Thermoelastic fracture problems using Extended Finite Element Method



By Bharat Bhushan (153100048)

Under the guidance of Prof. Salil S. Kulkarni

Department of Mechanical Engineering, IIT Bombay

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Outline

- Introduction
- Motivation
- Literature Survey
- Work done
- Problem definition
- Conclusion





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- These stresses becomes very large around a discontinuity i.e crack tip. If temperature variation is sufficiently large, it can lead to failure.
- Applications: Nuclear power plants, cylinder-nozzle intersection in pressure vessels, aerodynamic heating of high-speed aircraft, ultra fast pulse lasers etc.



(a) The cylinder-nozzle intersection. (www.knowledge.autodesk.com)



(b) Cracked head of baffle bolt of Belgian Nuclear Reactor.(www.miningawareness.wordpress.com)

source: Tian, X., Shen. (2006). A direct finite element method study of generalized thermoelastic problems. International Journal of Solids and Structures, 43(7), 2050-2063.



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 - When $\phi=2\pi$, the problem becomes a crack problem and displacement and derivative of displacement vary as $u \propto r^{\frac{1}{2}}$ and $u' \propto r^{-\frac{1}{2}}$ respectively.
- As thermo-elastic problems are also governed by Laplace's equation, temperature will vary as $r^{\frac{1}{2}}$ and heat fluxes will be unbounded at the crack tip.

source: Atkinson, K. E. (1997). The numerical solution of integral equations of the second kind (Vol. 4). Cambridge university press.



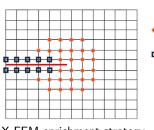
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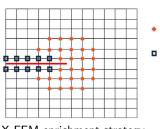


Tip-enriched Node



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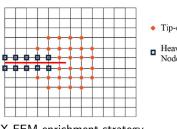


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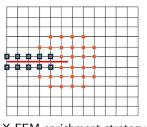


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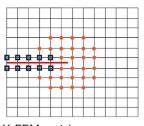


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 - No need of remeshing
 - Accurate solution



- Tip-enriched Node
- Heaviside-enriched
 Node



X-FEM enrichment strategy

Two types of enrichment functions in X-FEM



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 The nodes which belongs to the elements totally cut by the crack, are enriched by and Heaviside function.

$$h(x,y) = \begin{cases} 1, & \text{for } y \ge 0 \\ -1, & \text{for } y \le 0 \end{cases}$$



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• The nodes of elements which contains cracktip are enriched by γ :

$$u^{h} = \sum_{i} N_{i}(x)u_{i} + \sum_{j \in J} N_{j}(x)h(x)a_{j} + \sum_{k \in K} N_{k}(x) \left(\sum_{l=1}^{4} \gamma_{l}(x)b_{kl}\right)$$

$$v^{h} = \sum_{i} N_{i}(x)v_{i} + \sum_{j \in J} N_{j}(x)h(x)c_{j} + \sum_{k \in K} N_{k}(x) \left(\sum_{l=1}^{4} \gamma_{l}(x)d_{kl}\right)$$

$$where, \quad \gamma = \left[\sqrt{r}\cos\left(\frac{\theta}{2}\right), \sqrt{r}\sin\left(\frac{\theta}{2}\right), \sqrt{r}\sin\left(\frac{\theta}{2}\right)\sin(\theta), \sqrt{r}\cos\left(\frac{\theta}{2}\right)\sin(\theta)\right]$$

Source:Belytschko, T., & Black, T. (1999). Elastic crack growth in finite elements with minimal remeshing. International journal for numerical methods in engineering, 45(5), 601-620.



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- Solution of various thermoelastic fracture problems and comparison with the analytical solutions.
- Comparison between the results of FEM and X-FEM programs.





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$$\varepsilon_{ij} = \varepsilon_{ij}^{(M)} + \varepsilon_{ij}^{(T)} = \frac{1+\nu}{E} \sigma_{ij} - \frac{\nu}{E} \sigma_{kk} \delta_{ij} + \alpha (T-T_0) \delta_{ij}$$



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• It can be inverted to get following stress-strain relationship:

$$\begin{cases}
\sigma_{x} \\
\sigma_{y} \\
\tau_{xy}
\end{cases} = \frac{E}{(1-\nu^{2})} \begin{bmatrix} 1 & \nu & 0 \\
\nu & 1 & 0 \\
0 & 0 & 1-\nu \end{bmatrix} \begin{cases} \varepsilon_{x} - \alpha \Delta T \\
\varepsilon_{y} - \alpha \Delta T \\
\varepsilon_{xy}
\end{cases}$$

