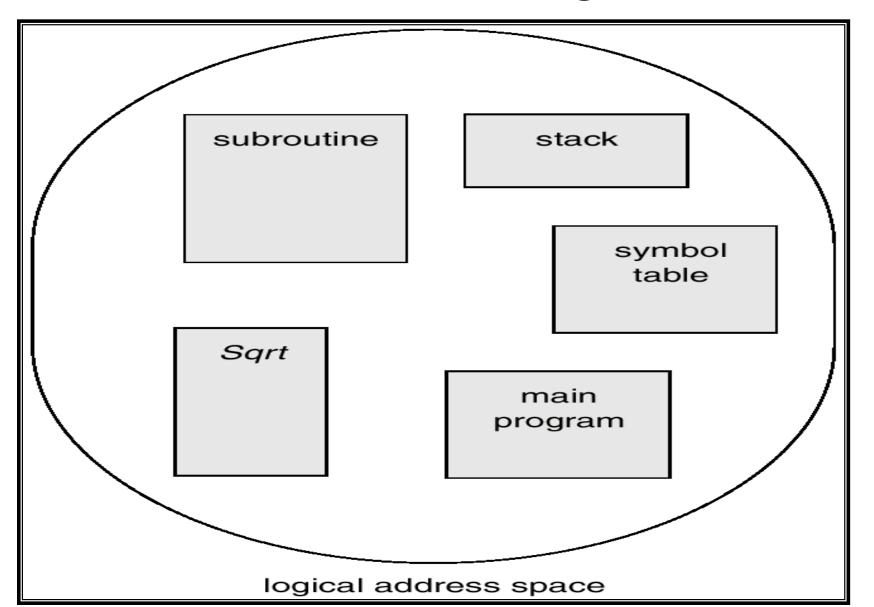


# Segmentation

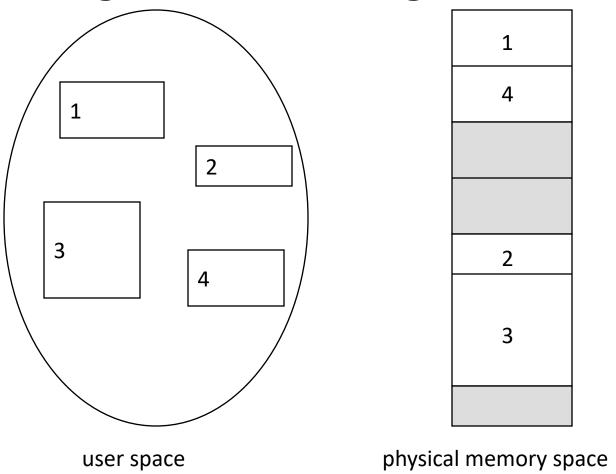
- Paging issues
  - Space: Size of page table
  - Searching time
- Segmentation is a memory-management scheme that supports user view of memory.
- Users prefer to view memory as a collection of variable-sized segments without any ordering.
- Logical address space is a collection of segments.
  - Each segment has name and length.
  - The address specify segment name and length.
- A program is a collection of segments. A segment is a logical unit such as:

```
main program,
procedure,
function,
method,
object,
local variables, global variables,
common block,
stack,
symbol table, arrays
```

# User's View of a Program



# Logical View of Segmentation



### Segmentation Architecture

Logical address consists of a two tuple:

<segment-number, offset>,

- Segment table maps two-dimensional physical addresses;
   each table entry has:
  - base contains the starting physical address where the segments reside in memory.
  - limit specifies the length of the segment.
- Segment-table base register (STBR) points to the segment table's location in memory.
- Segment-table length register (STLR) indicates number of segments used by a program;

segment number *s* is legal if *s* < STLR.

# Segmentation Architecture (Cont.)

#### Relocation.

- dynamic
- by segment table

#### • Sharing.

- shared segments
- same segment number

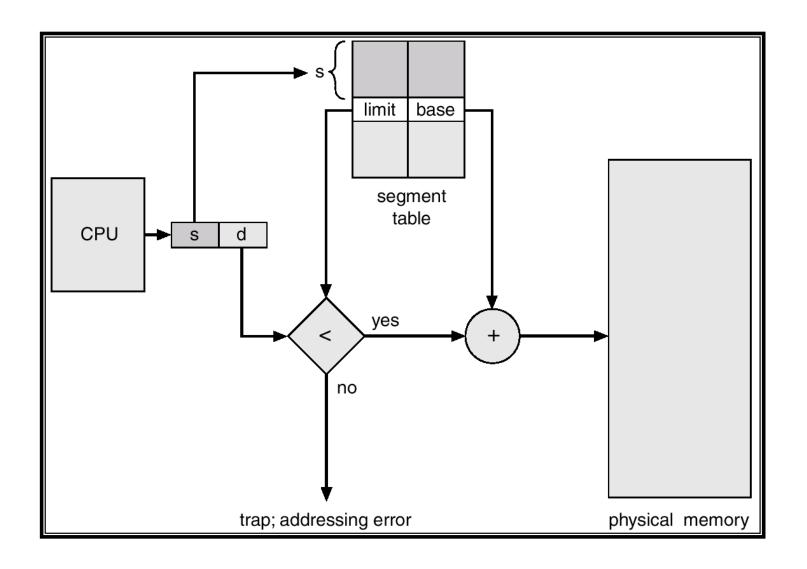
#### • Allocation.

