- 1. Griffiths 3.15
- 2. Griffiths 3.22
- 3. Show $\frac{d}{dt}\langle \hat{p} \rangle = -\left(\frac{dV(x)}{dx}\right)$. Briefly compare this to its classical analog. (Note: if you don't discuss this, you won't get credit.)
- 4. Griffiths 3.37
- 5. Griffiths 3.43

Bryant Har bjh254

 $\begin{array}{c}
\left(\frac{1}{2}\right)\left[\left(\frac{1}{2}\right)\left(\frac{p^{2}}{2m}\right)^{2}\right] = \frac{1}{2m}\left(\frac{1}{2k}\right)^{2} = \frac{1}{2m}\left(\frac{1}{2k}\right)^{2} + \frac{1}{2m}\left(\frac{1}{2k}$

For Stationary States, $O_H=0 \Rightarrow reduces to O \ge O$ (useless)

 $\frac{Q_{3.22}}{|d\epsilon|} |\sigma_{H}\sigma_{t} \geq \frac{t\pi}{2} \quad \text{but} \quad \sigma_{Q} = \left| \frac{dQ_{\lambda}}{d\epsilon} \right| \sigma_{E}. \quad \text{Let } Q_{=x} \Rightarrow \left| \frac{d\langle x \rangle}{d\epsilon} \right| = \frac{|\langle p \rangle|}{m} = \frac{1}{m} |\langle p \rangle| \\ \left| \frac{d\langle x \rangle}{d\epsilon} \right| = \frac{1}{m} |\langle p \rangle| = \Rightarrow \quad \sigma_{H}\sigma_{E} = \frac{m}{|\langle \hat{p} \rangle|} \sigma_{H}\sigma_{x} \geq \frac{t\pi}{2} \Rightarrow \left| \frac{d\langle x \rangle}{d\epsilon} \right| = \frac{|\langle p \rangle|}{m} = \frac{1}{m} |\langle p \rangle| \\ \left| \frac{d\langle x \rangle}{d\epsilon} \right| = \frac{1}{m} |\langle p \rangle| = \Rightarrow \quad \sigma_{H}\sigma_{E} = \frac{m}{|\langle \hat{p} \rangle|} \sigma_{H}\sigma_{x} \geq \frac{t\pi}{2} \Rightarrow \left| \frac{d\langle x \rangle}{d\epsilon} \right| = \frac{|\langle p \rangle|}{m} = \frac{1}{m} |\langle p \rangle| \\ \left| \frac{d\langle x \rangle}{d\epsilon} \right| = \frac{1}{m} |\langle p \rangle| = \Rightarrow \quad \sigma_{H}\sigma_{E} = \frac{m}{|\langle \hat{p} \rangle|} \sigma_{H}\sigma_{x} \geq \frac{t\pi}{2} \Rightarrow \left| \frac{d\langle x \rangle}{d\epsilon} \right| = \frac{1}{m} |\langle p \rangle|$

 $\hat{\rho} = -i\hbar \nabla = \frac{\Im(\rho)}{\Im t} = -i\hbar \int_{dt}^{d} (4^* \nabla^4) dx = -i\hbar \int_{dx}^{d} \frac{d\Psi^*}{\Im t} \nabla\Psi + \Psi^* \nabla \frac{d\Psi}{\Im t} = -\hat{H} \Psi^* (\nabla \Psi) - \Psi^* \nabla (\hat{H} \Psi) dx$ $\int_{dx} \left[-\hat{H} \Psi^* (\nabla \Psi) - \Psi^* \nabla (\hat{H} \Psi) \right] = \int_{dx}^{d} \left[\frac{\hbar^2}{2m} (\Psi^* \nabla^3 \Psi - \nabla^2 \Psi^* \nabla \Psi) + (\nabla \Psi^* \nabla^4 \nabla \Psi - \Psi^* \nabla (\nabla \Psi)) \right] = \int_{dx}^{d} \left[\frac{\hbar^2}{2m} (\Psi^* \nabla^3 \Psi - \nabla^2 \Psi^* \nabla \Psi) - \nabla^2 \Psi^* \nabla \Psi \right]$ $+ (\nabla \Psi^* \nabla^4 \nabla \Psi - \Psi^* \nabla \Psi - \Psi - \Psi^* \nabla \Psi - \Psi^* \nabla \Psi - \Psi - \Psi -$