Governing Equations of Thermoelasticity



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• The governing equations of the thermo-elasticity is derived as:

$$\frac{\partial}{\partial x} \left[c_{11} \frac{\partial u}{\partial x} + c_{12} \frac{\partial v}{\partial y} \right] + \frac{\partial}{\partial y} \left[c_{66} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] - (c_{11} + c_{12}) \alpha \frac{\partial T}{\partial x} - f_x = 0$$

$$\frac{\partial}{\partial x} \left[c_{66} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + \frac{\partial}{\partial y} \left[c_{12} \frac{\partial u}{\partial x} + c_{22} \frac{\partial v}{\partial y} \right] - (c_{11} + c_{12}) \alpha \frac{\partial T}{\partial y} - f_y = 0$$

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• We can develop a week form of above equations by approximating u,v and T over a typical finite element Ω^e as:

$$u(x,y) = \sum_{i=1}^{n} N_i(x,y)u_i \ , v(x,y) = \sum_{i=1}^{n} N_i(x,y)v_i \ , T(x,y) = \sum_{i=1}^{n} N_i(x,y)T_i$$



$$\begin{split} -\int_{\Omega} \left[c_{11} \frac{\partial N_{i}}{\partial x} \frac{\partial N_{j}}{\partial x} u_{j} + c_{12} \frac{\partial N_{i}}{\partial x} \frac{\partial N_{j}}{\partial y} v_{j} \right] dx dy + \int_{\Omega} \left[c_{66} \frac{\partial N_{i}}{\partial y} \frac{\partial N_{j}}{\partial y} u_{j} dx dy + \frac{\partial N_{i}}{\partial y} \frac{\partial N_{j}}{\partial x} v_{j} \right] dx dy \\ -\int_{\Omega} \frac{\partial N_{i}}{\partial x} \beta N_{j} T_{j} dx dy + \int_{\Omega} N_{i} f_{x} dx dy + \int_{\Gamma} N_{i} \vec{t} dx = 0 \end{split}$$



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$$k \int_{\Omega} \left(\frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial x} + \frac{\partial N_i}{\partial y} \frac{\partial N_j}{\partial y} \right) T_j dx dy - \int_{\Omega} N_i N_j q dx dy = \int_{\Gamma} N_i \bar{Q} ds$$



• Neglecting the body forces, above equations can be written in matrix form as:

$$\begin{bmatrix} K_{11} & K_{12} \\ 0 & K_{22} \end{bmatrix} \begin{Bmatrix} U^e \\ T^e \end{Bmatrix} = \begin{Bmatrix} F \\ Q \end{Bmatrix}$$



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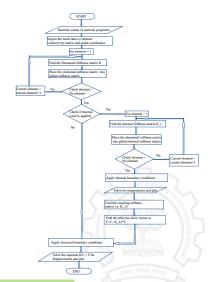
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$$[B] = \begin{bmatrix} \frac{\partial N_1}{\partial x} & 0 & \frac{\partial N_2}{\partial x} & 0 & \dots & \frac{\partial N_n}{\partial x} & 0 \\ 0 & \frac{\partial N_1}{\partial y} & 0 & \frac{\partial N_2}{\partial y} & \dots & 0 & \frac{\partial N_n}{\partial y} \\ \frac{\partial N_1}{\partial y} & \frac{\partial N_1}{\partial x} & \frac{\partial N_2}{\partial y} & \frac{\partial N_2}{\partial x} & \dots & \frac{\partial N_n}{\partial y} & \frac{\partial N_n}{\partial x} \end{bmatrix}, \ [B^{\theta}] = \begin{bmatrix} \frac{\partial N_1}{\partial y} & \frac{\partial N_2}{\partial y} & \dots & \frac{\partial N_n}{\partial y} \\ \frac{\partial N_1}{\partial y} & \frac{\partial N_2}{\partial y} & \frac{\partial N_2}{\partial y} & \dots & \frac{\partial N_n}{\partial y} \end{bmatrix}$$

$$N = \begin{bmatrix} N_1 & 0 & N_2 & 0 & \dots & N_n & 0 \\ 0 & N_1 & 0 & N_2 & \dots & 0 & N_n \end{bmatrix}, \ N^{\theta} = [N_1 \ \dots \ N_n]$$

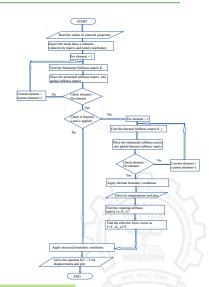


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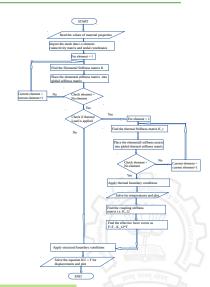
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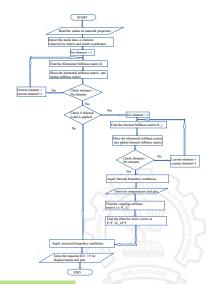


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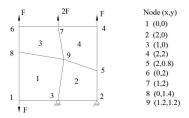
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A flow-chart showing the steps of the programming is shown in the figure.