- first fit/best fit
- external fragmentation

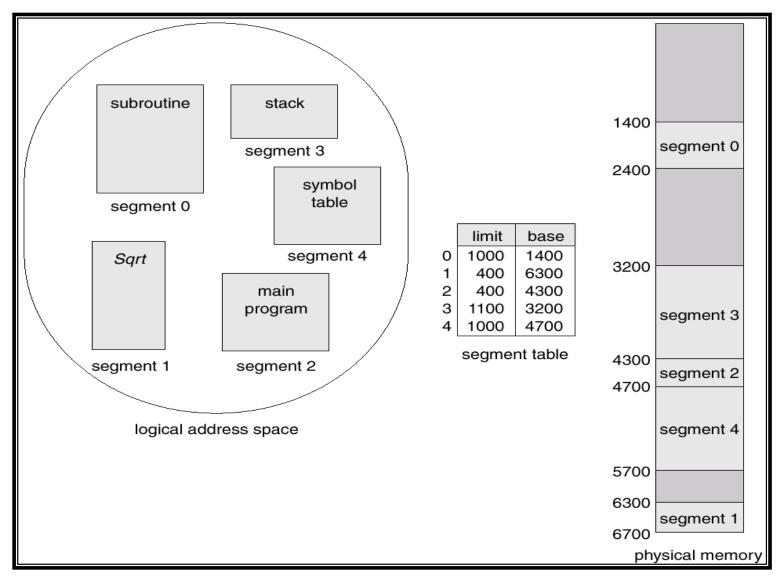
# Segmentation Architecture (Cont.)

- Protection. With each entry in segment table associate:
  - validation bit =  $0 \Rightarrow$  illegal segment
  - read/write/execute privileges
- Protection bits associated with segments; code sharing occurs at segment level.
- Since segments vary in length, memory allocation is a dynamic storage-allocation problem.
- A segmentation example is shown in the following diagram

