

HW 01

Ex 2

$$w^* = \text{argmax}_w p(w|y)$$

$$p(y|w) = \mathcal{N}(y; Xw, \sigma^2 I)$$

$$p(w) = \mathcal{N}(w; 0, s^2 I) \rightarrow L2$$

$$p(w) = \frac{1}{2b} \exp^{-\frac{|w|}{b}} \rightarrow L1$$

Sol (a) $w_{\text{MAP}} = \text{argmax}_w p(w|y)$

$$= \text{argmax}_w \frac{p(y|w) p(w)}{p(y)}$$

$$= \text{argmax}_w p(y|w) p(w)$$

$$\log(w_{\text{MAP}}) = \text{argmax}_w [\log(p(y|w)) + \log(p(w))] \quad \text{--- (1)}$$

Now FOR L2

$$\log p(w) = -\frac{1}{2} w^T (s^2 I)^{-1} w + \text{constant}$$

$$= -\frac{1}{2s^2} w \cdot w^T + \text{constant} \quad \text{--- (2)}$$

$$\begin{aligned}
 \log P(y|\omega) &= \log N(\vec{y}; X\vec{\omega}, \sigma^2 I) \\
 &= -\frac{1}{2} (\vec{y} - X\vec{\omega})^T (\sigma^2 I)^{-1} (\vec{y} - X\vec{\omega}) \\
 &= -\frac{1}{2\sigma^2} (\vec{y} - X\vec{\omega})(\vec{y} - X\vec{\omega})^T \quad \text{--- (3)}
 \end{aligned}$$

Combining (1), (2), (3)

$$\begin{aligned}
 \log w_{\text{map}} &= \arg\max_w \left[-\frac{1}{2\sigma^2} (X\vec{\omega} - \vec{y})(X\vec{\omega} - \vec{y})^T - \frac{1}{2s^2} \omega \cdot \omega^T \right] \\
 &= \arg\max_w \left[-\frac{1}{2\sigma^2} \|X\omega - y\|^2 - \frac{1}{2s^2} \|\omega\|^2 \right] \\
 &= \arg\min_N \left[\frac{1}{N} \|X\omega - y\|^2 + \frac{\sigma^2}{Ns^2} \|\omega\|^2 \right]^2
 \end{aligned}$$

For L2, $\ell(\omega) = \frac{1}{N} \|X\omega - y\|^2 + \lambda \|\omega\|^2$

Thus ridge regression is equivalent to MAP estimate

where $\lambda = \frac{\sigma^2}{Ns^2}$

FOR L1

$$\begin{aligned}
 \log P(\omega) &= \log \left(\frac{1}{2b} \exp^{-\frac{|\omega|}{b}} \right) \\
 &= -\log 2b - \frac{|\omega|}{b} \\
 &= -\frac{|\omega|}{b} \quad \text{--- (4)}
 \end{aligned}$$

Putting (1), (2), (4)

$$\begin{aligned}\log w_{\text{map}} &= \underset{w}{\text{argmax}} \left[\frac{-1}{2\sigma^2} \|Xw - Y\|^2 - \frac{\|w\|}{b} \right] \\ &= \underset{w}{\text{argmin}} \left[\frac{1}{N} \|Xw - Y\|^2 - \frac{2\sigma^2}{b} \|w\| \right]\end{aligned}$$

& L_1 (LASSO) minimizes to,

$$E(w) = \frac{1}{N} \|Xw - Y\|^2 + \lambda \|w\|$$

Thus, Lasso is equivalent to MAP estimate

where $\lambda = \frac{2\sigma^2}{b}$

SOL(b)

$$p(w) = N(w; m_0, S_0)$$

$$p(w|y, m_0, S_0) = N(w; m, \Sigma)$$

$$p(y|w) = N(y; Xw, \sigma^2 I)$$

Now if $p(x) = N(x|u, \Lambda^{-1})$

& $p(y|x) = N(y|Ax+b, L^{-1})$

then the marginal distribution of y and conditional distribution of x given y are

$$p(y) = N(y|Au+b, L^{-1} + A\Lambda^{-1}A^T)$$

$$\& p(x|y) = N(x|\{A^T L(y-b) + \Lambda u\}, \Sigma)$$

$$\Sigma = (\Lambda + A^T L A)^{-1}$$

Thus $P(w/y, m_0, S_0)$
 $= N(x | \Sigma \{A^T L (y-b) + A\mu\}, \Sigma)$ } As $P(w)$ &
 $P(y/w)$ are
both normal.

where

$x = w$	$b = 0$
$\mu = m_0$	$A = X$
$\Lambda^{-1} = S_0$	$L = (\sigma^2 I)^{-1}$

$\Rightarrow P(w/y, m_0, S_0)$
 $= N(w | \Sigma \{X^T (\sigma^2 I)^{-1} (y) + (S_0)^{-1} m_0\}, \Sigma)$
 $\Sigma = ((S_0)^{-1} + X^T (\sigma^2 I)^{-1})^{-1}$

Hence

mean, $m = \Sigma \{X^T (\sigma^2 I)^{-1} (y) + (S_0)^{-1} m_0\}$
covariance, $S = \Sigma$
where $\Sigma = ((S_0)^{-1} + X^T (\sigma^2 I)^{-1})^{-1}$