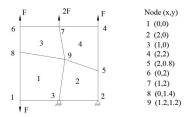
• A square plate is taken and meshed with 4 elements as shown in figure below.







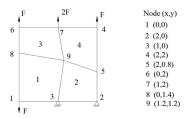
- A square plate is taken and meshed with 4 elements as shown in figure below.
- Minimum number of essential boundary conditions is fixed to eliminate the rigid body motions







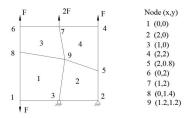
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- Loads are applied such that there is constant state of stress in the body



(a) Mesh Configuration



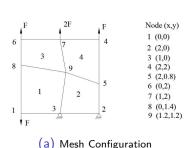
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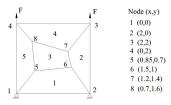


(b) Results of Patch Test 1

	Gauss Points	- /25	- /25	- /25
	Gauss Points	$\sigma_x/2F$	$\sigma_y/2F$	$\tau_{xy}/2F$
Element 1	1	-0.222×10^{-15}	1	0.1665×10^{-15}
	2	0.2498×10^{-15}	1	0.1665×10^{-15}
Liement 1	3	0.3058×10^{-15}	1	0.222×10^{-15}
	4	0	1	0
	1	-0.222×10^{-15}	1	0
Element 2	2	41633×10^{-15}	1 .	0.111×10^{-15}
	3	0.02775×10^{-15}	1	0.138×10^{-15}
	4	-0.1110×10^{-15}	1	-NO
	1	0.222×10^{-15}	1 2	0.1665×10^{-15}
Element 3	2	0.0555×10^{-15}	1	0.222×10^{-15}
Element 3	3	-0.0555×10^{-15}	1	0
	4	0.22204×10^{-15}	1	0
Element 4	1	-0.222×10^{-15}	1	0.1665×10^{-15}
	2	0.222×10^{-15}	1 /	0.1665×10^{-15}
	3	0.3058×10^{-15}	1	0.222×10^{-15}
	4	0.222×10^{-15}	1	0



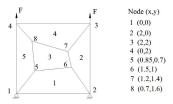
 Another patch test is performed on a plate with 5 element mesh and solved and results are tabulated as shown below



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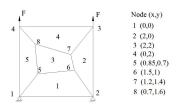
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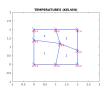
(a) Mesh Configuration

(b) Results of Patch Test 2

	Gauss Point	σ_x/F	σ_y/F	τ_{xy}/F
	1	0.166×10^{-15}	1	0.1665×10^{-15}
Element 1	2	-0.033×10^{-15}	1	0.1665×10^{-15}
	3	-0.063×10^{-15}	1	0.222×10^{-15}
	4	0	1	0
	1	0.062×10^{-15}	1	0
Element 2	2	41633×10^{-15}	1	-0.222×10^{-15}
Liement 2	3	0.02775×10^{-15}	1	0.138×10^{-15}
	4	-0.2220×10^{-15}	1	0
	1	0.222×10^{-15}	1	0.1665×10^{-15}
Element 3	2	0.0555×10^{-15}	1	0.222×10^{-15}
Element 3	3	-0.0555×10^{-15}	1	0
	4	0.22204×10^{-15}	1	0
Element 4	1	-0.222×10^{-15}	1	0.1665×10^{-15}
	2	0.222×10^{-15}	1	0.1665×10^{-15}
	3	-0.063×10^{-15}	1	0.222×10^{-15}
	4	0.222×10^{-15}	1	0
Element 5	1	-0.422×10^{-15}	1	0.1665×10^{-15}
	2	0.222×10^{-15}	1	0.1665×10^{-15}
	3	-0.063×10^{-15}	1	0.222×10^{-15}
	4	0.222×10^{-15}	1	0



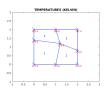
• Another patch was performed to validate the thermal code.



(a) Temperature distribution



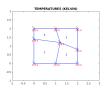
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- Same problem as patch test was taken



(a) Temperature distribution



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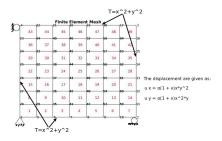
(b) Results of Patch test 3

3	TEMPERATURE:	S (KELVIN)	_
2.5			
2	alix alix	2016	- 1
1.5	4	3	-
1	7	in .	-
1.5	, /	2 276 K	-
0	273 K 273 K	2711	-
15			- 1
-1	15 0 05 1	15 2 25	_

(a) Temperature distribution

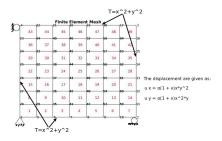
Nodes	Nodes Temperatures		$Q_{\times}(W)$	
1	273	200	0.125×10^{-10}	
2	273	200	0.155×10^{-10}	
3	273	200	0.222×10^{-10}	
4	281	200	0	
5	276	200	& INDIAN OSTITUS	
6	281	200	0	
7	281	200	0.111×10^{-10}	
8	279	200	0.138×10^{-10}	
9	278	200	0	