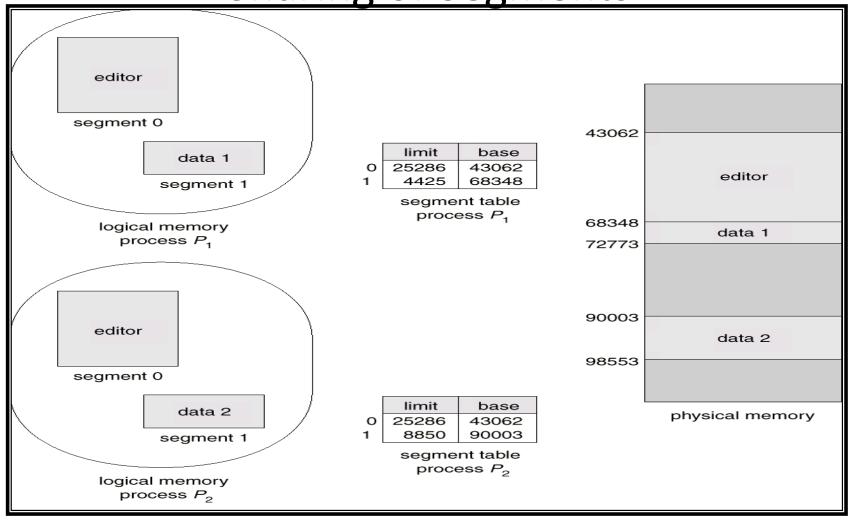
# Segmentation Hardware



# **Example of Segmentation**



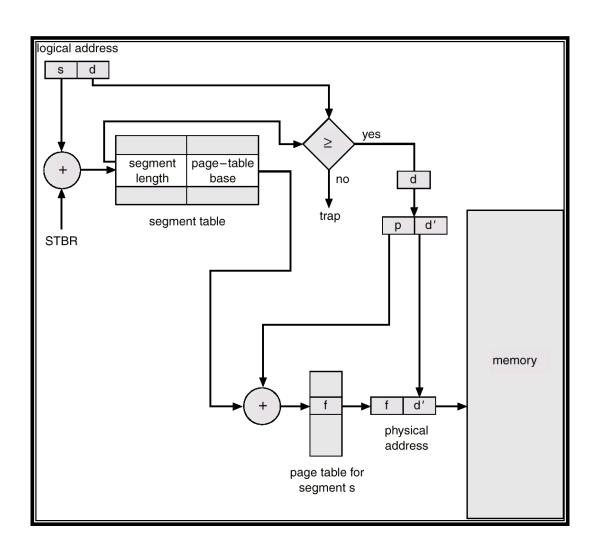
**Sharing of Segments** 



# Segmentation with Paging – MULTICS

- The MULTICS system solved problems of external fragmentation and lengthy search times by paging the segments.
- Solution differs from pure segmentation in that the segment-table entry contains not the base address of the segment, but rather the base address of a page table for this segment.

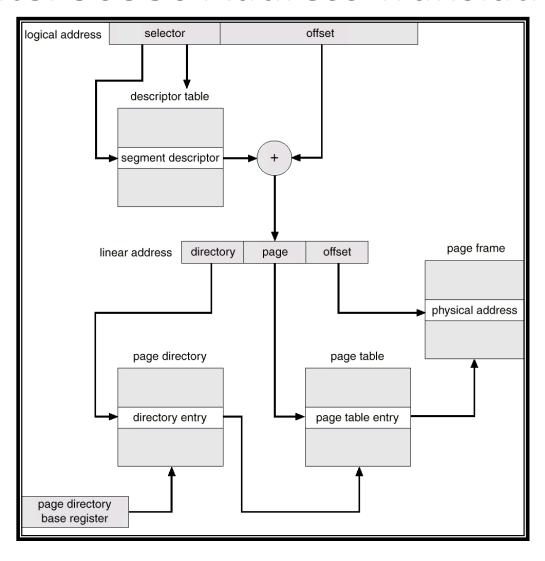
#### **MULTICS Address Translation Scheme**



# Segmentation with Paging – Intel 386

 As shown in the following diagram, the Intel 386 uses segmentation with paging for memory management with a two-level paging scheme.

#### Intel 30386 Address Translation



### Page Frame Management

- Page frames are 4KB in Linux.
- The kernel must keep track of the current status of each frame.
  - Are page frames allocated or free?
  - If allocated, do they contain process or kernel pages?
  - Linux maintains an array of page frame descriptors (one for each frame) of type struct page.
- NOTE: see the mm directory for memory management, especially page alloc.c.

### Page Frame Descriptors

- Each descriptor has several fields, including:
  - count equals 0 if frame is free, >0 otherwise.
  - flags an array of 32 bits for frame status.
    - Example flag values:
      - PG locked page cannot be swapped out.
      - PG\_reserved page frame reserved for kernel code or unusable.
      - PG\_Slab included in a slab (more later).

# The mem map Array

- All page frame descriptors are stored in the mem\_map array.
- Descriptors are less than 64 bytes. Therefore, mem\_map requires about 4 page frames for each MB of RAM.
- The MAP\_NR macro computes the number of the page frame whose address is passed as a parameter:
  - -#define MAP\_NR(addr) (\_\_pa(addr) >>
    PAGE\_SHIFT)
  - pa macro converts logical address to physical.

#### Requesting Page Frames

- Main routine for requesting page frames is:
   \_\_get\_free\_pages(gfp\_mask,order)
- Request 2°rder contiguous page frames.
- gfp\_mask specifies how to look for free frames. It is a bitwise OR of several flags, including:
  - GFP\_WAIT Allows kernel to discard page frame contents to satisfy request.
  - GFP\_IO Allows kernel to write pages to disk to free page frames for new request.
  - GFP\_HIGH/MED/LOW Request priority. Usually user requests are low priority while kernel requests are higher.
    - eg., GFP\_ATOMIC=\_\_GFP\_HIGH; GFP\_USER=\_GFP\_WAIT=1|\_GFP\_IO=1|\_GFP\_LOW;

## Releasing Page Frames

Main routine for freeing pages is:

```
Free_pages (addr, order)
```

- Check frame at physical address addr.
  - If not reserved, decrement descriptor's **count** field.
    - If count==0, free 2<sup>order</sup> contiguous frames.
      - » **free\_pages\_ok()** inserts page frame descriptor of 1<sup>st</sup> free page in list of free page frames.

# **External Fragmentation**

- External fragmentation is a problem when small blocks of free page frames are scattered between allocated page frames.
  - Becomes impossible to allocate large blocks of contiguous page frames.
- Solution:
  - Use paging h/w to group non-contiguous page frames into contiguous linear (virtual) addresses.
  - Track free blocks of contiguous frames & attempt to avoid splitting large free blocks to satisfy requests.
    - DMA controllers, which bypass the paging hardware, sometimes need contiguous page frames for buffers.
    - Contiguous frame allocation can leave page tables unchanged TLB contents don't need to be flushed, so memory access times are reduced.