 $\int dx \left(\Psi^* v^3 \Psi - V^2 \Psi^* v \Psi \right) = \nabla \Psi^* v^2 \Psi^*_{-} v^2 \Psi^*_{-} v \Psi \begin{bmatrix} v + \frac{1}{2} v^2 \Psi^*_{-} V + \frac{1}{2} u^2 \Psi^*_{-} v \Psi = 0 \\ - \langle \nabla V \rangle + \frac{h^2}{2m} \int dx \left(\Psi^* v^3 \Psi - V^2 \Psi^*_{-} v \Psi \right) = - \langle \nabla V \rangle + \frac{h^2}{2m} \langle O \rangle = \frac{O \langle \hat{P} \rangle}{O \pm} = - \langle \frac{d V}{d x} \rangle$

This is identical to the analogous classical law $\frac{dP}{dt} = F = -\frac{dU}{dx}$. Force is neg deriv of potential $\frac{1}{2}$ time deriv of momentum.

This makes sense. Over expectation, quantum systems follow classical laws.

(ehrenfests theorem)

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Q3.371 $\frac{d}{dt} \langle Q \rangle = \frac{1}{4} \langle \hat{\hat{H}}, \hat{\hat{Q}} \rangle + \langle \frac{2}{2} \rangle
  Let Q = xp in Eq. 3.73, \frac{d}{d\epsilon}\langle xp \rangle = \frac{i}{\hbar}\langle [\hat{H}, xp] \rangle + \langle 3xp \rangle \Rightarrow \langle no \text{ operator } \epsilon \text{ dependence} \rangle
   [T_{1}x] = Txf - xTf = -\frac{t^{2}}{2n}x\nabla f - \frac{t^{2}}{2n}x\nabla f + xTf - xTf = -\frac{it}{m}
[T_{1}p] = Tpf - pTf = Tpf - Tpf = 0
  (V,x) = Vxf-xVf = Vxf-Vxf=0 [V,p]=Vpf-pVf=Vpf-(pV)f-yof=-pV=it OV
\Rightarrow \frac{i}{t}(H_1 \times p) = \frac{i}{h} \left[ -\frac{ih}{m} \langle p^2 \rangle + ih \langle x \nabla V \rangle \right] = 2\langle T \rangle - \langle x \frac{\partial V}{\partial x} \rangle
            \frac{\partial}{\partial E} \langle xp \rangle = 2\langle T \rangle - \langle x \frac{\partial V}{\partial x} \rangle In Stationary state, \frac{\partial}{\partial E} \langle xp \rangle = 0 since all expectations are independent
                                                              of time unless otherwise stateds
     V = \frac{1}{2} m(\omega x)^2 \Rightarrow V' = m\omega^2 x \Rightarrow x \frac{\partial V}{\partial x} = m\omega^2 x^2 = 2\langle V \rangle
      => 2\langle T \rangle = 2\langle V \rangle \Rightarrow \langle T \rangle = \langle V \rangle as desired
   Q3.43 | | z|2= Re(x)2 + In(x)2 = 4[(z+2*)2-(z-2*)2]
 a) \Rightarrow \sigma_A^2 \sigma_B^2 \ge |\langle f | g \rangle|^2 = \frac{1}{4} [(z + z^*)^2 - (z - z^*)^2]
    Per hint, we retain } examine the Re term (other goes to <c>2)
    \langle f|g \rangle = \langle (\hat{A} - \langle A \rangle) (\hat{B} - \langle B \rangle) \gamma \gamma \gamma \gamma = \langle AB \rangle - \langle A \rangle \langle B \rangle - \langle A \rangle \langle B \rangle - \langle A \rangle \langle B \rangle
    => \langle f|g\rangle + \langle g|f\rangle = \langle AB\rangle - \langle AXB\rangle + \langle BA\rangle - \langle AXB\rangle = \langle AB\rangle + \langle BA\rangle - 2\langle AXS\rangle = D
  b) A = B \Rightarrow \hat{C} = 0, \sigma_A^{4} \ge \frac{1}{4} (\langle A^2 \rangle + \langle A^2 \rangle - 2\langle A \rangle \langle A \rangle)^2 = \frac{4}{4} (\langle A^2 \rangle - \langle A \rangle^2)^2 = V_{ar}(\hat{A})^2 = \sigma_A^{4}
                   => Ox Ox > Ox They are in fact always equal
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