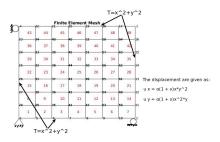


• A square plate of dimension 2×2 is taken and meshed as shown





- A square plate of dimension 2×2 is taken and meshed as shown
- Temperature distribution of $T = x^2 + y^2$ is applied on 4 boundaries of plate

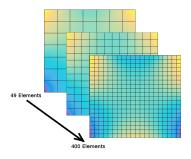


- A square plate of dimension 2×2 is taken and meshed as shown
- Temperature distribution of $T = x^2 + y^2$ is applied on 4 boundaries of plate
- a heat source $q=\frac{\partial^2 T}{\partial x^2}+\frac{\partial^2 T}{\partial y^2}=4$ is applied throughout the body
- Mesh is refined and to get the more accurate results

Mesh Refinements

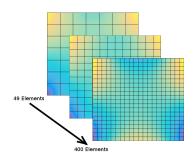


Mesh Refinements





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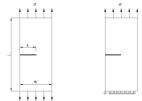
Errors obtained after mesh refinements

Number of Elements	Error in u _x	Error in u _y	Error in σ_x	Error in σ_y	Error in $ au_{xy}$
7 × 7	5.783469×10^{-10}	5.783469×10^{-10}	6.668255×10^{2}	6.668255×10^2	3.615391×10^{2}
12 × 12	1.764697×10^{-11}	1.764697×10^{-11}	1.000597121	1.000597121	0.031722
20 × 20	1.265804×10^{-12}	1.265804×10^{-12}	0.994299467	0.994299467	0.005781

Plate with edge crack



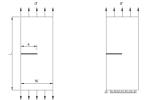
Plate with edge crack



(a) Plate with edge crack

 $\bullet\,$ A plate with edge crack is meshed in ANSYS and imported to MATLAB

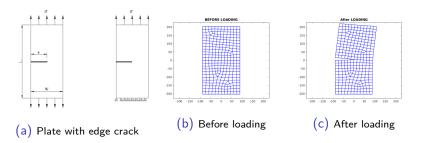
Plate with edge crack



(a) Plate with edge crack

- A plate with edge crack is meshed in ANSYS and imported to MATLAB
- Boundary conditions are applied and stresses ahead of cracktip is plotted

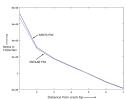
Plate with edge crack



- A plate with edge crack is meshed in ANSYS and imported to MATLAB
- Boundary conditions are applied and stresses ahead of cracktip is plotted
- The results obtained by MATLAB code is compared with the ANSYS solution



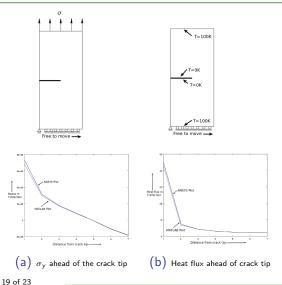




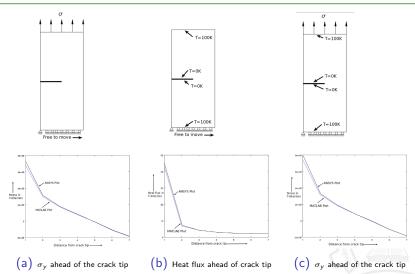
(a) σ_v ahead of the crack tip

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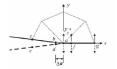




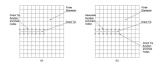


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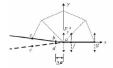


(a) Crack closure technique

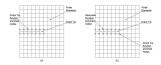


(b) X-FEM enrichment of nodes



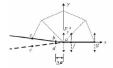


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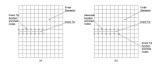


(b) X-FEM enrichment of nodes

Crack closure integral:
$$G_I = \frac{W}{B\Delta a} = \frac{F_y^a u_y^b}{2B\Delta a}$$
 Thus, $K_I = \sqrt{\frac{G_I}{E}} = 5.24586910 \times 10^9$ Pa \sqrt{m} Analytical: $K_I = C * \sigma \sqrt{\pi a} = 4.726065 \times 10^9$ Pa \sqrt{m}



(a) Crack closure technique



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Method used	$\%$ Error = $\{K_{theoretical} - K_{numerical}/K_{theoretical}\} imes 100$
Finite Element Method	11.1%
Extended Finite Element Method	4%



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- As the hydrogen diffusion in cracked bodies are governed by the Poisson's equation similar to the thermoelastic problems, we will modify the X-FEM program to solve problems of hydrogen-diffusion

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