# The Buddy System

- Free page frames are grouped into lists of blocks containing 2<sup>n</sup> contiguous page frames.
  - Linux has 10 lists of 1,2,4,...,512 contiguous page frames.
  - Physical address of 1<sup>st</sup> frame in a block is a multiple of the group size e.g., multiple of 16\*2<sup>12</sup> for a 16-page-frame block.

# **Buddy Allocation**

- Example: Need to allocate 65 contiguous page frames.
  - Look in list of free 128-page-frame blocks.
  - If free block exists, allocate it, else look in next highest order list (here, 256-page-frame blocks).
  - If first free block is in 256-page-frame list, allocate a 128-page-frame block and put remaining 128-page-frame block in lower order list.
  - If first free block is in 512-page-frame list, allocate a 128-page-frame block and split remaining 384 page frames into 2 blocks of 256 and 128 page frames. These blocks are allocated to the corresponding free lists.
- Question: What is the worst-case internal fragmentation?

## **Buddy De-Allocation**

- When blocks of page frames are released the kernel tries to merge pairs of "buddy" blocks of size b into blocks of size 2b.
- Two blocks are buddies if:
  - They have equal size b.
  - They are located at contiguous physical addresses.
  - The address of the first page frame in the first block is aligned on a multiple of  $2b*2^{12}$ .
- The process repeats by attempting to merge buddies of size 2b, 4b, 8b etc...

# **Buddy Data Structures**

- An array of 10\* elements (one for each group size) of type **free area struct**.
  - free\_area[0] points to array for non-ISA DMA buddy system.
  - free\_area[1] points to array for ISA DMA buddy system.
  - Linux 2.4.x has a 3<sup>rd</sup> buddy system for high physical memory!
     Makes dynamic memory mgt fast!
- A group of binary arrays (bitmaps) for each group size in each buddy system.

# Example Buddy Memory Mgt

- 128MB of RAM for non-ISA DMA.
  - free\_area[0][k] consists of n bits, one for each pair of blocks of size  $2^{K}$  page frames.
    - Each bit in a bitmap is 0 if a pair of buddy blocks are **both** free or allocated, else 1.
  - free\_area[0][0] consists of 16384 bits, one for each pair of the 32768 page frames.
  - free\_area[0][9] consists of 32 bits, one for each pair of blocks of 512 contiguous page frames.

## Memory Area Management

- Memory areas are contiguous physical addresses of arbitrary length e.g., from a few bytes to several KBs.
- Could use a buddy system for allocating memory in blocks of size 2<sup>K</sup> within pages, and then another for allocating blocks in power-of-2 multiples of pages.
- Linux uses a *slab allocator* for arbitrary memory areas.
  - Memory is viewed as a collection of related objects.
    - Objects are cached when released so that they can be allocated quickly for new requests.
    - Memory objects of the same type are repeatedly used e.g., process descriptors for new/terminating processes.
  - Can have memory allocator for commonly used objects of known size and buddy system for other cases.

### **Linux Slab Allocator**

- Objects of same type are grouped into caches.
  - Can view caches by reading /proc/slabinfo.
  - Caches are divided into *slabs*, with >=1 page frames containing both allocated & free objects.
  - See mm/slab.c for more details.
- A newly created cache does not contain any slab or free objects.
- Slabs are assigned to a cache when:
  - A request for allocating a new object occurs.
  - Cache does not already have a free object.
    - Buddy system is invoked to get new pages for a slab.

### Slab De-allocation

- A slab is released only if the following conditions hold:
  - Buddy system is unable to satisfy a new request for a group of page frames.
  - Slab is empty all objects in it are free.
- Destructor methods\* on objects in an empty slab are invoked.
- Contiguous page frames in slab are returned to buddy system.
- NOTE: when objects are created, they also have corresponding constructor methods (possibly NULL valued) that can initialize objects.

# Object Alignment

- Memory accesses usually faster if objects are word aligned e.g., on 4-byte boundaries with 32-bit Intel architecture.
- Linux does not align objects if space is continually wasted as a result.
  - Linux rounds up object size to a factor of cache size if internal fragmentation does not exceed a threshold.
    - Idea is to trade fragmentation for aligning object of larger size.

## General Purpose Objects

- Linux maintains a list of general purpose objects, having geometrically distributed sizes from 32 to 131072 bytes.
- These objects are allocated using:

```
void *kmalloc(size_t size, int flags);
```

- flags is same as for get\_free\_pages().
  - e.g. **GFP\_ATOMIC**, **GFP\_KERNEL**.
- Gen purpose objects are freed using kfree().